

GGL

Generic Geometry Library for Boost

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April 2009***





Contents

- > Introduction and history (10 min)
- > Usage (30 min)
- > Internals (30 min)
- > Extensibility (20 min)

- > Questions or discussions
 - Allowed during session 😊

Introduction and History





Introduction (1)

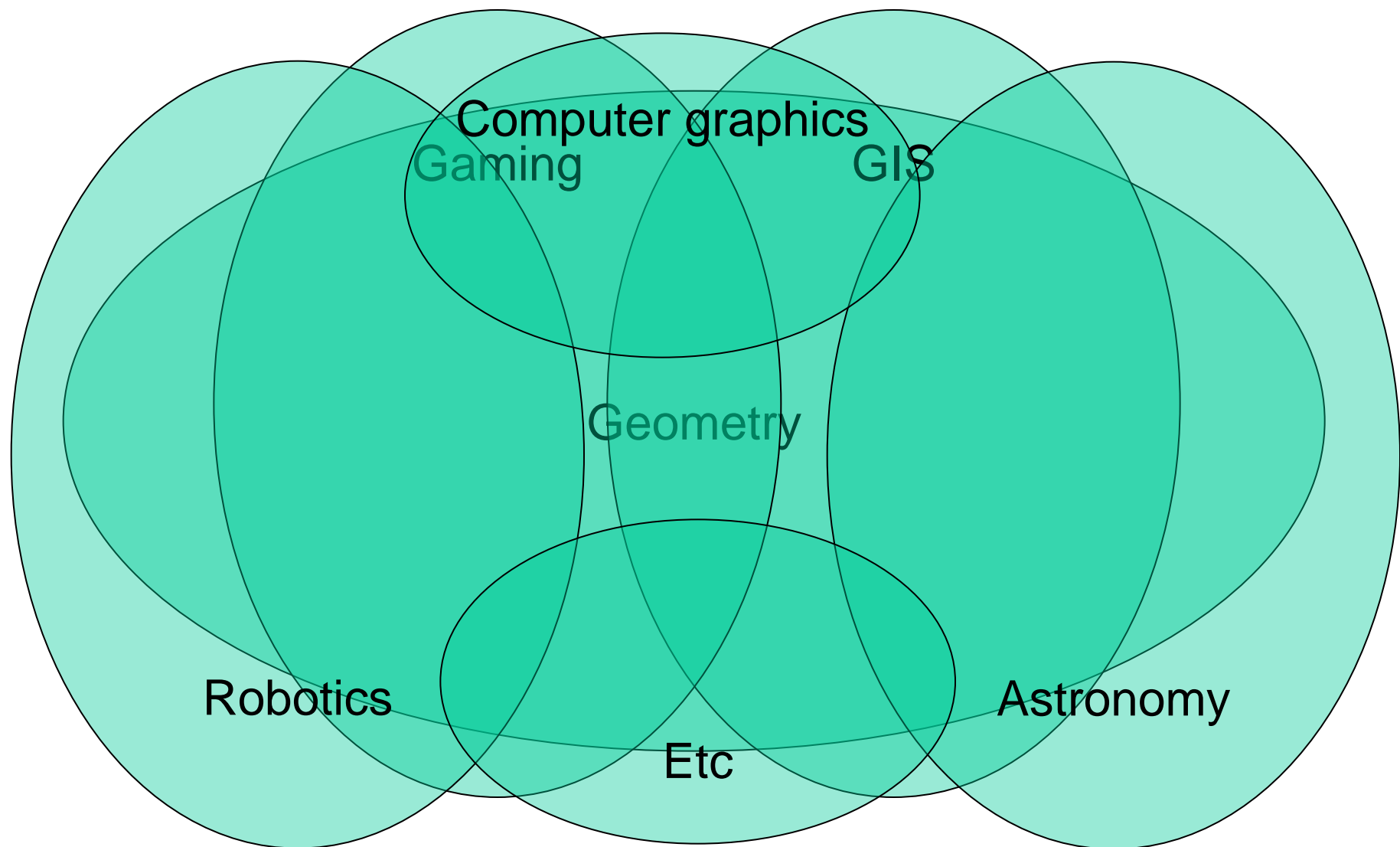
- > Generic Geometry Library
- > Library concerning geometry based on generic programming and templates
- > Target:

```
int a[2] = {1,1};  
int b[2] = {2,3};  
double d = distance(a, b);  
cout << "Distance :" << d;
```
- > Follows Boost conventions
- > Follows std:: conventions where possible
- > Follows OGC conventions where appropriate

- > Dimension agnostic
 - > Coordinate system agnostic
 - > Based on concepts
 - > Non intrusive
-
- > Rich
 - > Generic
 - > Blazing



Introduction (3)



- > GGL (geolib), Geodans Geographic Library
- > Started in 1995
- > Developed until 2003
- > Frozen...
- > Revived and revised in 2007
- > New core (geometry) based on templates
- > First preview: January 2008
- > ...
- > Fourth preview: February 2009



History (2)



- > Barend Gehrels (Geodan, Amsterdam) from (1995), 2007
- > Bruno Lalande (Paris, Boost contributor) from April 2008
- > Mateusz Loskot (Cadcorp, London) from March 2009

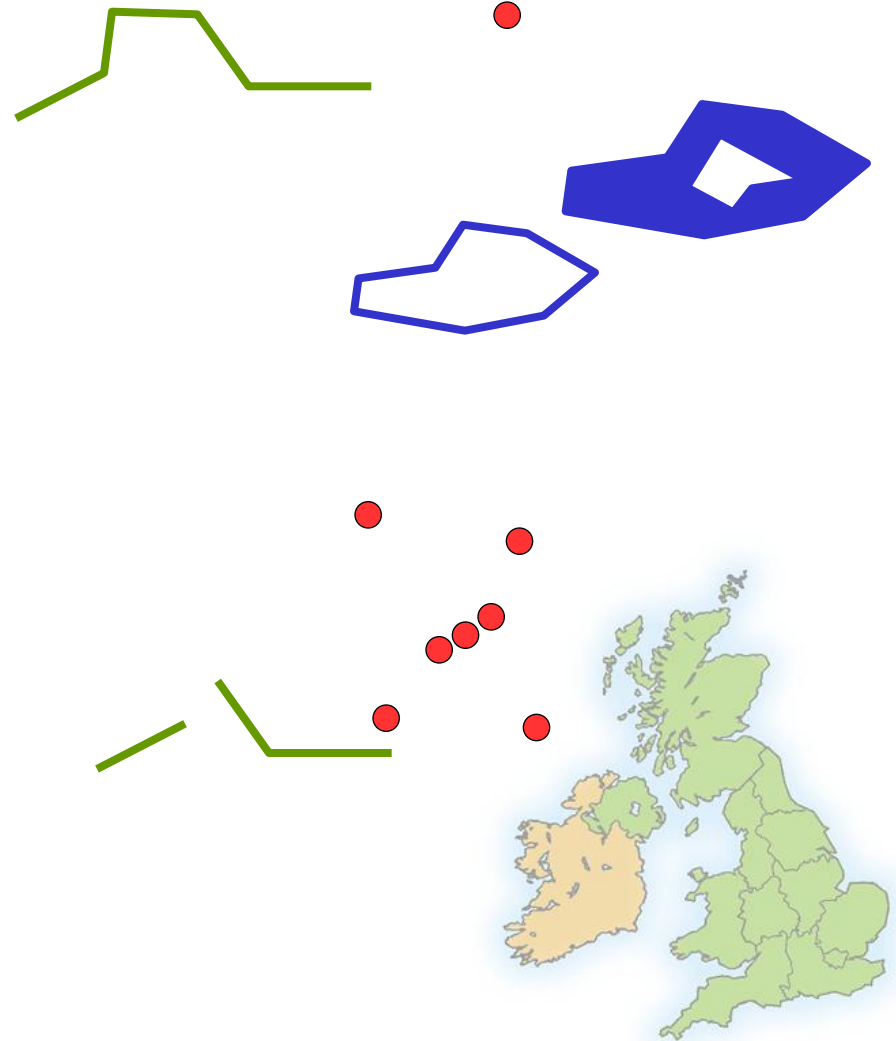
Usage





Geometries

- > point
- > linestring
- > polygon
 - linear_ring
- > multi_point
- > multi_linestring
- > multi_polygon

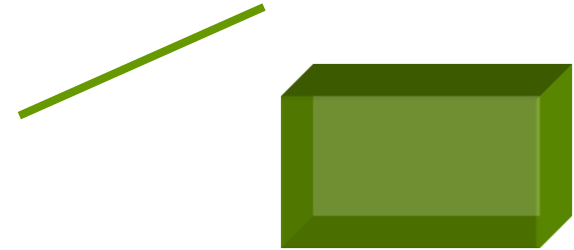




Other geometries

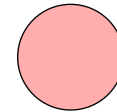
> “Helper” geometries

- Segment
- Box



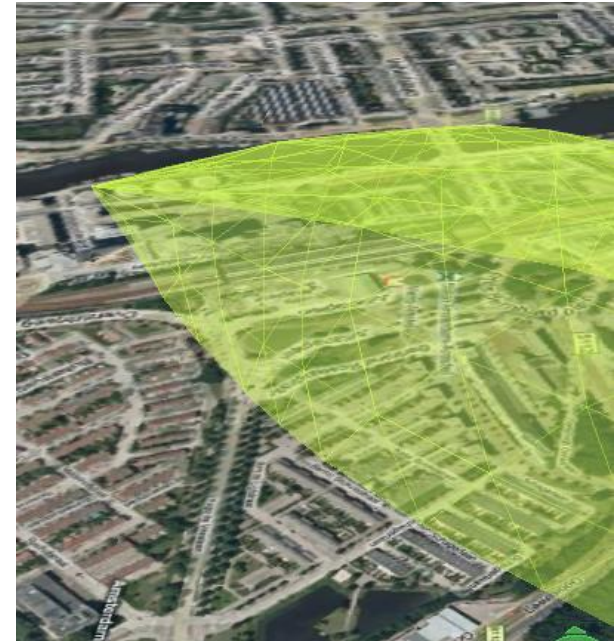
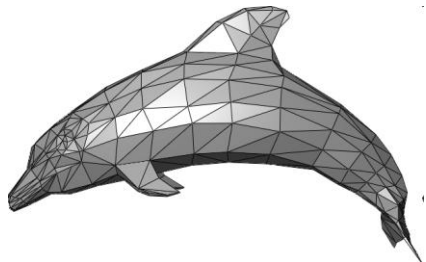
> Other geometries

- n-sphere



> 3D geometries

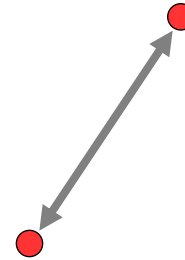
- polyhedron
- multi_polyhedron





Samples: distance, points

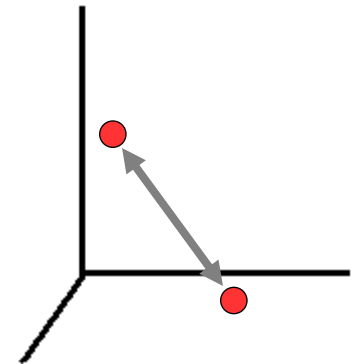
```
int a[2] = {1,1};  
int b[2] = {2,3};  
double d = ggl::distance(a, b);  
cout << "Distance:" << d << endl;
```



```
boost::tuple<double, double> c = boost::make_tuple(3.7, 2.0);  
boost::tuple<double, double> d = boost::make_tuple(5.1, 8.2);  
cout << distance(c, d) << endl;
```

```
cout << distance(a, c) << endl; // on different types
```

```
typedef ggl::point<float, 3> p;  
p e = ggl::make<p>(1, 2, 3);  
p f = make<p>(4, 5, 6);  
cout << distance(e, f) << endl; // 3D
```





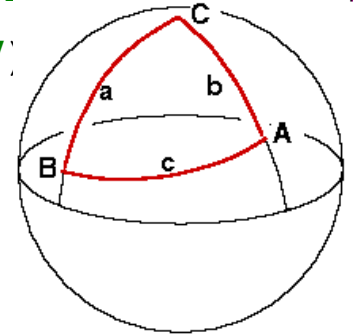
Distance, explanation

- > GGL supports different point types
 - > Points following the concepts are supported
 - > `double[2]`, `double[3]`, `tuple`, `ggl::point`
 - > custom geometries
-
- > same function **distance** for all types
 - > **distance** works also on different point types



Samples: distance, geographic

```
typedef point<float, 2, cs::geographic<degree> > lola;  
lola amsterdam = parse<lola>("52 22 23 N", "4 53 32 E");  
lola aspen = parse<lola>("39 11 32 N", "106 49 28 W");  
cout << distance(amsterdam, aspen) << endl;
```



- > Cartesian, spherical, geographic
- > Behind the screens a different *calculation* is chosen
- > This is called the **strategy**, a compile-time policy bound to coordinate system

```
cout << distance(amsterdam, aspen,  
    strategy::distance::vincenty<lola>()) << endl;
```

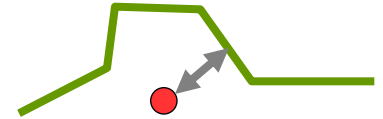
- > The strategy can also be specified by the user



Samples: distance, linestrings



```
typedef boost::tuple<double, double> p;  
std::vector<p> line;  
line.push_back(boost::make_tuple(1.0, 5.0));  
line.push_back(boost::make_tuple(8.0, 3.4));  
line.push_back(boost::make_tuple(7.5, 1.2));  
p point = boost::make_tuple(3, 3);  
cout << distance(line, point);
```



- > Linestrings (curves, sequences of points, polylines) are `std::vector`'s
- > All algorithms work on `boost::range`'s

```
boost::range_const_iterator<std::vector<p> >::type it;  
it = boost::begin(line);  
cout << distance(point, make_pair(it, it + 2)) << endl;
```



Samples: distance, distance result

```
typedef boost::tuple<int, int> p;  
typedef ggl::distance_result<p, p>::type dr;  
dr r = ggl::distance(make_tuple(1, 2), make_tuple(3, 4));
```

- > The result is still **squared**: $a^2 + b^2$
- > Expensive **sqrt** not applied

```
double d = r;
```

- > Delayed calculation of sqrt
- > Relevant for multi-comparisons on distance (e.g. in simplify)
- > Spherical distances: no square root
- > Distance might be compared in “degrees” instead (avoiding multiplying with radius each time)
- > The distance result is strategy-dependant



Distance, summary

- > one function
- > many supported geometry-types
- > many dimensions
- > many behaviours
- > different return types

	Pnt	Ls	Poly	MP	ML	MP
Pnt	*	*	*	*	*	*
Ls	*	*	*	*	*	*
Poly	*	*	*	*	*	*
MP	*	*	*	*	*	*
ML	*	*	*	*	*	*
MP	*	*	*	*	*	*

Cartesian	*
Spherical	*
Geographic	*

2D	*
3D	*
N-D	*

- > All algorithms work on all geometry types...
- > ... and on custom types
- > Many of them are “coordinate agnostic” and use strategies as “side”, “distance”
- > Not all is implemented / applicable for 3D
- > Algorithms are modeled according to OGC
- > More algorithms added or planned



Standard algorithms

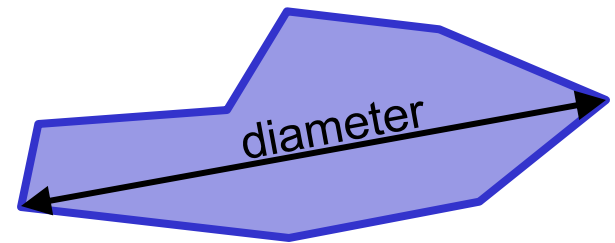
- > because linestrings, rings, multi* are `std::vector` / `boost::` compatible...
- > ... all these algorithms can be applied
 - `std::reverse(line.begin(), line.end(), ...)`
 - `std::copy(line.begin(), line.end(), ...)`
 - `boost::begin(line)`
 - `boost::end(line)`
 - `boost::size(line)`
 - `boost::range_const_iterator<Line>::type`
 - `std::for_each`
 - etc



More algorithms

> geometric properties:

- area
- length
- perimeter
- centroid
- *volume*
- *contents*
- envelope
- is_convex
- is_simple
- diameter





Compile-time algorithms

> compile-time functions / meta-functions :

- point_type
- tag
- coordinate_type
- coordinate_system
- replace_point_type
- dimension
- topological_dimension
- is_linear
- is_multi



More algorithms



> boolean relations:

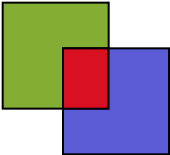
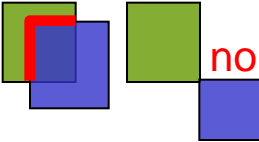
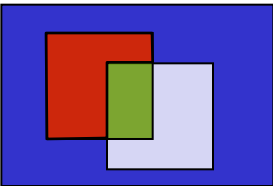

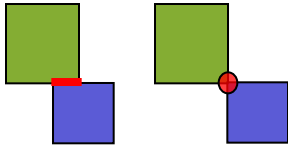
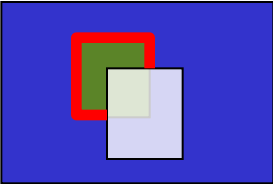
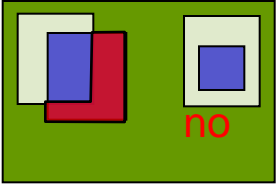
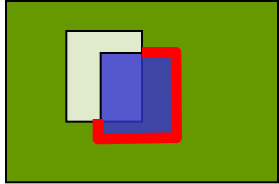
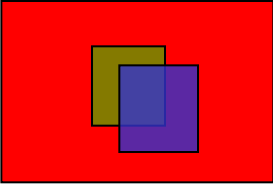
- within
- touches
- intersects
- overlaps
- disjoint
- contains
- equals
- crosses

> other relations

- relate
- distance



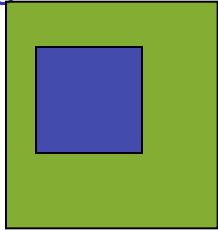
Theory of spatial relationships

DE9IM dimension extended 9 intersection matrix (for polygons)	Interior	Boundary	Exterior
Interior	 $-1 / 2$	 $-1 / 1$	 $-1 (eq/in) / 2$
Boundary	 $-1 / 1$	 $-1 / 0 / 1$	 $-1 (eq/in) / 1$
Exterior	 $-1 (eq/in) / 2$	 $-1 (eq/in) / 1$	 2

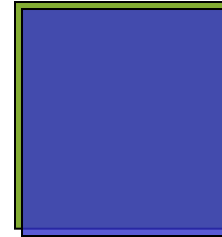


Theory of spatial relationships

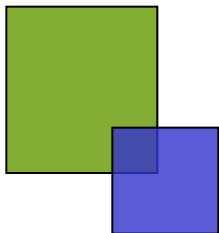
A: green
B: blue



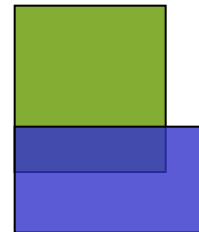
	I	B	E
I	2	1	2
B	-1	-1	1
E	-1	-1	2
within			
1--0--102			



	I	B	E
I	2	-1	-1
B	-1	1	-1
E	-1	-1	2
equals			
1---0---2			



	I	B	E
I	2	1	2
B	1	0	1
E	2	1	2
overlaps			
212101212			



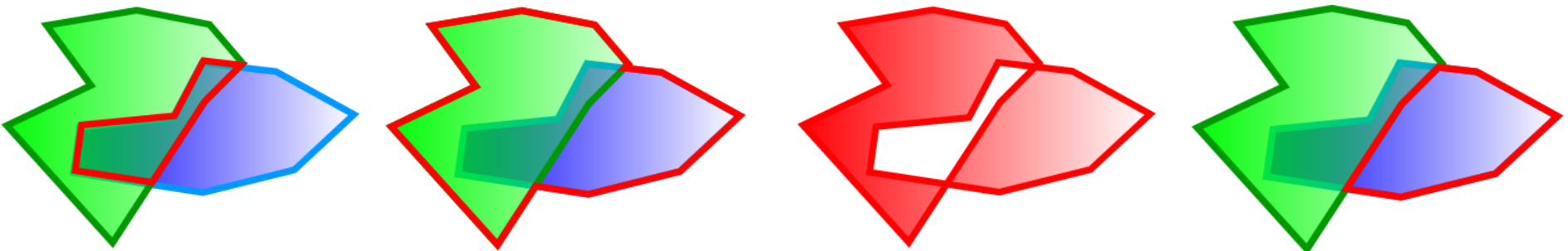
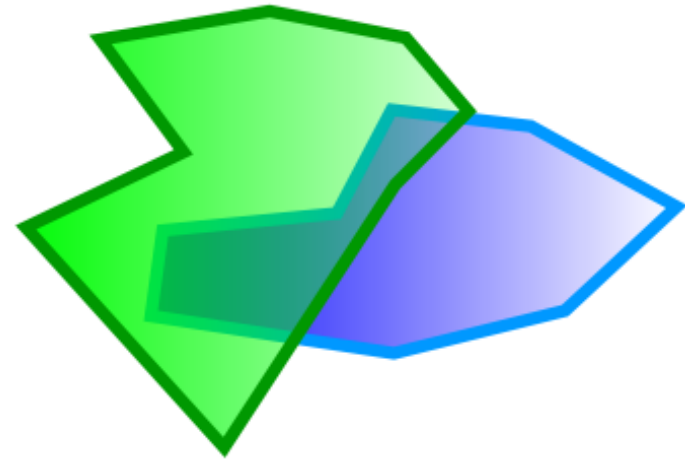
	I	B	E
I	2	1	2
B	1	1	1
E	2	1	2
overlaps (t)			
212111212			



More algorithms

> point set relationships

- intersection (AND)
 - clip
- union (OR)
- symmetric_difference (XOR)
- difference (AND NOT)





More algorithms

>Change:

- simplify
- *disperse*
- *spline*
- *densify*
- buffer
- convex_hull
- transform

>Utilities / internals

- sectionalize
- midpoints
- remove_identations
- remove_holes
- convert

>Construction / editing

- assign
- parse
- make
- append
- correct
- clear

>Other:

- closest_pair
- *minimum bounding ball*
- *largest empty circle*
- *oriented bounding box*

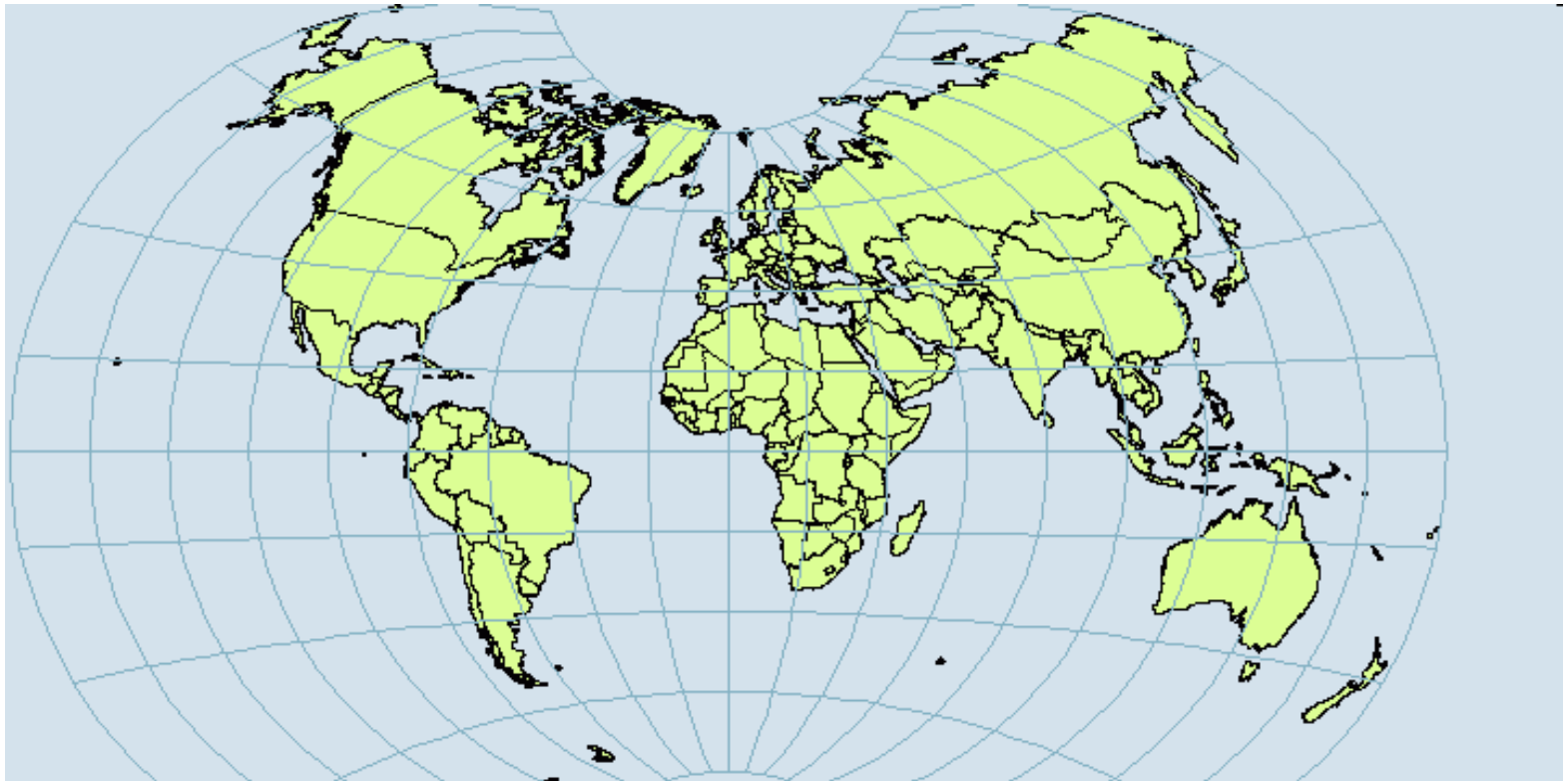
- > Rtree
- > BSP
- > PRTree
- > QuadTree

- > Working on:
 - a set of geometries
 - a set of vertices within a geometry
 - a set of geometries within a multi-geometry



Projections

- > Map Projections
- > Proj4 conversion
- > Transform



- > Matrix transformations
- > uBLAS is used
- > Scaling, rotation, etc
- > Transform from radian to degree v.v.
- > Transform via map projection
- > Generic Transform

Internals and details





Use of other boost libraries (1)

- > Boost Type Traits (e.g. `remove_const`)
- > Boost Range
- > Boost Concept Check
- > Boost Numeric Conversion (`cast`, `bounds`)
- > Boost MPL
- > Boost Static Assert
- > Boost Iterator
- > Boost Smart Pointer (`shared_ptr`, in spatial index / projections)
- > Boost uBLAS (for transformations)

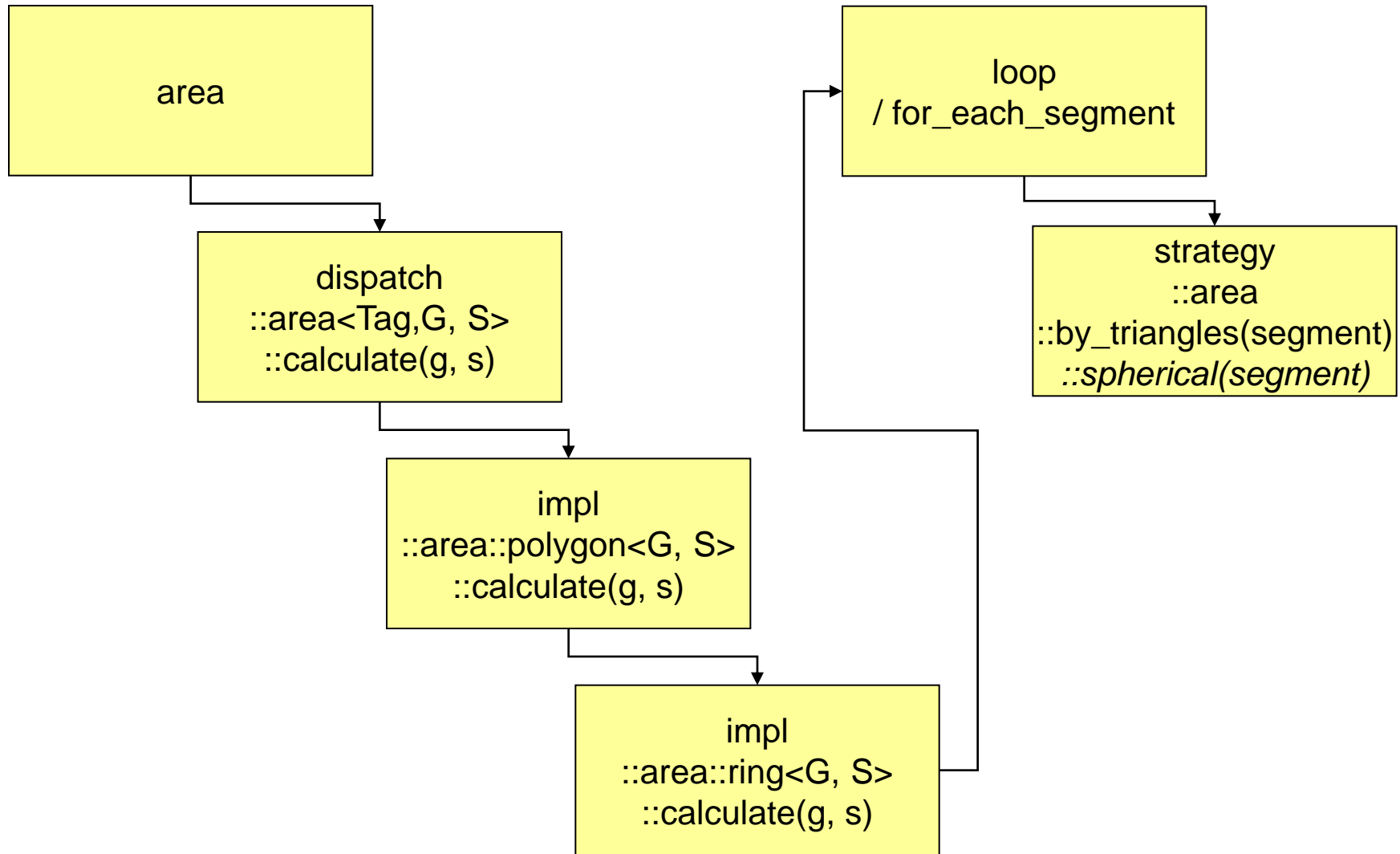


Use of other Boost Libraries (2)

- > Adapted geometries:
 - Boost Array
 - Boost Tuple
- > IO and parsing
 - Boost Tokenizer
 - Boost Conversion (lexical cast)
 - Boost String Algo
- > Testing
 - Boost Test
 - Boost Timer
- > Examples and applications
 - Boost Graph
 - Boost Lambda
 - Boost Function



Generic programming and tag dispatching



> Two types of tags:

- tag identifying kind of geometry
 - choose algorithm
- tag identifying coordinate system
 - choose strategy

> Specializations of “dispatch”:

- per tag (possibly of more than one geometry)
- per dimension
- per coordinate system
- per other property



Concepts and tag dispatching

- > “Other property”: meta-functions as:
 - is_linear
 - is_multi
 - topological_dimension
- > Used for specializations
- > No “concept refinement”
- > “meta-function finetuning”

Extensibility





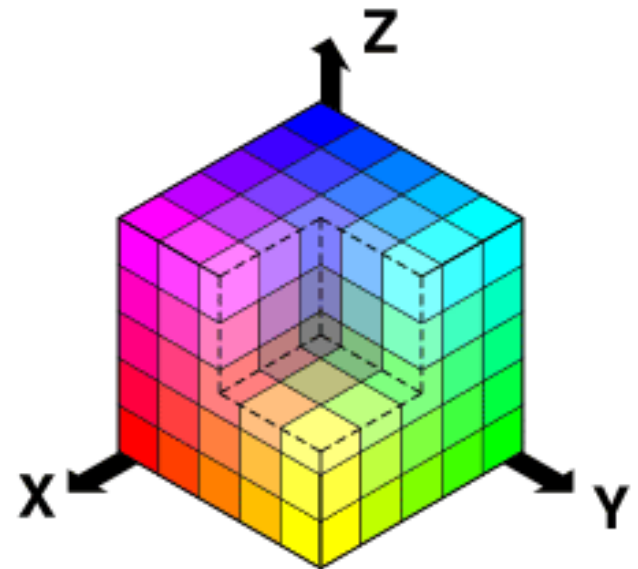
Customization

- > Concepts
- > Generic
- > Non intrusive



- > Library can handle other point types
- > Add traits
- > Or use “REGISTER”

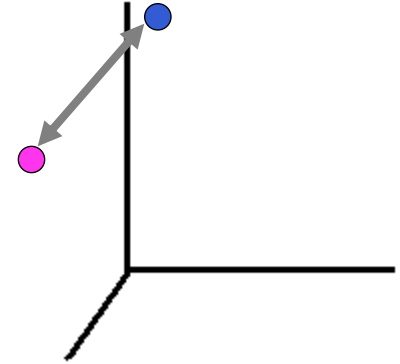
```
struct my_color  
{  
    double red, green, blue;  
};
```





Customization: color cube point

```
// Sample point, defining three color values
struct my_color
{
    double red, green, blue;
};
```



```
GEOMETRY_REGISTER_POINT_3D(my_color, double,
    cs::cartesian, red, green, blue)
```

```
my_color c1 = ggl::make<my_color>(255, 3, 233);
my_color c2 = ggl::make<my_color>(0, 50, 200);
```

```
cout << "color distance " << c1 << " to " << c2 << " is " <<
    ggl::distance(c1,c2) << endl;
```

- > Custom linestring
- > GPS track
- > Custom polygon (triangle)
- > Overriding one algorithm



Customization: GPS point



```
struct gps_point
{
    double latitude, longitude, height;
    double speed;
    // Date/time, heading, etc

    gps_point() {}

    gps_point(const std::string& c1,
              const std::string& c2,
              double h, double s)
        : height(h)
        , speed(s)
    {
        ggl::parse(*this, c1, c2);
    }
};

GEOMETRY_REGISTER_POINT_2D(gps_point, double,
                           cs::geographic<degree>, longitude, latitude)
```




Customization: GPS track



```
// Declare a custom linestring which will have the GPS points
struct gps_track : std::vector<gps_point>
{
    std::string owner;
    int route_identifier;
    // etc

    gps_track(int i, const std::string& o)
        : owner(o)
        , route_identifier(i)
    {}
};

// Register the track, using traits

namespace ggl { namespace traits {

template <>
struct tag<gps_track>
{
    typedef linestring_tag type;
};

}}
```



Customization: GPS point



```
int main()
{
    // Declare a "GPS Track" and add some GPS points
    gps_track track(23, "Mister G");
    track.push_back(gps_point("52 22 23 N", "4 53 32 E", 50, 180));
    track.push_back(gps_point("52 10 00 N", "4 59 59 E", 110, 170));
    track.push_back(gps_point("52 5 20 N", "5 6 56 E", 0, 90));

    std::cout
        << "track:  " << track.route_identifier << std::endl
        << "from:    " << track.owner << std::endl
        << "as wkt:  " << ggl::wkt(track) << std::endl
        << "length:  " << ggl::length(track)/1000.0 << " km" << std::endl;

    return 0;
}
```



Customization: Custom triangle



```
template <typename P>
struct triangle : public boost::array<P, 3> { };

namespace ggl { namespace traits {

// Register the triangle as being a ring
template <typename P>
struct tag<triangle<P> >
{
    typedef ring_tag type;
};

}}

// somewhere
triangle<boost::tuple<double, double> > t;
    t[0] = boost::make_tuple(0, 0);
    t[1] = boost::make_tuple(5, 0);
    t[2] = boost::make_tuple(2.5, 2.5);

    std::cout << "Triangle: " << kml(t) << std::endl;
    std::cout << "Area: " << area(t) << std::endl;
```



Customization, triangle

- > All algorithms for triangle are that of RING
- > But wait...
- > For a triangle there is also an easier formula

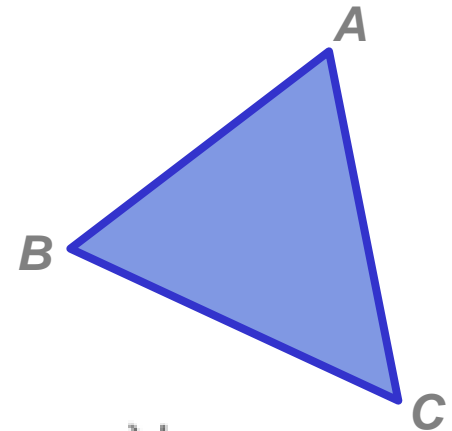


Customization: Custom triangle



```
// Specializations of area dispatch structure, implement algorithm
namespace ggl { namespace dispatch {

template<typename P, typename Strategy>
struct area<ring_tag, triangle<P>, Strategy >
{
    static inline double calculate(const triangle<P>& t, const Strategy &)
    {
        return
            0.5 * (
                (get<0>(t[2]) - get<0>(t[0])) * (get<1>(t[1]) - get<1>(t[0]))
                - (get<0>(t[1]) - get<0>(t[0])) * (get<1>(t[2]) - get<1>(t[0]))
            );
    }
};
```



$$S = \frac{1}{2} |(x_C - x_A)(y_B - y_A) - (x_B - x_A)(y_C - y_A)|$$

- > **Generic** library for **Geometry**
- > First library for Geography based on Generic Programming
- > More than Geography
- > Boost needs Geometry!



Thanks!

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