

ETROC1 TDC Test Block Design Note

This document aims to provide information for ETROC1 TDC Test Block chip test.

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1 ETROC1 TDC Test Block chip overview

ETROC1 is the second prototype of ETROCn (Endcap Timing Readout Chip) that is being developed for the LGAD-based CMS Endcap Timing Layer (ETL) or HL-LHC. The ETROC1 TDC Test Block chip a crucial important test module for testing the function and specification of the Time-to-Digital (TDC). It is developed with TSMC 65 nm CMOS process with 1p9m-3x1u1z. All the building block have metal layers up to M7. The M8 and M9 metal layers are reserved for power supply ring.

The ETROC1 TDC Test Block chip is used to measure the leading edge arriving time (TOA) and time over threshold (TOT) of a pulse that was generated by analog front-end circuit. Each input pulse will be convert to three digital time, TOA digital time (10 bit), TOT digital time (9 bit), and Calibration digital time (10 bit), respectively. The Calibration digital time can be converted from 320 MHz input clock.

The ETROC1 TDC Test Block chip aims to provide a chance to test some important specification and characteristic of the design TDC. The tape-out date is in late August, 2019, and turnaround is 9 weeks. Figure 1 illustrates the function diagram of the ETROC1 TDC Test Block chip. The die size of the ETROC1 TDC Test Block chip is about 0.7 mm x 1.9 mm (including seal ring). It has 26 pads in total while the opening area of each pad is about 65 um x 130 um.

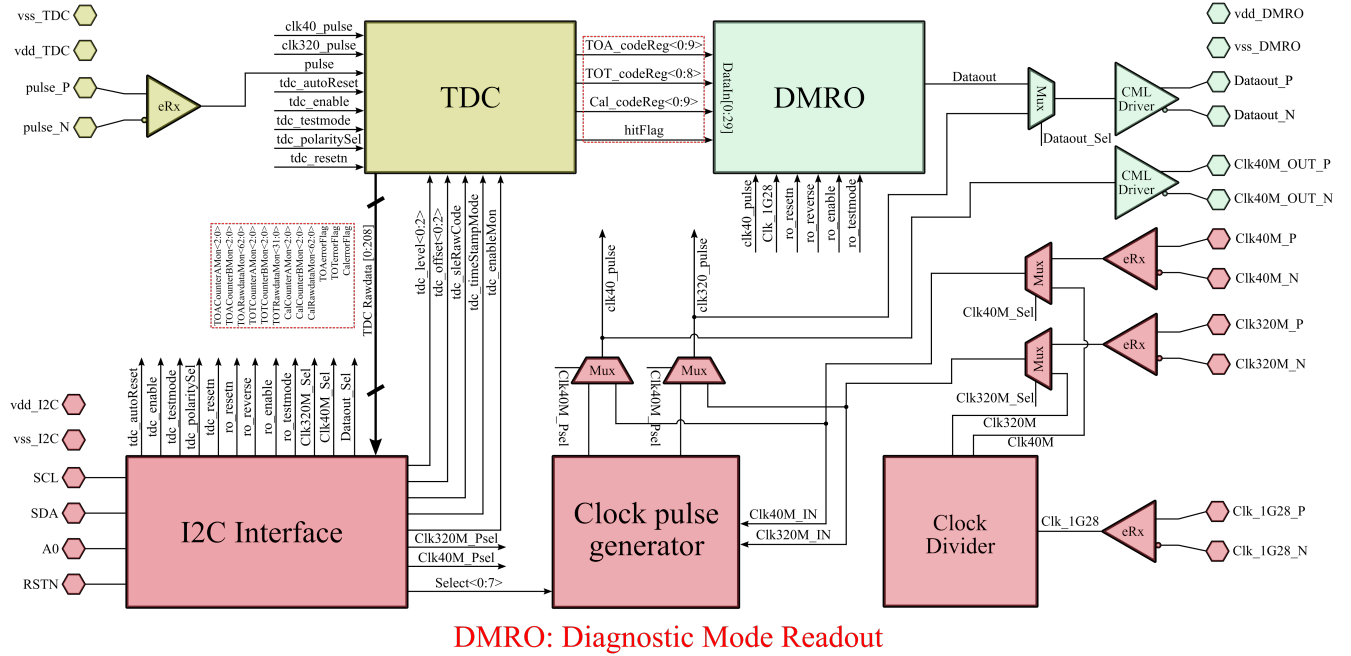


Figure 1: ETROC1 TDC Test Block chip function diagram

The ETROC1 TDC Test Block chip mainly includes 5 modules, Time-to-Digital (TDC), Diagnostic Mode Readout (DMRO), I2C Interface, Clock Pulse Generator, Clock Divider and GRO (Gate Ring Oscillator). The same color modules share a pair of power supply as shown in the Figure 1. The supply voltage of each power supply is 1.2 V.

The layout of ETROC1 TDC Test Block chip is shown as Figure 2. The Dataout_N pad is named as the pin 1, from the anti-clockwise direction, the pad number is increasing with the step 1, and the last pad GRO_Out_N is numbered as 26. The ETROC1 TDC Test Block is located at the upper right corner. The safe distance between pads and edge of ETROC1 chip is 60 um. There are four sets of power supply ring from left to right on the layout. GRO power ring, I2C power supply ring, TDC power supply ring and DMRO power supply ring, respectively.

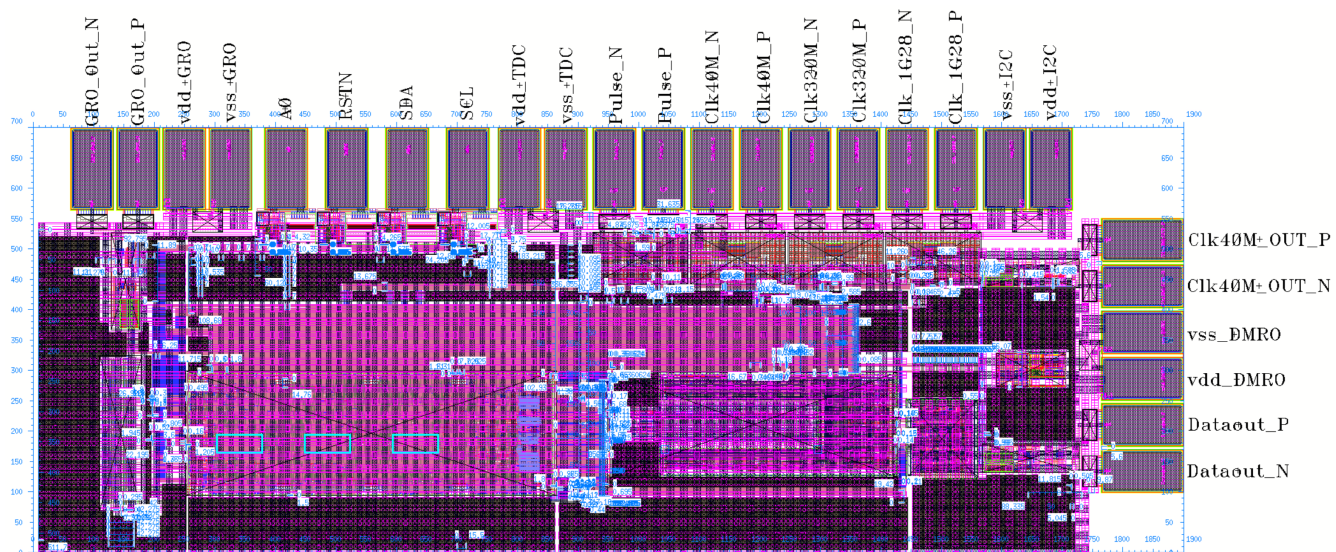


Figure 2: ETROC1 TDC Test Block chip layout

2 Pin Assignment

The ETROC1 TDC Test Block chip has 26 pads that can be divided into three types: general IO pads, differential IO pads, and power IO pads, respectively. The 26 pads are located on adjacent two sides of the square chip. The below table listed the detail pad information of the ETROC1 TDC Test Block chip.

Table 1: ETROC1 TDC Test Block Chip pads information

| NO. | Name | Location (x,y) | Type | Description |
|-----|--------------|---------------------|----------------|---|
| 1 | Dataout_N | (977.615, 1214.71) | Digital Out | 1.28G high speed serial data negative output |
| 2 | Dataout_P | (1058.195, 1214.71) | Digital Out | 1.28G high speed serial data positive output |
| 3 | DMRO_VDD | (897.035, 1214.71) | Power supply | Power supply for DMRO module, 1.2V |
| 4 | DMRO_VSS | (820.855, 1214.71) | Ground | Ground for DMRO module |
| 5 | Clk40M_OUT_N | (659.695, 1214.71) | Digital Out | 40M clock negative output |
| 6 | Clk40M_OUT_P | (740.275, 1214.71) | Digital Out | 40M clock positive output |
| 7 | I2C_VDD | (85.29, 549.965) | Power supply | Power supply for I2C module and Clock modules, 1.2V |
| 8 | I2C_VSS | (85.29, 473.785) | Ground | Ground for I2C module and Clock modules |
| 9 | Clk_1G28_P | (85.29, 730.58) | Digital In | 1.28G clock positive input |
| 10 | Clk_1G28_N | (85.29, 650) | Digital In | 1.28G clock negative input |
| 11 | Clk320M_P | (85.29, 891.74) | Digital In | 320M clock positive input |
| 12 | Clk320M_N | (85.29, 811.16) | Digital In | 320M clock negative input |
| 13 | Clk40M_P | (85.29, 1052.9) | Digital In | 40M clock positive input |
| 14 | Clk40M_N | (85.29, 972.32) | Digital In | 40M clock negative input |
| 15 | Pulse_P | (422.355, 1214.71) | Analog In | Pulse positive input |
| 16 | Pulse_N | (341.775, 1214.71) | Analog In | Pulse negative input |
| 17 | TDC_VDD | (579.115, 1214.71) | Power supply | Power supply for TDC module, 1.2V |
| 18 | TDC_VSS | (502.935, 1214.71) | Ground | Ground for TDC module |
| 19 | SCL | (85.29, 373.82) | Digital In | I2C module serial clock |
| 20 | SDA | (85.29, 273.855) | Digital In/Out | I2C module serial data |
| 21 | RSTN | (85.29, 173.885) | Digital In | I2C module reset, low active |
| 22 | A0 | (241.81, 1214.71) | Digital In | I2C module external address select |
| 23 | GRO_VDD | (579.115, 1214.71) | Power supply | Power supply for GRO module, 1.2V |
| 24 | GRO_VSS | (502.935, 1214.71) | Ground | Ground for GRO module |
| 25 | GRO_Out_P | (422.355, 1214.71) | Digital Out | GRO output |
| 26 | GRO_Out_N | (341.775, 1214.71) | Digital Out | GRO output |

3 Time-to-Digital (TDC)

3.1 TDC overview

Time-to-digital converter (TDC) converts the time interval to the digital output. The TDC takes as input the discriminator output and records the time of arriving (TOA) and time over threshold (TOT) for a fixed discriminator threshold. The TOA and TOT TDC bin size should not exceed 30 ps and 100 ps, respectively. To allow improvements in particle identification in heavy ion collision events, the TDC measurement time window is extended to 12.5 ns.

The ETROC1 TDC consists of three parts: TDC Controller, TDC Delay Line, and TDC Encoder. Figure 2 shows the block diagram of TDC module and interconnection of each part.

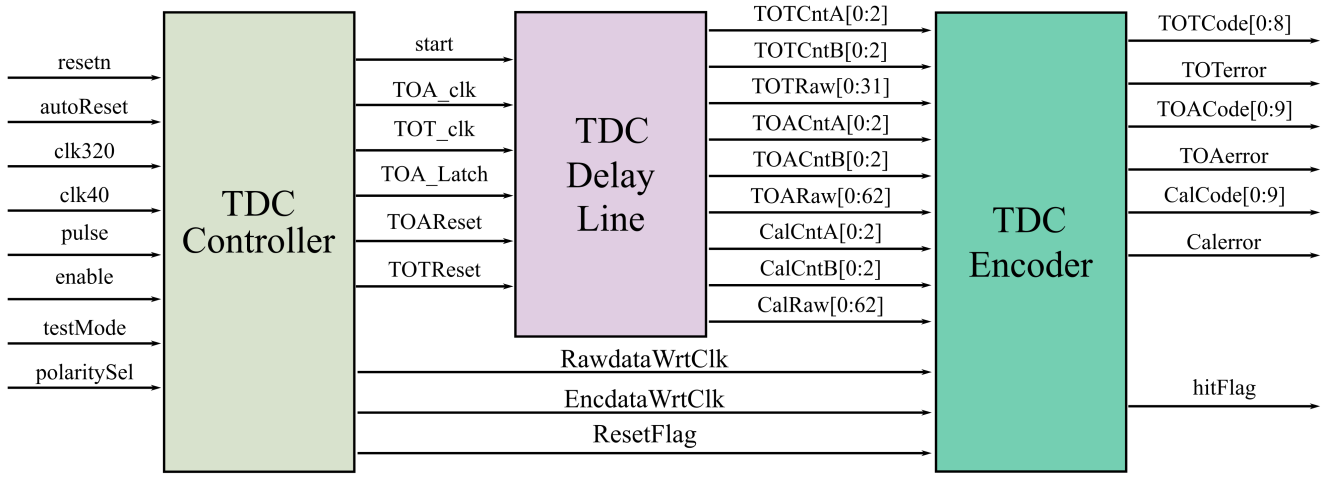


Figure 3: TDC block diagram

3.2 TDC Controller

The TDC Controller generates two groups of signals: signal pulse/clock for TDC Delay Line and clock signal for TDC Encoder. The pulse is the measured signal and valid during the meaWindow that is the area between the falling edge of the `clk40` and the first rising edge of `clk320`. The TOA is defined as time interval between leading edge of pulse signal and first rising edge of the `clk320`. The TOT is defined as the width of pulse signal. The `clk320` is used to calibrate average bin size of the TDC Delay Line.

The block diagram of TDC Controller is shown as Figure 3. The TDC Controller mainly contains Measure Window Generating Logic, Reset Generator, Core Pulse Generator, and TDC Readout Controller. The Measure Window can disable or enable the whole TDC via `enable` control bit. In test mode, the Measure Window Generator generates a fixed test pulse without pulse input and in the working mode, the input pulse is from the external waveform generator or front-ended discriminator. The Reset Generator generates the sync reset signal to reset DFFs in the pulse generator. In auto reset mode, it reset for every 40 MHz clock period. The Core Pulse Generator receives valid input pulse signal and generates start signal, TOA/TOT sampling clock for delayline (GRO). The TDC Readout Controller generates readout clock and signal for TDC Encoder and delayline.

The details schematic and implementation will be discussed in the below sections.

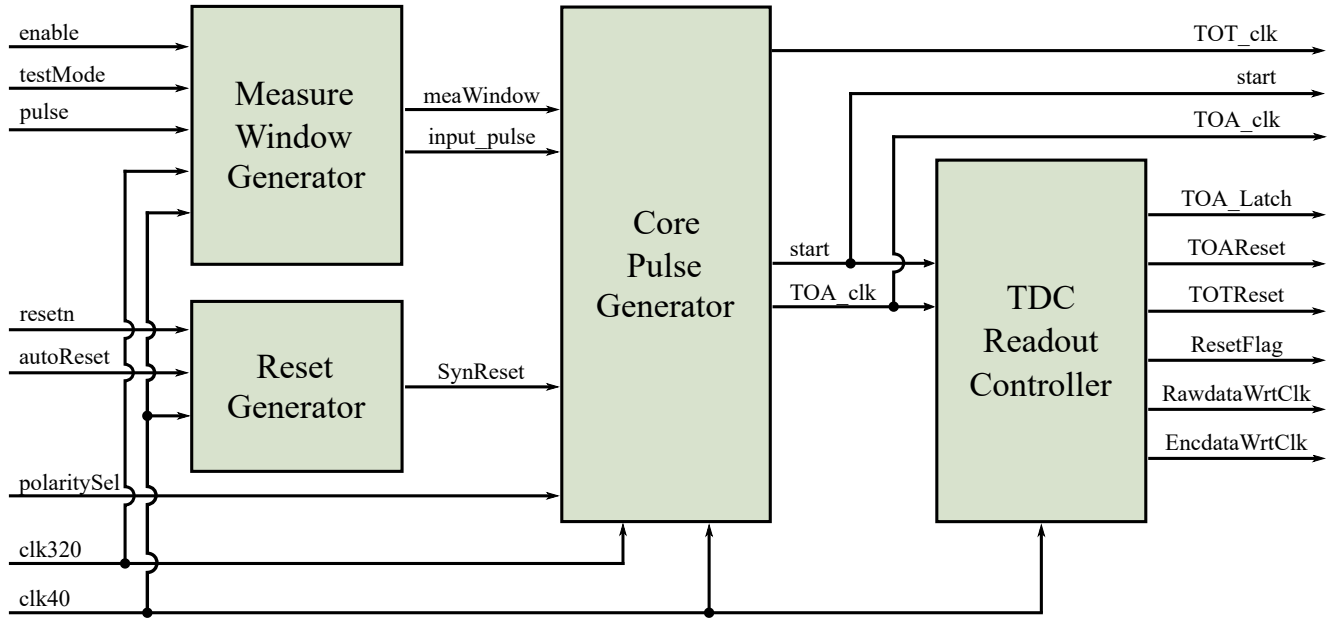


Figure 4: TDC Controller Block Diagram

3.2.1 Measure Window Generator

The Measure Window is a positive pulse signal to exclude the input signal beyond the pulse window. The width of the meaWindow is determined by the falling edge of 40 MHz clock and the first leading edge of 320 MHz clock, up to 12.5 ns. The meaWindow width is programmable by shifting the clk32 clock phase with 3.125 ns setup which is implemented by global clock generator. When enable is deasserted, the meaWindow signal disables all the output signals. The schematic and timing of Measure Window Generator logic is shown as Figure 4.

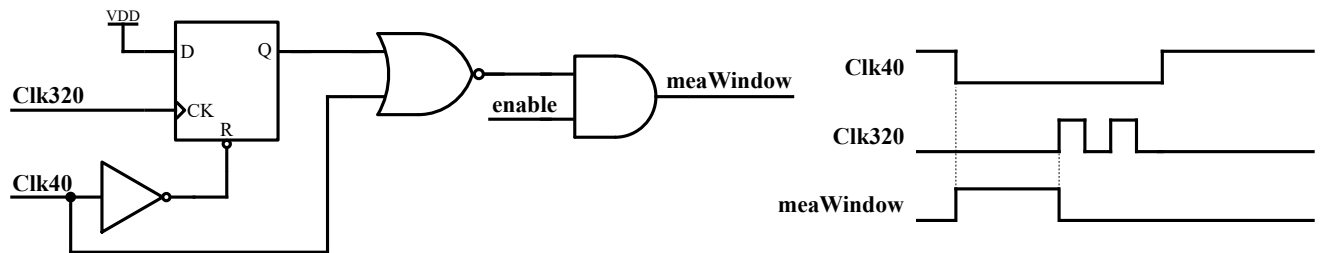


Figure 5: Schematic and timing of Measure Window Generator

When there are more than one pulse in the meaWindow, only the first pulse will be measured and other pulse will be neglected automatically. If the pulse beyond the meaWindow occurs, it will not disturb the next measurement.

3.2.2 Reset Generator

The Reset Generator has two reset modes that are the autoReset mode and the external reset mode. The synReset signal is active low. When autoReset is true, the Start Pulse Generator is reset for every 25 ns right before the measure window. In autoReset mode, the periodic reset signal (rstn_clk40) is a negative pulse generated at the falling edge of the 40 MHz

clock. The delay time t_3 is about 200 ps. User also can reset the Start pulse generator with an external resetn signal that is asynchronous with the clk40. The schematic of Reset Generator is shown as the Figure 5.

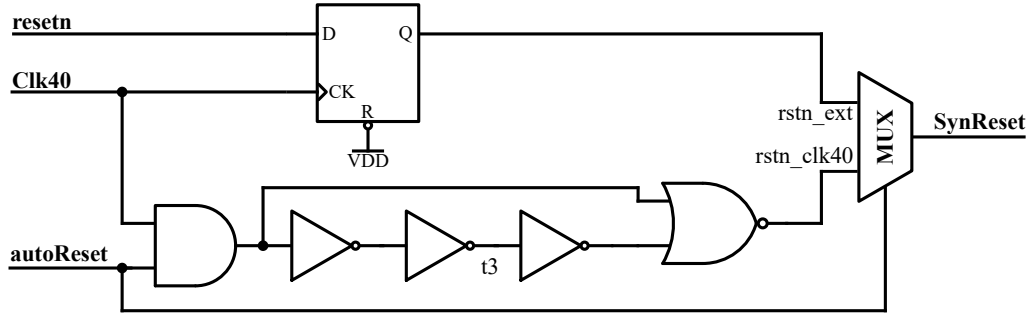


Figure 6: Schematic of Reset Generator

3.2.3 Start Pulse Generator Logic

In this section, we detail introduce the Pulse Generator Core Logic. The Pulse Generator Core Logic is used to generate Start pulse signal, TOA_clk, and TOT_clk, respectively. The Start pulse signal controls the delay line. When the Start pulse is asserted, the delay line oscillates. The TOA_clk signal is a clock signal to record the time interval between the leading edge of Start signal and the first rising edge of clk320. Similarly, the TOT_clk signal is also a clock signal to measure the time interval between leading edge and falling edge of Start pulse signal. The schematic of Start pulse generator logic is shown as Figure 6.

When testMode is asserted, Start pulse generator is in self test mode and a pulse signal copied from meaWindow with delay time of τ_0 is tested. If the rising edge of input pulse is in the meaWindow pulse, the input pulse rising edge causes start from low level to high level and its falling edge causes TOT_clk from low level to high level; otherwise, the Start keeps low level.

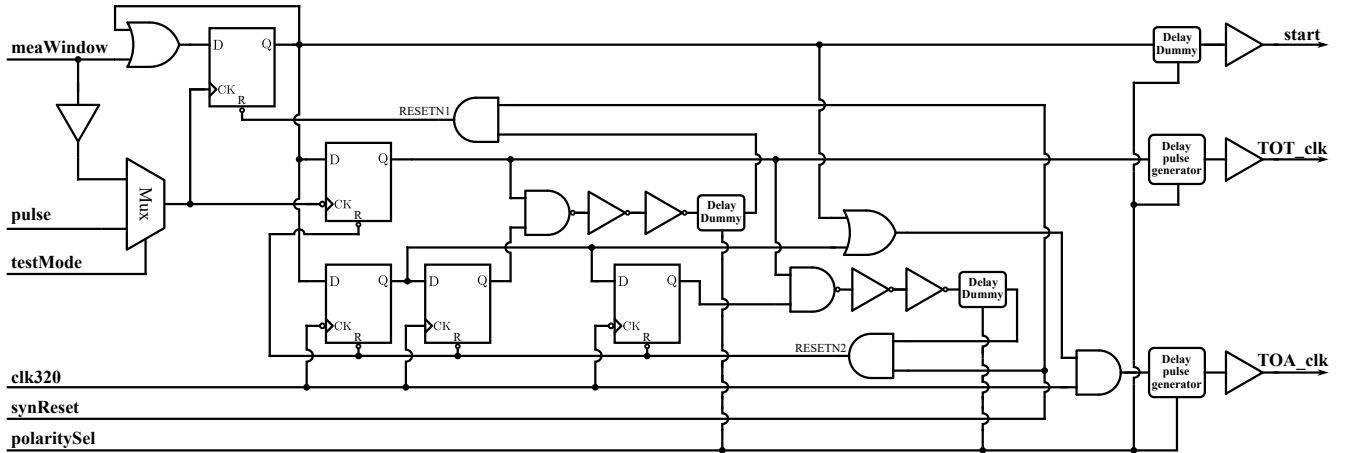


Figure 7: Schematic of Core Pulse Generator

After two rising edges of 320 MHz, when both $QC1 = 1$ and $QC3 = 1$, a resetn1 signal is generated. After two falling edges of 320 MHz, when both $QC1 = 1$ and $QC4 = 1$, a resetn2 signal is generated. A global reset (synReset) signal is used to reset all DFFs in the circuit.

When polaritySel is asserted, the TOA_clk and TOT_clk output signal are negative pulses generated at the rising edge of 320 MHz clock and the rising edge of input pulse, respectively. The negative pulse width (≈ 400 ps) is enough for DFFs data setup, All clock output signals are extra delayed with τ_4 .

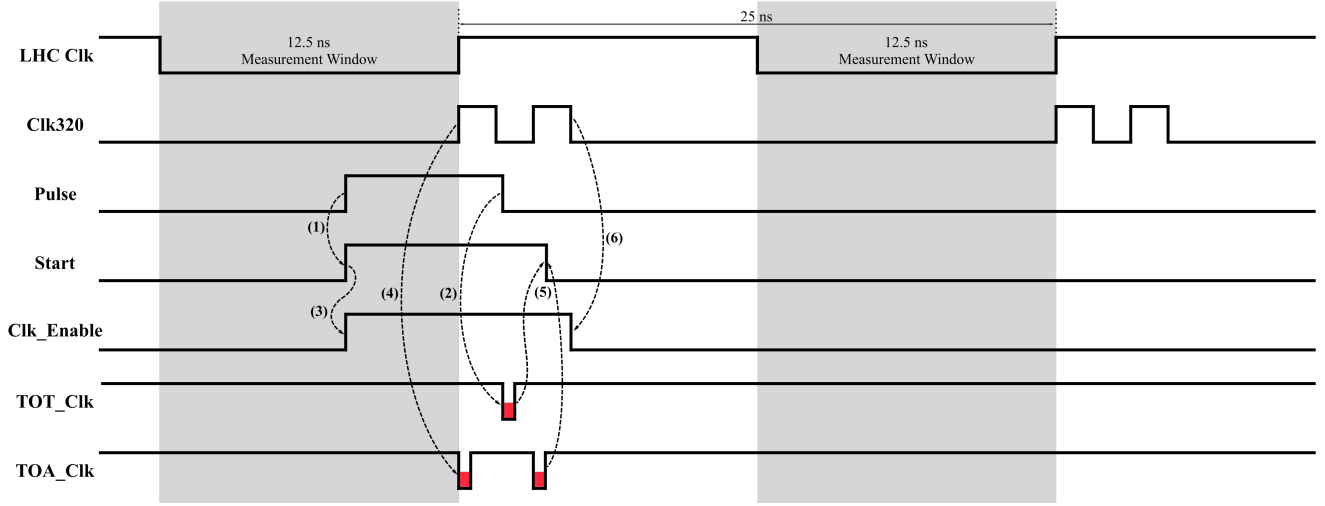


Figure 8: Timing diagram of Core Pulse Generator

The timing diagram of the Core Pulse Generator is depicted as Figure 6. The LHC Clk signal is generated by LHC detector with the frequency of 40 MHz. The low level half period of LHC Clk is used as a measurement window with the width 12.5 ns. When the rising edge of pulse occurs the measurement window, the clock signals (TOA_Clk and TOT_Clk) will be generated, otherwise, the clock signals will keep high level. The first rising edge of 320 MHz aligns with the rising edge of LHC Clk (40 MHz).

The 320 MHz is used to calibrate TDC Delay Line average bin size. At the first rising edge of 320 MHz Clock, We can record the digital code ($d1$) at this moment. Similarly, at the second rising edge of clk320, digital code ($d2$) is recorded by TOA_ck clock signal. The width between the first and second rising edge of clk320 is constantly 3.125 ns. The average bin size of Delay line is $3.125 \text{ ns}/(d2 - d1)$.

3.2.4 TDC Readout Controller

The Readout Controller generates two groups of control signal for Delay Line and TDC Encoder, respectively. The TOA_Latch, TOAReset, and TOTReset are for TDC Delay Line and the RawdataWrtClk, EncdataWrtClk, and ResetFlag are for TDC Encoder. The Figure 8 shows the schematic of Readout Controller.

If the rising edge of start occurs, the QCP is high until QC1 is latched by falling edge of clk40 because the XOR gate senses the difference of QC1 and QC2. The QCP enable the RawdataWrtClk and EncdataWrtClk. If burst events occur, the ResetFalg is active after last event is record. The TOAReset and TOTReset negative width are 400 ps, ensure the registers are reset before the sampling process. The internal DFFs output are accessible via slow control for debug and test purpose.

The RawdataWrtclk signal is used to latch the Delay Line sampling data at the rising edge and the EncdataWrtClk signal latches the encoded sampling data for output. The ResetFlag resets the hitFlag, TOAerrorFlag, TOTerrorFlag, and Calerror-Flag.

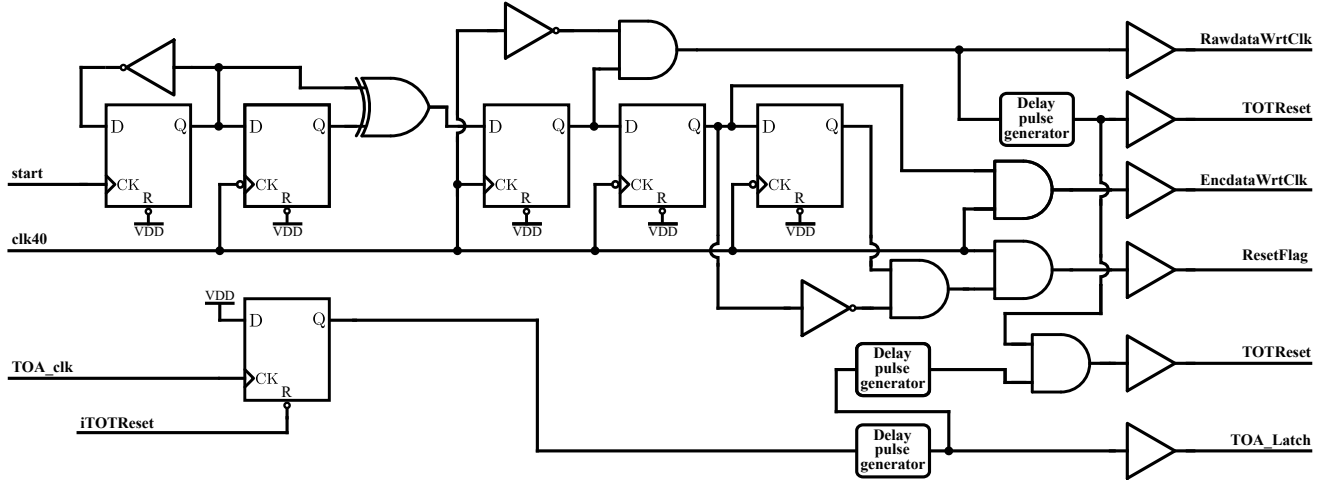


Figure 9: Schematic of TDC Readout Controller

3.3 TDC Delay Line

The TDC Delay Line is the main component of whole TDC. The resolution of TDC is determined by TDC Delay Line. The TDC Delay is composed by 63 Single Tap Delay Line as a Ring Oscillator. The TDC utilizes a combination of coarse time and fine time for the time measurement.

3.3.1 Single Tap Delay Line

The Single Tap Delay Line is composed by Two DFFs and one NAND. The NAND gate is used to generate minimum latency that is determined by the CMOS process and the two DFFs latch the TOA and TOT fine phase, respectively. The NAND gate and DFF are all ELT layout that has good performances. The Figure 10 shows the schematic of Single Tap Delay Line (red dashed line enclosed).

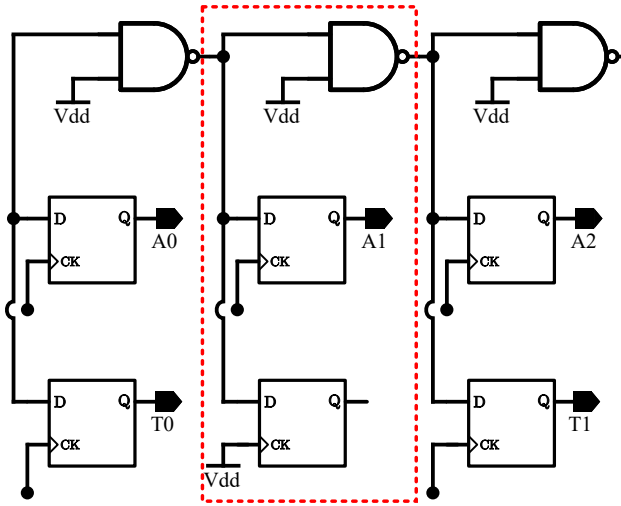


Figure 10: Schematic of Single Tap Delay Line

3.3.2 63 Tap Delay Line

A 63-tap gated ring oscillator (GRO) is used for the core TDC delay line, with uniform and uncontrolled **NAND** gate delay cells and 20 ps latency per cell. The load of all the nodes are well matched and the period of oscillator is about $2 * 62 * 20ps = 2.52ns$. This is a simple and fast GRO structure with no latency control logic, no DLL used. Instead, real time calibration will be used because each hit will be measured twice using two consecutive clocks. One delay line is used for both TOA/TOT measurements. TOA bin size is one cell delay latency ($\simeq 20$ ps) and TOT bin size is twice the cell delay latency ($\simeq 40$ ps). Dynamic range is configurable and up to 12.5 ns for both TOA and TOT measurement. TOA DNL estimated to be ± 0.15 LSB and INL is about ± 0.3 LSB. Figure 11 shows the schematic of 63 Tap delay line.

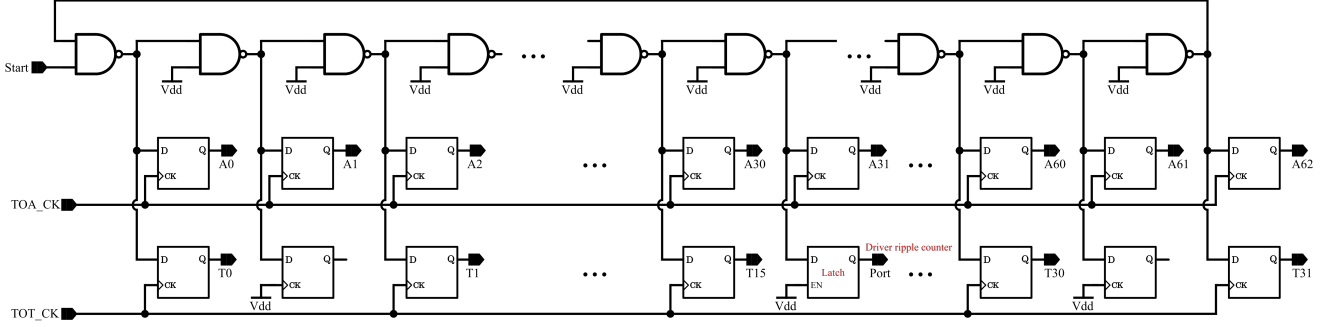


Figure 11: Schematic of 63 Tap Delay Line

When the Start is asserted, the NAND gated ring is oscillating with the period of 2.52 ns at post-layout simulation. The TOA_CK and TOT_CK are used to latch the TOA and TOT fine phase at the rising edge. The Start, TOA, and TOT signal are all generated by TDC Controller. The ripple counters was driven by the output of TOT Tap 31. The one is driven by the rising edge and the other one is driven by the falling edge of the output of TOT Tap 31.

3.3.3 Clock Tree Design

In order to decrease the clock skew and jitter of the TOA and TOT clock distribution on layout, we have adopted the most common and conservative clock distribution scheme, known as **T-tree**. The schematic of TOA clock T-tree is depicted as Figure 12.

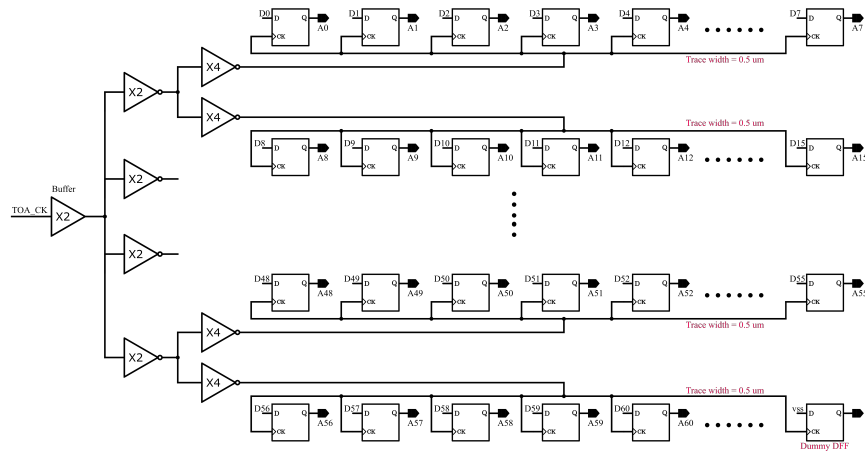


Figure 12: Schematic of TOA clock distribution

3.3.4 Coarse Counter

The TDC coarse counter that is a 3-bit ripple counter records the TDC delay line coarse phase. we used two ripple counter that have 180° to eliminate the metastability of itself. Figure 13 shows the schematic of coarse counter of delay line.

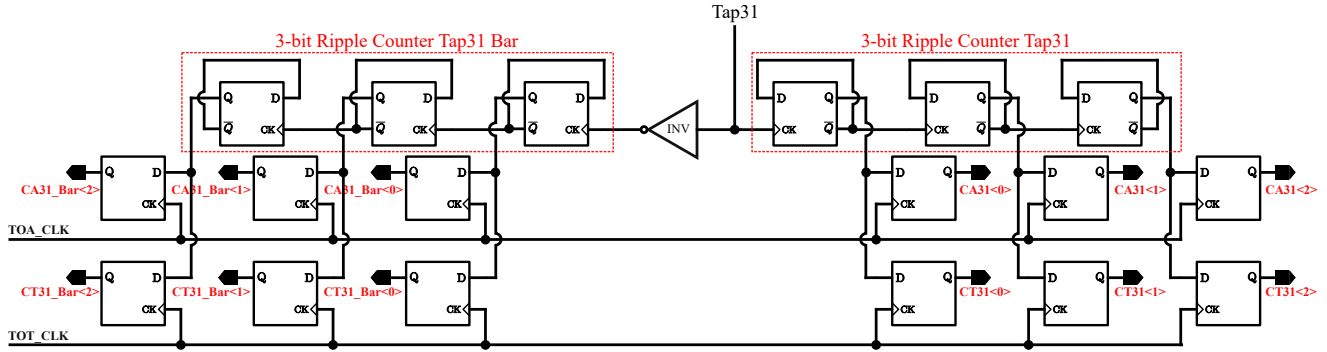


Figure 13: Schematic of TOA clock distribution

3.4 TDC Encoder

TDC Encoder is used to convert the TOA, TOT and Calibration sampling code into binary code (TOA is 10-bit, TOT is 9-bit and Calibration is 10-bit). The TOA and Calibration have the identical encode logic. Each encode logic

3.4.1 TOA and Calibration Encoder Logic

3.4.2 TOT Encoder Logic

3.4.3 Bubble Tolerance Logic

4 Diagnostic Mode Readout (DMRO)

4.1 Scrambler

4.2 PRBS7 Generator

4.3 Serializer

5 Clock Pulse Generator

6 Clock Divider

7 Gate Ring Oscillator (GRO)

8 I2C Interface

The ETROC1 TDC Test Block chip employs an I2C interface as slow control. The slave provides 32 bytes for writing and 16 bytes for reading by ETROC1. A 4-bit chip ID and a 4-bit chip revision are available as well. The registers in the I2C are triplicated to mitigate SEU. The slave address is 7'b010001X, the LSB of address is determined by the external pad A0.

Table 2: ETROC1 TDC Test Block Chip pads information

| NO. | Name | Reg name | Description | Default value |
|-----|-----------------------------|-------------|---|---------------|
| 1 | Dataout_disCMLDriver_BIAS | REG_00[0] | Disable Data output CML Driver | 1'b0 |
| 2 | Clk40Mout_disCMLDriver_BIAS | REG_00[1] | Disable Clk40M output CML Driver | 1'b0 |
| 3 | tdc_offset< 6 : 0 > | REG_01[6:0] | TDC ripple counter meta-stability window offset | 7'b0000000 |
| 4 | tdc_enable | REG_01[7] | Enable TDC | 1'b1 |
| 5 | tdc_level< 2 : 0 > | REG_02[2:0] | TDC Encoder bubble tolerance | 3'b001 |
| 6 | tdc_testMode | REG_02[3] | TDC test mode | 1'b0 |
| 7 | tdc_selRawCode | REG_02[4] | Select TDC raw code, always "0" | 1'b0 |
| 8 | tdc_resetsn | REG_02[5] | TDC reset signal | 1'b1 |
| 9 | tdc_polaritySel | REG_02[6] | TDC controller output polarity select | 1'b1 |
| 10 | tdc_autoReset | REG_02[7] | TDC automatic reset signal | 1'b0 |
| 11 | Clk40Mout_AmplSel< 2 : 0 > | REG_03[2:0] | 40 MHz clock CML output amplitude select | 3'b001 |
| 12 | tdc_enableMon | REG_03[3] | Enable TDC raw data output | 1'b1 |
| 13 | tdc_timeStampMode | REG_03[4] | TDC Calibration data timeStamp mode | 1'b1 |
| 14 | Dataout_AmplSel< 2 : 0 > | REG_04[2:0] | 1.28 GHz Serial data output amplitude select | 3'b001 |
| 15 | ro_testmode | REG_04[3] | DMRO test mode select | 1'b0 |
| 16 | ro_enable | REG_04[4] | Enable DMRO | 1'b1 |
| 17 | ro_reverse | REG_04[5] | DMRO output data reverse | 1'b0 |
| 18 | ro_resetsn | REG_04[6] | DMRO reset, low active | 1'b1 |
| 19 | ro_revclk | REG_04[7] | DMRO 40 MHz clock reverse | 1'b0 |
| 20 | Dataout_Sel | REG_05[0] | 1.28 GHz data output when asserted | 1'b1 |
| 21 | Clk320M_Psel | REG_05[1] | 320M pulse comes external pad when asserted | 1'b1 |
| 22 | Clk40M_Psel | REG_05[2] | 40M pulse comes external pad when asserted | 1'b1 |
| 23 | Clk320M_Sel | REG_05[3] | 320M clock comes internal when asserted | 1'b1 |
| 24 | Clk40M_Sel | REG_05[4] | 40M clock comes internal when asserted | 1'b1 |
| 25 | Pulse_Sel< 7 : 0 > | REG_06[7:0] | 320M clock pulse location select | 8'b00000011 |
| 26 | Clk40M_equalizer< 1 : 0 > | REG_07[1:0] | 40M clock input eRx equalizer intensity | 2'b00 |
| 27 | Clk40M_invertData | REG_07[2] | 40M clock input eRx data invert | 1'b0 |
| 28 | Clk40M_enableTermination | REG_07[3] | Enable 40M clock input eRx termination | 1'b1 |
| 29 | Clk40M_setCommonMode | REG_07[4] | Set 40M clock input eRx common mode | 1'b1 |
| 30 | Clk40M_enableRx | REG_07[5] | Enable 40M clock input eRx | 1'b1 |
| 31 | Clk320M_equalizer< 1 : 0 > | REG_08[1:0] | 320M clock input eRx equalizer intensity | 2'b00 |
| 32 | Clk320M_invertData | REG_08[2] | 320M clock input eRx data invert | 1'b0 |
| 33 | Clk320M_enableTermination | REG_08[3] | Enable 320M clock input eRx termination | 1'b1 |
| 34 | Clk320M_setCommonMode | REG_08[4] | Set 320M clock input eRx common mode | 1'b1 |
| 35 | Clk320M_enableRx | REG_08[5] | Enable 320M clock input eRx | 1'b1 |
| 36 | Clk1G28_equalizer< 1 : 0 > | REG_09[1:0] | 1.28G clock input eRx equalizer intensity | 2'b00 |
| 37 | Clk1G28_invertData | REG_09[2] | 1.28G clock input eRx data invert | 1'b0 |
| 38 | Clk1G28_enableTermination | REG_09[3] | Enable 1.28G clock input eRx termination | 1'b1 |
| 39 | Clk1G28_setCommonMode | REG_09[4] | Set 1.28G clock input eRx common mode | 1'b1 |

| | | | | |
|----|--------------------------|-------------|---|--------|
| 40 | Clk1G28_enableRx | REG_09[5] | Enable 1.28G clock input eRx | 1'b1 |
| 41 | Pulse_equalizer< 1 : 0 > | REG_0A[1:0] | TDC pulse input eRx equalizer intensity | 2'b00 |
| 42 | Pulse_invertData | REG_0A[2] | TDC pulse input eRx data invert | 1'b0 |
| 43 | Pulse_enableTermination | REG_0A[3] | Enable TDC pulse input eRx termination | 1'b1 |
| 44 | Pulse_setCommonMode | REG_0A[4] | Set TDC Pulse input eRx common mode | 1'b1 |
| 45 | Pulse_enableRx | REG_0A[5] | Enable TDC Pulse input eRx | 1'b1 |
| 46 | TDCRawData_Sel | REG_0B[0] | TDC Raw data group select | 1'b1 |
| 47 | GRO_TOT_CK | REG_0B[1] | GRO TOT clock | 1'b1 |
| 48 | GRO_TOTRST_N | REG_0B[2] | GRO TOT reset, low active | 1'b1 |
| 49 | GRO_TOA_Latch | REG_0B[3] | GRO TOA Latch clock | 1'b1 |
| 50 | GRO_TOA_CK | REG_0B[4] | GRO TOA clock | 1'b1 |
| 51 | GRO_TOARST_N | REG_0B[5] | GRO TOA reset, low active | 1'b1 |
| 52 | GRO_Start | REG_0B[6] | GRO Start signal, high active | 1'b0 |
| 53 | GROout_disCMLDriverBIAS | REG_0C[0] | Disable GRO output CML Driver | 1'b0 |
| 54 | GROout_AmplSel< 2 : 0 > | REG_0C[3:1] | GRO output CML Driver Amplitude select | 3'b001 |

TDC Test Block read-only register:

Table 3: ETROC1 TDC Test Block read-only registers information

| NO. | Reg name | TDCRawData_Sel=0 | TDCRawData_Sel=1 |
|-----|-------------|--|----------------------|
| 1 | REG_20[2:0] | CalCounterBMon[2:0] | TOACounterBMon[2:0] |
| 2 | REG_20[5:3] | CalCounterAMon[2:0] | TOACounterAMon[2:0] |
| 3 | REG_20[6] | CalerrorFlagReg | TOAerrorFlagReg |
| 4 | REG_21[7:0] | TOT_codeReg[7:0] | TOARawDataMon[7:0] |
| 5 | REG_22[7:0] | TOA_codeReg[6:0], TOT_codeReg[8] | TOARawDataMon[15:8] |
| 6 | REG_23[7:0] | Cal_codeReg[4:0], TOA_codeReg[9:7] | TOARawDataMon[23:16] |
| 7 | REG_24[7:0] | Cal_RawDataMon[31:29], Cal_codeReg[9:5] | TOARawDataMon[31:24] |
| 8 | REG_25[7:0] | Cal_RawDataMon[39:32] | TOARawDataMon[39:32] |
| 9 | REG_26[7:0] | Cal_RawDataMon[47:40] | TOARawDataMon[47:40] |
| 10 | REG_27[7:0] | Cal_RawDataMon[55:48] | TOARawDataMon[55:48] |
| 11 | REG_28[6:0] | Cal_RawDataMon[62:56] | TOARawDataMon[62:56] |
| 12 | REG_29[7:0] | HitFlag, TOTerrorFlagReg, TOTCounterAMon[2:0], TOTCounterBMon[2:0] | |
| 13 | REG_2A[7:0] | CalRawDataMon[7:0] | TOTRawDataMon[7:0] |
| 14 | REG_2B[7:0] | CalRawDataMon[15:8] | TOTRawDataMon[15:8] |
| 15 | REG_2C[7:0] | CalRawDataMon[23:16] | TOTRawDataMon[23:16] |
| 16 | REG_2D[7:0] | < *3 >Low, CalRawDataMon[28:24] | TOTRawDataMon[31:24] |
| 17 | REG_2E[5:0] | DBF_QC[5:0] | RO_DBF_QC[5:0] |

9 Test Contents

ETROC1 TDC Test Block chip is mainly used to test the specifications and features of the TDC.

10 Test platform and steps