

INDR 450/550

Spring 2022

Lecture 3: Simple forecasts

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Announcements

- The TA for the course is Tufail Ahmad (tahmad20@ku.edu.tr)
- Blackboard page is becoming active
 - Slides of first week's lectures
 - Links to books
- We may start looking at some data today
 - This week, we'll upload a video on basic analysis of some forecasting models

Reminder: estimators and properties

- Let us note that sample based estimators are themselves random variables.
 Each time we draw a new random sample, we'll get a different value for our estimator.
- Unbiasedness: A desirable property for an estimator is that it does not have a systematic error on the average (in expectation). The sample mean \bar{X} is an unbiased estimator of the population mean since:

$$E[\bar{X}] = \mu.$$

• Note that there are many unbiased estimators: X_1 and $(2X_1 + X_2)/3$ are also unbiased. Since:

$$E[X_1] = E[(2X_1 + X_2)/3] = \mu.$$

Reminder: estimators and properties

- Variance of the Estimator: Among unbiased estimators, it makes sense to prefer one with a lower variance.
- Assuming that our sample has variance σ^2 :

$$Var[\bar{X}] = \frac{\sigma^2}{n}$$

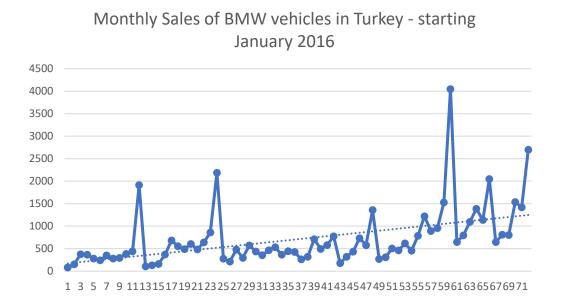
• whereas for the other estimators:

$$Var[X_1] = \sigma^2 \text{ and } Var[(2X_1 + X_2)/3] = \frac{5\sigma^2}{9}.$$

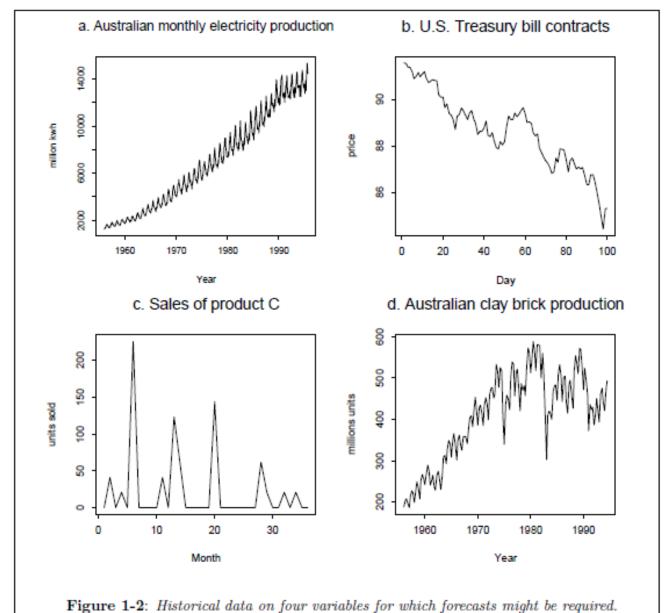
• We will see that for demand forecasting there is a trade-off between responsiveness and low variance.

Time series

- Demand data is typically in the form of a time series: an observation per period
- Note that we typically have sales data which may be different than the actual demand
- We'll forecast future values time series to eventually solve planning problems



Some more real data — Makridakis, Wheelwright, Hyndman (1997)



- We have data corresponding to a time series $y_1, y_2, ...y_T$. For our purposes, we can assume that y_t corresponds to demand in period t. The goal is to forecast the demand in period T + h h = 1, 2, ... given the observations.
- Here are some simple ideas: i) average

$$\hat{y}_{T+h|T} = \frac{\sum_{t=1}^{T} y_t}{T}$$

• ii) naive method

$$\hat{y}_{T+h|T} = y_T$$

• iii) seasonal naive method (where m is the seasonal period)

$$\hat{y}_{T+h|T} = y_{T+h-m} \text{ if } T + h - m \leq T.$$

• iv.) Drift (trend) estimation

$$\hat{y}_{T+h|T} = y_T + h\left(\frac{y_T - y_1}{T - 1}\right)$$

• v) moving average over k periods

$$\hat{y}_{T+h|T} = \left(\frac{y_{T-k+1} + y_{T-k+2} + ... + y_T}{k}\right)$$

• vi.) Exponential smoothing

$$\hat{y}_{T+1|T} = \alpha y_T + (1-\alpha)\hat{y}_{T|T-1}$$

where $0 \le \alpha \le 1$. Note that since $\hat{y}_{T|T-1} = \alpha y_{T-1} + (1-\alpha)\hat{y}_{T-1|T-2}$ we can recursively write:

$$\hat{y}_{T+1|T} = \alpha y_T + \alpha (1-\alpha) y_{T-1} + (1-\alpha)^2 \hat{y}_{T-1|T-2}$$

$$= \sum_{t=1}^{T} \alpha (1-\alpha)^{T-t} y_t$$

- To get some insight, let us consider some models that will generate data. Assume that ϵ_t are iid random variables with mean zero and standard deviation σ .
 - i) stationary i.i.d model

$$Y_t = c + \epsilon_t$$

ii) stationary seasonal model

$$Y_t = c_{t(mod\ m)} + \epsilon_t$$

iii) a model with linear trend

$$Y_t = bt + c + \epsilon_t$$

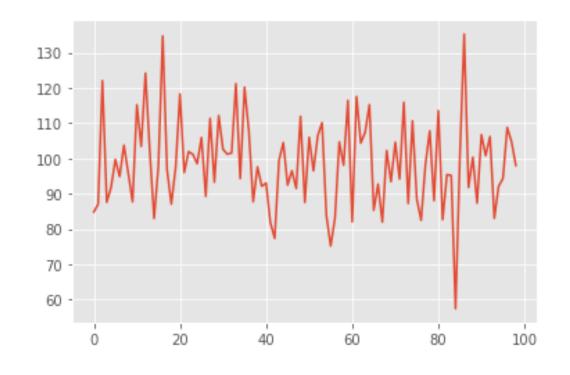
iv) a model with quadratic trend

$$Y_t = at^2 + bt + c + \epsilon_t$$

i) stationary i.i.d model

$$Y_t = c + \epsilon_t$$

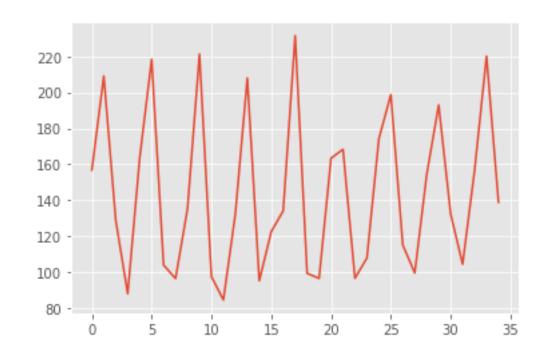
```
c=100; sigma=15;
y=[0]*101;
for i in range(1,100):
y[i] =c + sigma*random.normalvariate(0, 1)
```



ii) stationary seasonal model

$$Y_t = c_{t(mod\ m)} + \epsilon_t$$

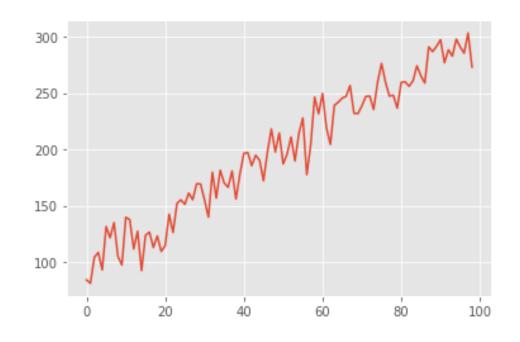
```
 ssc=[0]*4; \\ ssc[0]=100; ssc[1]=150; ssc[2]=200; ssc[3]=120; sigma=15; b=2; \\ yss=[0]*101; \\ for i in range(1,100): \\ yss[i] = ssc[i \% 4] + sigma*random.normalvariate(0, 1)
```



iii) a model with linear trend

$$Y_t = bt + c + \epsilon_t$$

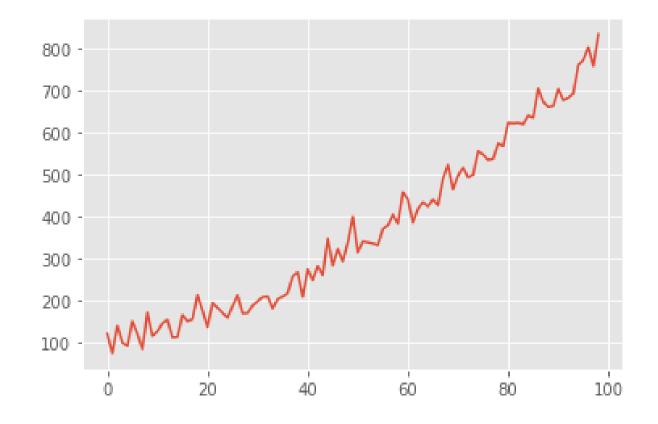
```
c=100; sigma=15; b=2;
ytr=[0]*101;
for i in range(1,100):
  ytr[i] =c + b*i+ sigma*random.normalvariate(0, 1)
```

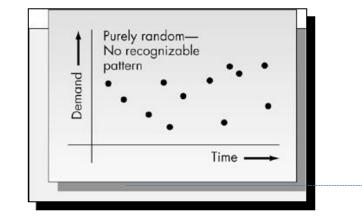


iv) a model with quadratic trend

$$Y_t = at^2 + bt + c + \epsilon_t$$

```
c=100; sigma=25; b=2; a=0.05; yqr=[0]*101; for i in range(1,100): yqr[i] =c + b*i+ a*i*i+ sigma*random.normalvariate(0, 1)
```





- We can now test the properties of the simple estimators:
 - i) stationary i.i.d model

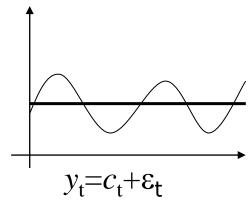
$$Y_t = c + \epsilon_t$$

- The average method and the naive method are both unbiased estimators: $E[\hat{Y_T}] = E[Y_T] = c$.
- The variance of the estimator $Var[\hat{Y}_T]$ is σ^2 for the naive method and σ^2/T for the average method.
- The drift method is also unbiased. The estimator of the drift term is zero in expectation.

- The k-period moving average is unbiased with variance σ^2/k .
- Exponential smoothing is unbiased with asymptotic variance (as $T \to \infty$): $(\alpha \sigma^2)/(2-\alpha)$.
- Note that there are many other unbiased forecasts for a simple stationary series, for instance

$$\hat{y}_{T+h} = y_{T_1},$$
 $\hat{y}_{T+h} = y_T + (y_{T-1} - y_{T-2}),$
 $\hat{y}_{T+h} = \beta y_T + (1 - \beta)y_{T-2} \ (0 \le \beta \le 1).$ etc.

• These simple models (MA and ES) are basic but effective and frequently used in practice thanks to their responsiveness. Note that MA puts equal weight on the k most recent observations whereas ES puts geometrically decreasing weight on all past observations.

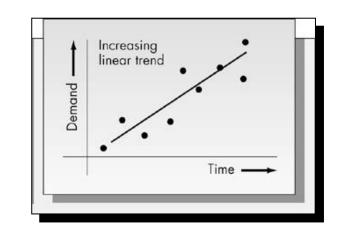


- None of the simple forecasts are unbiased for a seasonal series except for the naive seasonal forecast.
- By using the same principles we can build other simple unbiased forecasts.
- For instance, inspired by moving averages we have:

$$\hat{y}_{T+h|T} = \frac{y_{T+h-m} + y_{T+h-2m} + y_{T+h-3m}}{3}$$
 if $T+h-m \leq T$.

And inspired by exponential smoothing we have:

$$\hat{y}_{T+h|T} = \alpha y_{T+h-m} + (1-\alpha)\hat{y}_{T+h-2m}$$
 if $T+h-m \leq T$.



- Let's now check the simple trend model: $Y_t = bt + c + \epsilon_t$.
- The naive forecast is not unbiased: $\hat{y}_{T+h|T} = y_T$. Taking expectations: $E[\hat{Y}_{T+h}] = b(T+h) + c \neq E[Y_T] = bT + c$.
- Similarly, average, moving average, and exponential smoothing are not unbiased.
- This is expected because to capture the functional form (i.e. slope), we would need to estimate an additional term beyond the 'level' of the series.
- The trend forecast is unbiased:

$$E[\hat{Y}_{T+h|T}] = E\left[Y_T + h\left(\frac{Y_T - Y_1}{T - 1}\right)\right] = c + bT + hb = c + (T + h)b.$$

 We can of course develop other unbiased estimators. Inspired by the naive method:

$$\hat{y}_{T+h|T} = y_T + (y_T - y_{T_1})$$

Inspired by moving averages:

$$\hat{y}_{T+h|T} = y_T + \frac{(y_T - y_{T-1}) + (y_{T-1} - y_{T-2}) + (y_{T-2} - y_{T-3})}{3}$$

Inspired by exponential smoothing:

$$\hat{y}_{T+h|T} = y_T + \alpha(y_T - y_{T-1}) + (1 - \alpha)(\hat{y}_{T-1} - \hat{y}_{T-2})$$