

Evolving a C++ Library to C++0x Concepts

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Concepts Recap

```
auto concept LessThanComparable<typename T> {  
    bool operator<(T, T);  
}
```

```
template<typename T>  
    requires LessThanComparable<T>  
    const T& min(const T& x, const T& y) {  
        return x < y? x : y;  
    }
```

```
concept_map LessThanComparable<int> { }
```

```
int result = min(17, 42);
```



The Grand Claim(s)

- Concepts will make it easier to write better generic C++ libraries
- Why?
 - Concepts let us say what we mean, in code
 - Type checking of templates, concept maps
 - Many complicated template tricks go away
- The resulting generic libraries will be far more powerful and easier to use



How Will a C++0x Library Look?

- Concepts:
 - The library will contain concepts that describe its domain of applicability
 - Graphs, Matrices, Databases, Functions, etc.
- Generic algorithms:
 - Constrained templates based on those concepts
- Core data structures
 - Concept maps establish relationships between data structures and concepts



How Does it Differ From C++03?

- Short answer: everything with “template” will look a bit different
- Your documentation becomes code:
 - Concept documentation turns into concepts
 - Algorithm constraint documentation turns into requirements clauses
 - Data structure/concept relationships turn into concept maps
- Many of the changes make for a cleaner, tighter specification.



How Do We Get There?

- Two major components to this tutorial
 - How do we get from a C++03 library to a C++0x library using concepts?
 - How do we make that C++0x library backward-compatible with C++03?
- Bonus material: generic library composition



Library Evolution

C++03 \Rightarrow C++0x



Evolving a Library

1. Get your library building under C++0x
2. Convert concept documentation to concepts (first pass; very minimal)
3. Constrain algorithms
 - Start with the simplest algorithms!
 - You will have to tweak your concepts
4. Add concept maps for your data structures
5. Build in backward compatibility with C++03



Table 28—EqualityComparable requirements

expression	return type	requirement
<code>a == b</code>	convertible to <code>bool</code>	<code>==</code> is an equivalence relation, that is, it satisfies the following properties: <ul style="list-style-type: none">— For all <code>a</code>, <code>a == a</code>.— If <code>a == b</code>, then <code>b == a</code>.— If <code>a == b</code> and <code>b == c</code>, then <code>a == c</code>.

```
auto concept EqualityComparable<typename T>
{
    bool operator==(T, T);

    axiom Reflexivity(T x) { x == x; }
    axiom Symmetry(T x, T y) { if (x == y) y == x; }
    axiom Transitivity(T x, T y, T z) {
        if (x == y && y == z) x == z;
    }
}
```

Table 72—Input iterator requirements

operation	type	semantics, pre/post-conditions
<code>X u(a);</code>	<code>X</code>	post: <code>u</code> is a copy of <code>a</code> A destructor is assumed to be present and accessible.
<code>u = a;</code>	<code>X&</code>	result: <code>u</code> post: <code>u</code> is a copy of <code>a</code>
<code>a == b</code>	convertible to <code>bool</code>	<code>==</code> is an equivalence relation over its domain.
<code>a != b</code>	convertible to <code>bool</code>	<code>bool(a==b) != bool(a!=b)</code> over the domain of <code>==</code>
<code>*a</code>	convertible to <code>T</code>	pre: <code>a</code> is dereferenceable. If <code>a==b</code> and (a, b) is in the domain of <code>==</code> then <code>*a</code> is equivalent to <code>*b</code> .
<code>a->m</code>		pre: $(*a).m$ is well-defined Equivalent to $(*a).m$
<code>++r</code>	<code>X&</code>	pre: <code>r</code> is dereferenceable. post: <code>r</code> is dereferenceable or <code>r</code> is past-the-end. post: any copies of the previous value of <code>r</code> are no longer required either to be dereferenceable or to be in the domain of <code>==</code> .
<code>(void)r++</code>		equivalent to <code>(void)++r</code>
<code>*r++</code>	<code>T</code>	<code>{ T tmp = *r; ++r; return tmp; }</code>



InputIterator with Concepts

```
concept InputIterator<typename X>
    : Assignable<X>, EqualityComparable<X>
{
    typename value_type = X::value_type;
    typename difference_type = X::difference_type;
    typename reference = X::reference;
    typename pointer = X::pointer;

    requires SignedIntegral<difference_type> &&
        Convertible<reference, value_type> &&
        Arrowable<pointer, value_type>;
    typename postincrement_result;
    requires Dereferenceable<postincrement_result,
        value_type>;

    pointer operator->(X);
    X& operator++(X&);
    postincrement_result operator++(X&, int);
    reference operator*(X);
    bool operator!=(X x, X y);
}
```

Table 74—Forward iterator requirements

expression	return type	operational semantics	assertion/note pre/post-condition
<code>X u;</code>			note: <code>u</code> might have a singular value. note: a destructor is assumed.
<code>X()</code>			note: <code>X()</code> might be singular.
<code>X(a)</code>			<code>a == X(a)</code> .
<code>X u(a);</code> <code>X u = a;</code>		<code>X u; u = a;</code>	post: <code>u == a</code> .
<code>a == b</code>	convertible to <code>bool</code>		<code>==</code> is an equivalence relation.
<code>a != b</code>	convertible to <code>bool</code>	<code>!(a == b)</code>	
<code>r = a</code>	<code>X&</code>		post: <code>r == a</code> .
<code>*a</code>	<code>T&</code>		pre: <code>a</code> is dereferenceable. <code>a == b</code> implies <code>*a == *b</code> . If <code>X</code> is mutable, <code>*a = t</code> is valid.
<code>a->m</code>	<code>U&</code>	<code>(*a).m</code>	pre: <code>(*a).m</code> is well-defined.
<code>++r</code>	<code>X&</code>		pre: <code>r</code> is dereferenceable. post: <code>r</code> is dereferenceable or <code>r</code> is past-the-end. <code>r == s</code> and <code>r</code> is dereferenceable implies <code>++r == ++s</code> . <code>&r == &++r</code> .
<code>r++</code>	convertible to <code>const X&</code>	<pre>{ X tmp = r; ++r; return tmp; }</pre>	
<code>*r++</code>	<code>T&</code>		



ForwardIterator with Concepts

```
concept ForwardIterator<typename X>
    : InputIterator<X>, DefaultConstructible<X>
{
    requires Convertible<reference, const value_type&> &&
               Arrowable<pointer, const value_type&> &&
               Convertible<postincrement_result, const X&>;
};
```

```
concept MutableForwardIterator<typename X>
    : ForwardIterator<X>, BasicOutputIterator<X>
{
    requires SameType<reference, value_type&> &&
               Arrowable<pointer, value_type&>;
};
```



Specifying `for_each`

□ Without concepts:

```
template<class InputIterator, class Function>
    Function
    for_each(InputIterator first, InputIterator last,
             Function f);
```

□ With concepts:

```
template<InputIterator Iter,
         CopyConstructible Function>
    requires Callable1<Function,
                     InputIterator<Iter>::reference>
    Function
    for_each(Iter first, Iter last, Function f);
```



Let The Compiler Help

```
template<InputIterator Iter, typename T>
requires EqualityComparable<Iter::reference, T>
Iter find(Iter first, Iter last, const T& value) {
    while (first < last && !(*first == value))
        ++first;
    return first;
}
```

ConceptGCC

find.cpp: In function 'Iter find(Iter, Iter, const T&)':
find.cpp:7: error: no match for 'operator<' in 'first < last'



Specifying `copy`

□ Without concepts:

```
template<class InputIterator, class OutputIterator>
OutputIterator
copy(InputIterator first, InputIterator last,
      OutputIterator result);
```

□ Thinking about copy semantics...

- The current specification allows conversions while we copy.
- Did we mean for those conversions to happen?
 - If we didn't, are we stuck with them?
 - Many such choices when evolving a library



copy with Concepts

- We could tighten the semantics of copy...

```
template<InputIterator InIter,  
        BasicOutputIterator OutIter>  
    requires SameType<InIter::value_type,  
                     OutIter::value_type>  
  
    OutIter  
    copy(InIter first, InIter last, OutIter result);
```

- Or model copy as it is today...

```
template<InputIterator InIter, typename OutIter>  
    requires OutputIterator<OutIter,  
                           InIter::value_type>  
  
    OutIter  
    copy(InIter first, InIter last, OutIter result);
```



Today's advance

□ Without concepts:

```
template <class InputIterator, class Distance>
    void advance(InputIterator& i, Distance n);
```

“Since only random access iterators provide + and – operators, the library provides two template functions `advance` and `distance`. These functions use + and – for random access iterators (and are, therefore, constant time for them); for input, forward and bidirectional iterators they use ++ to provide linear time implementations.”



Today's advance, in practice

```
template<class InputIterator, class Distance>
    void advance_impl(InputIterator& i, Distance,
                      input_iterator_tag);
template<class InputIterator, class Distance>
    void advance_impl(InputIterator& i, Distance,
                      bidirectional_iterator_tag);
template<class InputIterator, class Distance>
    void advance_impl(InputIterator& i, Distance,
                      random_access_iterator_tag);

template <class InputIterator, class Distance>
    void advance(InputIterator& i, Distance n)
    {
        typedef iterator_traits<InputIterator>::iterator_category
            Cat;
        advance_impl(i, n, Cat());
    }
```



advance **with** enable_if

```
template <class InIter, class Distance>
    typename enable_if<is_input_iterator<InIter>::value
                        && !is_bidir_iterator<InIter>::value
                        >::type
    void advance(InputIterator& i, Distance n);
```

```
template <class InIter, class Distance>
    typename enable_if<is_bidir_iterator<InIter>::value
                        && !is_ra_iterator<InIter>::value
                        >::type
    void advance(InputIterator& i, Distance n);
```

```
template <class InIter, class Distance>
    typename enable_if<is_ra_iterator<InIter>::value
                        >::type
    void advance(InputIterator& i, Distance n);
```



advance with Concepts

```
template <InputIterator Iter>
    void advance(Iter& i, Iter::difference_type n);
```

```
template <BidirectionalIterator Iter>
    void advance(Iter& i, Iter::difference_type n);
```

```
template <RandomAccessIterator Iter>
    void advance(Iter& i, Iter::difference_type n);
```

Same overloading behavior as before, without the hidden function, traits, or tag dispatching.



Constraining Class Templates

```
template<typename T1, typename T2>
struct pair {
    pair();
    pair(const pair&);
    pair(const T1&, const T2&);
    template<typename U1, typename U2>
        pair(const pair<U1, U2>&);
    pair& operator=(const pair&);

    T1 first;
    T2 second;
};
```



```
template<typename T1, typename T2>
struct pair {
    requires DefaultConstructible<T1> &&
               DefaultConstructible<T2>
    pair();
    requires CopyConstructible<T1> &&
               CopyConstructible<T2>
    pair(const pair&);
    requires CopyConstructible<T1> &&
               CopyConstructible<T2>
    pair(const T1&, const T2&);
template<typename U1, typename U2>
    requires Convertible<U1, T1> && Convertible<U2, T2>
    pair(const pair<U1, U2>&);
    requires Assignable<T1> && Assignable<T2>
    pair& operator=(const pair&);
};
```



Concept Maps

- Quoth the C++03 Standard:
“A `vector` satisfies all of the requirements of a container and of a reversible container (given in two tables in 23.1) and of a sequence,”
- Express this as code:

```
template<CopyConstructible T>  
concept_map Sequence<vector<T>> { }
```

```
template<CopyConstructible T>  
concept_map  
    ReversibleContainer<vector<T>> { }
```



Checking Concept Maps

```
raiter.cpp:12: error: 'concept_map  
MutableRandomAccessIterator<std::_Bit_iterator>' does not meet the nested  
requirements of its concept  
raiter.cpp:12: note:  same-type constraint  
'std::SameType<MutableRandomAccessIterator<Iter>::reference,  
MutableRandomAccessIterator<Iter>::value_type&>' is not satisfied  
( 'std::_Bit_reference' is not 'bool&')
```

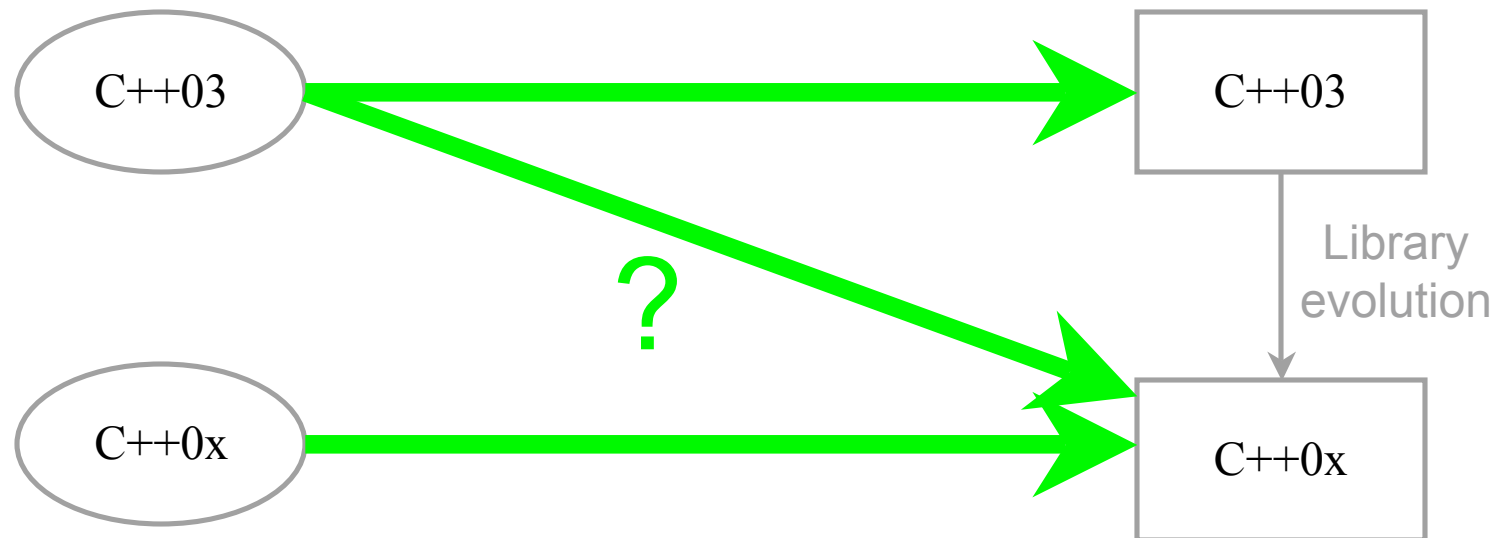
```
concept_map  
    MutableRandomAccessIterator<_Bit_iterator>  
    { }
```



What Backward Compatibility?

User Code

Library Code



User-Defined Iterators

- What if I defined my own iterator type to use with Standard Library algorithms?
 - Without concepts: you need to specialize `iterator_traits` or provide typedefs.
 - With concepts: you need to provide a concept map.
- Can we keep backward compatibility with `iterator_traits`-style iterators?
 - Yes, with a clever concept map template.



Mapping User-Defined Iterators

- Existing iterators will somehow have iterator traits defined

```
struct my_iterator {  
    typedef std::input_iterator_tag iterator_category;  
    typedef char value_type;  
    typedef const char& reference;  
    // ...  
};
```

- We need our concept map to:
 - Query those iterator traits
 - Match those traits to the right concept
 - Write this automatically:

```
concept_map InputIterator<my_iterator> {} // automatic?
```



Extracting Iterator Traits

```
auto concept _Iter_traits<typename Iter> {  
    typename iterator_category =  
        iterator_traits<Iter>::iterator_category;  
    typename value_type =  
        iterator_traits<Iter>::value_type;  
    typename reference =  
        iterator_traits<Iter>::reference;  
    typename pointer =  
        iterator_traits<Iter>::pointer;  
    typename difference_type =  
        iterator_traits<Iter>::difference_type;  
}
```



The Escape Hatch

- The `late_check` keyword introduces a late-checked template:
 - Late-checked templates have `requires` clauses
 - Users must meet the template requirements
 - *Template body is not type-checked until instantiation time.*



Mapping User-Defined Iterators

```
late_check template<typename Iter>
    requires _Iter_traits<Iter> &&
        Convertible<_Iter_traits<Iter>::iterator_category,
                    input_iterator_tag>
    concept_map InputIterator<Iter> {
        typedef _Iter_traits<Iter>::value_type
            value_type;
        typedef _Iter_traits<Iter>::difference_type
            difference_type;
        typedef _Iter_traits<Iter>::pointer pointer;
        typedef _Iter_traits<Iter>::reference reference;
        typedef _Iter_traits<Iter>::difference_type
            difference_type;
    };
```



From the User's Perspective

- C++03 uses of the C++0x library “just work”:

```
void f(my_iterator first, my_iterator last) {  
    std::find(first, last, 'a');  
}
```

- Under the hood:

- Compiler looks for a concept map
`InputIterator<my_iterator>`

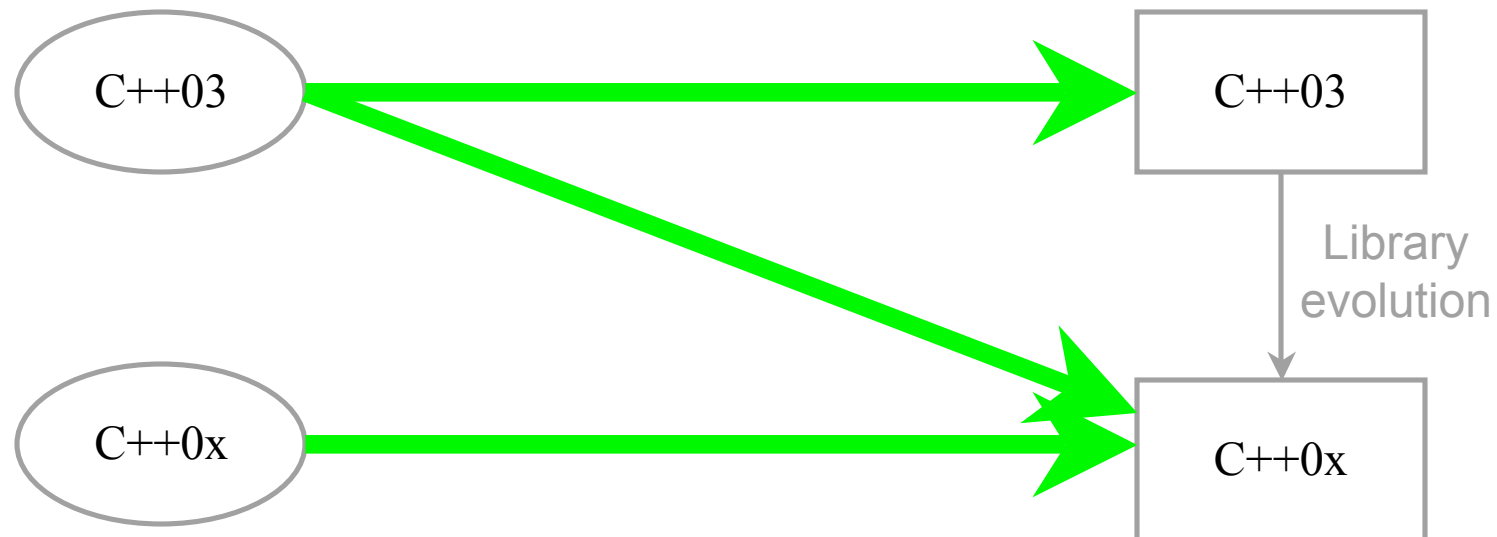
- Concept map template queries
`iterator_traits`, produces concept map



What Backward Compatibility?

User Code

Library Code



The Death of `iterator_traits`?

- ❑ Traits don't work with constrained templates
 - Traits rely entirely on specialization...
 - Specialization does not play well with modular type checking
- ❑ Can we kill `iterator_traits`?
 - No: existing code relies on it

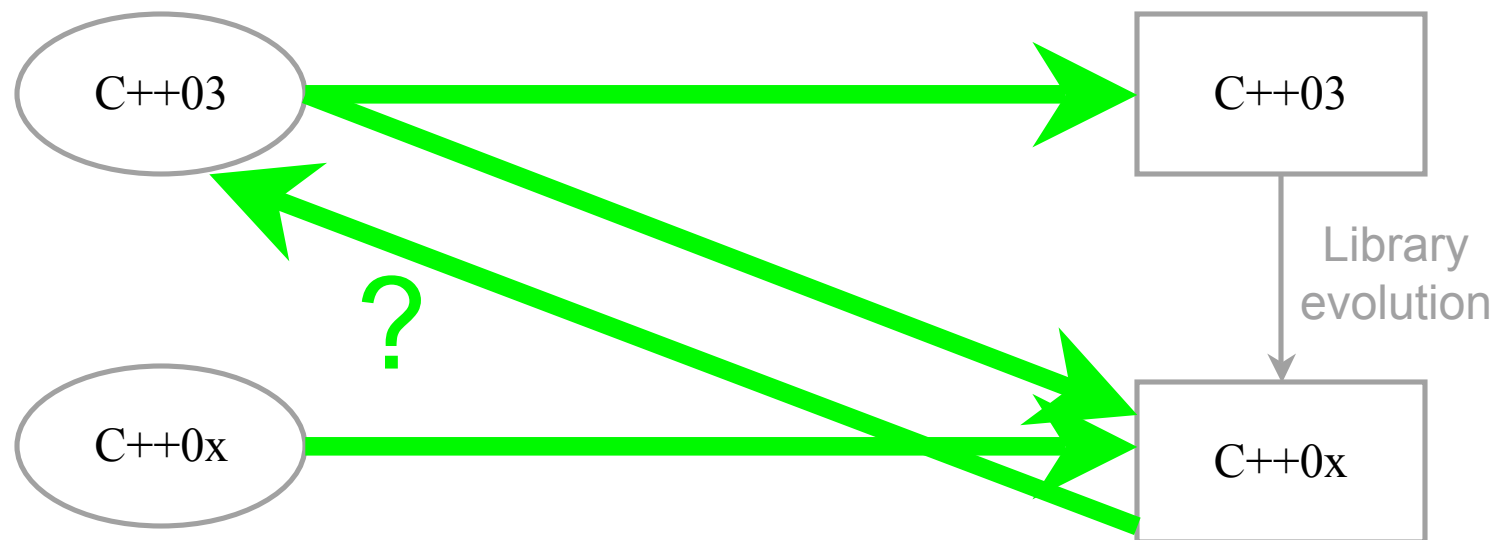
```
template<typename Iter>
    typename iterator_traits<Iter>::difference_type
    distance(Iter first, Iter last);
```



What Backward Compatibility?

User Code

Library Code



A New Life for `iterator_traits`

- Provide partial specializations of `iterator_traits` based on concepts

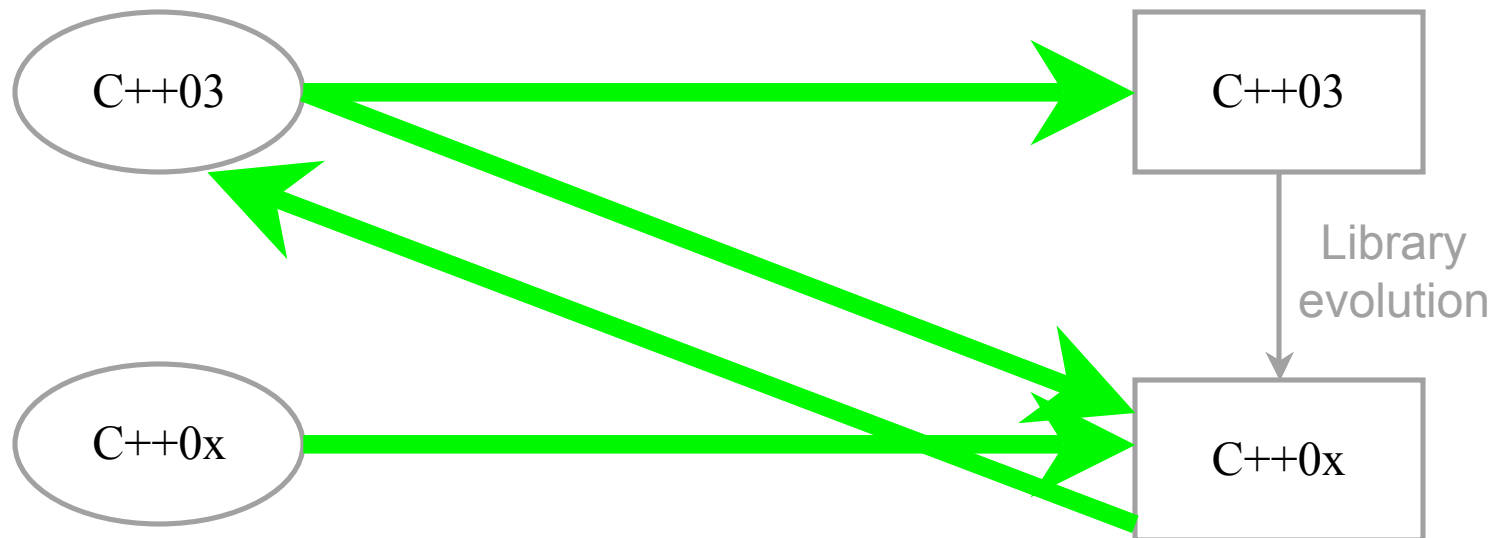
```
template<typename Iter>
    requires InputIterator<Iter>
struct iterator_traits<Iter> {
    typedef input_iterator_tag iterator_category;
    typedef InputIterator<Iter>::value_type value_type;
    typedef InputIterator<Iter>::difference_type
        difference_type;
    typedef InputIterator<Iter>::pointer pointer;
    typedef InputIterator<Iter>::reference reference;
};
```



Backward Compatibility

User Code

Library Code



A Better `is_convertible`

```
template<typename T, typename U>
struct is_convertible {
    static const bool value = false;
};
```

```
auto concept Convertible<typename T, typename U> {
    operator U(T);
}
```

```
template<typename T, typename U>
requires Convertible<T, U>
struct is_convertible<T, U> {
    static const bool value = true;
};
```



“Trait-Informed” Concepts

- We can write a concept to detect true/false:

```
concept True<bool Condition> { }  
concept_map True<true> { }
```

- And use that concept to inform concepts via traits:

```
concept TriviallyDefaultConstructible<typename T>  
    : DefaultConstructible<T> { }  
  
template<typename T>  
    requires DefaultConstructible<T> &&  
        True<has_trivial_default_constructor<T>::value>  
concept_map TriviallyDefaultConstructible<T> { }
```



What about C++03?

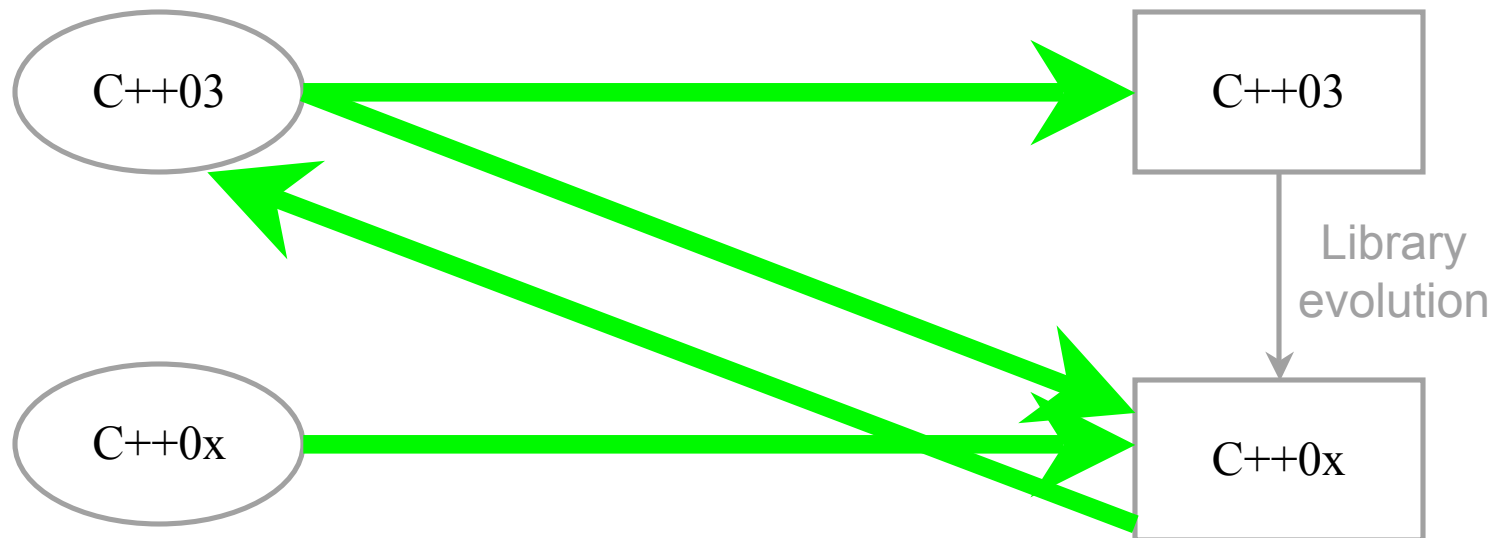
- Ubiquitous C++0x support is still far off on the horizon
 - We need our libraries to compile as C++03 and C++0x
- Compatibility with C++03 is going to require some effort
 - Macros (as few as we can)
 - “Fake” concepts



C++03/C++0x Libraries Distinct

User Code

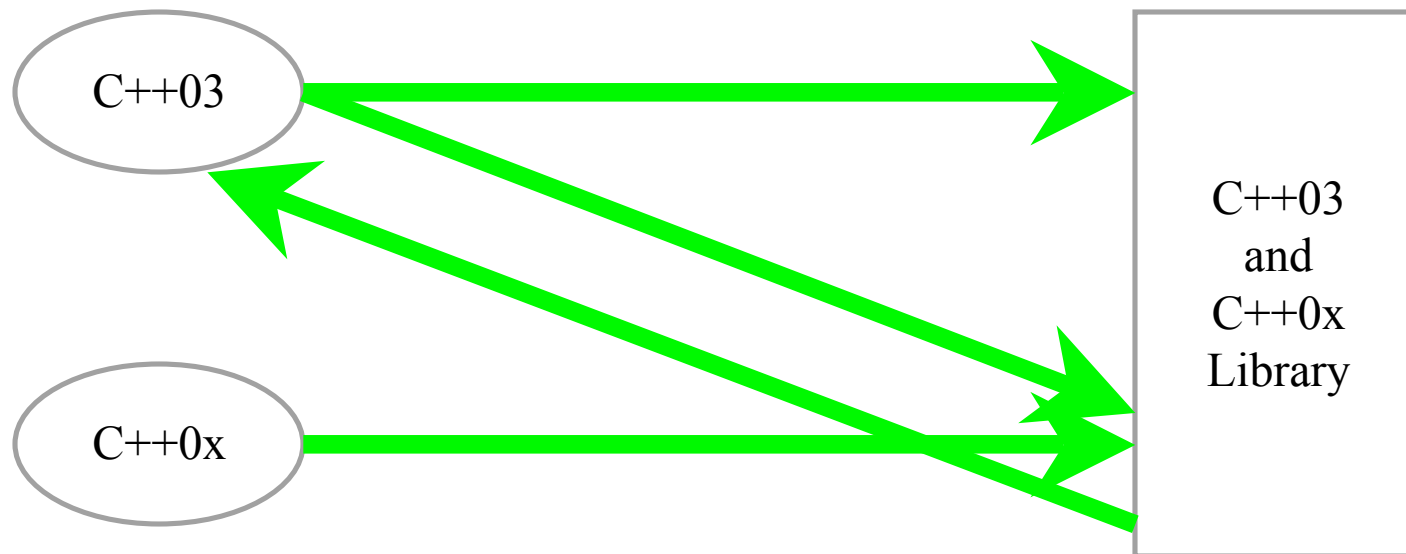
Library Code



A More Practical Approach

User Code

Library Code



C++03/C++0x

```
template<typename Iter, typename T>
requires
    InputIterator<Iter> &&
    EqualityComparable<InputIterator<Iter>::value_type, T>
Iter find(Iter first, Iter last, const T& value) {
    while (first != last && !(*first == value))
        ++first;
    return first;
}
```



Macro BOOST_REQUIRE

```
#ifndef BOOST_HAS_CONCEPTS
#   define BOOST_REQUIRE(...) requires __VA_ARGS__
#else
#   define BOOST_REQUIRE(...)
#endif

template<typename Iter, typename T>
BOOST_REQUIRE(
    InputIterator<Iter> &&
    EqualityComparable<InputIterator<Iter>::value_type, T>)
Iter find(Iter first, Iter last, const T& value) {
    while (first != last && !(*first == value))
        ++first;
    return first;
}
```



Dealing with Associated Types

- We handle associated types differently in C++03 vs. C++0x

- C++03: Traits

```
template<typename Iter>
    typename iterator_traits<Iter>::difference_type
    distance(Iter first, Iter last);
```

- C++0x: Associated types

```
template<typename Iter>
    BOOST_REQUIRES (InputIterator<Iter>)
    InputIterator<Iter>::difference_type
    distance(Iter first, Iter last);
```



Associated Types, Approach #1

- Remember our concept-based specializations of `iterator_traits`?

```
template<typename Iter>
BOOST_REQUIRES(InputIterator<Iter>)
typename iterator_traits<Iter>::difference_type
distance(Iter first, Iter last);
```

- Unfortunately, this solution is neither here nor there
 - Mixes C++03/C++0x paradigms



Associated Types, Approach #2

- Assumption: C++0x view is cleaner
- Solution: build concept look-alikes in C++03

```
#ifndef BOOST_HAS_CONCEPTS
template<typename Iter>
struct InputIterator : std::iterator_traits<Iter> { };

template<typename Iter>
struct ForwardIterator : InputIterator<Iter> { };
#endif

template<typename Iter>
    BOOST_REQUIRES (InputIterator<Iter>)
    typename InputIterator<Iter>::difference_type
    distance (Iter first, Iter last);
```

Necessary in C++03, harmless in C++0x



Concept-Based Overloading

- ❑ Concept-based overloading in C++03 uses two tricks:
 - Tag dispatching
 - `enable_if/SFINAE`
- ❑ Concept-based overloading in C++0x is expressed directly via overloads
- ❑ Macro solution is possible
 - ... but it is ugly
 - *really ugly*



An Open Problem

- Good C++03/C++0x implementations of concept-based are unknown
 - The C++03 hacks are egregious
- Known approaches and ideas:
 1. Use three (!) macros and a C++03 dispatching function
 2. Macroize `enable_if` checks for C++03
 3. Completely separate C++03/C++0x overloading/dispatching logic



“Obsoleted” Template Tricks

Trick	Concept Equivalent
Type traits	Concepts
Tag dispatching	Concept-based overloading
Concept checking, Concept archetypes	Constrained templates
<code>sizeof</code> , SFINAE tricks	Concepts
<code>enable_if</code>	Requirements clause
Adaptors/façades	Concept maps



Concepts, Generic Libraries, and Composition



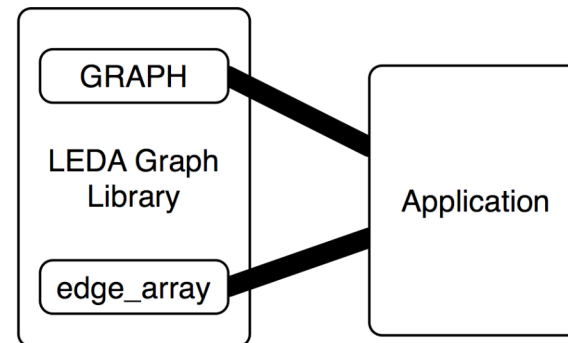
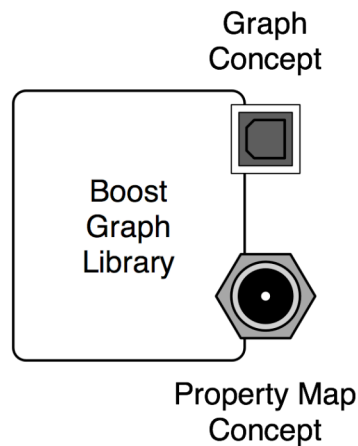
The Boost Graph Library

- We want to “conceptualize” the Boost Graph Library
 - Easier to use, easier to implement
 - More composable with other libraries

```
concept Graph<typename G> {  
    typename vertex_type;  
    typename edge_type;  
    ForwardIterator OutEdgeIterator;  
  
    int num_vertices(G);  
    int out_degree(vertex_type, G);  
    pair<OutEdgeIterator, OutEdgeIterator>  
        out_edges(vertex_type, G);  
}
```



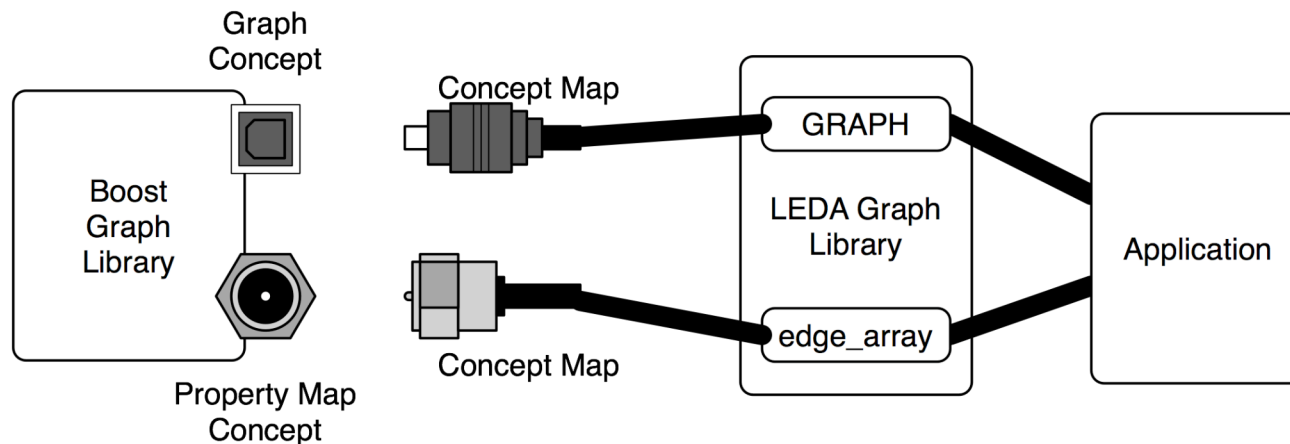
Concept Maps for Composition



```
leda::GRAPH<Server, Link> internet_graph;  
leda::edge_array<double> total_latency;  
boost::shortest_paths(internet_graph, start, total_latency);
```



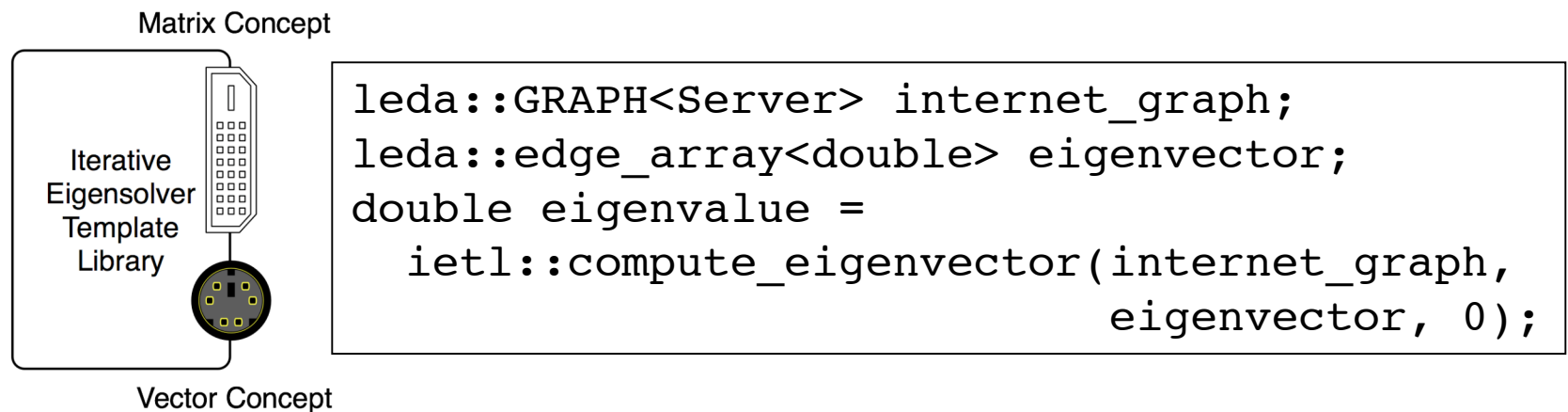
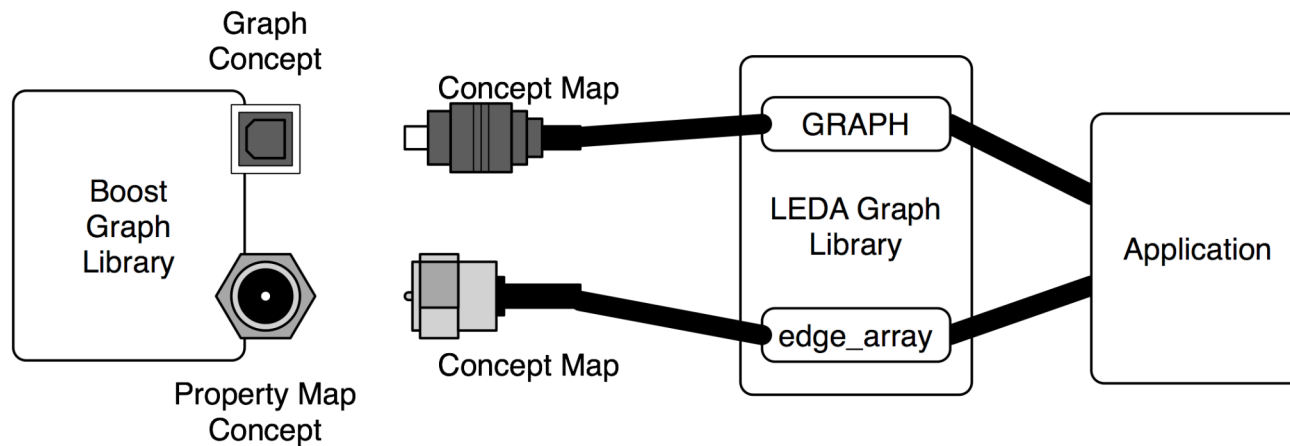
Concept Maps for Composition



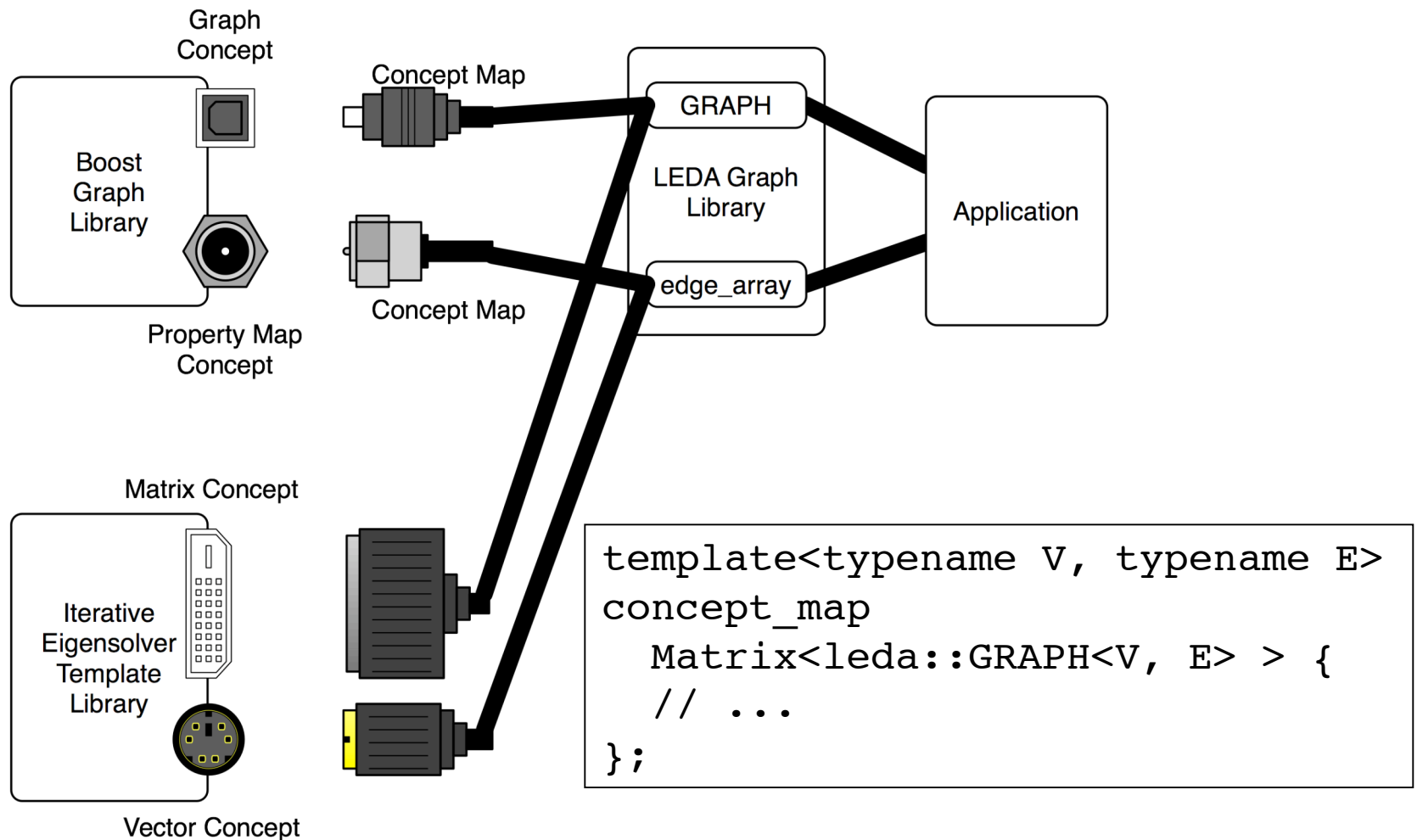
```
template<typename V, typename E>
concept_map Graph<leda::GRAPH<V, E> > {
    typedef leda::leda_node vertex_type;
    int num_vertices(const leda::GRAPH<V, E>& g) {
        return g.number_of_nodes();
    }
    int out_degree(vertex_type v, const leda::GRAPH<V, E>&) {
        return outdeg(v);
    }
};
```



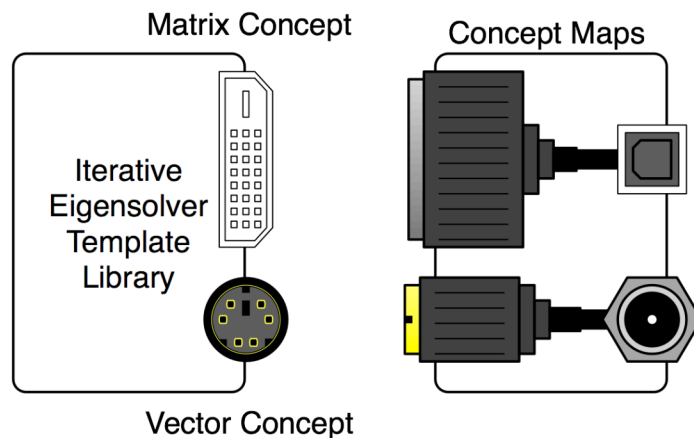
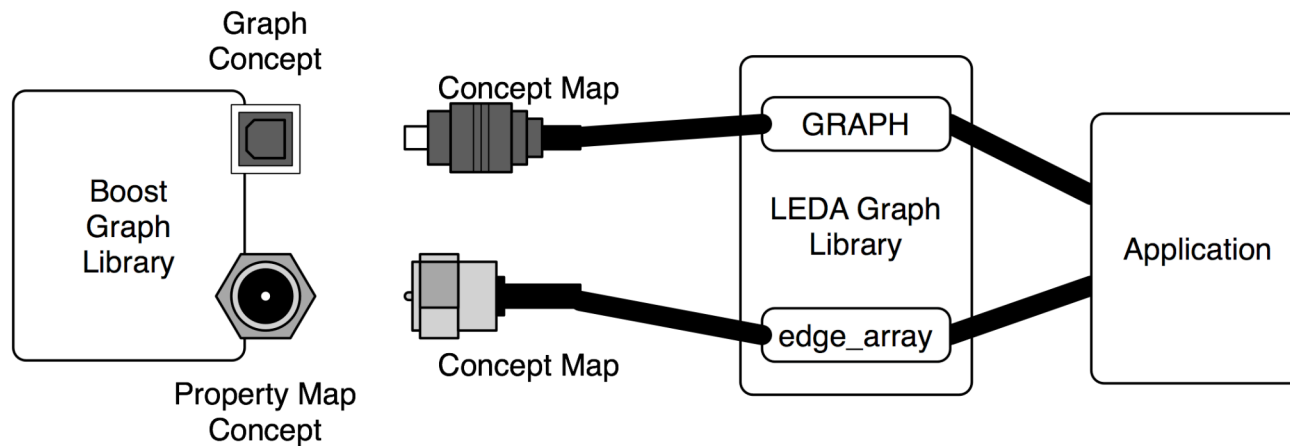
Concept Maps for Composition



Concept Maps for Composition

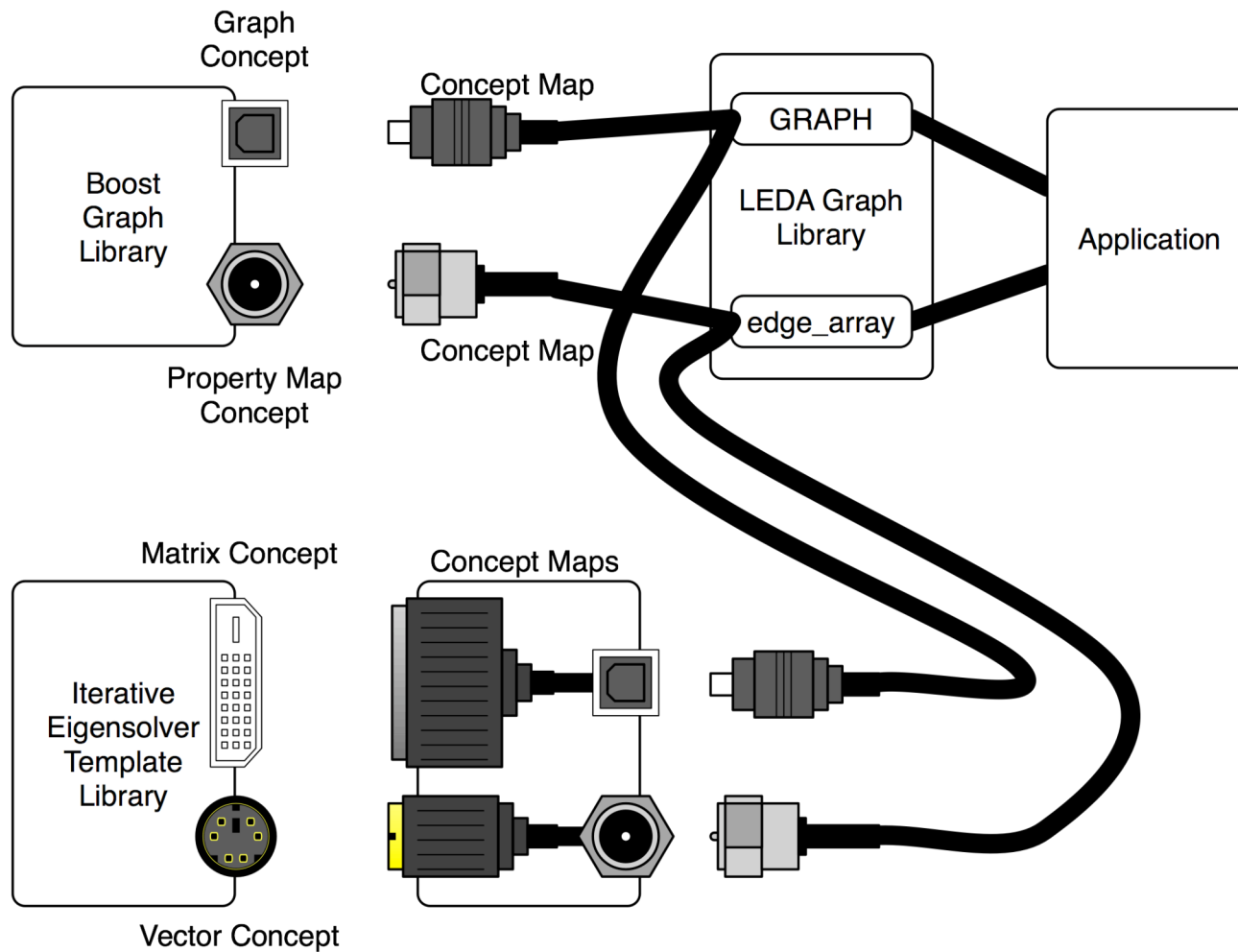


Concept Maps for Composition



```
template<typename G>
requires Graph<G>
concept_map Matrix<G> {
    // ...
};
```

Concept Maps for Composition



Summary: C++0x Evolution

- Evolving a library takes time and patience
 - Start small, with toy versions of your library
 - Evolve from the bottom up
- C++03/C++0x libraries are possible
 - Concept maps, trait specializations for backward compatibility
 - Some macros are necessary
 - Documentation effort is simplified (use C++0x)
 - Better testing coverage; more to test



A Call To Arms

- Boost is a vehicle for change in the C++ community
- Try new C++0x features
- C++0x-specific implementations of Boost libraries



I WANT YOU
TO HELP MAKE
C++0x GREAT

