

INDR 450/550

Spring 2022

Lecture 17: GAMs and Trees

April 18, 2022

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Announcements

- Class Exercise at the end of lecture today. If you are participating online, please upload your document under Course Contents/Class Exercises
- Lab 7 material (on lasso and ridge) and a short video are available
- Exam on May 7.
 - Some exercises will be available

The first seven labs were uploaded. Please follow them.

Predictive Analytics

- Remaining topics (to complete at the latest the week after the spring break)
 - Validation
 - Model selection / regularization
 - Non-linear regressions,
 - Generalized additive models, Tree-based methods (today)

Non-linear regressions: basis functions

- Basis Functions: Consider a family of transformations for the predictor X: $b_1(X), b_2(X),...,b_n(X)$.
- Polynomials are an example where we have $b_i(X) = X^i$.
- We then consider the following regression using the basis variables:

$$y_t = \beta_0 + \beta_1 b_1(x_t) + \beta_2 b_2(x_t) + \dots + \beta_n b_n(x_t) + \epsilon_t$$

 All tools from ordinary least squares regression are available under such transformations.

Non-linear regressions: knots / cubic splines

- Approximations of functions using knots fall in the class of spline approximations.
- Note that when we use a knot $(t t_1)^+$, we are allowing a slope change at t_1 . This results in a change of slope at t_1 and therefore a non-smooth fit.
- To have a smooth curve, we need continuity at the knot and also the continuity of the first and second derivatives.
- The basis that gives such smooth functions consists of the following knots:

$$\left((t-t_1)^+\right)^3 = \left\{ egin{array}{ll} (t-t_1)^3 & ext{if } t>t_1 \ 0 & ext{otherwise} \end{array}
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Non-linear regressions: knots / cubic splines

To determine the location and the number of knots: try several ones and choose by cross-validation.

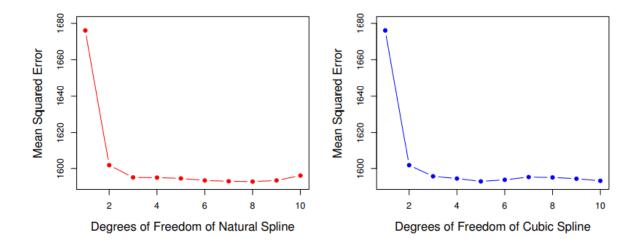


FIGURE 7.6. Ten-fold cross-validated mean squared errors for selecting the degrees of freedom when fitting splines to the Wage data. The response is wage and the predictor age. Left: A natural cubic spline. Right: A cubic spline.

From An Introduction to Statistical Learning, James, Witten, Hastie, Thibshirani

Some trials on the Google Share Price Data

• I also a tried a cubic spline with three knots at 25,40 and 60.

RMSE (train) = 40.53

Non-linear regressions: GAMS

 Generalized additive models extend the one predictor approach to multiple predictors assuming a model of the form:

$$y_t = \beta_0 + f_1(x_{t2}) + f_2(x_{t2}) + ... + f_p(x_{tp}) + \epsilon_t$$

• We separately explain the effects of each predictor and then sum them up.

Non-linear regressions: GAMS

- GAMs are flexible tools somewhere between linear regression and non-parametric approaches.
- With standard basis functions (i.e. cubic splines) we can use least squares regression to fit GAMs.
- Since non-linearity is considered, they may be more accurate fits than a linear regression.
- We can control the smoothness of the curve that is fit by the choice of basis
- GAMs do not consider interaction effects between predictors but these can be added manually.
- They extend to logistic regression directly.

Non-linear regressions: GAMS / Gradient Boosting

 Gradient boosting is a sequential optimization approach that has proved useful in improving predictions. Consider:

$$y_t = \beta_0 + f_1(x_{t2}) + f_2(x_{t2}) + ... + f_p(x_{tp}) + \epsilon_t$$

- Instead of trying to solve the least squares problem with all predictors (and their transformations), we use a greedy sequential optimization approach.
- We fit each of the p predictors separately and individually. We select the one that gives the best MSE and compute the residuals from this best fit.
- We then use the remaining predictors to find the best individual fit that explains the residuals from the first round.
- and continue in this manner fitting the best individual predictor the remaining residuals after each round.
- Note that more of the remaining residual is explained in each round.

From An Introduction to Statistical Learning, James, Witten, Hastie, Thibshirani

- Tree-based methods segment the predictor space into multiple regions in a smart way. They then make a very simple prediction for each region using the training data.
- The prediction for a given region is simply the average of the observations in the training data that fall into that region.
- Conceptually simple and easy to explain.
- But require additional work to be competitive with earlier methods (ridge, lasso, GAMs etc.)

Predicting the salary of a baseball player using his experience (years) and Performance (# of hits).

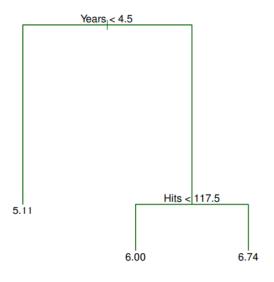
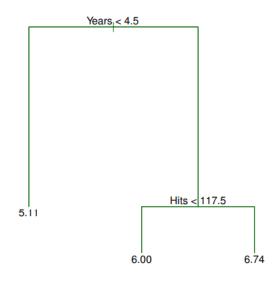
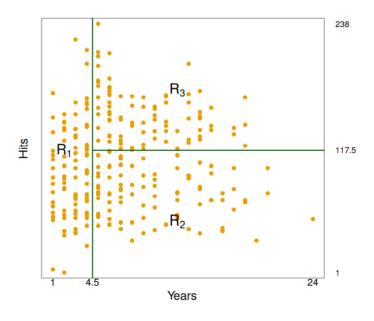


FIGURE 8.1. For the Hitters data, a regression tree for predicting the log salary of a baseball player, based on the number of years that he has played in the major leagues and the number of hits that he made in the previous year. At a given internal node, the label (of the form $X_j < t_k$) indicates the left-hand branch emanating from that split, and the right-hand branch corresponds to $X_j \ge t_k$. For instance, the split at the top of the tree results in two large branches. The left-hand branch corresponds to Years>=4.5. The tree has two internal nodes and three terminal nodes, or leaves. The number in each leaf is the mean of the response for the observations that fall there.

- Here's a summary of the basic approach.
 - We divide the predictor space (the space of all possible values of the predictors $(X_1, X_2, ..., X_p)$ into J distinct (non-overlapping regions) $R_1, R_2, ..., R_j$.
 - ② For any observation that falls in region R_j , we use the same prediction: the average of all observations from that region in the training set.
 - Note that this is natural for binary variables. If it's a weekend day, we make a prediction based on past weekend days and if it's a week day, we make a prediction based on week days.
- We are making a prediction for \mathbf{x}_p that falls in region R_j . The mean of all training observations in $R_i = 200$, then $\hat{y}(\mathbf{x}_p) = 500$





• The common approach is to divide to predictor space into *p* dimensional boxes. We then choose *J* overlapping boxes such that:

$$\sum_{j=1}^J \sum_{i \in R_j} (y_i - \bar{y}_{R_j})^2$$

- We immediately note that finding the exactly optimal partition (boxes) is computationally prohibitive.
- We take a greedy approach called recursive binary splitting.

Tree-based Methods: recursive binary splitting

• For each predictor X_j , we find the optimal cutpoint s: to do this we define the half planes:

$$R_1(j,s) = \{X | X_j < s\} \text{ and } R_2(j,s) = \{X | X_j \ge s\}$$

and we seek the cutpoint s that minimizes

$$\sum_{i:x_i \in R_1(j,s)} (y_i - \bar{y}_{R1})^2 + \sum_{i:x_i \in R_2(j,s)} (y_i - \bar{y}_{R2})^2$$

 We repeat this for all predictors and choose the one that leads to lowest residual sum of squares as the top split of the tree.

Tree-based Methods: recursive binary splitting

- The top of the tree now splits at the chosen predictor j, and cutoff s'.
- We repeat the same procedure for the second split. We are then dividing the partition from stage 1 further.
- We repeat the splitting until we reach the desired number of regions or few observations remain in each region.
- This it not computationally difficult when the number of predictors is not large.

Tree-based Methods: pruning

- Note that as usual, overfitting is an issue. We would prefer trees that are small (i.e. use few regions) to avoid overfitting.
- We can stop the split when the incremental decrease in RSS is lower than a threshold but the this would not be the globally optimal way to do it.
- A better strategy first grows a large tree and then prunes it down to obtain a smaller subtree.

Tree-based Methods: pruning

- We grow a large tree T_0 using recursive binary splitting.
- We consider a penalty parameter α and solve the following minimization problem:

$$\min \sum_{m=1}^{|T|} \sum_{x_i \in R_m} (y_i - \hat{y}_{R_m})^2 + \alpha |T|$$

where T denotes the number of terminal nodes of the subtree T.

• This is similar to lasso. If $\alpha=0$, we use the initial tree T_0 but as α increases some of the terminal nodes will have to be reduced resulting in a loss in residual sum of squares. The optimization finds the right tradeoff between which branches to prune and the loss in residual sum of squares.

Tree-based Methods: pruning algorithm

Algorithm 8.1 Building a Regression Tree

- 1. Use recursive binary splitting to grow a large tree on the training data, stopping only when each terminal node has fewer than some minimum number of observations.
- 2. Apply cost complexity pruning to the large tree in order to obtain a sequence of best subtrees, as a function of α .
- 3. Use K-fold cross-validation to choose α . That is, divide the training observations into K folds. For each $k = 1, \ldots, K$:
 - (a) Repeat Steps 1 and 2 on all but the kth fold of the training data.
 - (b) Evaluate the mean squared prediction error on the data in the left-out kth fold, as a function of α .
 - Average the results for each value of α , and pick α to minimize the average error.
- 4. Return the subtree from Step 2 that corresponds to the chosen value of α .

Tree-based Methods: classification

- The tree-based approach extends directly to classification problems.
- The only difference is that as before MSE or RSS cannot be the error criterion.
- The error function takes into account the classification errors.
 - There are other useful error measurements such as:
 - Gini index
 - Cross-entropy

Tree-based Methods: advantages and disadvantages

- Decision trees for regression are easy to communicate and understand
- Natural for qualitative predictors
- But do not have the same level of predictive accuracy as the previous models
- There are some robustness issues. A small change in data can lead to a big change in the resulting regression tree.
- The variance of the typical tree-based regression estimator is high (much higher than a linear regression based estimator).