

Master's thesis in
Applied Computer Science

CoolingGen

A parametric 3D-modeling software for turbine
blade cooling geometries using NURBS

July 18, 2022

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I hereby declare that this thesis has been written by myself and no other resources than those mentioned have been used.

A handwritten signature in blue ink, appearing to read 'Lüken', with a stylized, cursive script.

Göttingen, July 18, 2022

Abstract

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1 Introduction

1.1 Motivation

1.2 State of the Art

1.3 Problem Statement

2 Methods

2.1 Bézier Curves

Bézier curves are named after the french engineer Pierre Bézier, who famously utilized them in the 1960s to design car bodies for the automobile manufacturer Renault [Béz68]. Today, they are used in a wide variety of vector graphics applications (i.e. in font representation on computers). At first glance, the definition of the Bézier curve might seem cumbersome, but given the mathematical foundation and a few graphical representations, it becomes apparent why they are such a powerful tool in computer-aided design.

2.1.1 Definition

Definition 2.1.1. The *Bernstein basis polynomials* of degree n on the interval $[t_0, t_1]$ are defined as

$$b_{n,k,[t_0,t_1]}(t) := \frac{\binom{n}{k}(t_1 - t)^{n-k}(t - t_0)^k}{(t_1 - t_0)^n}, \quad (2.1)$$

for $k \in \{0 \dots n\}$.

Definition 2.1.2. A *Bézier curve* of degree n is a parametric curve $C_{P,[t_0,t_1]} : [t_0, t_1] \rightarrow \mathbb{R}^3$ that has a representation

$$C_{P,[t_0,t_1]}(t) = \sum_{k=0}^n b_{n,k,[t_0,t_1]}(t)P_k = \sum_{k=0}^n \frac{\binom{n}{k}(t_1 - t)^{n-k}(t - t_0)^k}{(t_1 - t_0)^n} P_k. \quad (2.2)$$

We call the elements of the set $P = \{P_0, P_1, \dots, P_n\}$ the *control points* of C_P .

Remark. Let $t_0 = 0$ and $t_1 = 1$. Then 2.2 simplifies to

$$b_{n,k}(t) := b_{n,k,[0,1]}(t) = \binom{n}{k}(1 - t)^{n-k}t^k. \quad (2.3)$$

Also, 2.1 simplifies to

$$C_P(t) := C_{P,[0,1]}(t) = \sum_{k=0}^n \binom{n}{k}(1 - t)^{n-k}t^k P_k. \quad (2.4)$$

This case is the only case considered in this thesis.

2.1.2 de Casteljau's Algorithm

The computation of equation 2.4 is usually performed using de Casteljau's algorithm. This is because the algorithm yields a simple implementation and lower complexity than straightforwardly computing equation 2.4. The algorithm was proposed by Paul de Faget de Casteljau for the automobile manufacturer Citroën in the 1960s.

Algorithm 1 de Casteljau's algorithm

```
1: Input  
2:    $P = \{P_0, P_1, \dots, P_n\}$       set of control points  
3:    $t$                                 real number  
4: Output  
5:    $P_0^{(n)} = C_P(t)$               the point on the Beziér curve w.r.t. to  $t$   
6: procedure DECASTELJAU( $P, t$ )  
7:    $P^{(0)} \leftarrow P$   
8:   for  $i = 1, 2, \dots, n$  do  
9:     for  $j = 0, 1, \dots, n - i$  do  
10:       $P_j^{(i)} = (1 - t) \cdot P_j^{(i-1)} + t \cdot P_{j+1}^{(i-1)}$   
    return  $P_0^{(n)}$ 
```

A visual representation of algorithm 1 yields a triangular scheme. To compute one point on a Beziér curve C_P with degree n , one has to perform $n^2 - n$ additions and just as many scalar multiplications.

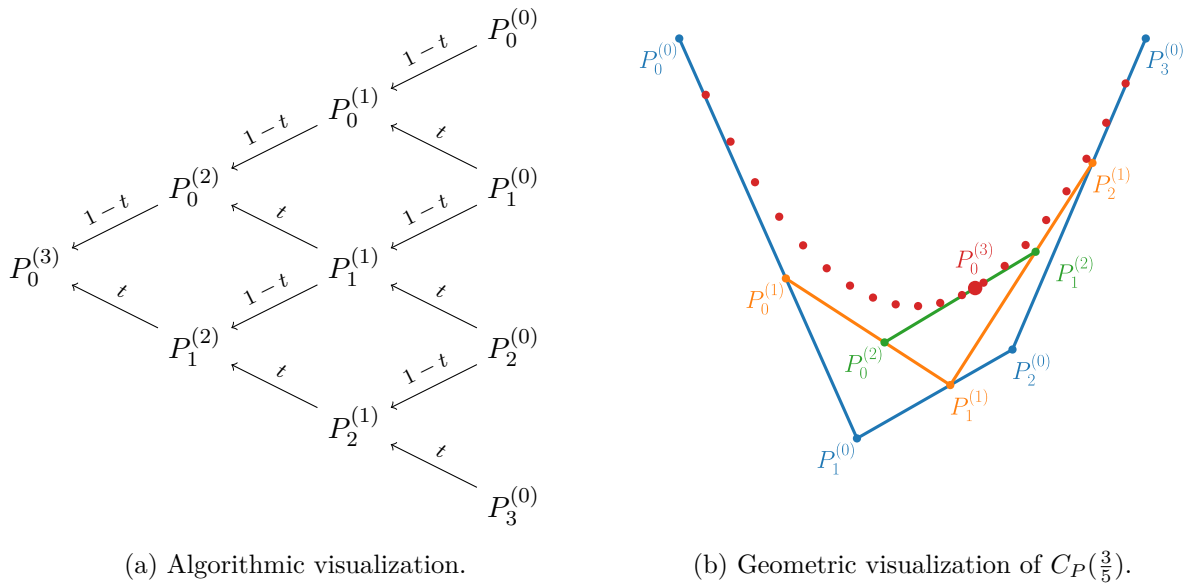


Figure 2.1: Visual representations of de Casteljau's algorithm.

Interestingly, the representation of the algorithm in Figure 2.1 also gives rise to an intuitive visualization of the geometric shape of the Beziér curve C_P . For all $i \in \{0, \dots, n\}$ and all $j \in \{0, \dots, n - i\}$, the point $P_j^{(i+1)}$ is the convex combination (always w.r.t. t) of $P_j^{(i)}$ and $P_{j+1}^{(i)}$. Thus $P_j^{(i+1)}$ always lies on the line segment between $P_j^{(i)}$ and $P_{j+1}^{(i)}$, as can also be observed in 2.1.

2.1.3 Properties

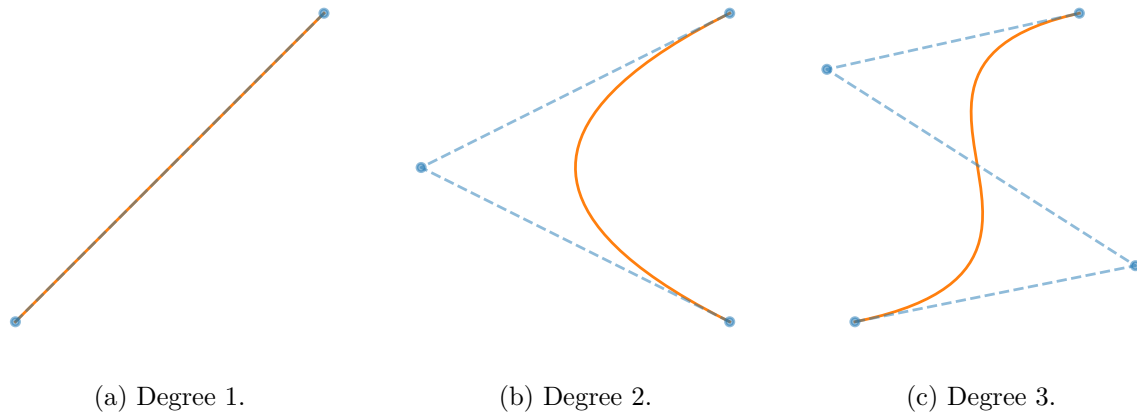


Figure 2.2: Beziér curves of different degrees (orange) and their control points (blue).

2.2 Non-Uniform Rational B-Splines (NURBS)

2.2.1 Definition

2.2.2 Properties

2.2.3 de Boor's Algorithm

2.3 Methods on NURBS Objects

2.3.1 Affine Transformations

2.3.2 The Frenet-Serret Apparatus

2.3.3 Finding Intersections

2.3.4 Interpolation

2.4 Jet Engine Design Specifics

2.4.1 Fundamental Terms

2.4.2 The S2M Net

2.4.3 Fillet Creation

3 Results

3.1 Cooling Geometries And Their Parametrizations

3.1.1 Chambers

3.1.2 Turnarounds

3.1.3 Slots

3.1.4 Film Cooling Holes

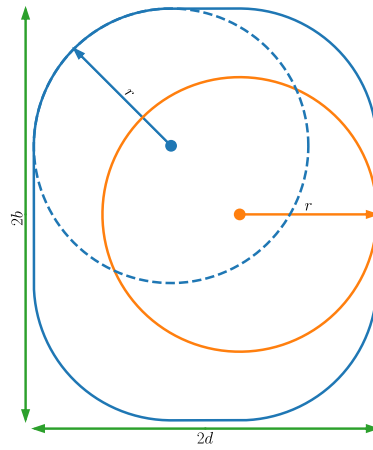


Figure 3.1: yeah

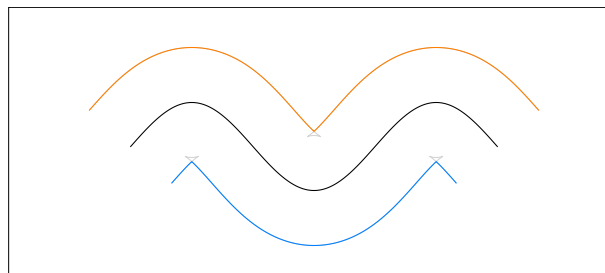


Figure 3.2: yeah

3.1.5 Impingement Inserts

3.2 Export for CENTAUR

3.3 Export for Open CASCADE

4 Discussion

4.1 Future Work

4.2 Conclusion

[Pie97]

5 References

- [Béz68] Pierre E. Bézier. “How Renault Uses Numerical Control for Car Body Design and Tooling”. In: *SAE Technical Paper Series*. SAE International, Feb. 1968. DOI: 10 . 4271/680010.
- [Pie97] Les A. Piegl. *The NURBS book*. Springer, 1997, p. 646. ISBN: 3540615458.