

## Lecture Notes 5

### Process Synchronization

- Producer Consumer – Incorrect implementation of Producer Consumer

```
//Producer Code
while(true){
    while(counter == BUFFER_SIZE);
    buffer[in] = nextProduced;
    in = (in + 1) % BUFFER_SIZE;
    counter++;
}

//Consumer Code
while(true){
    while(counter == 0);
    nextConsumed = buffer[out];
    out = (out + 1) % BUFFER_SIZE;
    counter--;
}
```

- Race Condition – The result of multiple processes accessing and manipulating the same data concurrently depends upon order of access
- Process Synchronization and Coordination – The joining up (or handshaking) at specific time to agree upon actions
- Critical Sections – Critical portion of code that only one process can execute concurrently
  - Enter/Exit Section – The code that enters/exits the critical section
  - Mutual Exclusion – If process  $P_i$  is executing in critical section no other process is executing in the critical section
  - Progress – Only processes in remainder section can decide on next to enter
  - Bounded Waiting – Limit on the number of times process is “skipped” before entrance to critical section is granted
- Peterson’s Solution – Shared memory software solution to critical section problem

- Two Processes

```
#define FALSE 0
#define TRUE 1
#define N 2
volatile int Turn;
volatile int Interested[N];

void EnterSection(void){
    Interested [Me] = TRUE;
    Turn = Other;
    while(Interested [Other] && Turn == Other);
}

void ExitSection(void){
    Interested [Me] = FALSE;
}
```

- Hardware Support – Special hardware or instructions that support synchronization
  - Lock – A mechanism that prevents other processes from entering locked region
  - Atomic Instructions
    - Test and Set – Atomically tests and sets a memory location

```
EnterSection:
    tsl    lock
    jnz    EnterSection
    ret
```

```
ExitSection:
    move lock, #0
    ret
```

- **Swap** – Atomically swaps one memory location for register value

```
EnterSection:
    move register, #1
    swap register, lock
    cmp register, #0
    jne EnterSection
    ret
```

```
ExitSection:
    move lock, #0
    ret
```

- **Mutex Locks** – Mutual Exclusion Lock
  - **Busy Waiting** – Constant checking of memory location for change
  - **Spinlock** – A Mutex Lock implemented using busy wait
- **Semaphores** – Integer value that is access through atomic operations
  - **P, V?** (Proberen, Verhogen) or up/down or wait/signal
  - **Counting Semaphore** – Allows over unrestricted domain
  - **Binary Semaphore (Mutex Lock)** – Limited to 0 and 1

```
typedef struct{
    int Value;
    struct processqueue Waiting;
} Semaphore;
```

```
void down(Semaphore *s){
    s->Value--;
    if(s->Value < 0){
        enqueue(S->Waiting, thisproc);
        block();
    }
}

void up(Semaphore *s){
    process P;
    s->Value++;
    if(s->Value <= 0){
        P = dequeue(s->Waiting);
        wakeup(P);
    }
}
```

- **Deadlock** – Processes are waiting upon one another to release resources
- **Indefinite Blocking (or Starvation)** – Process is waiting to enter critical section, but other processes keep going ahead of it
- **Priority Inversion** – When a low priority process has a resource and is blocking a high priority process, but cannot release resource because medium priority process is running.
  - **Priority-Inheritance Protocol** – Protocol to prevent Priority Inversion dynamically
  - **Priority Ceiling Protocol** – Protocol to prevent Priority Inversion at design time

- Classic Problems of Synchronization
  - Bounded-Buffer – Producer consumer with a bounded buffer

```
#define N 100
typedef int semaphore;
semaphore mutex = 1;
semaphore empty = N;
semaphore full = 0;

void producer(void) {
    int item;
    while(TRUE) {
        produce_item(&item);
        down(&empty);
        down(&mutex);
        enter_item(item);
        up(&mutex);
        up(&full);
    }
}

void consumer(void) {
    int item;
    while(TRUE) {
        down(&full);
        down(&mutex);
        remove_item(&item);
        up(&mutex);
        up(&empty);
        consume_item(item);
    }
}
```

- Readers Writers – Unlimited readers, but writer needs mutual exclusion

```
typedef int semaphore;
semaphore mutex = 1;
semaphore db = 1;

void reader(void) {
    while(TRUE) {
        down(&mutex);
        rc = rc + 1;
        if(rc == 1) down(&db);
        up(&mutex);
        read_data_base();
        down(&mutex);
        rc = rc - 1;
        if(rc == 0) up(&db);
        up(&mutex);
        use_data_read();
    }
}

void writer(void) {
    while(TRUE) {
        think_up_data();
        down(&db);
        write_data_base();
        up(&db);
    }
}
```

- Dining-Philosophers – Each process needs multiple resources
  - N Philosophers, Plates and Forks
  - Need 2 Forks to Eat

```
#define N          5
#define LEFT      (i-1) % N
#define RIGHT     (i+1) % N
#define THINKING  0
#define HUNGRY    1
#define EATING    2

typedef int semaphore;
int state[N];
semaphore mutex = 1;
semaphore s[N];

void philosopher(int i){
    while(TRUE){
        think();
        take_forks(i);
        eat();
        put_forks(i);
    }
}

void test(int i){
    if(state[i] == HUNGRY && state[LEFT] != EATING && state[RIGHT] !=
    EATING){
        state[i] = EATING;
        up(&s[i]);
    }
}
```

```
void take_forks(int i){
    down(&mutex);
    state[i] = HUNGRY;
    test(i);
    up(&mutex);
    down(&s[i]);
}
```

```
void put_forks(int i){
    down(&mutex);
    state[i] = THINKING;
    test(LEFT);
    test(RIGHT);
    up(&mutex);
}
```

- Sleeping Barber – Keep process working when “clients”, sleep when none
  - Single Barber
  - Single Barber Chair
  - N Chairs for Customers

```
#define CHAIRS     5

typedef int semaphore;

semaphore customers = 0;
semaphore barbers = 0;
semaphore mutex = 1;
int waiting = 0;

void barber(void){
    while(TRUE){
        down(&customers);
        down(&mutex);
        waiting = waiting -
        1;
        up(&barbers);
        up(&mutex);
        cut_hair();
    }
}

void customer(void){
    down(&mutex);
    if(waiting < CHAIRS){
        waiting = waiting +
        1;
        up(&customers);
        up(&mutex);
        down(&barbers);
        get_haircut();
    }
    else{
        up(&mutex);
    }
}
```

- Monitors – Abstract Data Type that provides mutual exclusion inside the monitor
  - Semaphore Implementation
  - Bounded Buffer

```

monitor ProducerConsumer
  condition full, empty;
  integer count;
  procedure enter;
  begin
    if count = N then
      wait(full);
    enter_item;
    count := count + 1;
    if count = 1 then
      signal(empty)
    end;
  end;

  procedure remove;
  begin
    if count = 0 then
      wait(empty);
    remove_item;
    count := count - 1;
    if count = N - 1 then
      signal(full)
    end;
    count := 0;
  end monitor;

  procedure producer;
  begin
    while true do
      begin
        produce_item;
        ProducerConsumer.enter
      end
    end;
  end;

  procedure consumer;
  begin
    while true do
      begin
        ProducerConsumer.remove;
        consume_item
      end
    end;
  end;

```

- Deadlock – Processes are waiting upon one another to release resources
  - Necessary Conditions for Deadlock
    - Mutual Exclusion – Resource must be held in non-sharable mode
    - Hold and Wait – Process holds a resource and is waiting on another
    - No Preemption – Resources must be voluntarily released
    - Circular Wait – Must have cycle of processes waiting
  - Resource Allocation Graph – Directed graph of acquired and requested resources and processes
    - Request Edge – Directed edge from process to resource
    - Assignment Edge – Directed edge from resource to process
    - Deadlock occurs if cycle in Resource Allocation Graph
  - Deadlock Prevention – Makes sure that all necessary conditions cannot hold
  - Deadlock Avoidance – Requires additional information about all resources a process will require