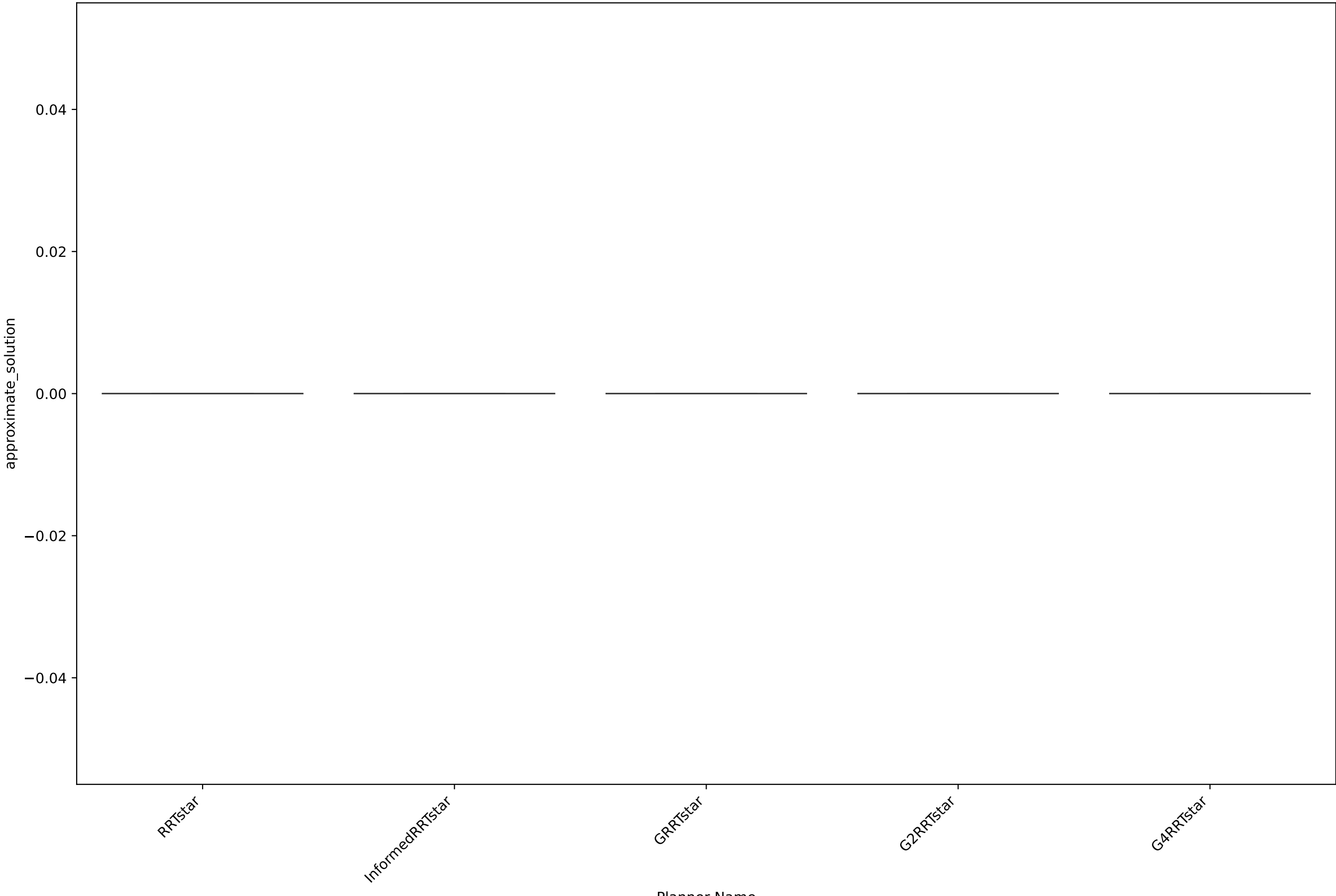
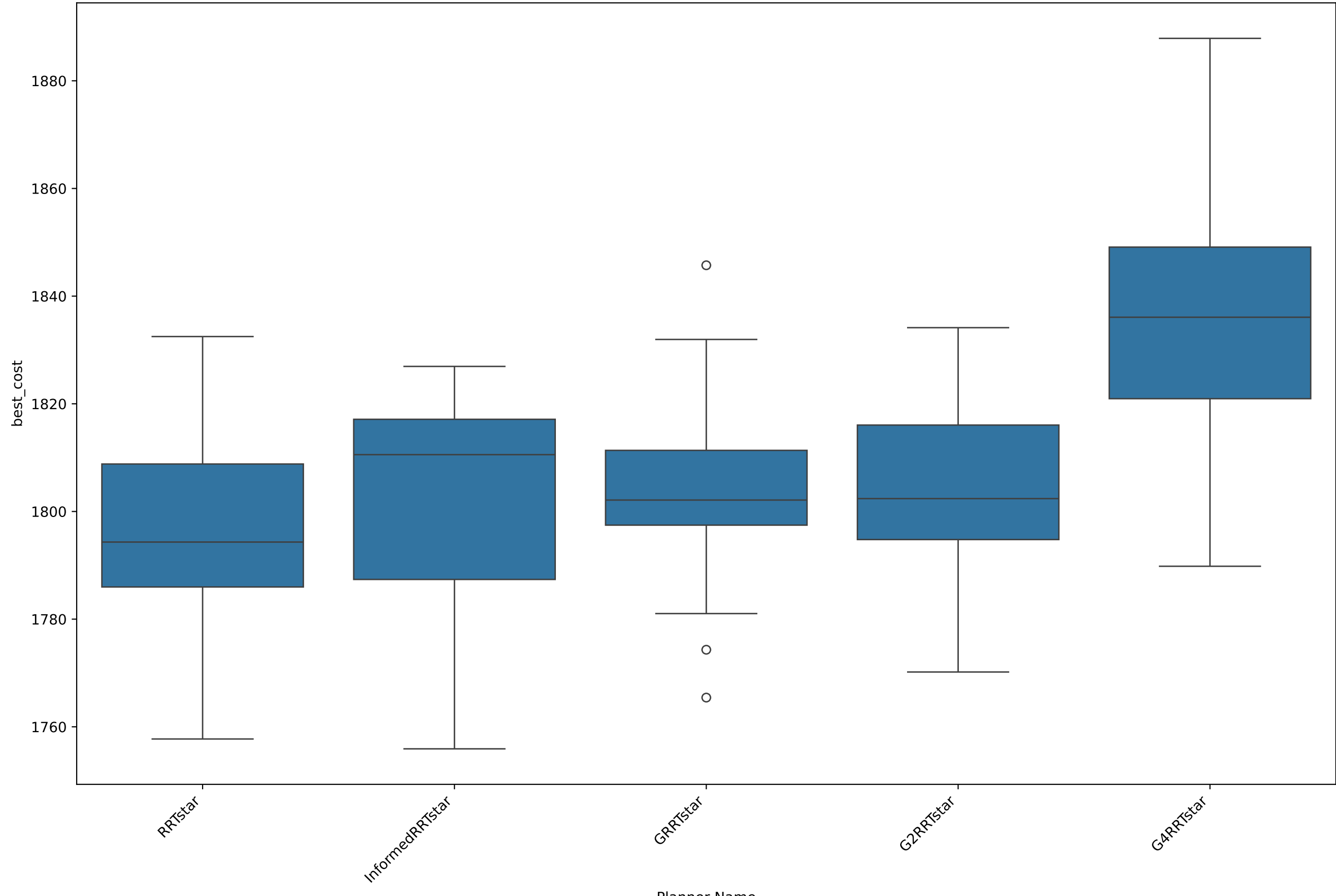


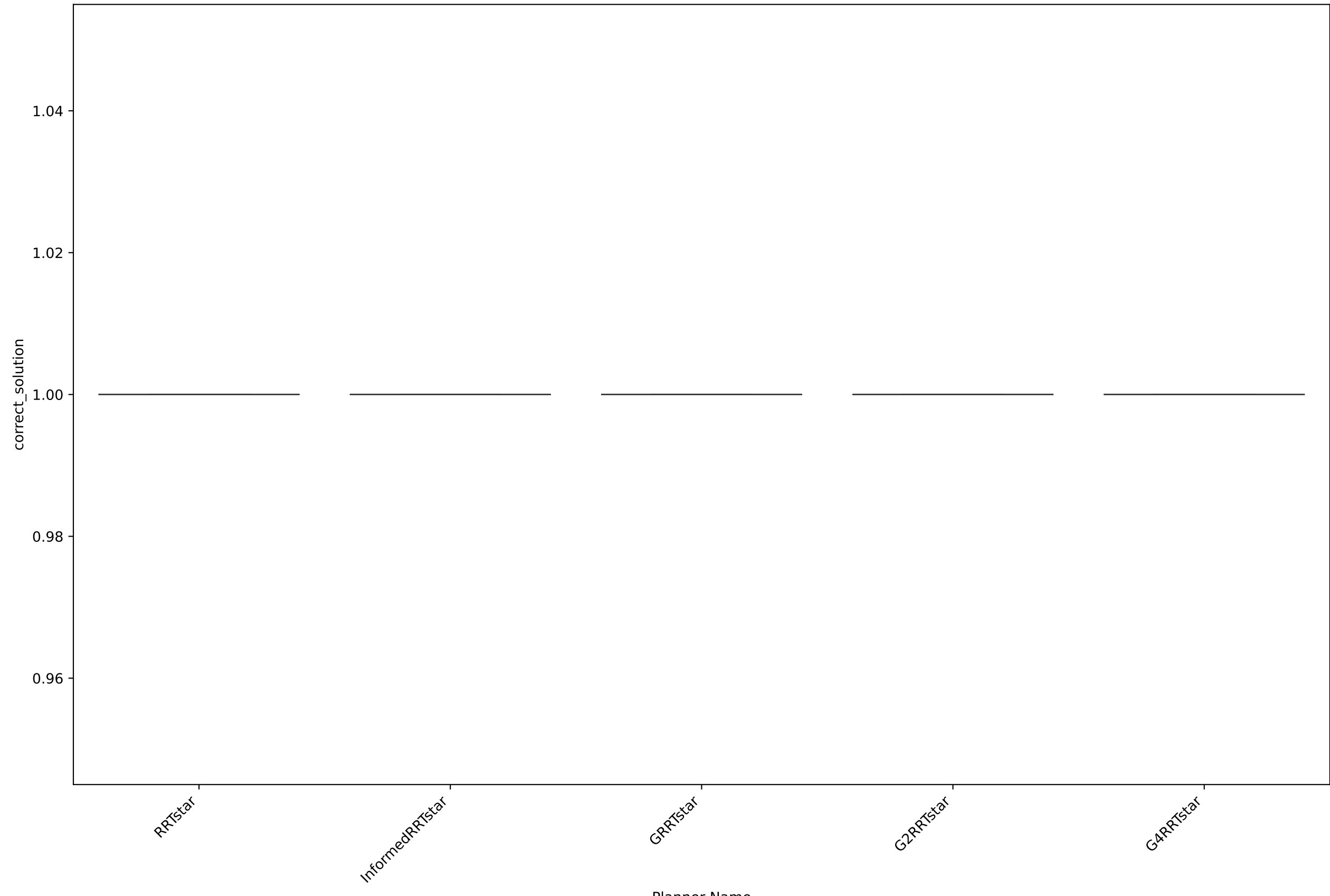
Box Plot of approximate_solution for Each Planner



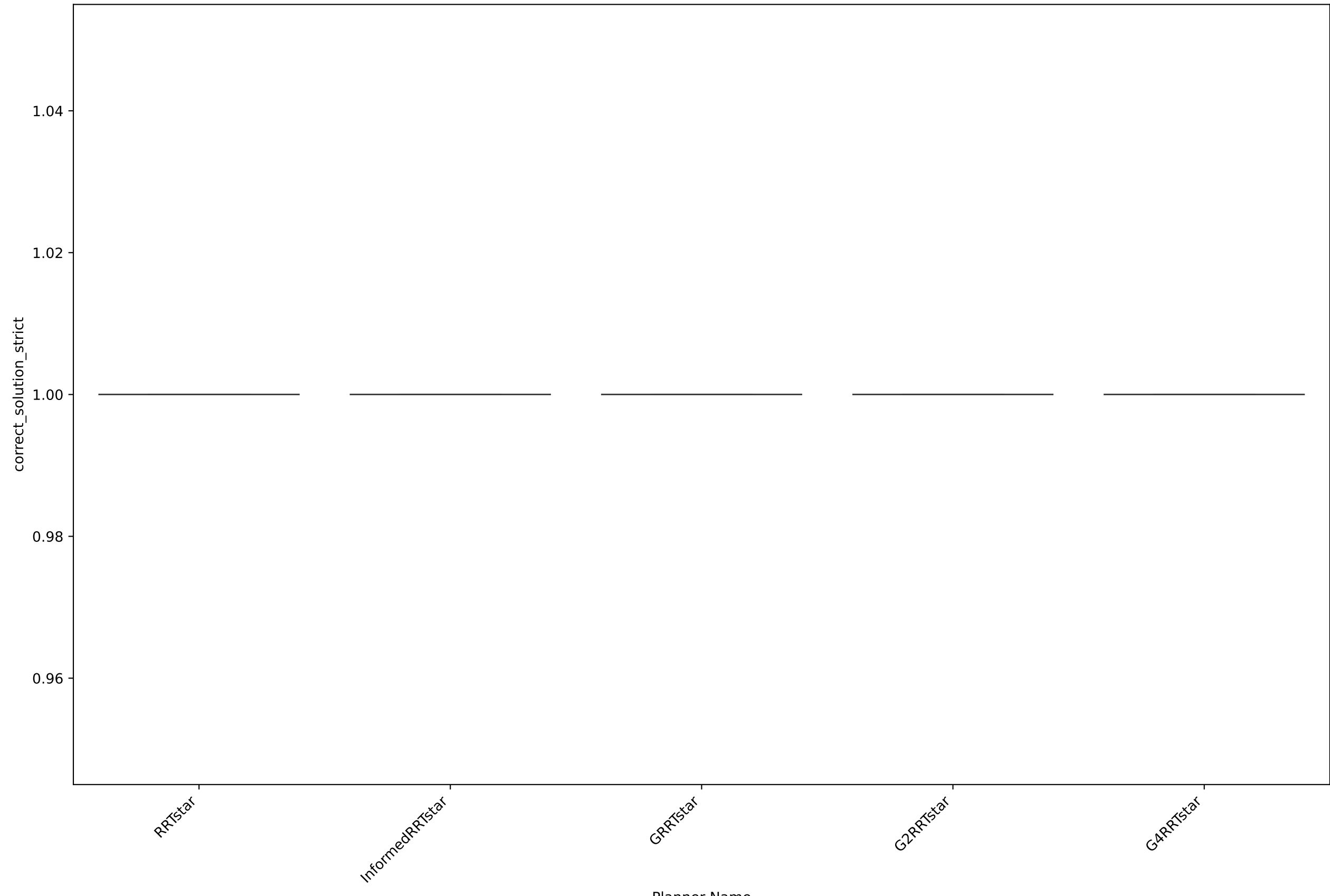
Box Plot of best_cost for Each Planner



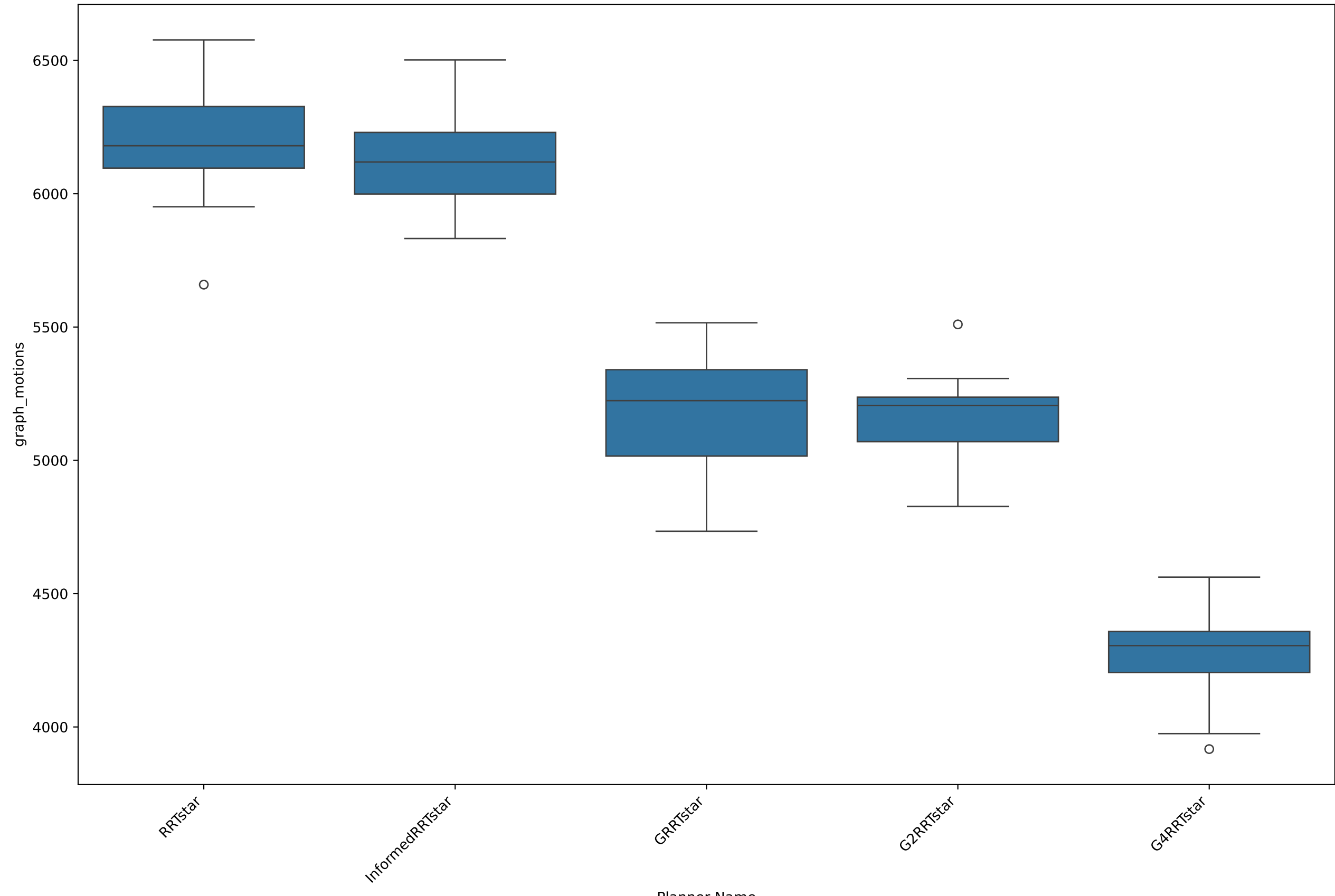
Box Plot of correct_solution for Each Planner

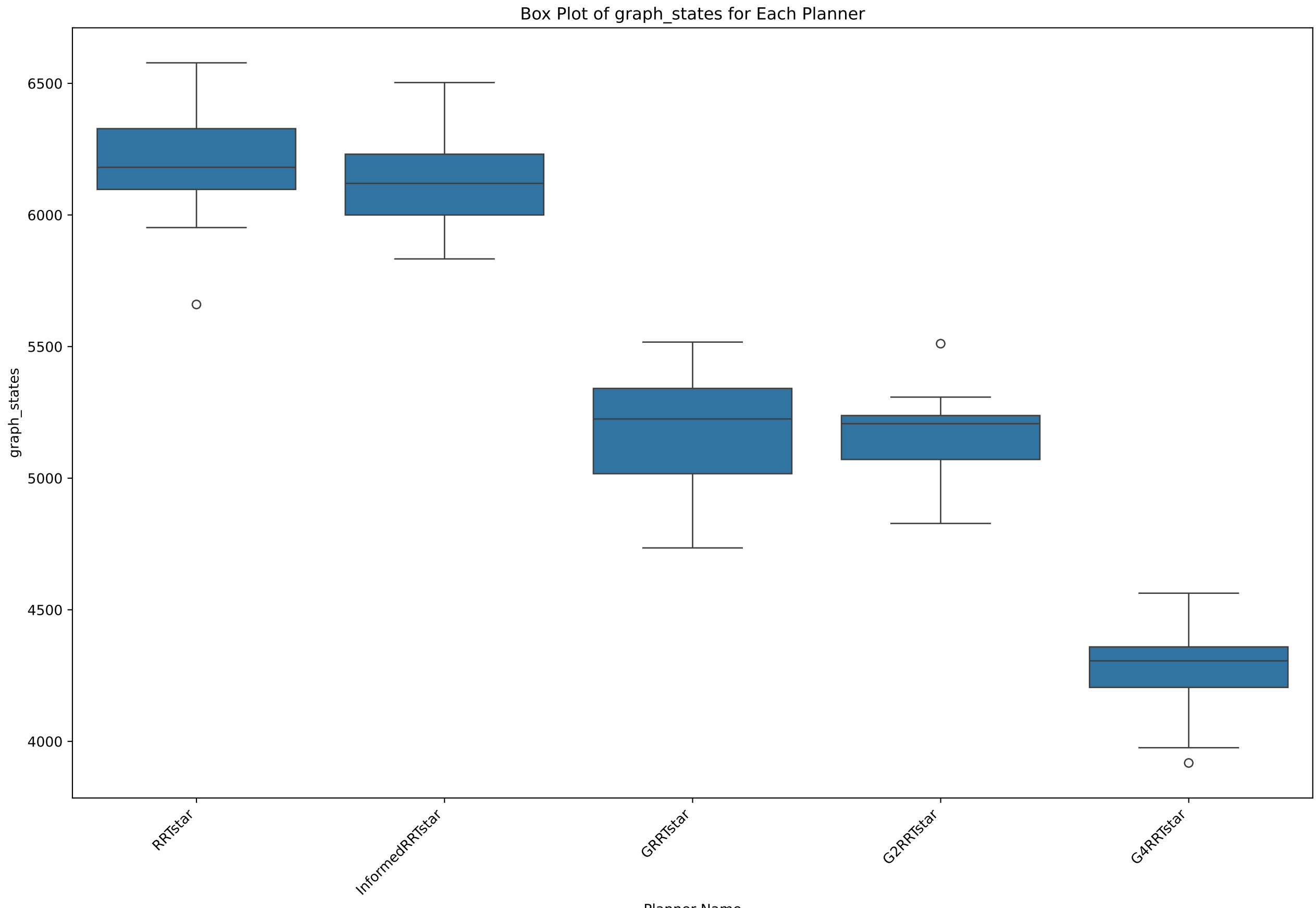


Box Plot of correct_solution_strict for Each Planner

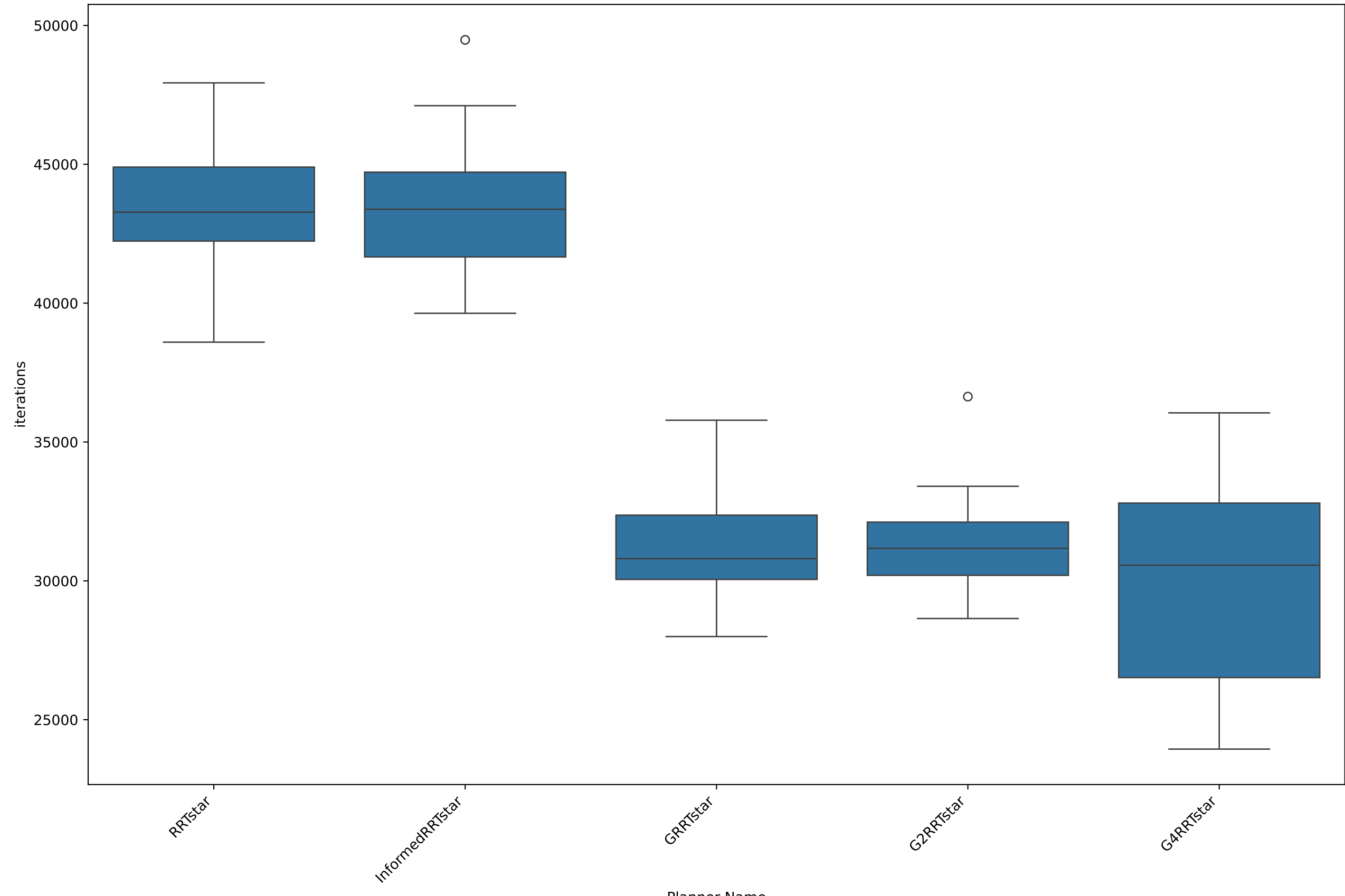


Box Plot of graph_motions for Each Planner

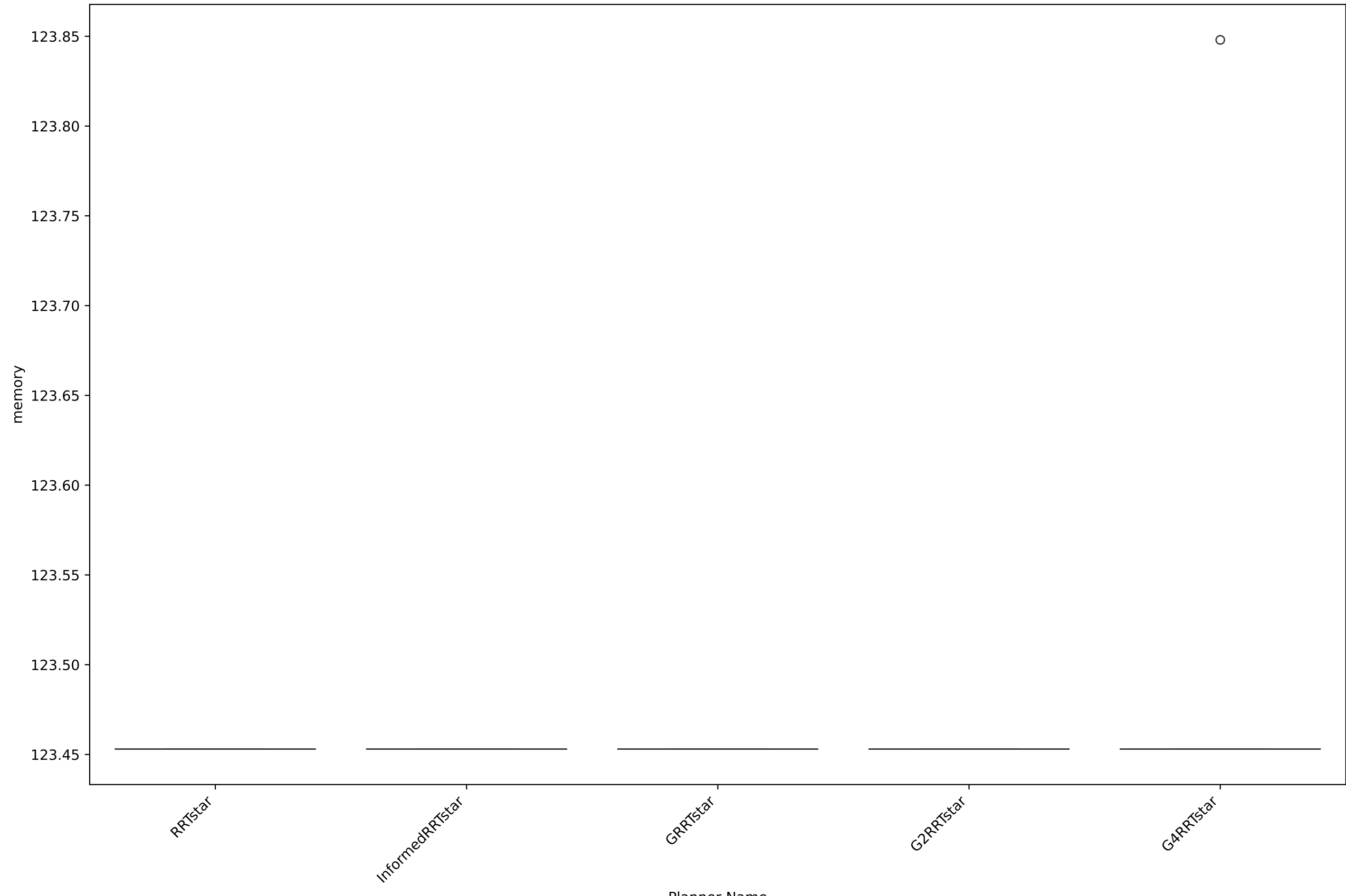




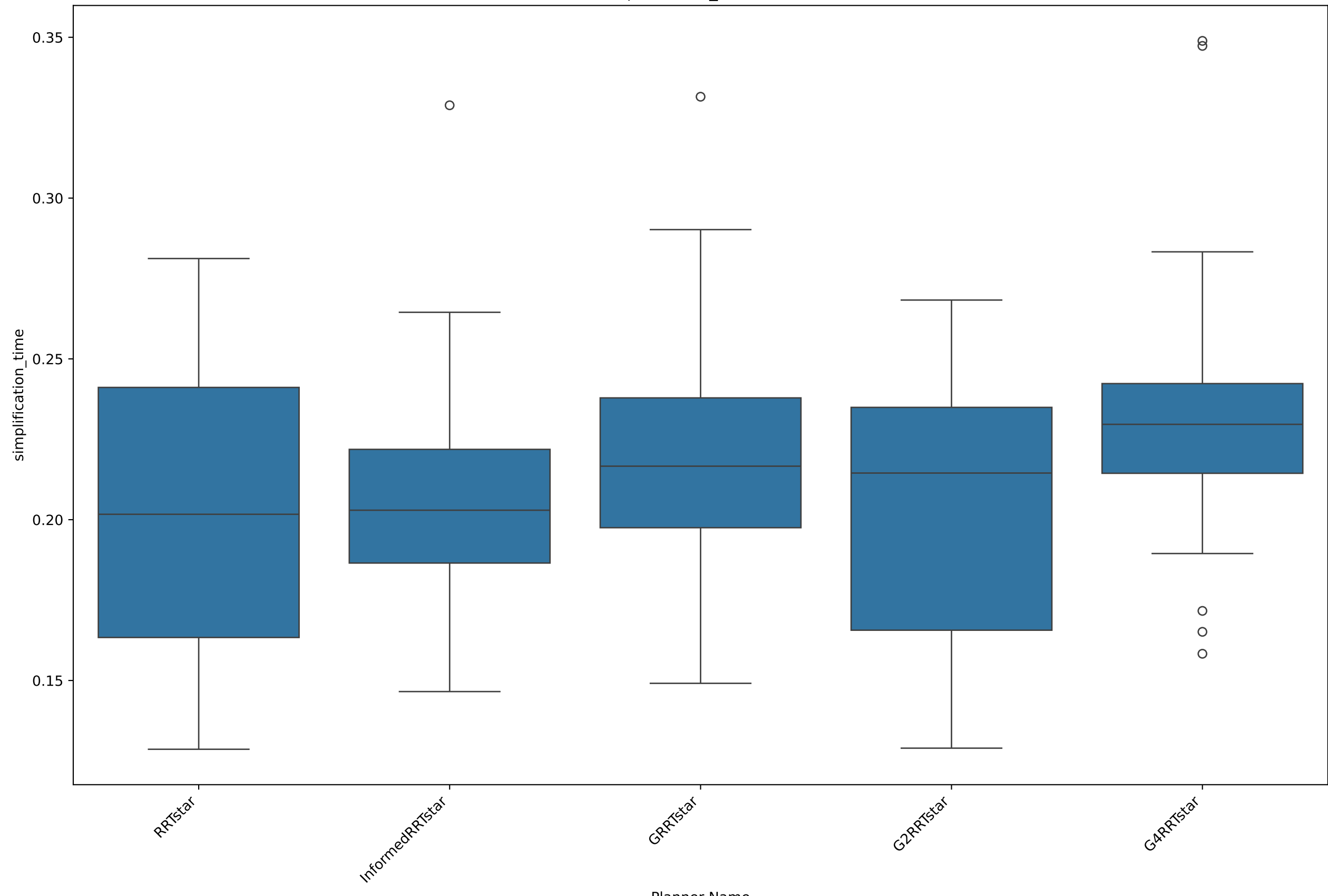
Box Plot of iterations for Each Planner



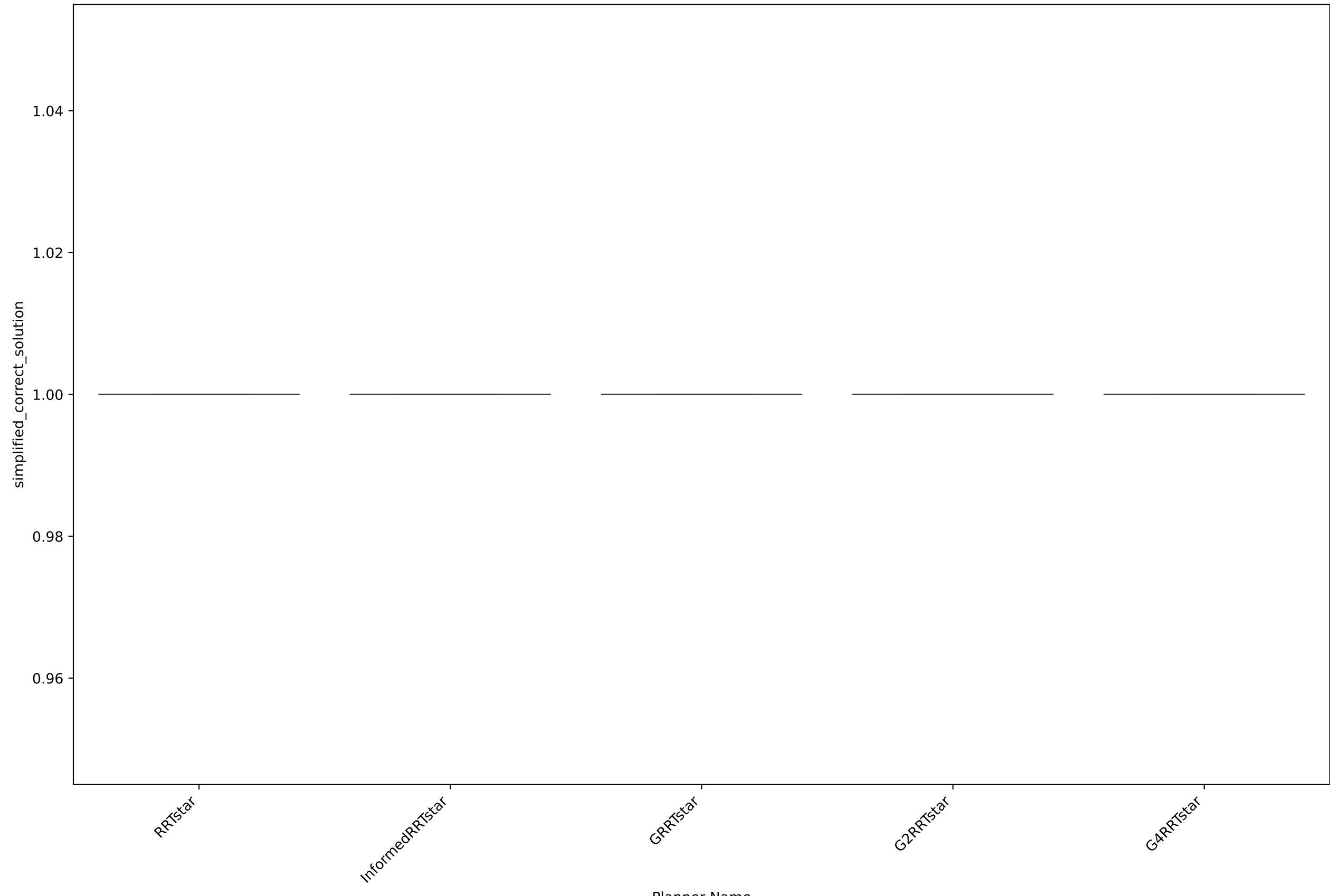
Box Plot of memory for Each Planner



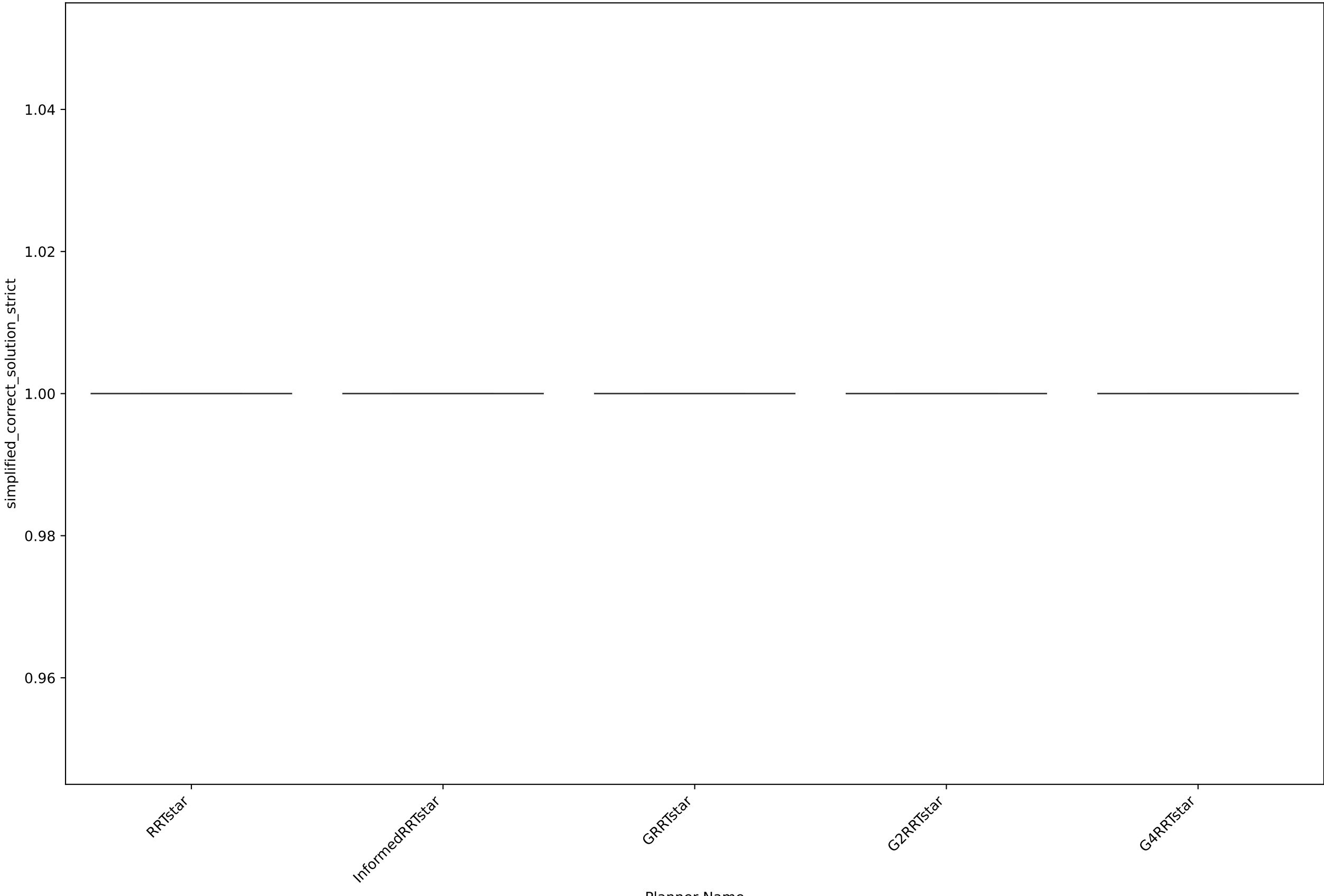
Box Plot of simplification_time for Each Planner



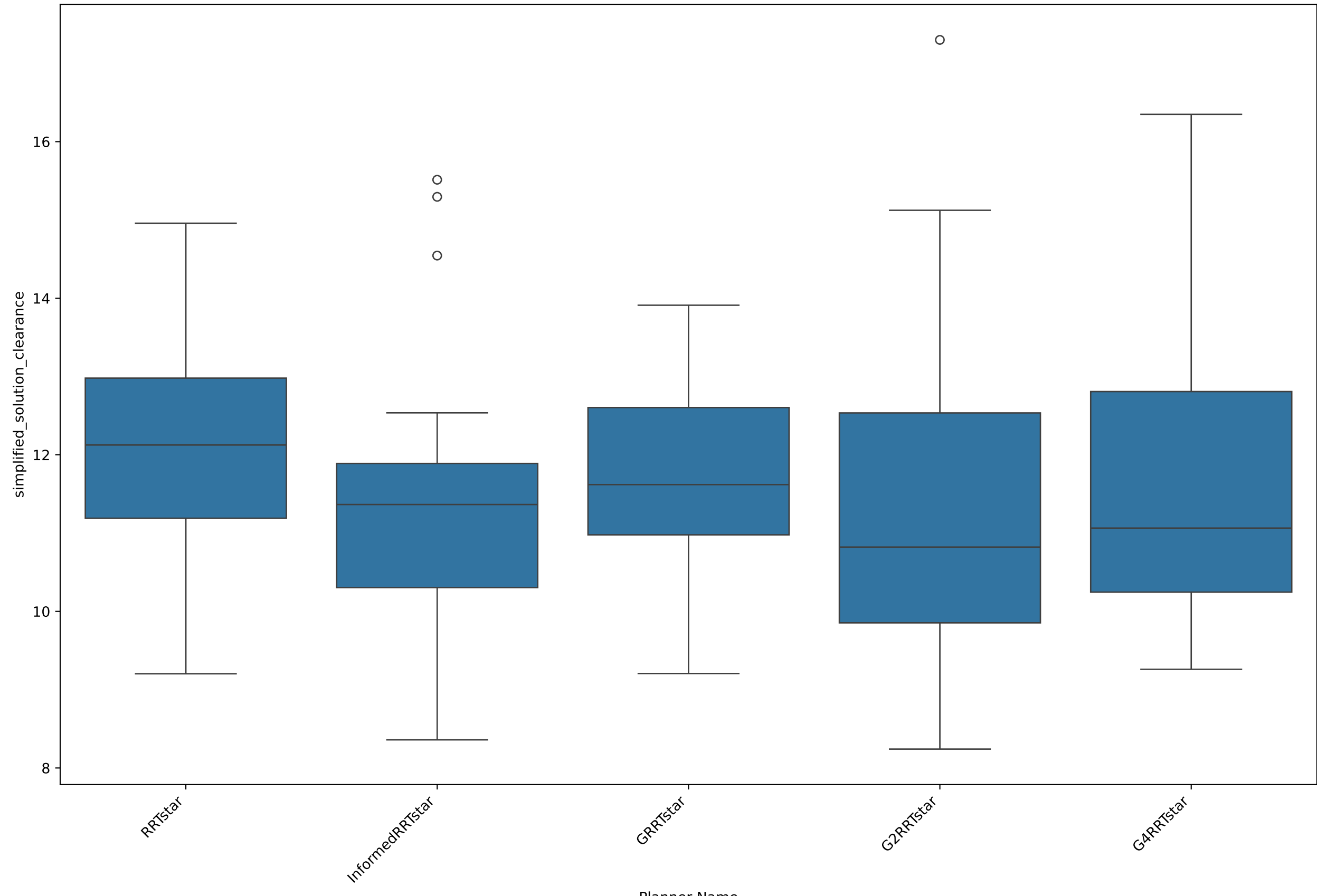
Box Plot of simplified_correct_solution for Each Planner



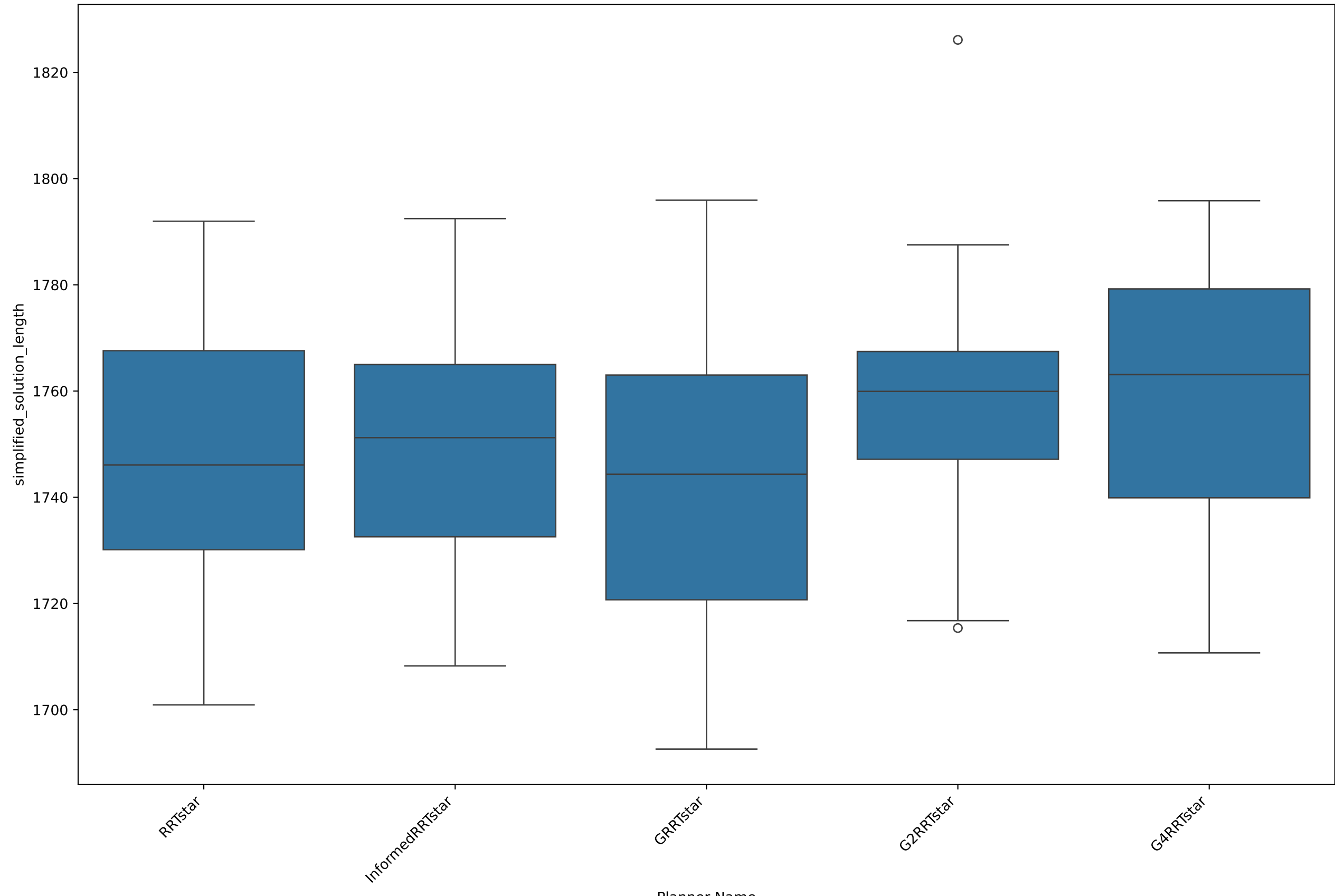
Box Plot of simplified_correct_solution_strict for Each Planner



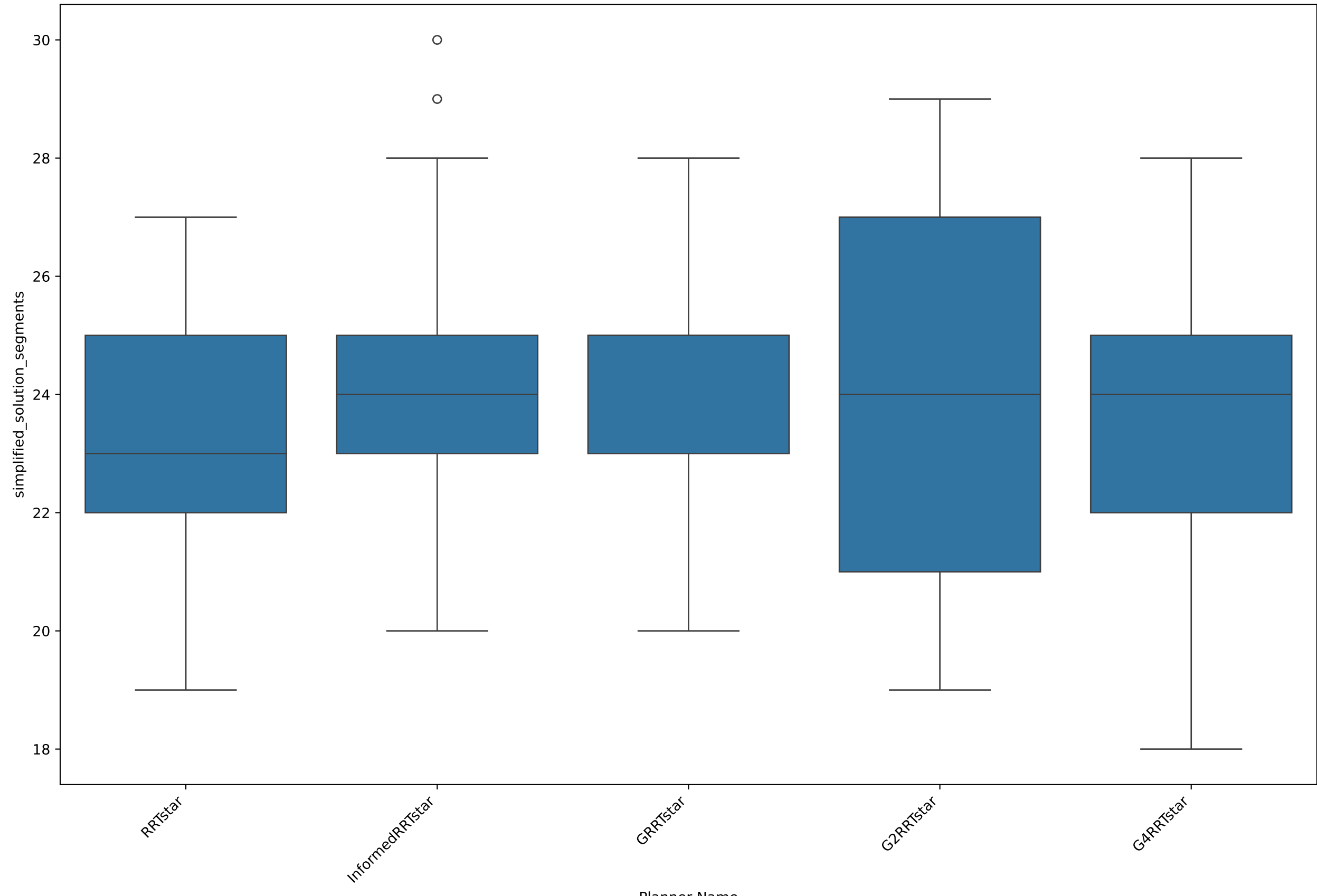
Box Plot of simplified_solution_clearance for Each Planner



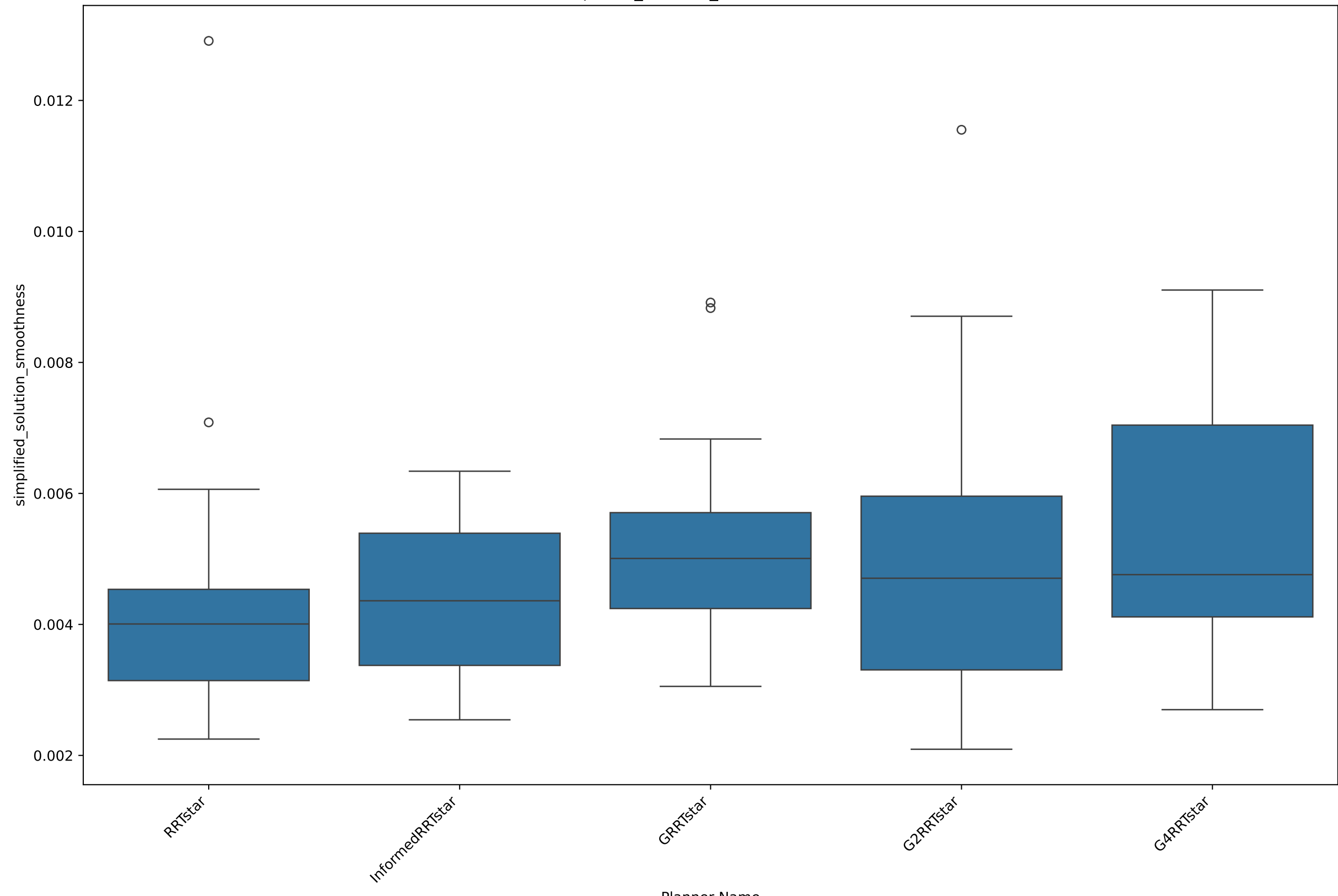
Box Plot of simplified_solution_length for Each Planner



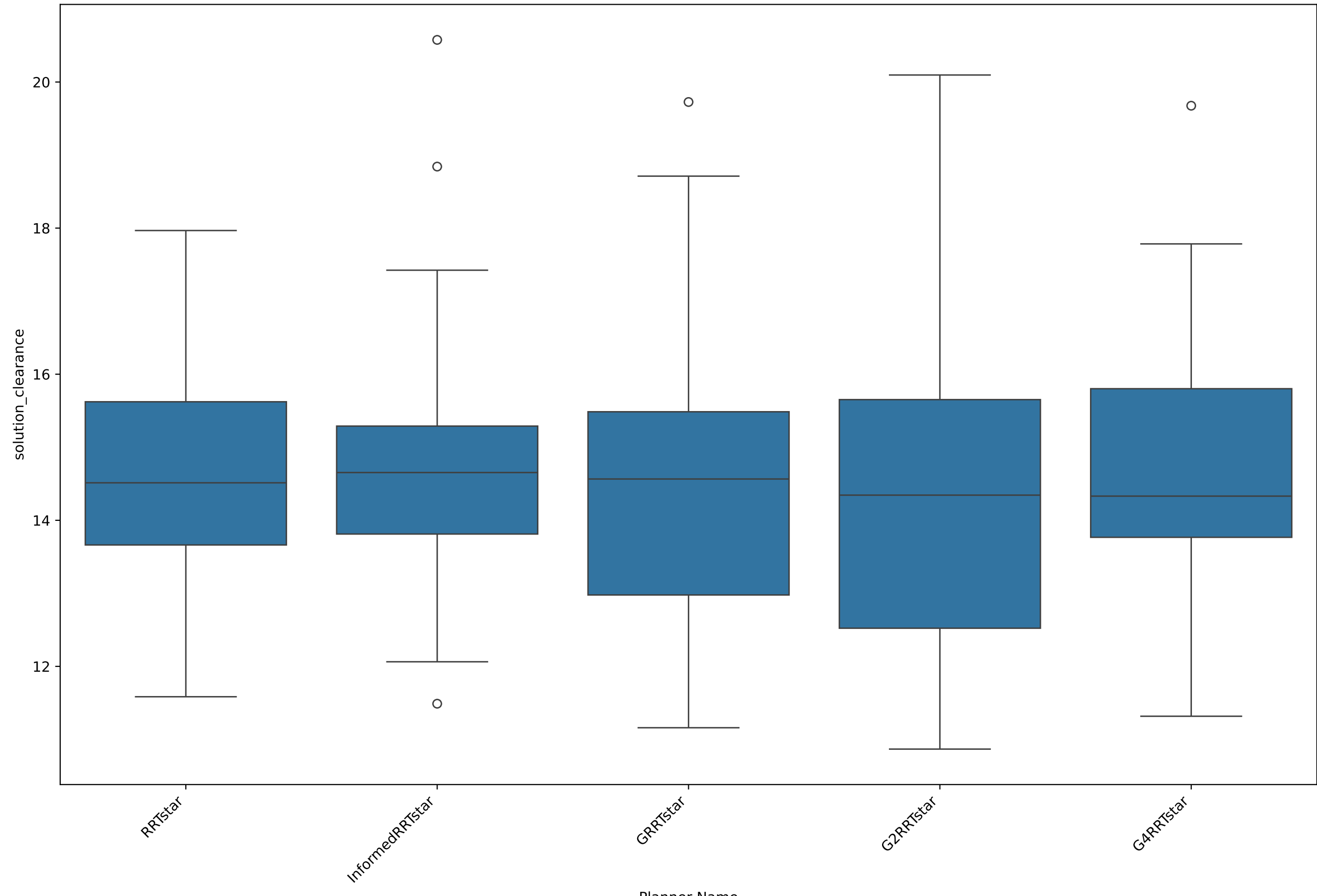
Box Plot of simplified_solution_segments for Each Planner



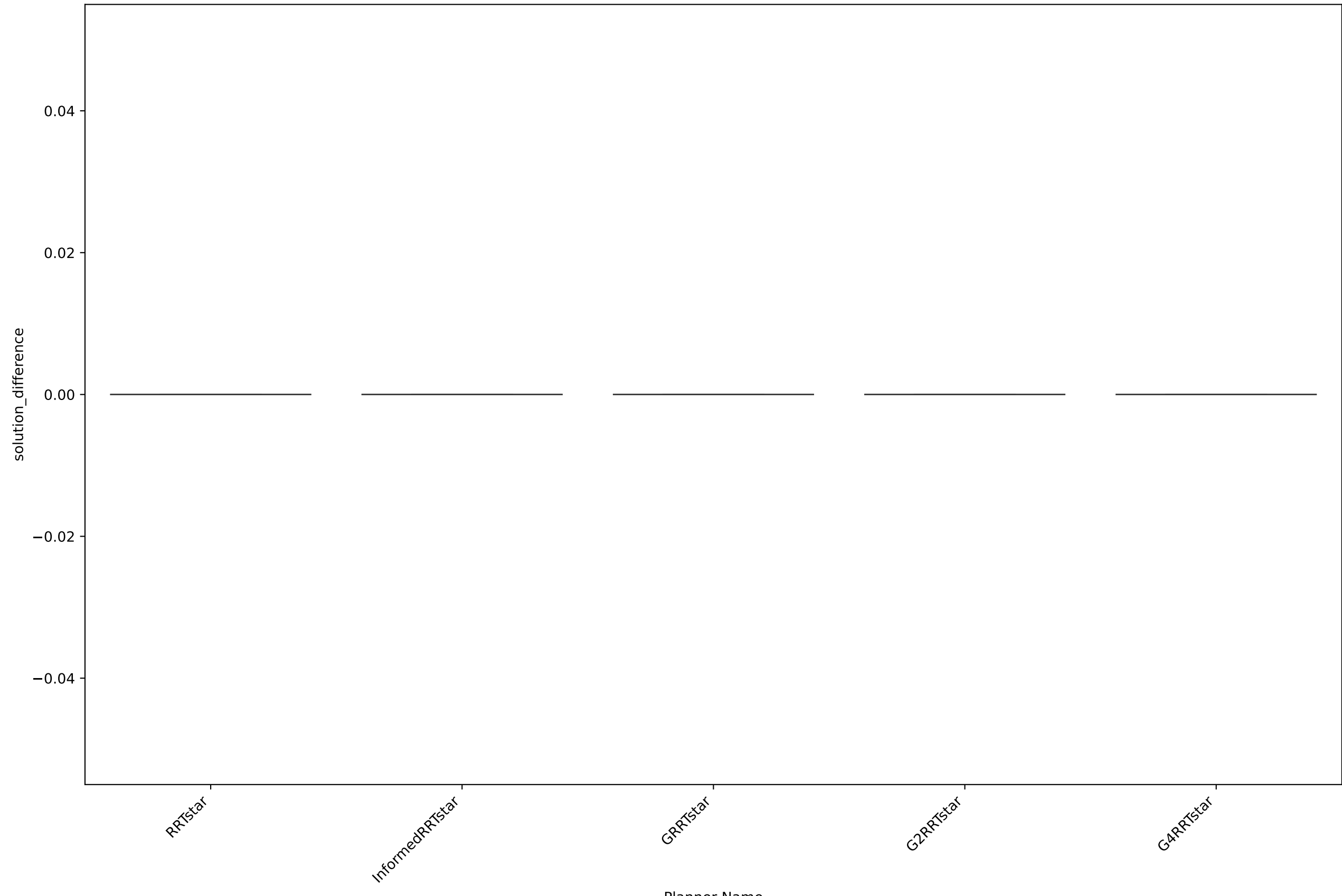
Box Plot of simplified_solution_smoothness for Each Planner



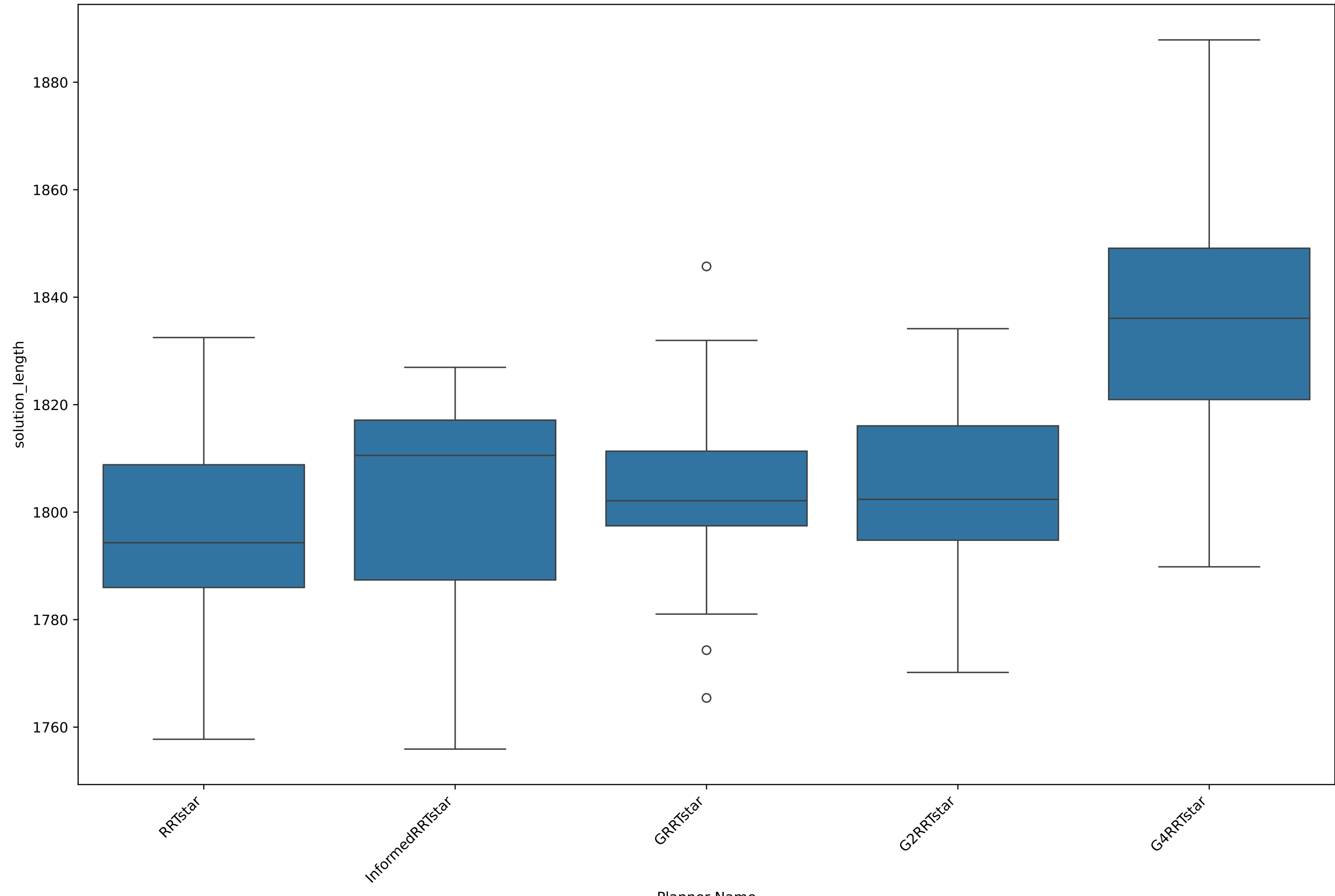
Box Plot of solution_clearance for Each Planner



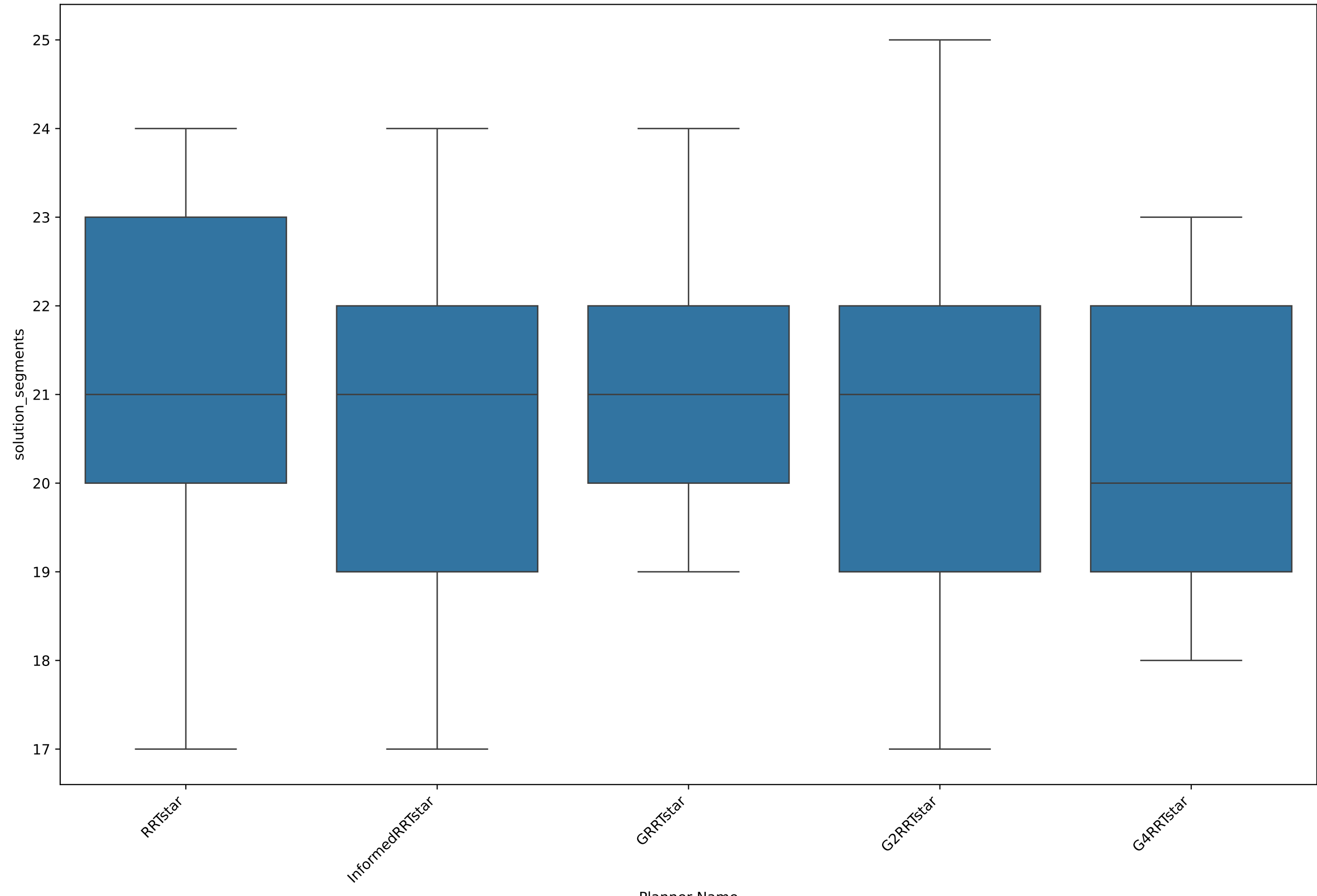
Box Plot of solution_difference for Each Planner



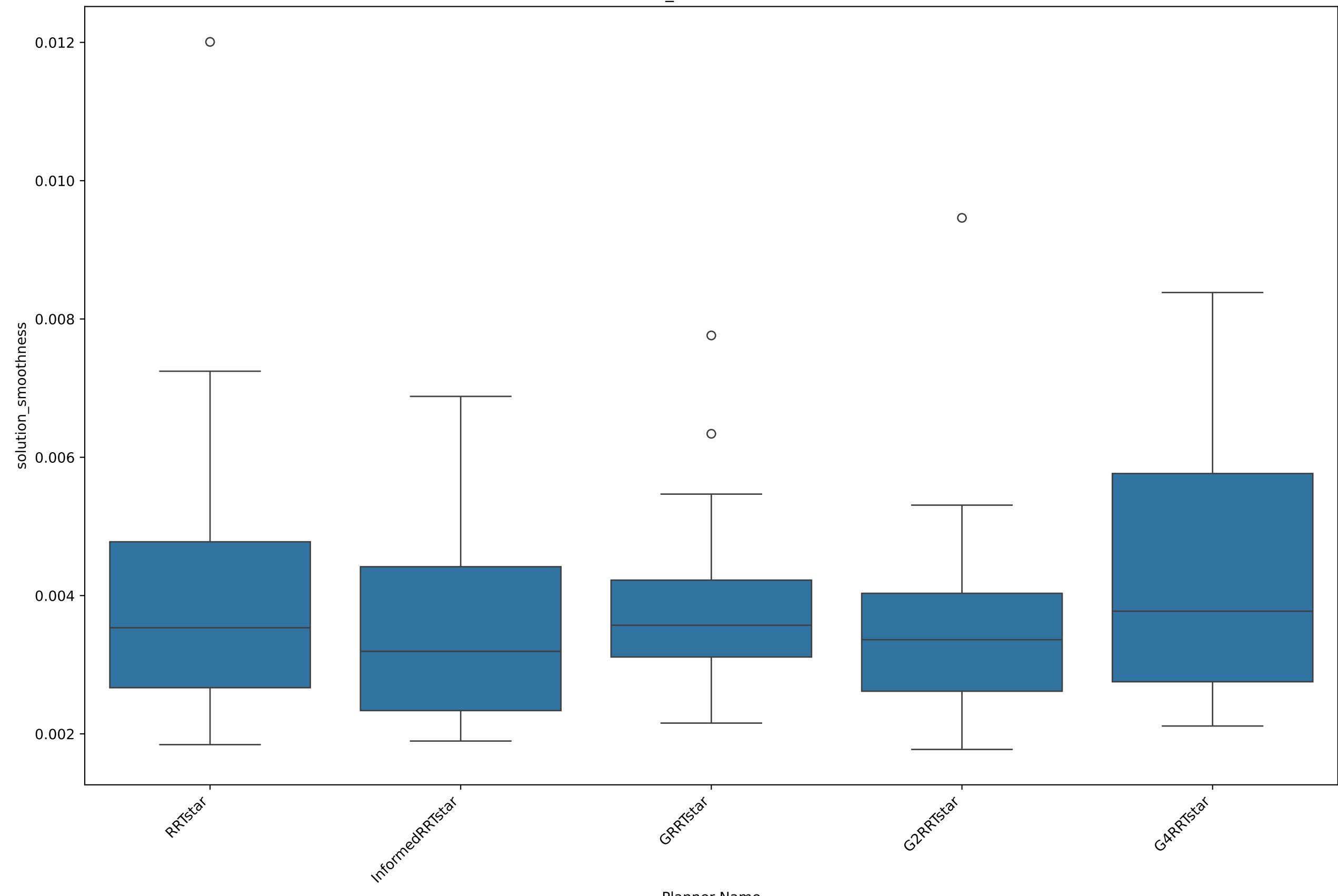
Box Plot of solution_length for Each Planner

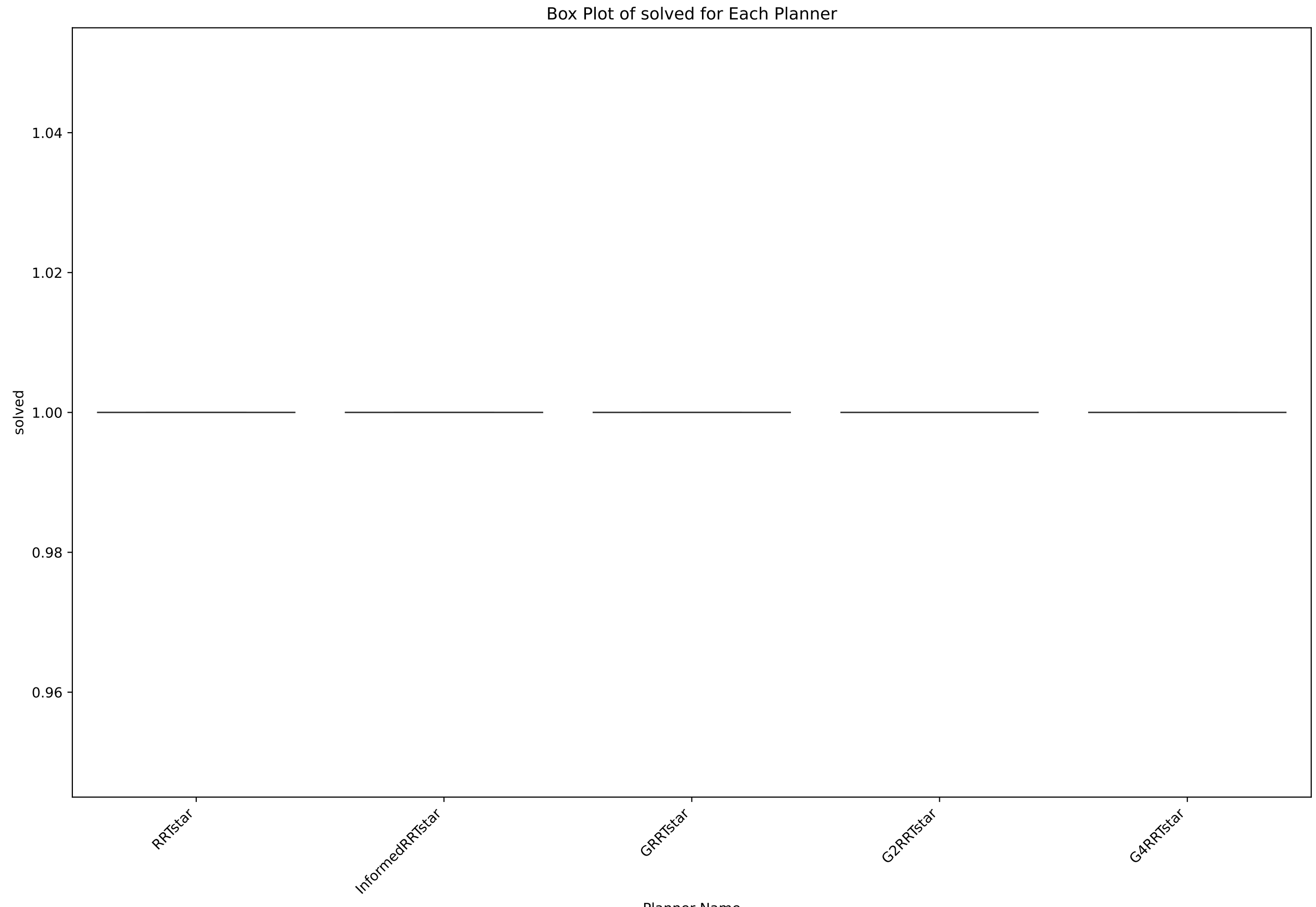


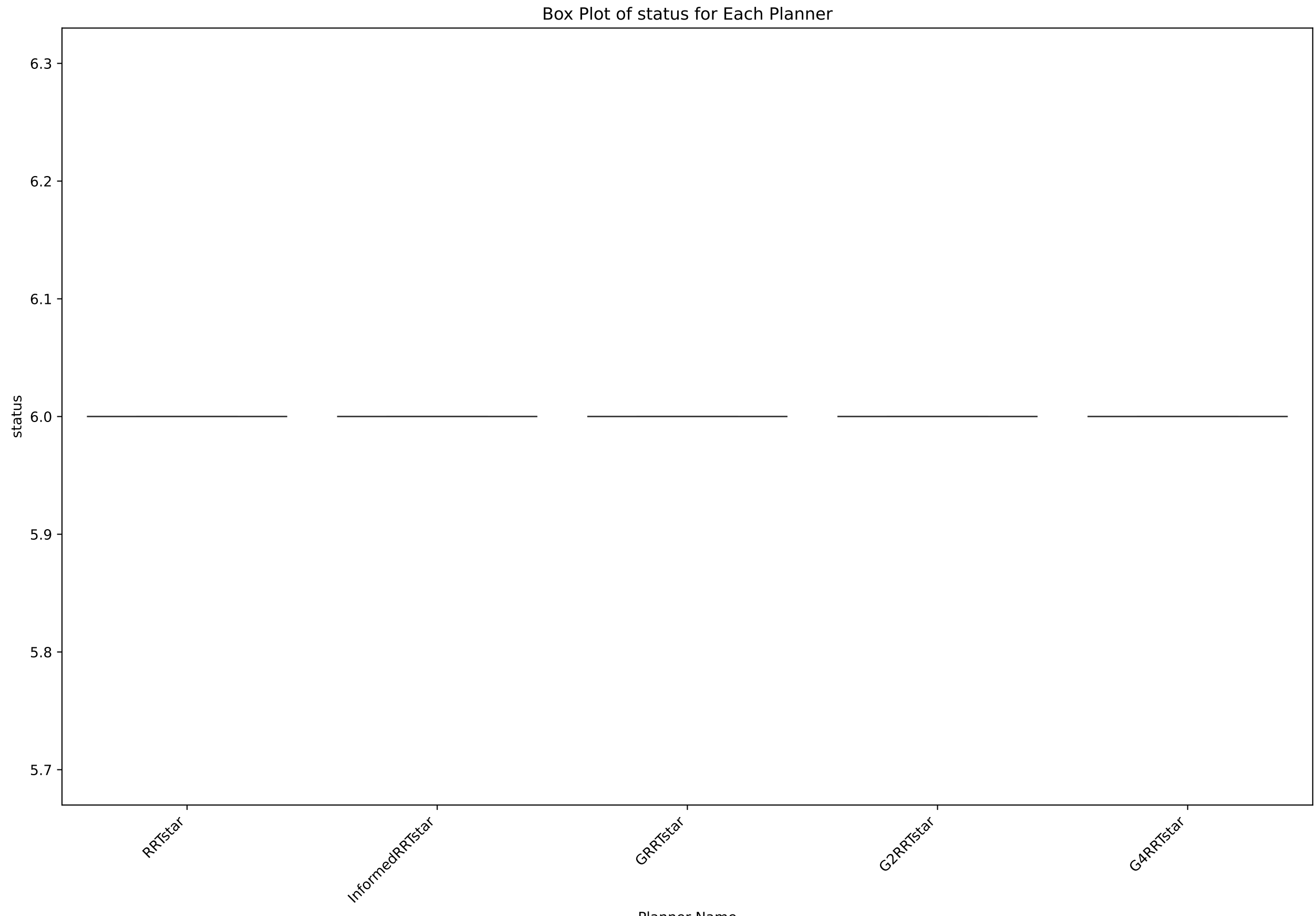
Box Plot of solution_segments for Each Planner



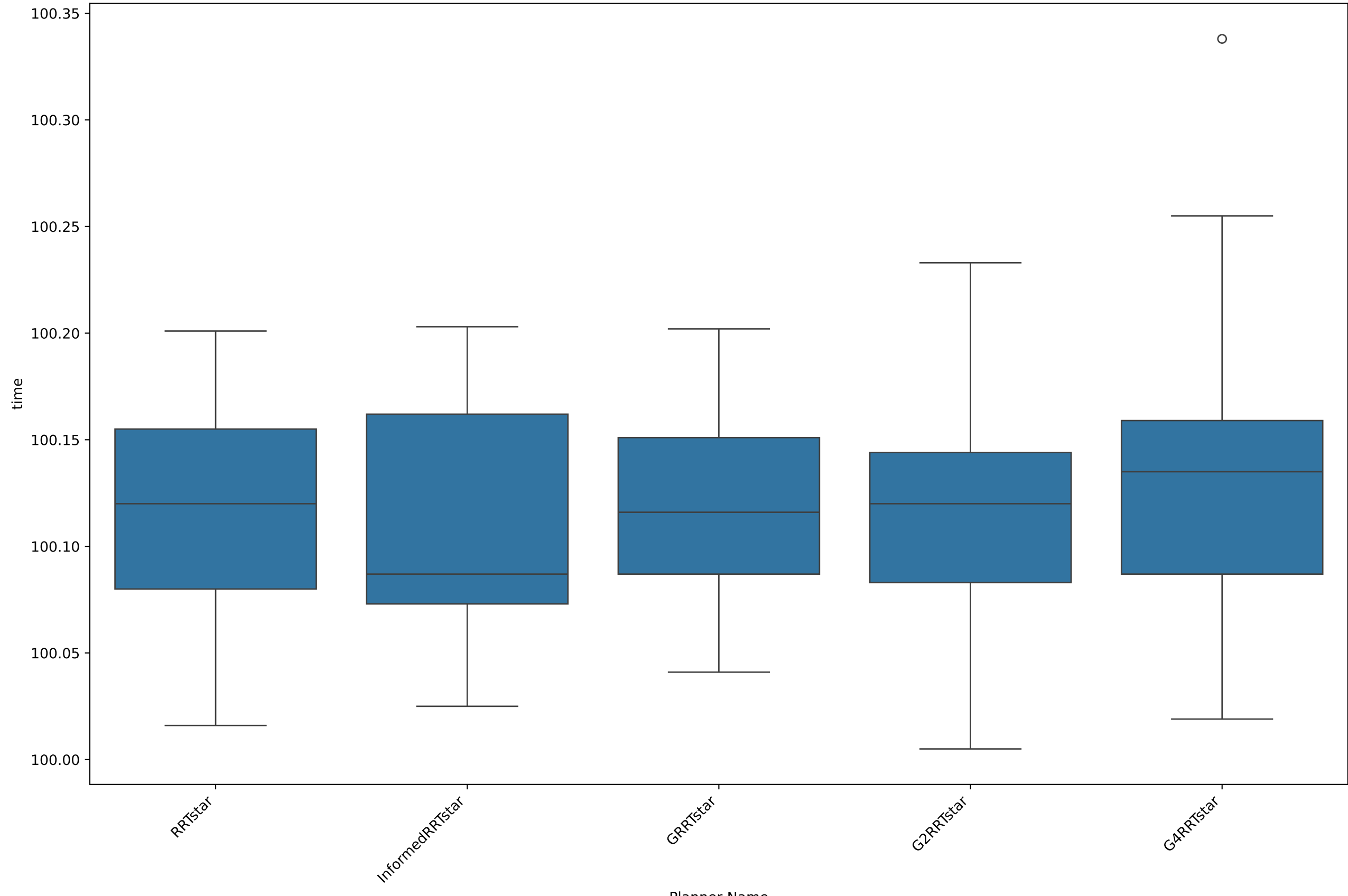
Box Plot of solution_smoothness for Each Planner







Box Plot of time for Each Planner



Box Plot of valid_segment_fraction for Each Planner

