

# Survey of Multi-Threaded Programming Support in C++11 and Boost

C++ Now 2013

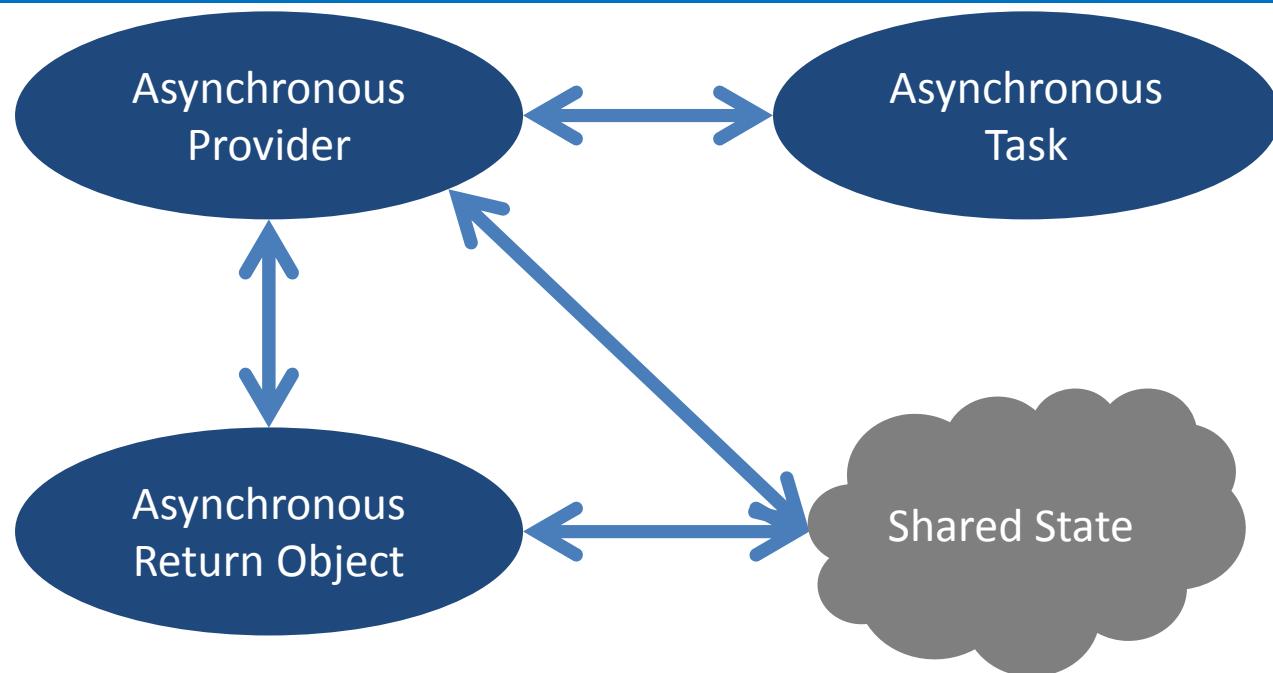
Rob Stewart

# Overview

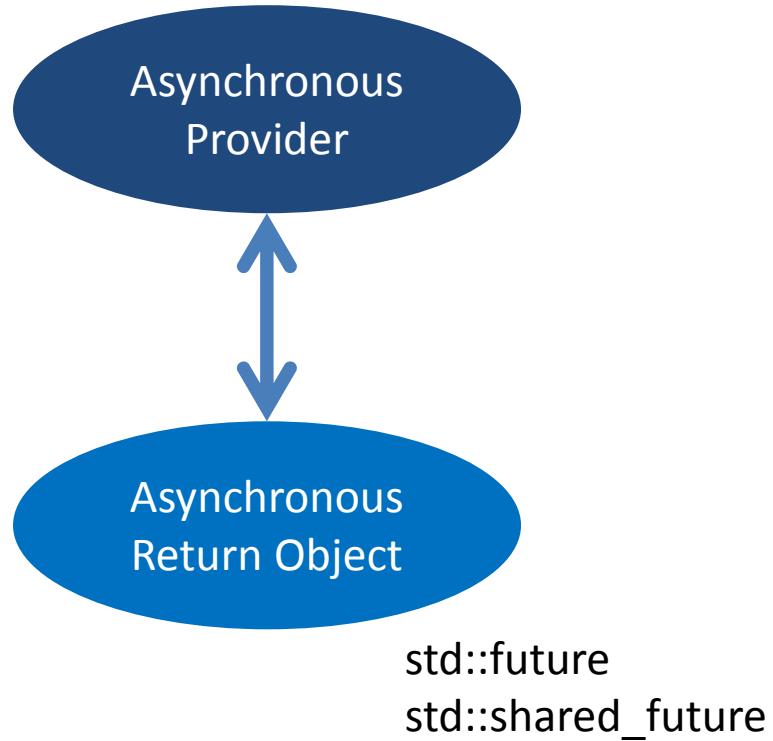
- Asynchronous computations
- Threads
- Synchronization primitives

# Asynchronous Computations

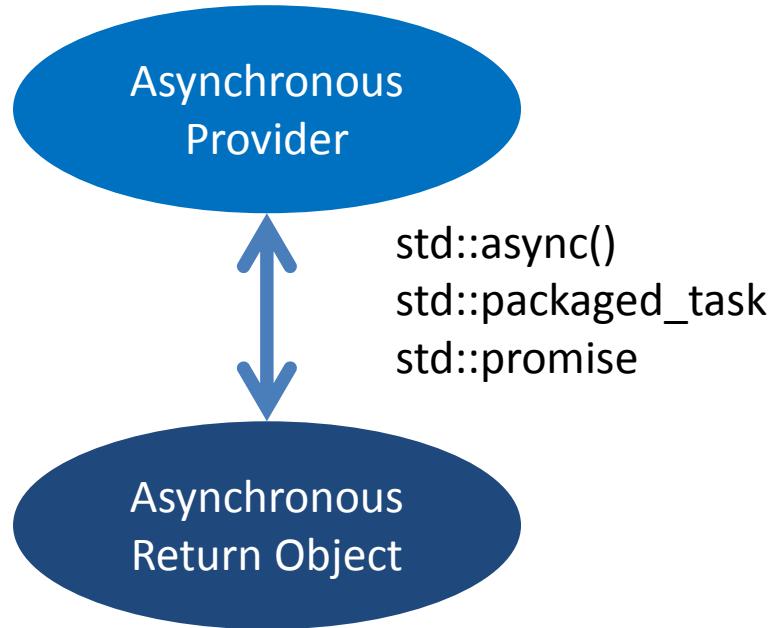
# Asynchronous Computations



# Asynchronous Return Objects

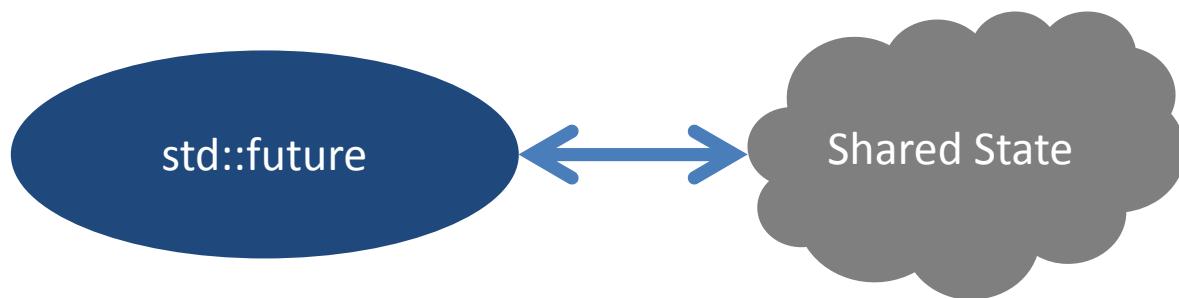


# Asynchronous Providers



# Asynchronous Return Objects

# std::future



# std::future

- Gets result from asynchronous task
  - Can block until result ready
  - Can wait a limited time for result
- One-to-one association with
  - Asynchronous provider
  - Shared state
- Once retrieve value, no longer available

# std::future Synopsis

```
// #include <future>

template <class T>
struct std::future
{
    future();
    future(future const &) = delete;
    future & operator =(future const &) = delete;
    future(future &&);
    future & operator =(future &&);
    ...
}
```

# std::future Synopsis

```
...
T get();      // std::future<T>
T & get();    // std::future<T &>
void get();  // std::future<void>

bool valid() const;

std::shared_future<T> share();
...
```

# std::future Synopsis (cont.)

```
...
void wait() const;

template <class Repr, class Period>
std::future_status wait_for(
    std::chrono::duration<Repr,Period> const &) const;

template <class Clock, class Duration>
std::future_status wait_until(
    std::chrono::time_point<Clock,Duration> const &) const;
};
```

# std::future\_status

```
enum class std::future_status
{
    deferred, ready, timeout
};
```

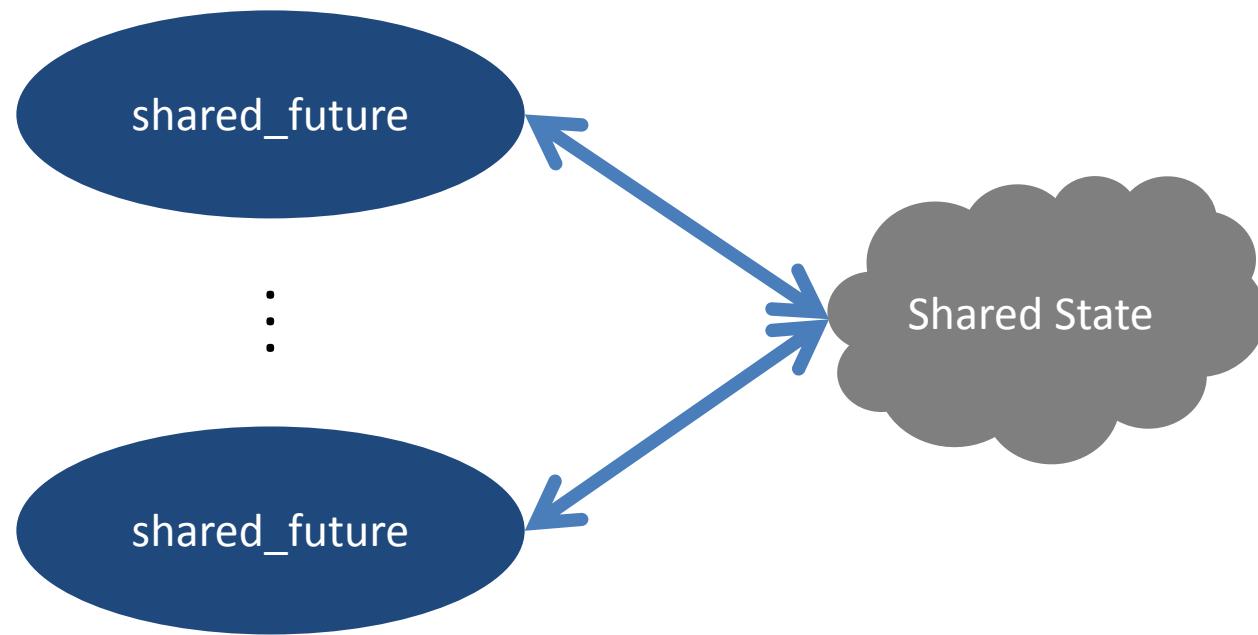
- **deferred**: Callable not yet invoked
- **ready**: Result ready
- **timeout**: Timeout exceeded before result ready

# boost::future

- `then()` member template invokes callable when shared state ready
- `get_state()` reports shared state's status
  - Uninitialized
  - Waiting
  - Ready
  - Moved
- Swappable

# std::shared\_future

# std::shared\_future



# std::shared\_future Differences

- Copyable: Copies retrieve same value
- Can retrieve value repeatedly
- Access to shared state is synchronized
- Members not synchronized (give copy to each thread)

# std::shared\_future Synopsis

```
// #include <future>

template <class T>
struct std::shared_future
{
    shared_future();
    shared_future(future<T> &&);
    shared_future & operator =(future<T> &&);

    shared_future(shared_future const &);
    shared_future & operator =(shared_future const &);

    shared_future(shared_future &&);
    shared_future & operator =(shared_future &&);

    ...
}
```

# std::shared\_future Synopsis (cont.)

```
...
// as for std::future:
get;
valid;
wait;
wait_for;
wait_until;

bool is_ready() const;
bool has_exception() const;
bool has_value() const;

void swap(shared_future &);
};
```

# `boost::shared_future`

- `get_state()` reports shared state's status
  - Uninitialized
  - Waiting
  - Ready
  - Moved

# Asynchronous Providers

# std::async()

# `std::async()`

- Runs asynchronous task
  - “Immediately,” in separate thread
  - On demand, in calling thread
- Returns result some time in future
- Simplified usage versus `std::thread`

# Using std::async()

```
#include <future>

int f(double);

int main()
{
    std::future<int> retval(std::async(f, 1.0));
    // do other things
    return retval.get();
}
```

# std::async() Callable

- Function pointer
- Lambda
- Member function pointer
  - Object pointer passed as argument to std::async()
- (Move-only) function object

# std::async() Synopsis

```
// #include <future>

template <class F, class... Args>
std::future<class std::result_of<F(Args...)>::type>
std::async(std::launch, F &&, Args &&...);

template<class F, class... Args>
std::future<class std::result_of<F(Args...)>::type>
std::async(F &&, Args &&...);
```

# std::async() Launch Policy

```
enum class std::launch
```

```
{
```

```
    async, deferred, sync=deferred, any=async|deferred
```

```
};
```

- **async**: Spawn new thread to run callable
- **deferred**: Invoke by thread asking for result
- **any**: Implementation defined

# Surprising std::async() Side Effect

```
#include <chrono>
#include <future>
#include <iostream>
using namespace std::chrono;

int main()
{
    auto const start(std::chrono::system_clock::now());
    std::async(std::launch::async, []
    {
        std::this_thread::sleep_for(std::chrono::hours(1));
    });
    auto const elapsed(duration_cast<minutes>(
        system_clock::now() - start));
    std::cout << elapsed.count() << std::endl;
}
```

# Unsurprising Equivalent

```
int main()
{
    auto const start(std::chrono::system_clock::now());
    {
        std::future<void> retval(std::async(std::launch::async, []
        {
            std::this_thread::sleep_for(std::chrono::hours(1));
        }));
        retval.get();
    }
    auto const elapsed(duration_cast<minutes>(
        system_clock::now() - start));
    std::cout << elapsed.count() << std::endl;
}
```

# boost::async() Synopsis

```
// #include <boost/thread/future.hpp>

template <class F>
boost::future<class boost::result_of<class boost::decay<F>::type()>::type>
boost::async(boost::launch, F &&);

template<class F>
boost::future<class boost::result_of<class boost::decay<F>::type()>::type>
boost::async(F &&);
```

# Variadic boost::async()

- For C++11 platform with
  - Variadic templates
  - rvalue references
  - decltype
  - <tuple>
- BOOST\_THREAD\_PROVIDES\_SIGNATURE\_PACKAGED\_TASK defined

# std::packaged\_task

# `std::packaged_task`

- Packages a callable for asynchronous invocation
  - `std::thread` thread procedure
  - Function argument
  - Direct invocation
  - Store in container for later use
- Get future before invocation

# std::packaged\_task Usage

```
#include <future>

int f(double);

int main()
{
    std::packaged_task<int(double)> task(f);
    std::future<int> retval(task.get_future());
    // 1. hand off task to another thread
    // 2. do things in current thread
    return retval.get();
}
```

# std::packaged\_task Synopsis

```
// #include <future>

template <class T> struct std::packaged_task; // undefined

template <class ResultType, class... ArgTypes>
struct std::packaged_task<ResultType(ArgTypes...)>
{
    packaged_task();

    packaged_task(packaged_task const &) = delete;
    packaged_task & operator =(packaged_task const &) = delete;

    packaged_task(packaged_task &&);
    packaged_task & operator =(packaged_task &&);

    ...
}
```

# std::packaged\_task Synopsis

...

```
template <class F>
explicit packaged_task(F);
```

```
template <class F, class Alloc>
packaged_task(std::allocator_arg_t, Alloc const &, F);
```

```
template <class R, class... Args>
packaged_task(R (*)(Args...));
```

```
void swap(packaged_task &);
```

...

# `std::packaged_task` Synopsis

```
...
explicit operator bool() const;

std::future<result_type> get_future();

void operator ()(ArgTypes...);

void make_ready_at_thread_exit(ArgTypes...);

void reset();
};
```

# `boost::packaged_task`

- Exact match function pointer constructor
- `valid()` equivalent to explicit `bool` conversion operator
- Can add callback to invoke if an associated future waits for the asynchronous result

# std::promise

# std::promise

- Vends a std::future (asynchronous provider)
- Not unlike std::packaged\_task:
  - Get future first
  - Use promise to set value or exception
- Low level provider

# std::promise Synopsis

```
// #include <future>

template <class T>
struct std::promise
{
    promise();
    ~promise();

    promise(promise const &) = delete;
    promise & operator =(promise const &) = delete;

    promise(promise &&);
    promise & operator =(promise &&);

    ...
}
```

# std::promise Synopsis (cont.)

```
...
template <class Alloc>
promise(std::allocator_arg_t, Alloc const &);

void swap(promise &);

...
```

# std::promise Synopsis (cont.)

```
...
std::future<T> get_future();

void set_value(T const &); // promise<T>
void set_value(T &&);    // promise<T>
void set_value(T &);      // promise<T &>
void set_value();          // promise<void>

void set_value_at_thread_exit(T const &);      // promise<T>
void set_value_at_thread_exit(T &&);           // promise<T>
void set_value_at_thread_exit(T &);             // promise<T &>
void set_value_at_thread_exit();                // promise<void>

};
```

# std::promise Synopsis (cont.)

```
...
void set_exception(T const &);      // promise<T>
void set_exception(T &&);          // promise<T>
void set_exception(T &);           // promise<T &>
void set_exception();              // promise<void>

void set_exception_at_thread_exit(T const &);    // promise<T>
void set_exception_at_thread_exit(T &&);        // promise<T>
void set_exception_at_thread_exit(T &);          // promise<T &>
void set_exception_at_thread_exit();              // promise<void>
};

}
```

# boost::promise

- Can add callback to invoke if an associated future waits for the asynchronous result

# Threads

# std::thread

- General way to run asynchronous task
  - Represents a thread of execution (except when default constructed)
  - Assembly language of threading
- Has unique ID
- Can be joined
- Can be detached
- Exposes native handle

# std::thread Synopsis

```
// #include <thread>

struct std::thread
{
    thread();
    ~thread();

    thread(thread const &) = delete;
    thread & operator =(thread const &) = delete;

    thread(thread &&);
    thread & operator =(thread &&);

    ...
}
```

# std::thread Synopsis

...

```
template<class F>
explicit thread(F);
```

```
template<class F, class Args...>
thread(F, Args...);
```

```
void swap(thread &);
```

...

# std::thread Synopsis (cont.)

```
...
id get_id() const;

bool joinable() const;

void join();

void detach();

native_handle_type native_handle();

static unsigned hardware_concurrency();
};
```

# std::thread Semantics

- Constructor with extra parameters works like std::bind
  - Arguments copied to internal storage
  - Arguments not converted to parameter type
  - Can create dangling references
  - Can use std::cref() and std::ref()
- Destructor calls std::terminate() if joinable()
- Like main(), unhandled exceptions trigger std::terminate()

# boost::thread

- Interruptible
  - Effected by boost::thread\_interrupted exceptions
  - Only triggered at *interruption points*
- Supports thread attributes
- Adds time-limited joins
- Destructor behavior controlled by  
BOOST\_THREAD\_PROVIDES\_THREAD\_DESTRUCTOR\_CALLS\_TERMINATE\_IF\_JOINABLE
  - Defined: calls std::terminate() if joinable
  - Undefined: calls detach()

# Namespace std::this\_thread

# Namespace std::this\_thread

## Synopsis

```
namespace std::this_thread
{
    thread::id get_id();

    void yield();

    template<class Repr, class Period>
    void sleep_for(std::chrono::duration<Repr, Period> const &);

    template<class Clock, class Duration>
    void sleep_until(std::chrono::time_point<Clock, Duration> const &);
}
```

# Namespace boost::this\_thread

## Synopsis

```
namespace boost::this_thread
{
    // as for std::this_thread

    void interruption_point();
    bool interruption_requested() noexcept;
    bool interruption_enabled() noexcept;

    class disable_interruption;
    class restore_interruption;
}
```

# Tying It Together: Implementing `async()`

# Implementing async()

```
template <class F, class ...Args>
std::future<typename std::result_of<F(Args...)>::type>
async(F _f, Args... _args)
{
    std::promise<std::result_of<F(Args...)>::type> promise;
    auto future(promise.get_future());
    std::thread thread(/*next slide*/);
    thread.detach();
    return std::move(future);
}
```

# Implementing async() (cont.)

```
...
std::promise<std::result_of<F(Args...)>::type> promise;
auto future(promise.get_future());
std::thread thread(
    [] (std::promise<return_type> && _promise,
        F _f, Arg &&... _args)
{
    // next slide
}, std::move(promise), _f, std::forward<Args>(_args)...);
thread.detach();
...
...
```

# Implementing async() (cont.)

```
...
std::thread thread(
    [] (std::promise<return_type> && _promise,
        F _f, Arg &&... _args)
{
    try
    {
        _promise.set_value(_f(std::forward<Args>(_args)...));
    }
    catch (...)
    {
        _promise.set_exception(std::current_exception());
    }
}, std::move(promise), _f, std::forward<Args>(_args)...);
...
...
```

# Synchronization Primitives

# Synchronization Primitives

- Lock concepts
- Mutexes
- Guards
- Condition Variables
- One-time Invocation

# Lock Concepts

# Lockable

```
struct Lockable
{
    void lock();
    bool try_lock();
    void unlock();
};
```

# TimedLockable

```
struct TimedLockable
{
    // as for Lockable

    template <class Repr,class Period>
    bool try_lock_for(std::chrono::duration<Repr,Period> const &);

    template <class Clock,class Duration>
    bool try_lock_until(
        std::chrono::time_point<Clock,Duration> const &);

};
```

# Mutexes

# Lockable Mutexes

- `std::mutex`: Unique lock ownership
- `std::recursive_mutex`
  - `lock()` and `try_lock()`
    - First call acquires mutex
    - Increment lock count
  - `unlock()`
    - Decrement lock count
    - Releases mutex when count is zero

# TimedLockable Mutexes

- `std::timed_mutex`: Unique lock ownership
- `std::recursive_timed_mutex`
  - `lock()` and `try_lock()`
    - First call acquires mutex
    - Increment lock count
  - `unlock()`
    - Decrement lock count
    - Releases mutex when count is zero

# Mutex Semantics

- DefaultConstructable
- **Not** CopyConstructable or CopyAssignable
- **Not** MoveConstructable or MoveAssignable
- **Not** Swappable

# Guards

# std::lock\_guard

# std::lock\_guard Semantics

- RAII class template
- Constructor locks or adopts Lockable
- Destructor unlocks Lockable

# std::lock\_guard Synopsis

```
// #include <mutex>

template <class M>
struct std::lock_guard
{
    typedef M mutex_type;

    lock_guard(lock_guard const &) = delete;
    lock_guard & operator =(lock_guard const &) = delete;

    explicit lock_guard(mutex_type &);

    lock_guard(mutex_type &, adopt_lock_t);

    ~lock_guard();

};
```

# `boost::lock_guard`

- No differences

# std::unique\_lock

# `std::unique_lock`

- RAII lock guard
- TimedLockable
- Flexible construction
  - Lock Lockable
  - Try to lock Lockable
  - Assume Lockable is locked
- Destructor unlocks if locked

# std::unique\_lock Synopsis

```
// #include <mutex>

template <class M>
struct std::unique_lock
{
    typedef M mutex_type;

    unique_lock(unique_lock const &) = delete;
    unique_lock & operator =(unique_lock const &) = delete;

    unique_lock(unique_lock &&);
    unique_lock & operator =(unique_lock &&);

    ~unique_lock();
    ...
}
```

# std::unique\_lock Synopsis

...

```
explicit unique_lock(mutex_type &);  
unique_lock(mutex_type &, adopt_lock_t);  
unique_lock(mutex_type &, defer_lock_t);  
unique_lock(mutex_type &, try_to_lock_t);
```

```
template<typename Repr,typename Period>  
unique_lock(mutex_type &,  
           std::chrono::duration<Repr,Period> const &);
```

```
template<typename Clock,typename Duration>  
unique_lock(mutex_type &,  
           std::chrono::time_point<Clock,Duration> const &);
```

...

# std::unique\_lock Synopsis (cont.)

```
...
// Lockable
void lock();
bool try_lock();
void unlock();

// TimedLockable
template<typename Repr, typename Period>
bool try_lock_for(std::chrono::duration<Repr,Period> const &);

template<typename Clock, typename Duration>
bool try_lock_until(
    std::chrono::time_point<Clock,Duration> const &);
...
```

# std::unique\_lock Synopsis (cont.)

```
...
explicit operator bool() const;
bool owns_lock() const;

Mutex * release();

Mutex * mutex() const;
};
```

# `boost::unique_lock`

- No differences

# Locking Function Templates

# Locking Function Motivation

- Locks must be locked in the same sequence to avoid deadlocks
- If using `try_lock()`, must unlock acquired locks, if one fails
- Must account for exceptions

# Locking Functions Synopses

```
// #include <mutex>
```

```
template <class class Lockable1, class... Lockables>
void std::lock(Lockable1 &, Lockables &...);
```

```
template <class class Lockable1, class... Lockables>
int std::try_lock(Lockable1 &, Lockables &...);
```

# Boost Locking Functions

- Limited to five locks
- Iterator-based overloads

# `std::condition_variable`

# std::condition\_variable

- Used to notify threads of state changes
- Changer
  - Acquire mutex
  - Change state
  - Notify one or all waiting threads
- Waiter
  - Acquire mutex
  - Wait on condition variable
  - Examine state

# std::condition\_variable Synopsis

```
// #include <condition_variable>

struct std::condition_variable
{
    condition_variable();

    condition_variable(condition_variable const &) = delete;
    condition_variable & operator =(condition_variable const &) = delete;

    ...
}
```

# std::condition\_variable Synopsis

...

**void notify\_one();**

**void notify\_all();**

**void wait(std::unique\_lock<std::mutex> &);**

**template <class Pred>**

**void wait(std::unique\_lock<std::mutex> &, Pred);**

...

# std::condition\_variable Synopsis (cont.)

```
...
template <class Repr, class Period>
cv_status wait_for(std::unique_lock<std::mutex> &,
                   std::chrono::duration<Repr,Period> const &);

template <class Repr, class Period, class Pred>
bool wait_for(std::unique_lock<std::mutex> &,
              std::chrono::duration<Repr,Period> const &, Pred);
...
...
```

# std::cv\_status

```
enum class std::cv_status
{
    no_timeout, timeout
};
```

- **timeout**: Timeout exceeded before result ready
- **no\_timeout**
  - Result ready before timeout
  - Spuriously awakened

# std::condition\_variable Synopsis (cont.)

```
...
template <class Clock, class Duration>
cv_status wait_until(std::unique_lock<std::mutex> &,
                     std::chrono::time_point<Clock, Duration> const &);

template <class Clock, class Duration, class Pred>
bool wait_until(std::unique_lock<std::mutex> &,
                std::chrono::time_point<Clock, Duration> const &, Pred);
};
```

# `boost::condition_variable`

- No differences

# `std::condition_variable_any`

# `std::condition_variable_any`

- Like `std::condition_variable` except...
- All wait functions use arbitrary `Lockable` type

# std::condition\_variable\_any

## Synopsis

```
// #include <condition_variable>

struct std::condition_variable_any
{
    // as for std::condition_variable

    template <class Lockable>
    void wait(Lockable &);

    template <class Lockable, class Pred>
    void wait(Lockable &, Pred);

    ...
}
```

# std::condition\_variable\_any

## Synopsis (cont.)

```
...
template <class Lockable, class Repr, class Period>
cv_status wait_for(Lockable &,
                   std::chrono::duration<Repr,Period> const &);

template <class Lockable, class Repr, class Period, class Pred>
bool wait_for(Lockable &,
              std::chrono::duration<Repr,Period> const &, Pred);
...
...
```

# std::condition\_variable\_any

## Synopsis (cont.)

```
...
template <class Lockable, class Clock, class Duration>
cv_status wait_until(Lockable &,
                     std::chrono::time_point<Clock,Duration> const &);

template <class Lockable, class Clock, class Duration, class Pred>
bool wait_until(Lockable &,
                std::chrono::time_point<Clock,Duration> const &, Pred);
};
```

# `boost::condition_variable_any`

- No differences

# Why std::condition\_variable and std::condition\_variable\_any?

- std::condition\_variable
  - Uses std::unique\_lock<std::mutex> only
  - Allows for optimizations not otherwise possible
- std::condition\_variable\_any
  - Uses an arbitrary Lockable
  - Can be less efficient
  - Typically implemented in terms of the former

# One-time Invocation

# One-time Invocation

- Invoke callable exactly once
  - One-time initialization
  - No races
  - No deadlocks
- Strong exception guarantee
  - Callable's exceptions propagated
  - Call considered not done if exception

# One-time Invocation Usage

```
#include <mutex>

std::once_flag one_time;

void f(int, char const *);

int main()
{
    std::call_once(one_time, f, 12, "Test");
}
```

# std::call\_once

```
// #include <mutex>

template<class F, class... Args>
void std::call_once(std::once_flag &, F, Args...);
```

# Boost One-time Invocation

- `boost::once_flag` requires static initialization from `BOOST_ONCE_INIT`
- `boost::call_once()` only accepts zero-argument callables

# Summary

- Asynchronous computations
- Threads
- Synchronization primitives

# Questions?

# Resources

- <http://www.boost.org/libs/thread/index.html>
- <http://www.stdthread.co.uk/doc/>
- <http://en.cppreference.com/w/cpp/thread>
- *C++ Concurrency in Action: Practical Multithreading* (Williams)