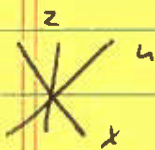


• PROJECTIONS...

\Rightarrow Axonometric project into xy -/ xz -/ yz -plane!

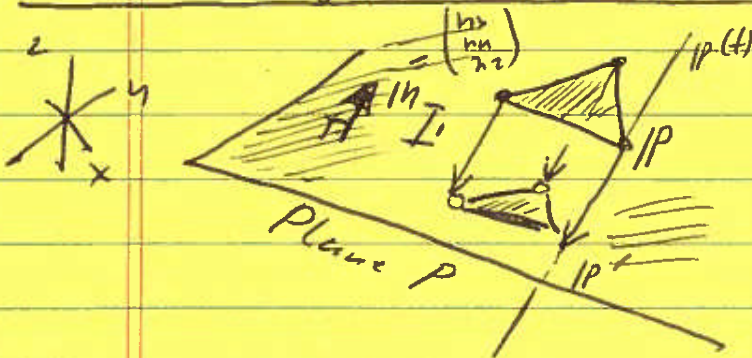
\Rightarrow 'Animation' : Continually rotate an object by $1^\circ, 2^\circ, 3^\circ, \dots, 360^\circ$ and

around arbitrary axis in 3D space, & project into coord. sys. planes



\Rightarrow "Movie"

• ORTHO PROJ. ONTO ARBITRARY PLANE IN 3D SPACE



① $P: Ax + By + Cz + D = 0$

② $IP(t) = \begin{pmatrix} x(t) \\ y(t) \\ z(t) \end{pmatrix}$

$= IP + t \cdot n$

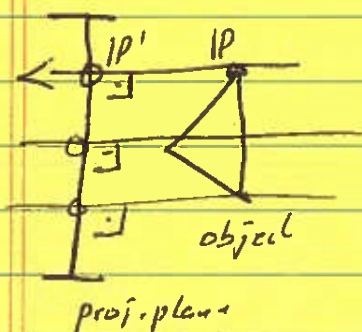
$= \begin{pmatrix} x \\ y \\ z \end{pmatrix} + t \begin{pmatrix} n_x \\ n_y \\ n_z \end{pmatrix}$

OR: Reduce to axonometric proj. into coord. sys. plane

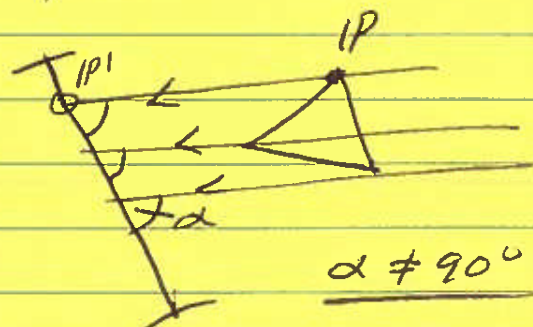
② into ①: $A \cdot (x + t n_x) + B \cdot (y + t n_y) + C \cdot (z + t n_z) = -D$
 $\Rightarrow t = \dots \Rightarrow \underline{IP(t) = \dots}$ ✓

• OBLIQUE PROJS

ortho proj:

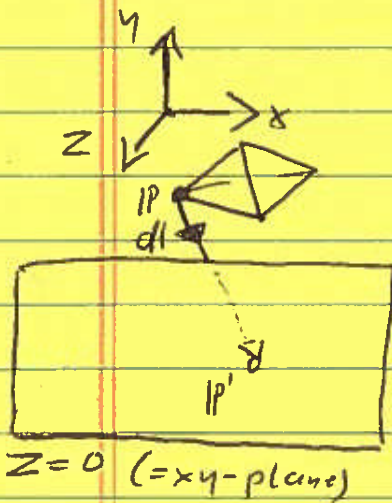


oblique:



$\alpha \neq 90^\circ$

• OBLIQUE PROJ IN MATRIX FORM



Ex: oblique proj. into $z=0$ plane
given: $d = \begin{pmatrix} dx \\ dy \\ dz \end{pmatrix}$, $dz \neq 0$

\Rightarrow Ray & line equation:

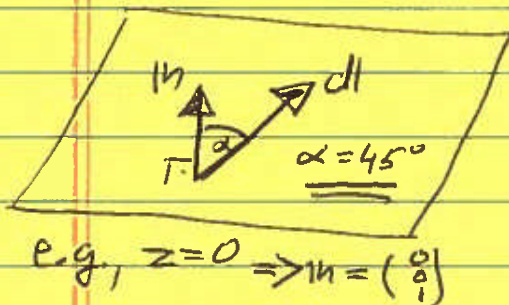
$$P' = \begin{pmatrix} x' \\ y' \\ 0 \end{pmatrix} = \begin{pmatrix} x \\ y \\ z \end{pmatrix} + t \cdot \begin{pmatrix} dx \\ dy \\ dz \end{pmatrix}$$

$$\Rightarrow 0 = z + t \cdot dz \Rightarrow t = -z/dz$$

$$\Rightarrow \begin{pmatrix} x' \\ y' \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & -dx/dz & 0 \\ 0 & 1 & -dy/dz & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix}$$

• SPECIAL / IMPORTANT ONES (OBLIQUE):

① CAVALIER: angle between h and $d = \underline{45^\circ}$
 (infinite possibilities)



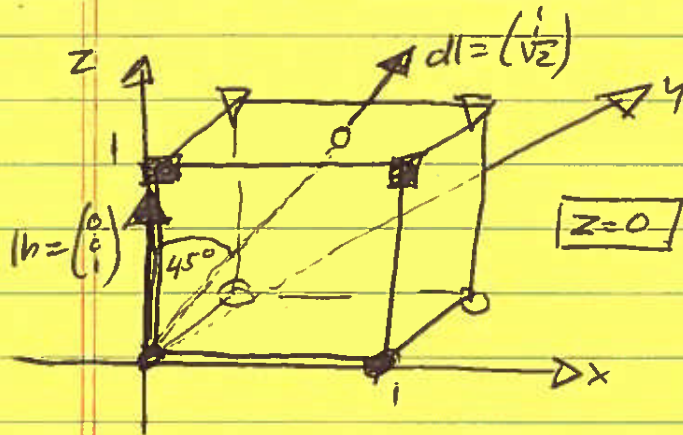
Ex: $z=0 \Rightarrow h = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$

$d = \begin{pmatrix} 1 \\ 1 \\ \sqrt{2} \end{pmatrix}$

{check: $h \cdot d / 2 = \sqrt{2}/2 = \cos(\alpha) \Rightarrow \underline{\alpha = 45^\circ}$ }

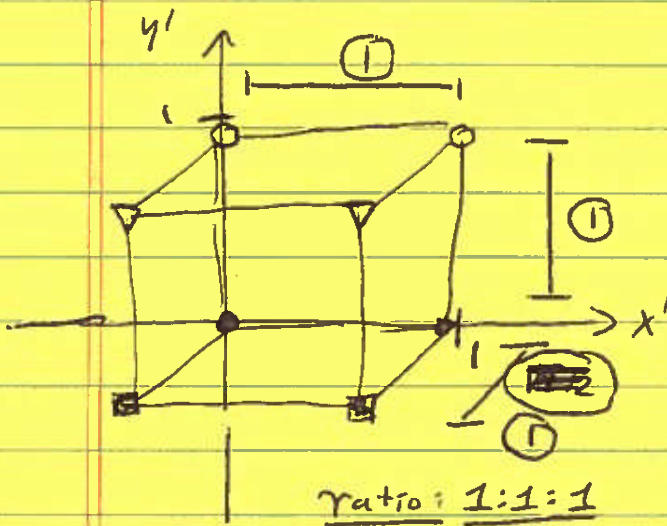
$$\Rightarrow \text{CAV} = \begin{pmatrix} 1 & 0 & -\sqrt{2}/2 & 0 \\ 0 & 1 & -\sqrt{2}/2 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

• Ex. Project UNIT CUBE using CAVALIER:



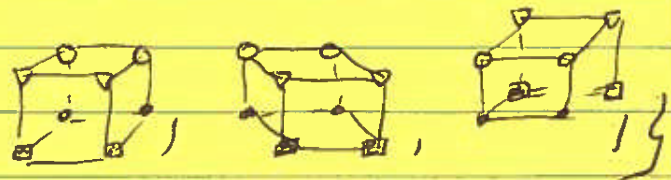
$$\begin{pmatrix} x' \\ y' \\ z'=0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & -dx/dz \\ 0 & 1 & -dy/dz \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$

$\sqrt{2}/2$

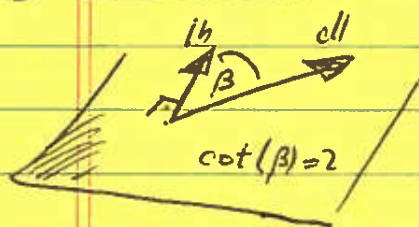


x	y	z	x'	y'
0	0	0	0	0
1	0	0	1	0
0	1	0	0	1
1	1	0	1	1
0	0	1	$\sqrt{2}/2$	$-\sqrt{2}/2$
1	0	1	$1 - \sqrt{2}/2$	$-\sqrt{2}/2$
0	1	1	$-\sqrt{2}/2$	$1 - \sqrt{2}/2$
1	1	1	$1 - \sqrt{2}/2$	$1 - \sqrt{2}/2$

{ ANIMATION: Rotate dl around Z -axis:



⑥ CABINET

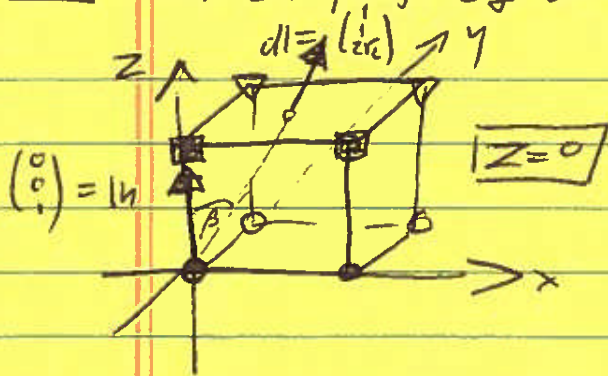


\Rightarrow infinite possibilities for plane & direction vector dl

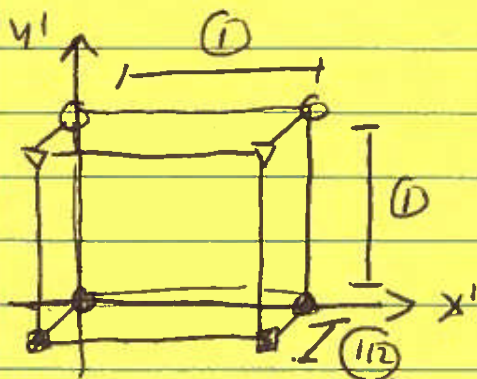
\Rightarrow Ex $lh = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$, $dl = \begin{pmatrix} 1 \\ 2\sqrt{2} \end{pmatrix}$
 $\Rightarrow \dots \cot(\beta) = 2 \}$

$$\Rightarrow CAB = \begin{pmatrix} 1 & 0 & -\sqrt{2}/4 & 0 \\ 0 & 1 & -\sqrt{2}/4 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Ex: CAB. proj. of UNIT CUBE:



$$\begin{pmatrix} x' \\ y' \\ z'=0 \end{pmatrix} = \begin{pmatrix} 1 & 0 & -\sqrt{2}/4 \\ 0 & 1 & -\sqrt{2}/4 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix}$$



ratio: $1:1:\sqrt{2}$

consequence of $\cot(\beta) = 2$

x	y	z	x'	y'
0	0	0	0	0
1	0	0	1	0
0	1	0	0	1
1	1	0	1	1
0	0	1	$-\sqrt{2}/4$	$-\sqrt{2}/4$
1	0	1	$1-\sqrt{2}/4$	$-\sqrt{2}/4$
0	1	1	$-\sqrt{2}/4$	$1-\sqrt{2}/4$
1	1	1	$1-\sqrt{2}/4$	$1-\sqrt{2}/4$

\Rightarrow Animation: rotate d around z -axis

\Rightarrow General: General oblique projection:

- any plane normal h ,
- any direction vector d
(not lying in the plane of projection)

==