Introducing MPLL.Graph

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Outline

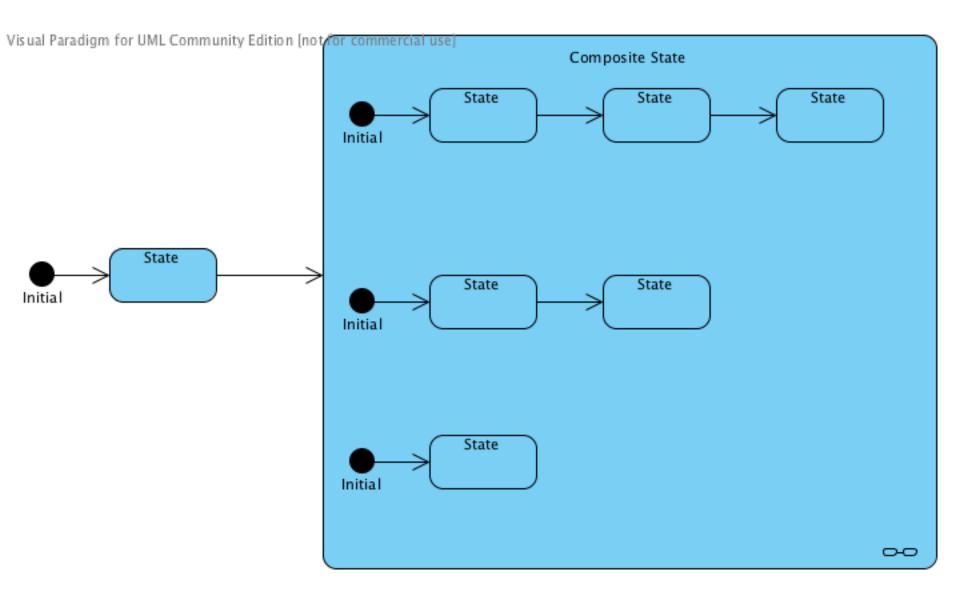
- MPL.Graph in Meta State Machine
- MPL.Graph Concepts & Algorithms
- MPL.Graph versus Meta Graph Library
- (prototype) Fusion.Graph
- Questions & Comments
- Fun Ideas

Meta State Machine

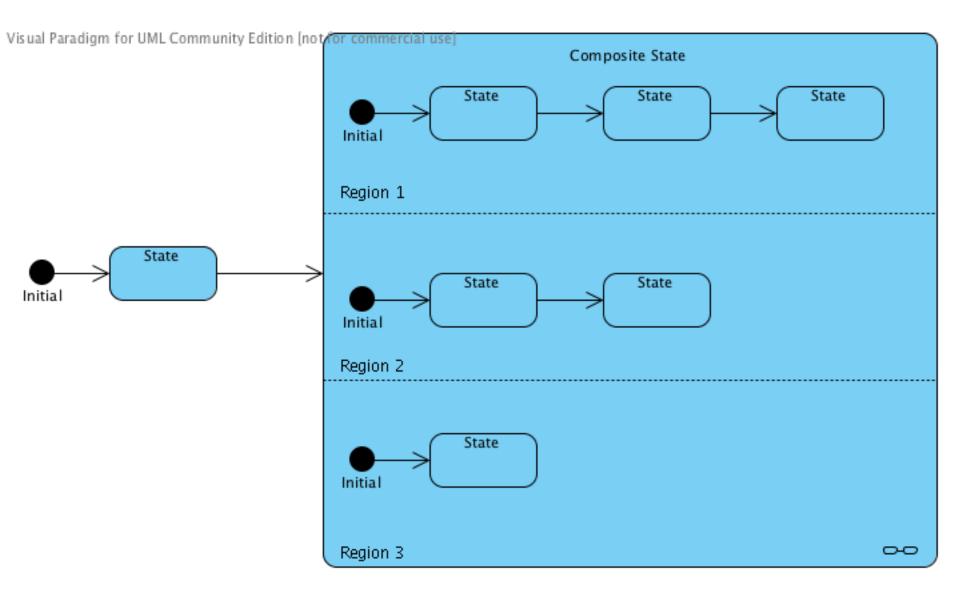
 Christophe Henry's implementation of UML state machines using metaprogramming

```
struct transition_table : mpl::vector<</pre>
      Start Event Next Action Guard
    +----+
 _row < Stopped , open_close , Open</pre>
 _row < Stopped , stop , Stopped // +-----+
 _row < Empty , open_close , Open</pre>
 _row < Empty , cd_detected , Stopped</pre>
 _row < Empty , cd_detected , Playing</pre>
 _row < Playing , stop , Stopped
 _row < Playing , pause , Paused
 _row < Playing , open_close , Open</pre>
    +----
 _row < Paused , end_pause , Playing
 >,
 _row < Paused , open_close , Open
                                        >,
 _row < AllOk , error_found , ErrorMode</pre>
 > {};
```

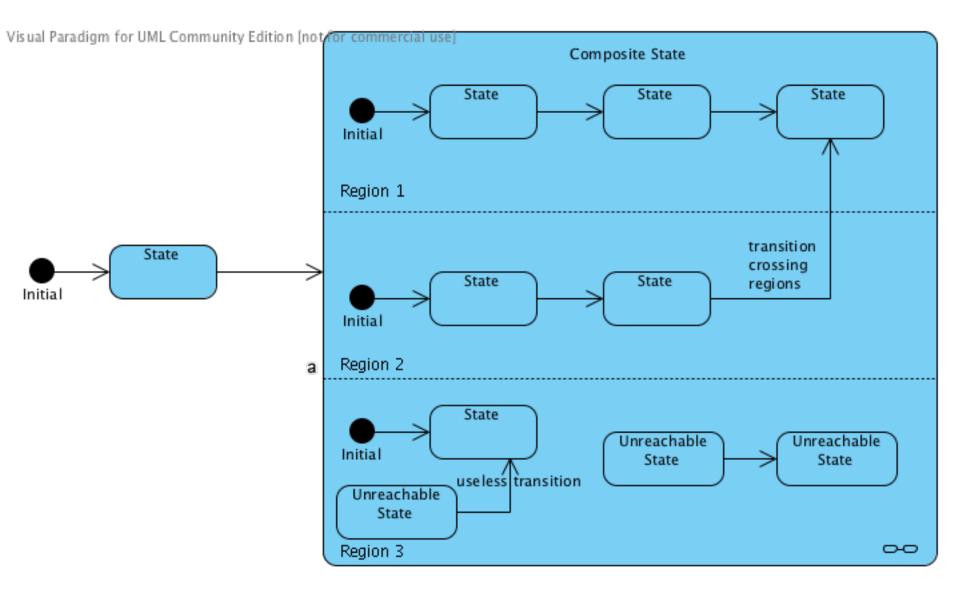
MSM – Orthogonal Regions



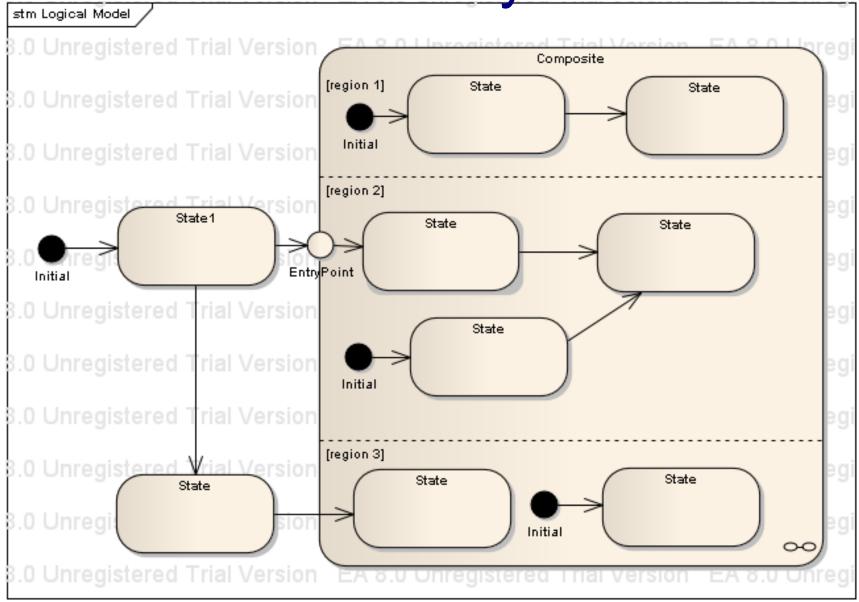
MSM – Orthogonal Regions



MSM – Orthogonality Errors



MSM – Entry Points



MPL.Graph

- Metafunction version of Boost.Graph
- All concepts except MutableGraph
- "Port" from BGL: "s/(/</"
- Lazy concepts: no need to choose implementation

MPL.Graph: BGL-like Concepts

```
// IncidenceGraph
template<typename Edge, typename Graph>
struct source : ...
{}:
template<typename Edge, typename Graph>
struct target : ...
{};
template<typename Vertex, typename Graph>
struct out_edges : ...
{};
template<typename Vertex, typename Graph>
struct out_degree : ...
{};
```

MPL.Graph Algorithms

- Depth First Search
- Breadth First Search
- Algos take visitors

MPL.Graph: depth_first_search

```
template<typename Graph, typename VisitorOps, typename VisitorState,
         typename Vertex,
         typename ColorState = create_search_color_map::type >
struct depth_first_search {
    // enter vertex
    typedef typename VisitorOps::template
        discover_vertex<Vertex, Graph, VisitorState>::type
            discovered_state:
    typedef typename search_color_map_ops::template
        set_color<Vertex, search_colors::Gray, ColorState>::type
            discovered_colors:
    // loop over out edges
    typedef typename
        mpl::fold<typename mpl_graph::out_edges<Vertex, Graph>::type,
                  mpl::pair<discovered_state, discovered_colors>,
                  mpl::if_<boost::is_same<</pre>
        search_color_map_ops::get_color<mpl_graph::target<mpl::_2, Graph>,
                    mpl::second<mpl::_1> >,
        search_colors::White>.
        // unseen target: recurse
          depth_first_search<Graph, VisitorOps,</pre>
               typename VisitorOps::template tree_edge<mpl::_2, Graph,
                     mpl::first<mpl::_1> >,
               mpl_graph::target<mpl::_2, Graph>,
               mpl::second<mpl::_1> >,
```

depth_first_search ctd.

```
// seen: back or forward edge
  mpl::pair<mpl::if_<boost::is_same<</pre>
  typename search_color_map_ops::template
   get_color<mpl_graph::target<mpl::_2, Graph>, mpl::second<mpl::_1 > >,
   search_colors::Gray>,
       typename VisitorOps::template back_edge<mpl::_2, Graph,
mpl::first<mpl::_1> >,
       typename VisitorOps::template forward_or_cross_edge<mpl::_2, Graph,
mpl::first<mpl::_1> > >, // Black
     mpl::second<mpl::_1> > >
    >::type after_outedges;
    // leave vertex, and done!
    typedef mpl::pair<typename VisitorOps::template
        finish_vertex<Vertex, Graph, typename
                 mpl::first<after_outedges>::type >::type,
                      typename search_color_map_ops::template
                        set_color<Vertex, search_colors::Black, typename</pre>
                       mpl::second<after_outedges>::type>::type>
        type;
};
```

Meta Graph Library

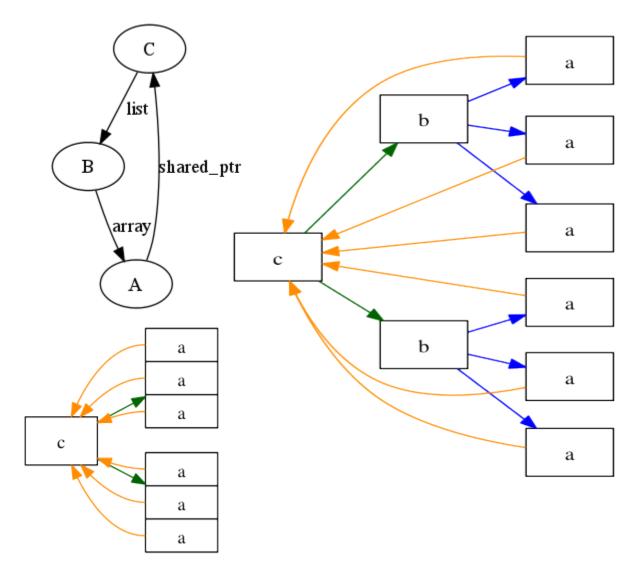
- Franz Alt's graph metaprogramming library
- Iterator-based design
- Better performance
- Strange metaprogramming style
- We will merge the best of both

Objects Pointing at Objects

- "Graphlike" or "graphy"
- Type relations known at compile time
- Any system of objects = heterogeneous graph
- What if we want to generate from metadata?
- Containment = Tree

Objects Pointing at Objects

```
class A;
class B;
class C {
    list<B> b_list;
};
class B {
    array<A,5> a_array;
};
class A {
    shared_ptr<C> c_sp;
};
```



Fusion.Graph

(in progress)

- As with BGL & MPL.Graph:
 - 1. Concepts
 - 2. One general-purpose implementation
 - 3. Algorithms

Fusion.Graph

```
template<typename InputGraph>
struct make fusion graph {
  struct type {
    template<typename VertexTag> struct vertex impl;
    template<typename EdgeTag>
    struct edge impl:
       EdgeTag::template link container<typename vertex impl<typename
               mpl graph::target<EdgeTag,InputGraph>::type>::type> {};
    template<typename VertexTag>
    struct vertex impl {
       struct type {
         typedef typename mpl::transform<typename
               mpl graph::out edges<VertexTag,InputGraph>::type,
                            fusion::pair<mpl:: 1,
                                    edge_impl<mpl::_1>>
                            >::type tag_n_impl_sequence;
         typedef typename mpl::joint_view<tag_n_impl_sequence,typename
               VertexTag::data type>::type all vertex data;
         typedef typename boost::fusion::result_of::as_map<all_vertex_data>::type
                     data type;
         data type data:
    }; }; };
```

MPL.Graph Status

- Performance: measure, improve
- More Algorithms
 - Topological Sort
 - Connected Components
 - Dijkstra's Shortest Paths?
- Another Application or Two
- Review

msm/mpl_graph dynagraph.org/mpl_graph/

Questions? Comments?

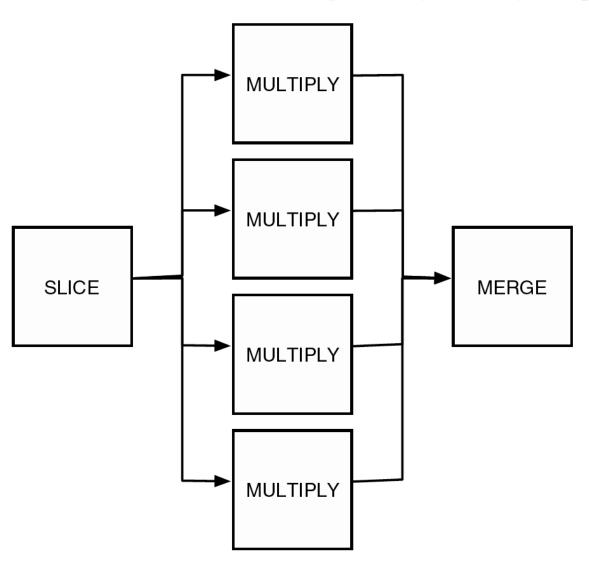
And onward!

WARNING: Everything after this point in the presentation is speculative. I think it's all possible! I'm working on some things & hoping others will work on other parts.

Quaff

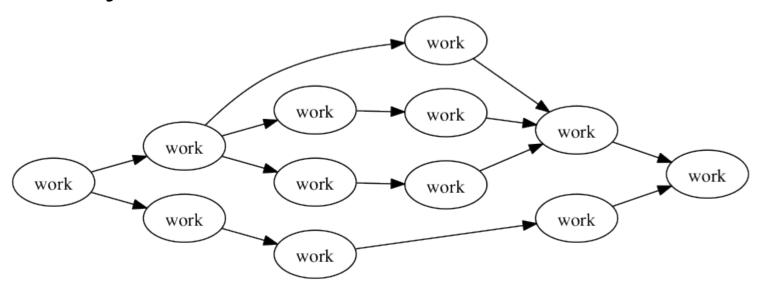
// Skeleton definition

typedef scm<slice, worker< repeat<4,mul>>, merge> app;



Quaff

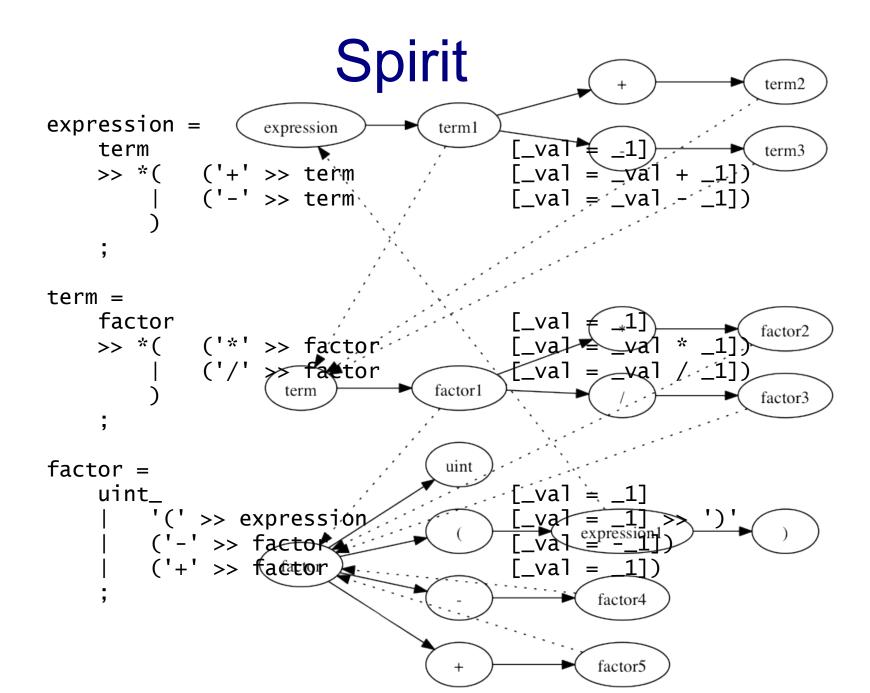
Go beyond Series-Parallel?

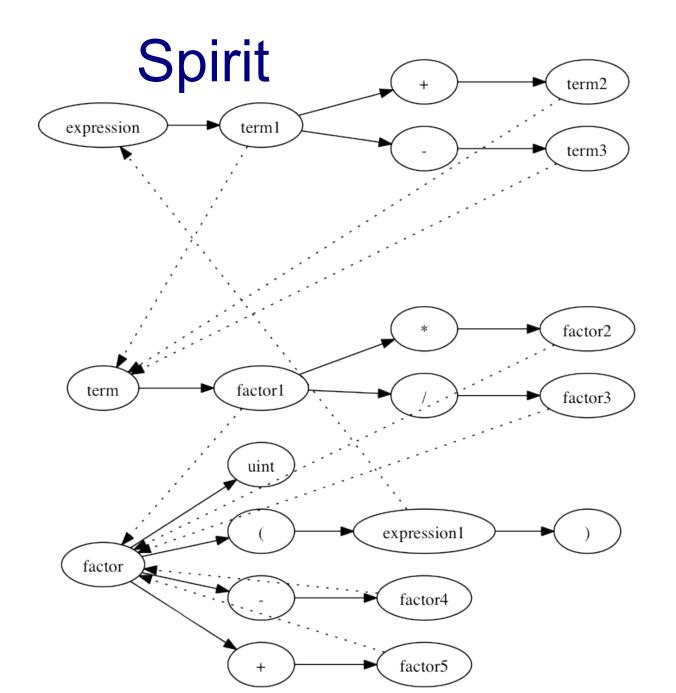


Also: optimize scheduling?

Spirit

```
expression =
                                            [\_val = \_1]
    term
    >> *( ('+' >> term
                                           [\_val = \_val + \_1])
     | ('-' >> term
                                           [\_val = \_val - \_1])
term =
    factor
                                            [\_val = \_1]
    >> *( ('*' >> factor | ('/' >> factor )
                                           [\_val = \_val * \_1])
                                     [\_val = \_val / \_1])
factor =
                                             [\_val = \_1]
    uint_
    | '(' >> expression
| ('-' >> factor
| ('+' >> factor
                                            [_va] = _1] >> ')'
                                            [\_val = -\_1]
                                            \lceil val = 1 \rceil
```





Spirit

- Analyze grammars?
- Abstract Syntax Tree nodes are generated from (simplified) grammar graph
- Thus nodes are a Fusion Graph already, without Fusion.Graph

An EDSL for Graphs

- Base it on GraphViz dot syntax
- For CT graph, need unique terminal types
 Something like:

$$g = (a >= b [_attr = value],$$

 $b >= c >= d);$

 General problem: turn expression tree into graph by finding common references

Call Graphs

- Can generate more complex types forward
- Branches represented as.. branches
- Configuration

Schemas

- XML
- DB
- C++?

Memory Management

- Once again, type graph describes object graph
- Find cycles in reference-counted pointers automatically
- Or something more sophisticated?

History

- 1997-2003 AT&T Dynagraph LGraph
- 2006 Johns Hopkins Dyna
- 2007 1st BoostCon
- 2008 Started Metagraph library
- 2009 MSM and Quaff @ BoostCon
- 2010 Split MPL.Graph and put in MSM

The Metagraph

- Graphs of graphs, graphs at levels of detail, nested graphs, subgraphs, n-dimensional graphs
- Build on Fusion.Graph
- Overlaid patterns refine/restrict
- Intrusive data structures multi-belonging