# Lab 4: Introduction to CUDA Programming

ECE 455: GPU Algorithm and System Design

Due: Submit completed PDF to Canvas by 23:25 PM 10/10

### Overview

This lab introduces CUDA, NVIDIA's parallel computing platform and API for programming GPUs. You will learn basic CUDA kernel programming, kernel launch configuration, and asynchronous execution with streams.

## Learning Objectives

In this lab, students will:

- Understand the basic structure of a CUDA program, including host code and device kernels.
- Learn how to configure kernel execution using grid and block dimensions.
- Gain experience in writing and launching simple CUDA kernels.
- Explore the use of CUDA streams for overlapping computation and data transfer.
- Implement and test basic parallel operations such as vector addition and SAXPY.
- Practice compiling and running CUDA programs using nvcc on the SLURM cluster.
- Develop skills to debug and verify correctness of GPU-based computations.

#### **Euler Instruction**

```
~$ ssh your_CAE_account@euler.engr.wisc.edu
~$ sbatch your_slurm_scrip.slurm
```

You should NEVER run your program on the log-in node with the interactive mode. Doing so will risk your account being blocked by the IT. Instead, you should work on your local machine and set up a GitHub repo to transfer code from your local machine to your Euler node, and then compile and run it using a proper sbatch script.

#### **Submission Instruction**

Specify your GitHub link here: https://github.com/boomchrisvanden/ECE455/HW04

Note that your link should be of this format: https://github.com/YourGitHubName/ECE455/HW04

## Problem 1: Hello World from GPU

Task: Write a CUDA kernel that prints "Hello from thread X" for each GPU thread.

#### Solution

```
hello.cu
```

```
#include <stdio.h>
__global__ void hello_kernel() {
    int tid = blockIdx.x * blockDim.x + threadIdx.x;
    printf("Hello from thread %d\n", tid);
}
int main() {
    hello_kernel <<<2, 4>>>();
    cudaDeviceSynchronize();
    return 0;
}
  p1.slurm
#!/usr/bin/env zsh
\#SBATCH --partition = instruction
\#SBATCH --time = 00:01:00
\#SBATCH --ntasks=1
\#SBATCH --cpus-per-task=1
\#SBATCH --gpus-per-task=1
#SBATCH -- time = 00:01:00
#SBATCH -- output = hello.output
```

## Problem 2: Understanding Thread Indexing

**Task:** Launch a kernel with a 2D grid and block. Each thread should print its (blockIdx.x, blockIdx.y) and (threadIdx.x, threadIdx.y).

#### Solution

./hello

thread\_indexing.cu

module load nvidia/cuda nvcc hello.cu -o hello

```
int main() {
    dim3 blocks(2, 2);
    dim3 threads(2, 3);
    print_indices <<<blocks, threads>>>();
    cudaDeviceSynchronize();
    return 0;
}
  p2.slurm
#!/usr/bin/env zsh
#SBATCH --partition=instruction
#SBATCH -- time = 00:01:00
\#SBATCH --ntasks=1
\#SBATCH --cpus-per-task=1
\#SBATCH --qpus-per-task=1
#SBATCH --time=00:01:00
\#SBATCH --output = thread\_indexing.output
module load nvidia/cuda
nvcc thread_indexing.cu -o thread_indexing
./thread_indexing
```

### Problem 3: Vector Addition

**Task:** Implement a CUDA kernel for C[i] = A[i] + B[i] for N = 1,000,000.

#### Solution:

```
vector_add.cu
```

```
#include <stdio.h>
#include <cuda_runtime.h>
__global__ void vector_add(const float *A, const float *B, float *C, int N
  ) {
    int i = blockIdx.x * blockDim.x + threadIdx.x;
    if (i < N) {</pre>
        C[i] = A[i] + B[i];
    }
}
int main() {
    int N = 1000000;
    size_t size = N * sizeof(float);
    float *h_A = (float*)malloc(size);
    float *h_B = (float*)malloc(size);
    float *h_C = (float*)malloc(size);
    for (int i = 0; i < N; i++) { h_A[i] = 1.0f; h_B[i] = 2.0f; }
```

```
float *d_A, *d_B, *d_C;
    cudaMalloc(&d_A, size);
    cudaMalloc(&d_B, size);
    cudaMalloc(&d_C, size);
    cudaMemcpy(d_A, h_A, size, cudaMemcpyHostToDevice);
    cudaMemcpy(d_B, h_B, size, cudaMemcpyHostToDevice);
    int threadsPerBlock = 256;
    int blocksPerGrid = (N + threadsPerBlock - 1) / threadsPerBlock;
    vector add << blocksPerGrid, threadsPerBlock >>> (d A, d B, d C, N);
    cudaMemcpy(h_C, d_C, size, cudaMemcpyDeviceToHost);
    printf("C[0] = \frac{1}{n}, h_C[0]);
    cudaFree(d_A); cudaFree(d_B); cudaFree(d_C);
    free(h_A); free(h_B); free(h_C);
    return 0;
}
  p3.slurm
#!/usr/bin/env zsh
\#SBATCH --partition = instruction
#SBATCH -- time = 00:01:00
\#SBATCH --ntasks=1
\#SBATCH --cpus-per-task=1
\#SBATCH --qpus-per-task=1
#SBATCH --time=00:01:00
\#SBATCH --output = vector\_add.output
module load nvidia/cuda
nvcc vector_add.cu -o vector_add
```

### Problem 4: SAXPY Kernel

Task: Implement y[i] = a \* x[i] + y[i] for N = 1,000,000 with a = 2.0.

#### Solution

./vector\_add

```
saxpy.cu
#include <stdio.h>

__global__ void saxpy(int n, float a, float *x, float *y) {
    int i = blockIdx.x * blockDim.x + threadIdx.x;
    if (i < n) y[i] = a * x[i] + y[i];
}
int main() {</pre>
```

```
int N = 1000000;
    size_t size = N * sizeof(float);
    float *x, *y, *d_x, *d_y;
    x = (float*)malloc(size);
    y = (float*)malloc(size);
    for (int i = 0; i < N; i++) { x[i] = 1.0f; y[i] = 2.0f; }</pre>
    cudaMalloc(&d_x, size);
    cudaMalloc(&d_y, size);
    cudaMemcpy(d_x, x, size, cudaMemcpyHostToDevice);
    cudaMemcpy(d_y, y, size, cudaMemcpyHostToDevice);
    int threadsPerBlock = 256;
    int blocksPerGrid = (N + threadsPerBlock - 1) / threadsPerBlock;
    saxpy << blocksPerGrid, threadsPerBlock >>>(N, 2.0f, d_x, d_y);
    cudaMemcpy(y, d_y, size, cudaMemcpyDeviceToHost);
    printf("y[0] = %f \ n", y[0]);
    cudaFree(d_x); cudaFree(d_y);
    free(x); free(y);
    return 0;
}
```

#### p4.slurm

```
#!/usr/bin/env zsh
#SBATCH --partition=instruction
#SBATCH --time=00:01:00
#SBATCH --ntasks=1
#SBATCH --cpus-per-task=1
#SBATCH --gpus-per-task=1
#SBATCH --time=00:01:00
#SBATCH --output=saxpy.output

module load nvidia/cuda
nvcc saxpy.cu -o saxpy
./saxpy
```

## Problem 5: Using CUDA Streams

**Task:** Split a vector addition into two halves and execute each in its own CUDA stream.

#### Solution

```
vector_add_streams.cu
#include <stdio.h>
   __global__ void vector_add(const float *A, const float *B, float *C, int N
    ) {
```

```
int i = blockIdx.x * blockDim.x + threadIdx.x;
    if (i < N) C[i] = A[i] + B[i];</pre>
}
int main() {
    int N = 1000000;
    size_t size = N * sizeof(float);
    float *A, *B, *C;
    float *d_A, *d_B, *d_C;
    A = (float*)malloc(size);
    B = (float*)malloc(size);
    C = (float*)malloc(size);
    for (int i = 0; i < N; i++) { A[i] = 1.0f; B[i] = 2.0f; }
    cudaMalloc(&d_A, size);
    cudaMalloc(&d_B, size);
    cudaMalloc(&d_C, size);
    cudaStream_t stream1, stream2;
    cudaStreamCreate(&stream1);
    cudaStreamCreate(&stream2);
    int half = N / 2;
    size_t half_size = size / 2;
    cudaMemcpyAsync(d_A, A, half_size, cudaMemcpyHostToDevice, stream1);
    cudaMemcpyAsync(d_B, B, half_size, cudaMemcpyHostToDevice, stream1);
    cudaMemcpyAsync(d_A + half, A + half, half_size,
       cudaMemcpyHostToDevice, stream2);
    cudaMemcpyAsync(d_B + half, B + half, half_size,
       cudaMemcpyHostToDevice, stream2);
    int threads = 256;
    int blocks_half = (half + threads - 1) / threads;
    vector_add<<<blooks_half, threads, 0, stream1>>>(d_A, d_B, d_C, half);
    vector_add<<<blocks_half , threads , 0 , stream2>>>(d_A + half , d_B +
       half, d_C + half, half);
    cudaMemcpyAsync(C, d_C, half_size, cudaMemcpyDeviceToHost, stream1);
    cudaMemcpyAsync(C + half, d_C + half, half_size,
       cudaMemcpyDeviceToHost, stream2);
    cudaStreamSynchronize(stream1);
    cudaStreamSynchronize(stream2);
    printf("C[0] = %f, C[N-1] = %f\n", C[0], C[N-1]);
    cudaStreamDestroy(stream1);
    cudaStreamDestroy(stream2);
    cudaFree(d_A); cudaFree(d_B); cudaFree(d_C);
```

```
free(A); free(B); free(C);
return 0;
}
```

### p5.slurm

```
#!/usr/bin/env zsh
#SBATCH --partition=instruction
#SBATCH --time=00:01:00
#SBATCH --ntasks=1
#SBATCH --cpus-per-task=1
#SBATCH --gpus-per-task=1
#SBATCH --time=00:01:00
#SBATCH --output=vector_add_streams.output
module load nvidia/cuda
nvcc vector_add_streams.cu -o vector_add_streams
./vector_add_streams
```

## Problem 6

Describe the challenges you encounter when completing this lab assignment and how you overcome these challenges.

I was confused on how the CUPA nemony harding methods work, so I had to Consult doccementation