



INDR 450/550

Spring 2022

Lecture 6: ARIMA processes

March 2, 2022

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Announcements

- The first lab video was uploaded on Friday. The second lab will be uploaded on Friday this week. Please follow them.
- First HW will be assigned this week
 - You can work in groups of two or three for the homeworks
- Looking forward to seeing you on campus next week.

Auto-Correlation

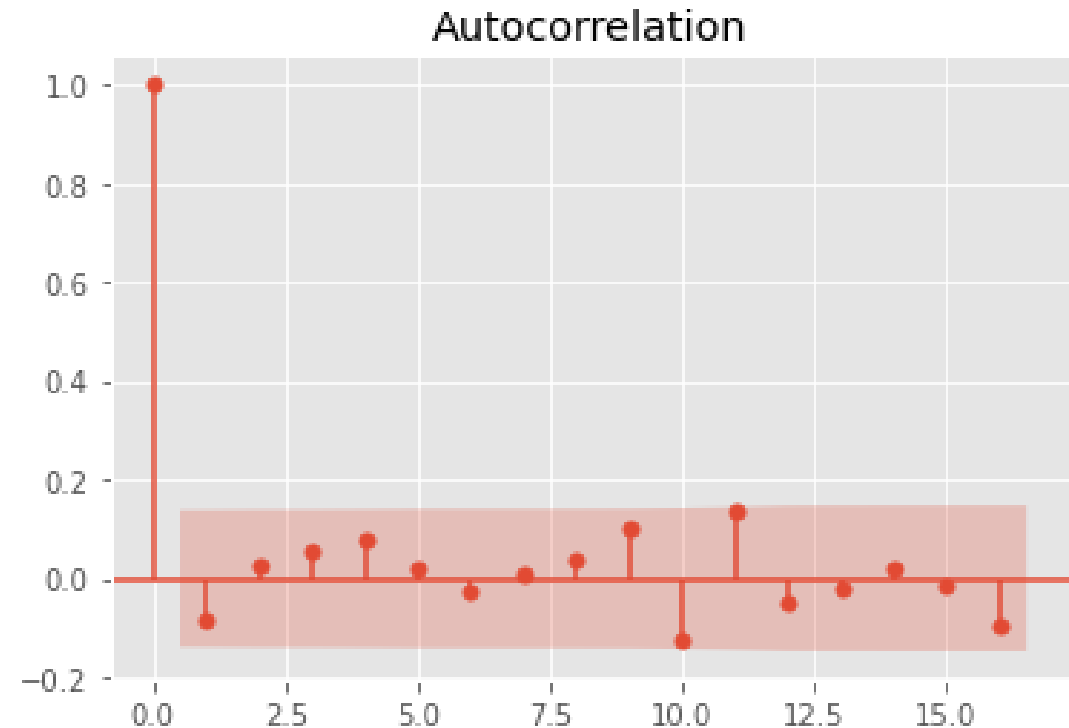
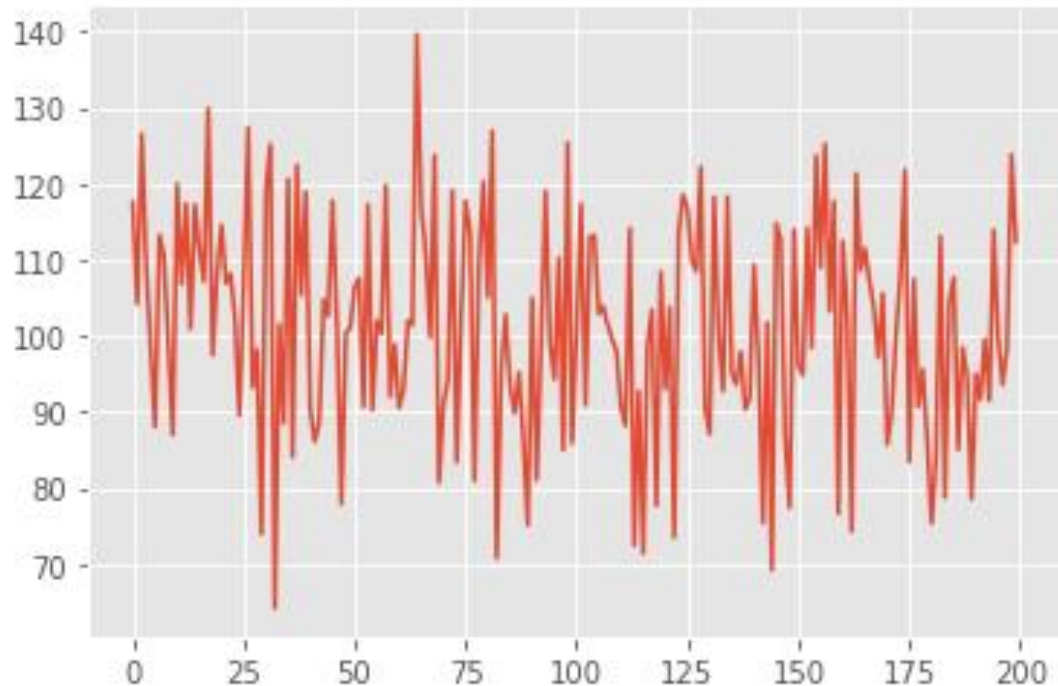
- Sample estimators:
 - For our purposes, we will be interested in the auto-correlation of the process that generates demand: for instance $\text{Corr}(Y_t, Y_{t-1})$ or $\text{Corr}(Y_t, Y_{t-k})$. This looks at the correlation between demand observation separated by k periods (how demand from k periods ago affects the demand today).
 - Note our paired observations are $(y_1, y_{1+k}), (y_2, y_{2+k}), \dots, (y_{n-k}, y_n)$.
 - The k -lag autocorrelation can then be estimated by:

$$r_k = \frac{\sum_{t=k+1}^n (y_t - \bar{y})(y_{t-k} - \bar{y})}{\sum_{t=1}^n (y_t - \bar{y})^2}$$

Auto-Correlation: stationary i.i.d demand

- Recall the simple model: $Y_t = c + \varepsilon_t$. Here's the autocorrelation structure:

The data (generated randomly)



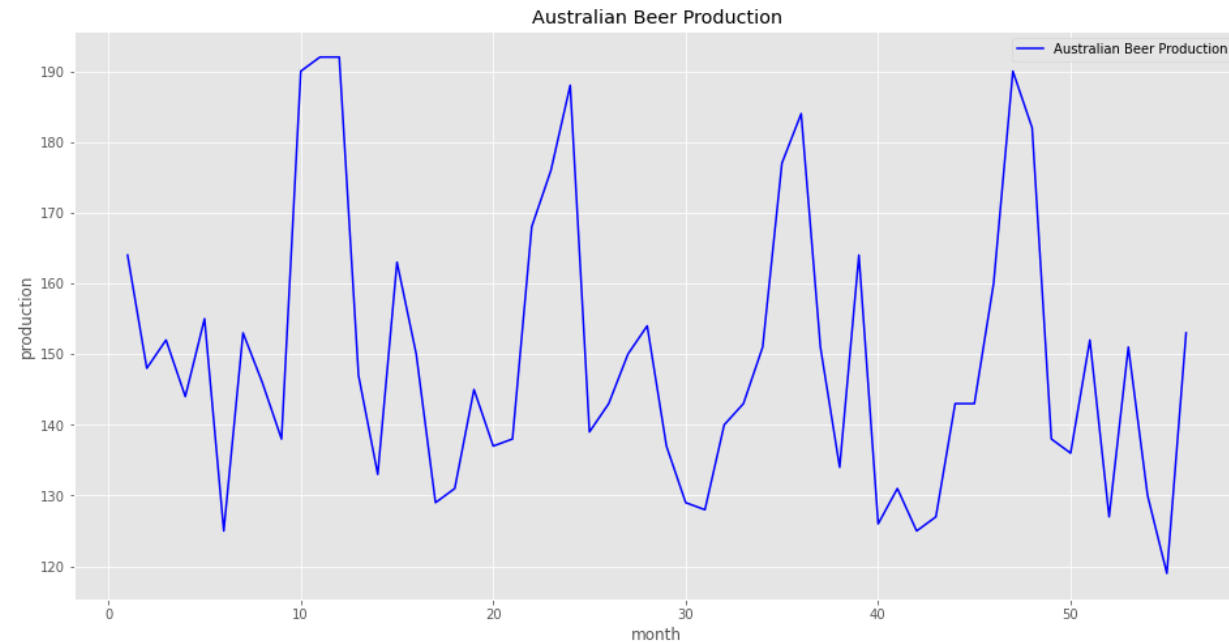
Auto-Correlation: The effects of patterns

- The effect of patterns:
 - We would like to explore the auto-correlation structure of the demand time series to construct models that can take into account the dependence explicitly.
 - First, a relatively trivial observation. All basic patterns in the data (trend, seasonality) etc. reflect onto the autocorrelation structure.
 - To perform any useful autocorrelation analysis, we first have to transform the data to remove the trend, seasonality etc.

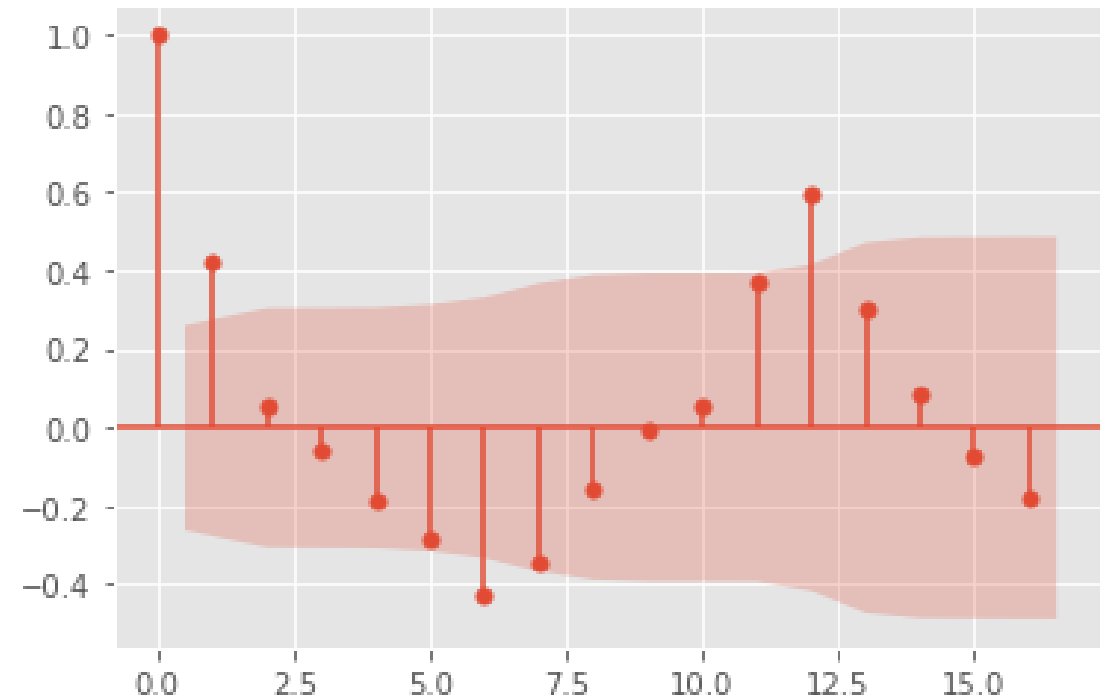
Auto-Correlation: The effects of patterns

- The effect of patterns:

Australian Monthly Beer Production



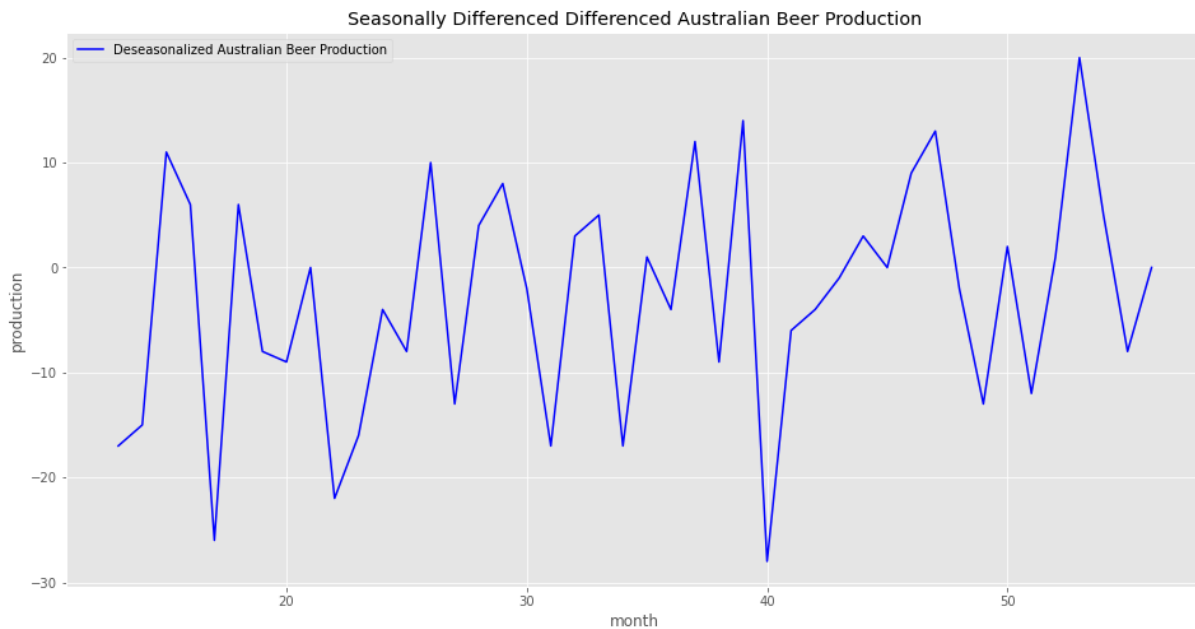
Autocorrelation



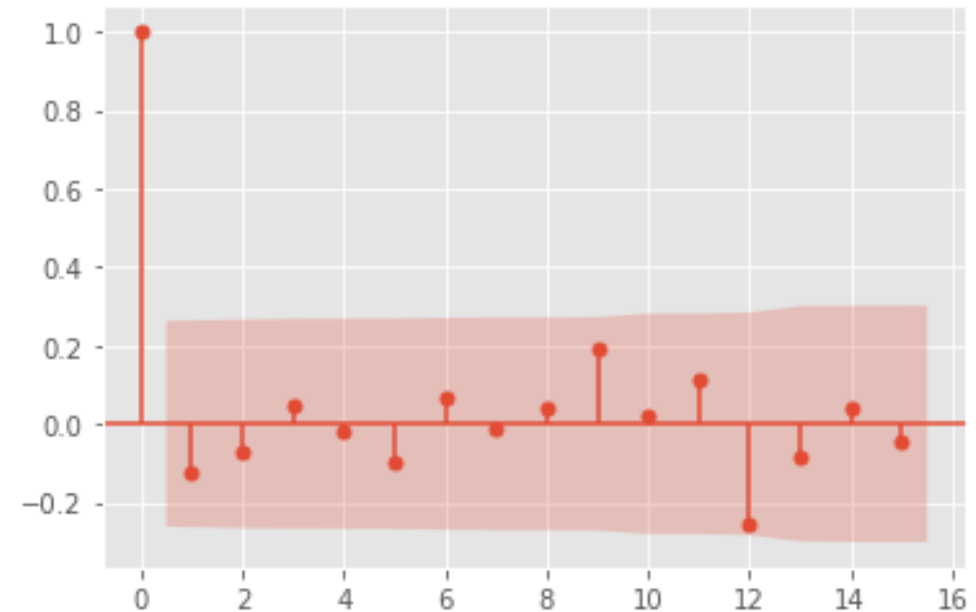
Auto-Correlation: The effects of patterns

- The effect of patterns: deseasonalized Australian Beer Production

Deseasonalized Australian Monthly Beer Production



Autocorrelation



After deseasonalizing no significant AC left. Then taking a simple seasonal difference would be a sufficient forecast.

Auto-Regressive (AR) models

- We started our modeling analysis with demand models that were in the form of $Y_t = f(t) + \epsilon_t$ (where ϵ_t are iid). Note that if we know $f(t)$ or once we figure out the functional form of its pattern from existing data, there is no remaining auto-correlation.
- We'll now consider models with a dependence structure. For instance, the AR model has the following structure:

$$Y_t = c + \phi_1 Y_{t-1} + \phi_2 Y_{t-2} + \dots + \phi_p Y_{t-p} + \epsilon_t$$

This is referred to as an AR- p model since it has p auto-regressive terms. Note that this is different than a typical regression because the right hand side involves terms from the same series (hence auto-regression).

Auto-Regressive models: AR(1)

- Let us consider the simplest model of this type, AR-1

$$Y_t = c + \phi_1 Y_{t-1} + \epsilon_t$$

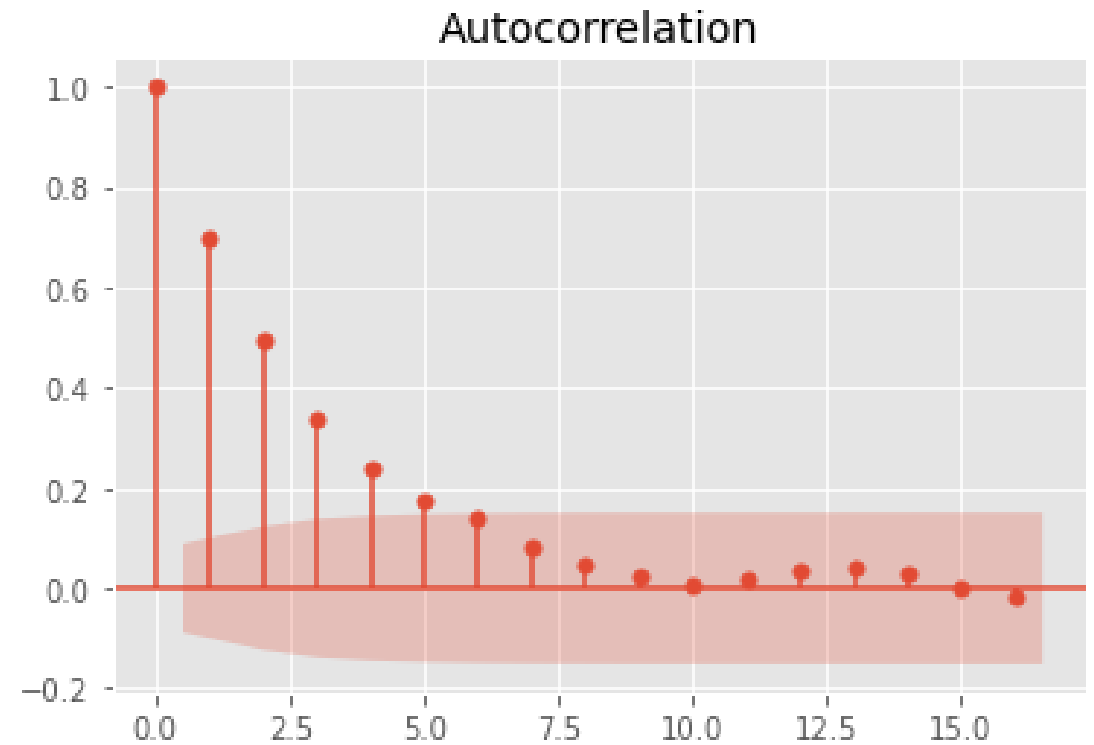
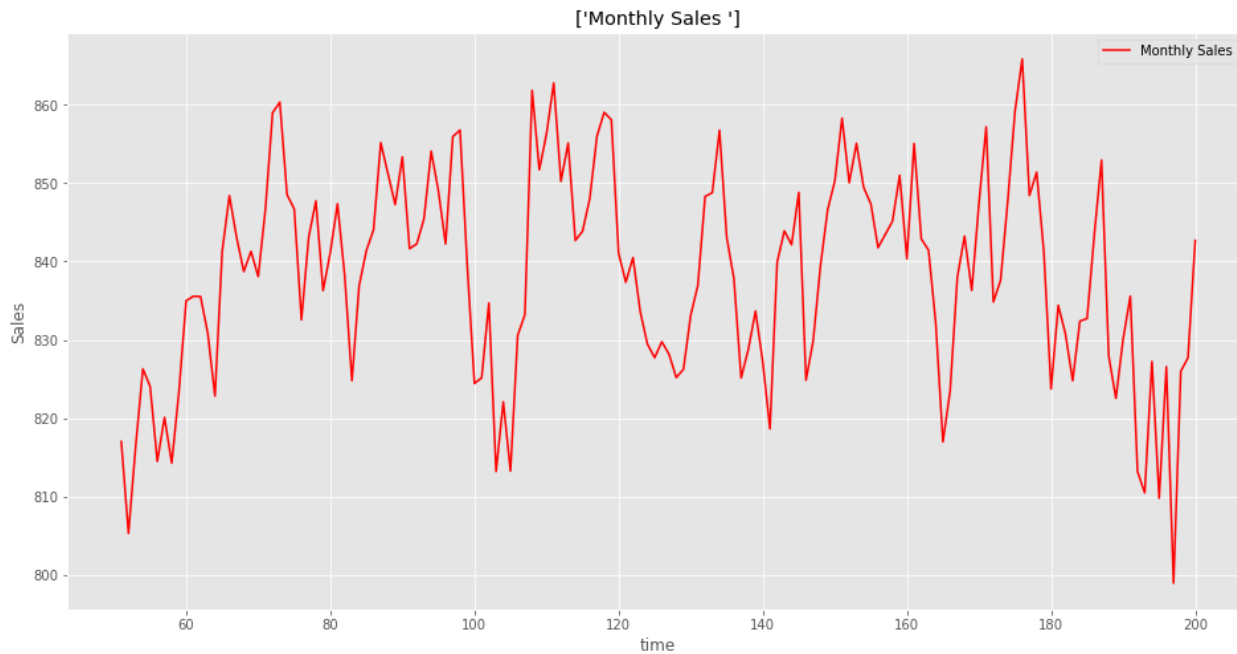
- We can already figure out some of the basic properties. First, we have to have the AR coefficient: $-1 < \phi_1 < 1$, otherwise the series would diverge (in expectation). Note that for general AR-p processes the stability conditions for the parameters are more complicated (please see Hyndman and Athansopoulos, Chapter 8).
- If we take ϕ_1 to be positive and high (i.e. close to 1), it is clear that Y_{t-1} and Y_t are highly correlated. In fact, we can verify that $\text{Corr}(Y_{t-1}, Y_t) = \phi_1$.
- But due to the recursive structure, Y_{t-2} and Y_t are also correlated. In fact, we can verify that $\text{Corr}(Y_{t-2}, Y_t) = \phi_1^2$ and in general $\text{Corr}(Y_{t-k}, Y_t) = \phi_1^k$.

Auto-Regressive models: AR(1)

- If we take ϕ_1 to be negative and high (i.e. close to -1), it is clear that Y_{t-1} and Y_t are highly but negatively correlated (i.e. ϕ close to -1). We know that $\text{Corr}(Y_{t-k}, Y_t) = \phi^k$. Therefore, we have positive AC at even lags and negative AC at odd lags.
- When ϕ is close to +1, the process tends to take high (i.e. above average values) for a number of consecutive periods and then may fall due to the error component, once it falls it tends to stay low for a while.
- When ϕ is close to -1, the process tends to alternate between high and low values in consecutive periods (zigzagging).

AR(1) Examples

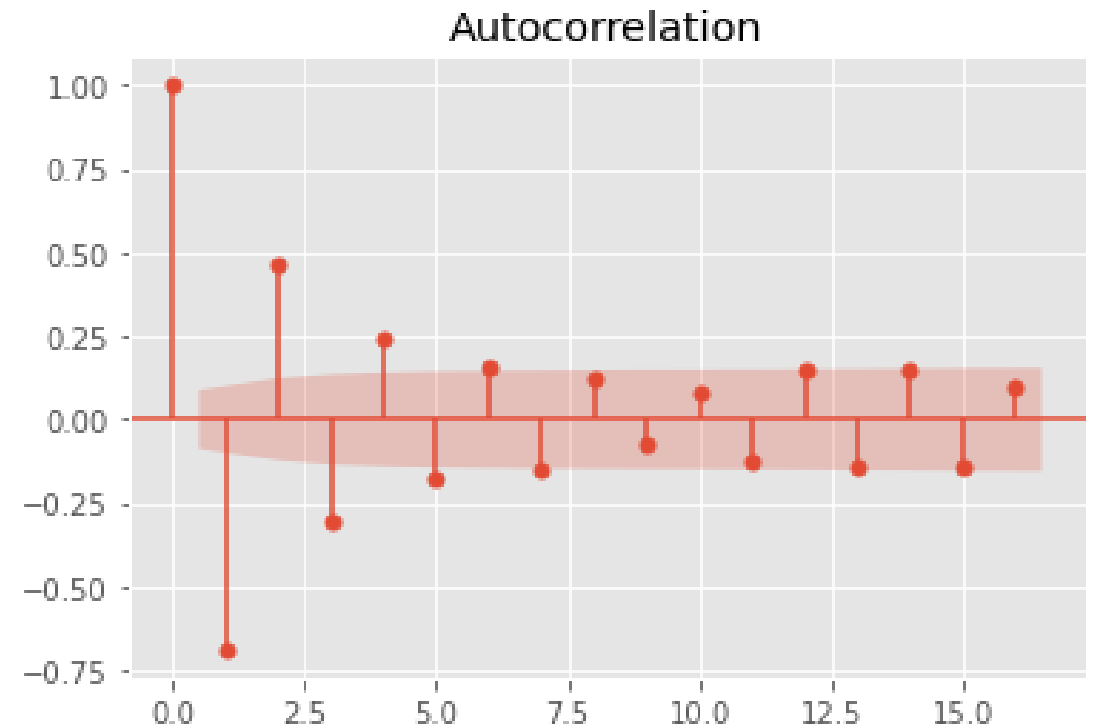
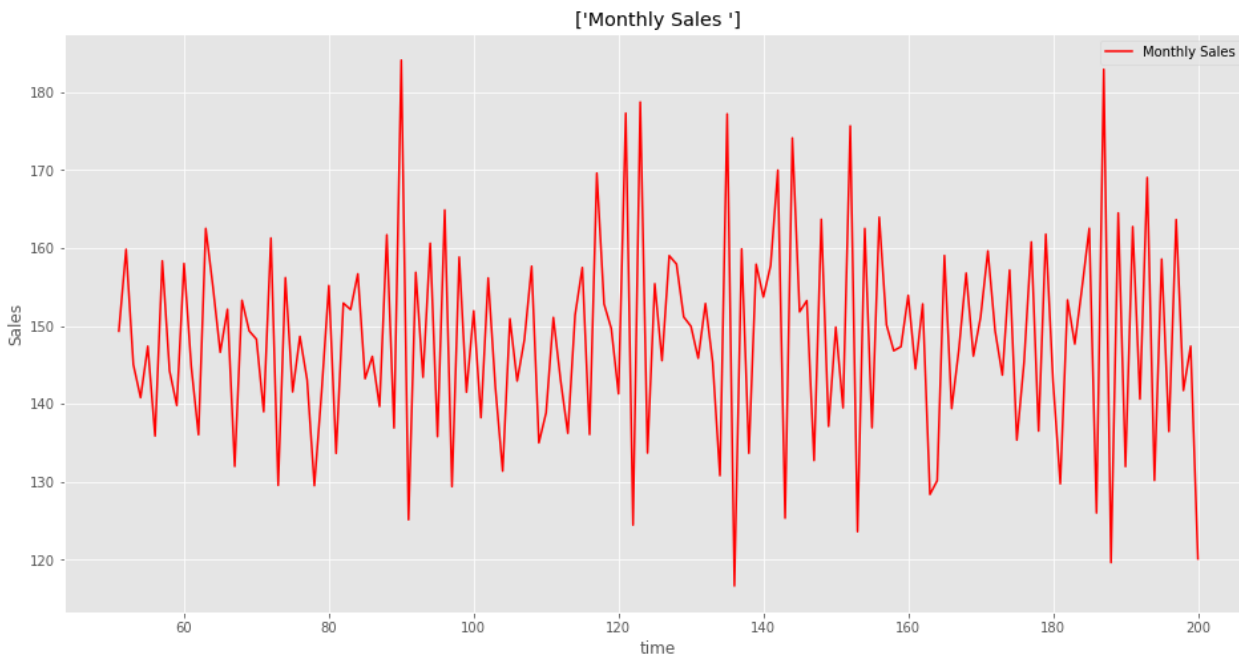
Randomly Generated Data: AR(1) with $\phi_1=0.7$.



Note the geometric decrease in the AC's starting from lag 1.

AR(1) Examples

Randomly Generated Data: AR(1) with $\phi_1 = -0.7$.



This time the AC's geometrically decreasing in absolute value but alternating in sign -,+, - etc.

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- $Y_t = 20 + (0.6)Y_{t-1} + \varepsilon_t$.

Moving Average (MA) models

- The AR-process generates dependence by making Y_t linearly dependent on Y_{t-k} . This is a particular type of dependence. An alternative to this to generate dependence through the error terms. The following process is called a Moving Average (MA)- process:

$$Y_t = c + \theta_1\epsilon_{t-1} + \theta_2\epsilon_{t-2} + \dots + \theta_q\epsilon_{t-q} + \epsilon_t$$

The above is referred to as an MA- q model since it has q MA terms.

- Note that this is considerably different than the AR-process. Y_t can be viewed as a weighted average of past q forecast errors. Depending on the sign of θ_j , the forecast error may have a positive or negative effect on Y_t .

Moving Average (MA) models: MA(1)

- Let us take MA-1

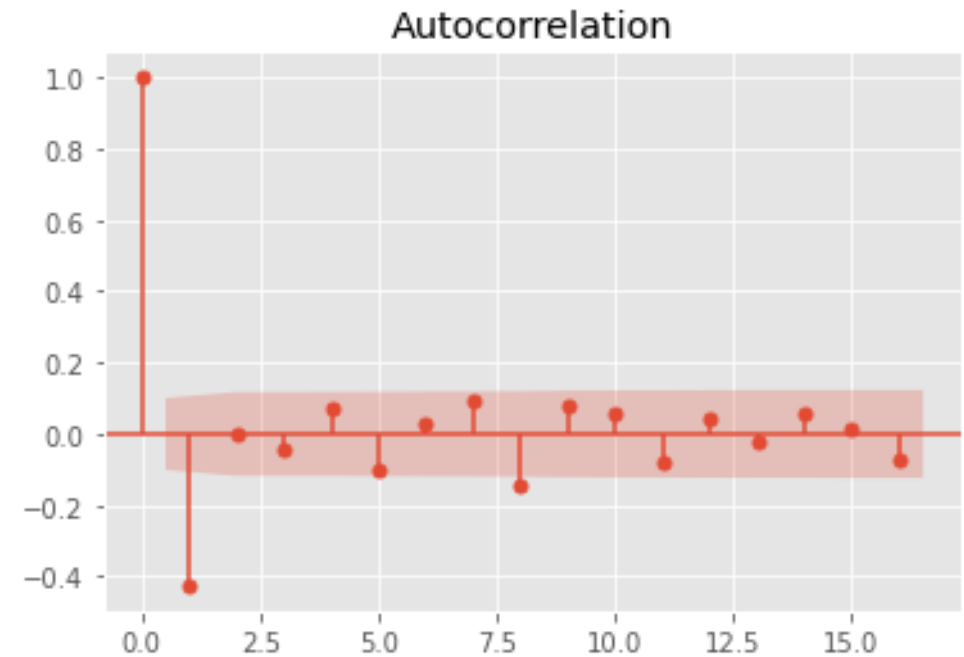
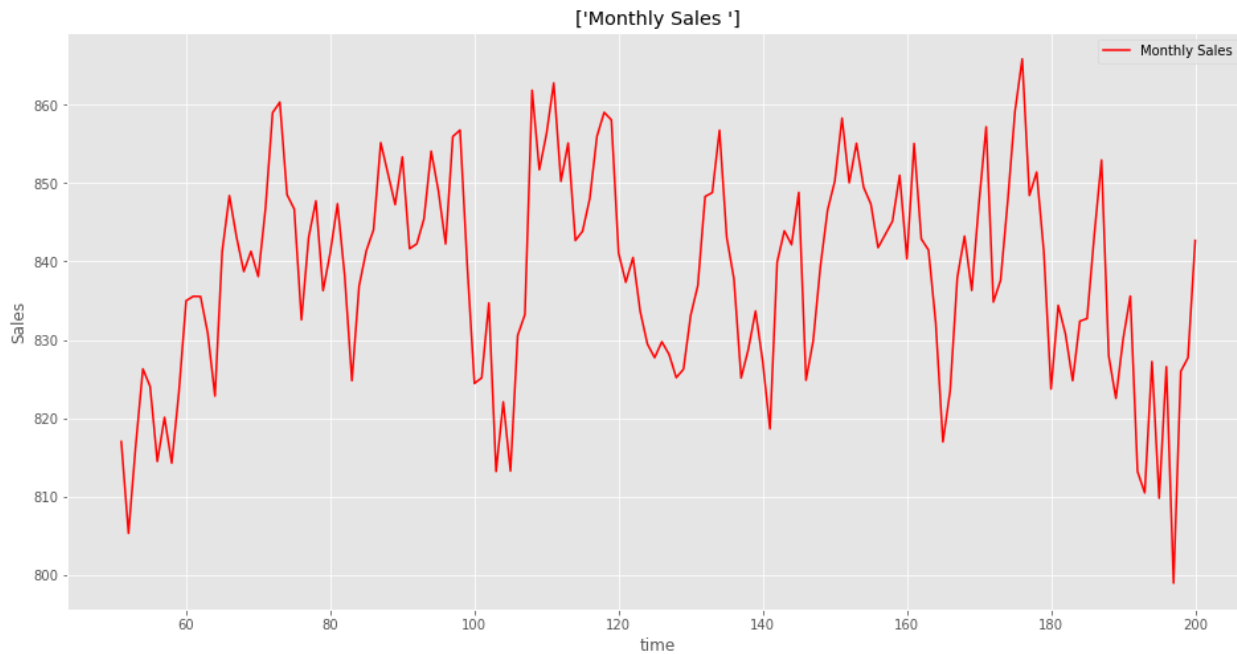
$$Y_t = c + \theta_1 \epsilon_{t-1} + \epsilon_t$$

- First, for stability we need $|\theta_1| < 1$. Once again for general MA-q processes the stability conditions for the parameters are more complicated (please see Hyndman and Athansapoulos, Chapter 8).
- Next, we can verify that Y_{t-1} and Y_t are correlated but Y_{t-2} and Y_t are not. Therefore, the auto-correlation structure is very different than the AR-process.

If θ_1 is positive then AC at lag 1 is negative, if θ_1 is negative then AC at lag 1 is positive.

MA(1) Examples

Randomly Generated Data: MA(1) with $\theta_1=0.7$.



Note that there is a single spike at lag 1 but no geometric decay (AC's at all other lags are insignificant).

ARMA Framework

- We can combine AR-terms and MA-terms. The resulting models are called ARMA and include both AR and MA components.

$$Y_t = c + \phi_1 Y_{t-1} + \phi_2 Y_{t-2} + \dots + \phi_p Y_{t-p} + \theta_1 \epsilon_{t-1} + \theta_2 \epsilon_{t-2} + \dots + \theta_q \epsilon_{t-q} + \epsilon_t$$

This is useful in practice because we need flexible models to fit data. Real auto-correlations rarely correspond to pure AR or MA processes.

ARMA: Mixing AR and MA

- ARMA: mixing AR and MA terms
- Ex: $Y_t = c + \phi_1 Y_{t-1} + \theta_1 \varepsilon_{t-4} + \varepsilon_t$
- A flexible model: Geometrical decrease starting from lag 1 but there is an additional single spike at lag 4.

Model Identification

- We have a fairly rich framework but we need to have a way of guiding the model fitting process.
- As we will see, a good part of model fitting may be automated but we obtain much better results if we can do some preliminary analysis to guide the fitting process.
- How do we identify the correct model (how many AR and MA terms at which lags?)
- This cannot be done by simply plotting the data.
- The ACF plot is useful but we need more help.

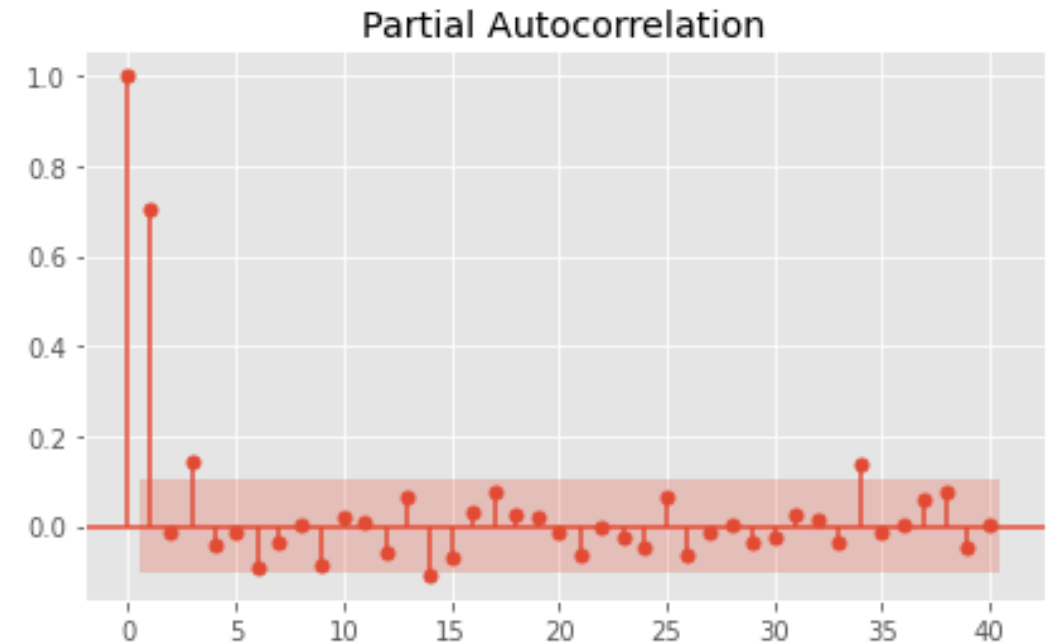
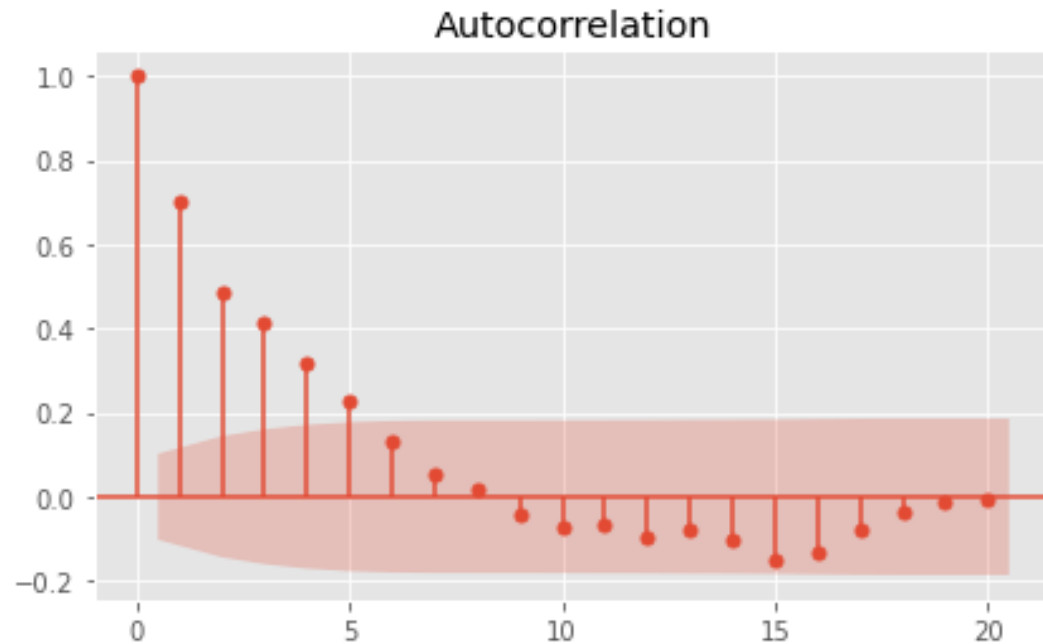
Model Identification: ACF and PACF

- Auto-Correlation Function (ACF) and Partial Auto-Correlation Function (PACF)
- The ACF gives the $\text{Corr}(Y_{t-k}, Y_t)$ as a function of the lag k .
- The PACF is the coefficient that corresponds to the coefficient lag- k when we run a linear regression with lagged observations on the right hand side.
- The ACF and PACF capture different aspects. For instance an AR(1) process has the highest AC at lag 1 but also geometrically decreasing AC's at lags 2, 3 etc. The PA coefficient just takes a non-zero value at lag 1 but there is no PA at other lags.

$$Y_t = c + \phi_1 Y_{t-1} + \epsilon_t$$

AR ACF-PACF patterns

Randomly Generated Data: AR(1) with $\phi_1=0.7$.



Note that the PAC has a spike at lag 1 but vanishes at higher lags.

MA(1) ACF-PCF patterns

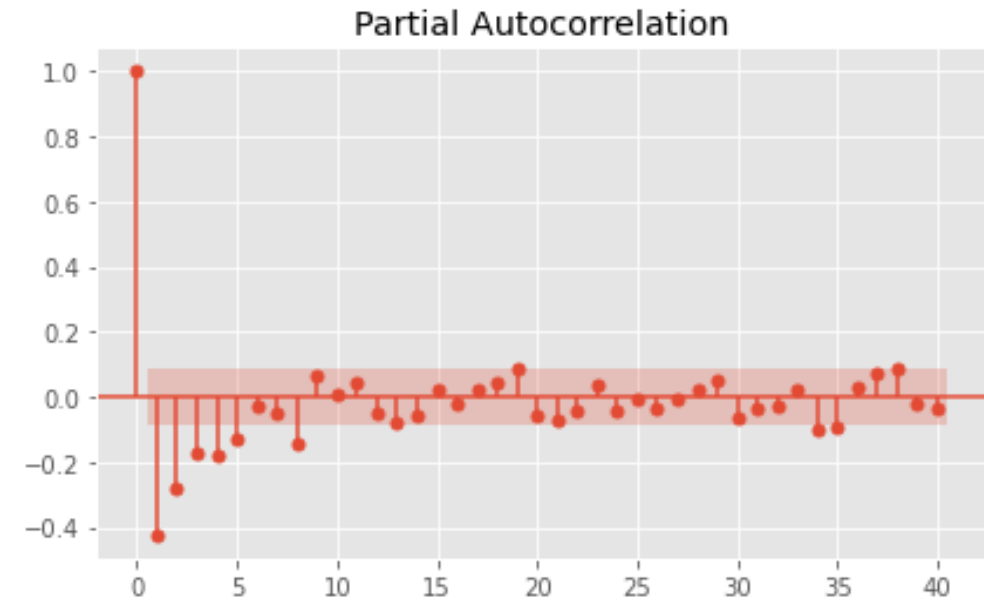
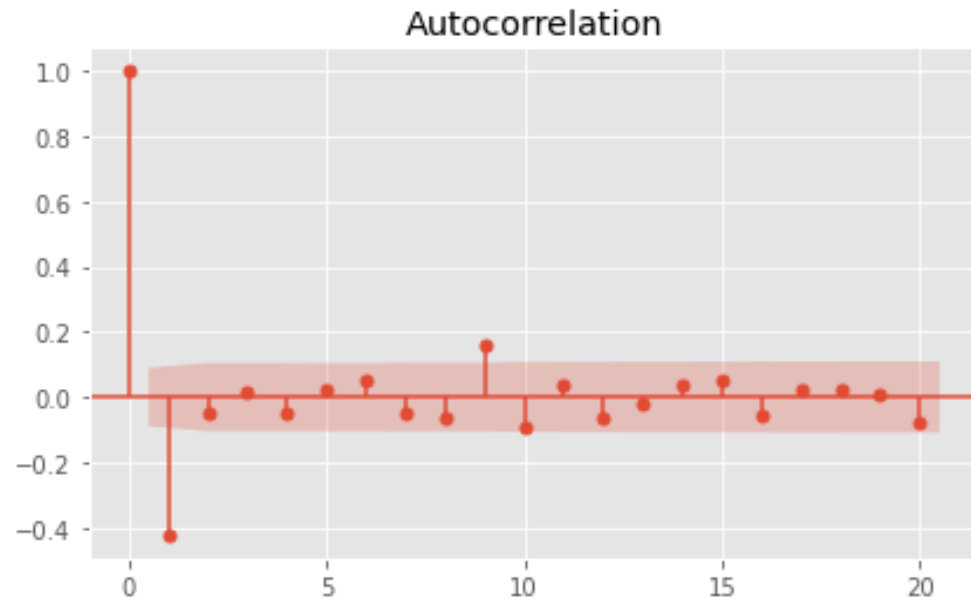
- For an MA(1) process things reverse
- The ACF plot only shows AC at lag 1 but no AC at higher lags.
- The PACF plot shows the highest PAC at lag 1 but also geometrically decreasing PAC's at higher lags.

$$Y_t = c + \theta_1 \epsilon_{t-1} + \epsilon_t$$

- This enables us to distinguish MA and AR patterns from the ACF and PACF.

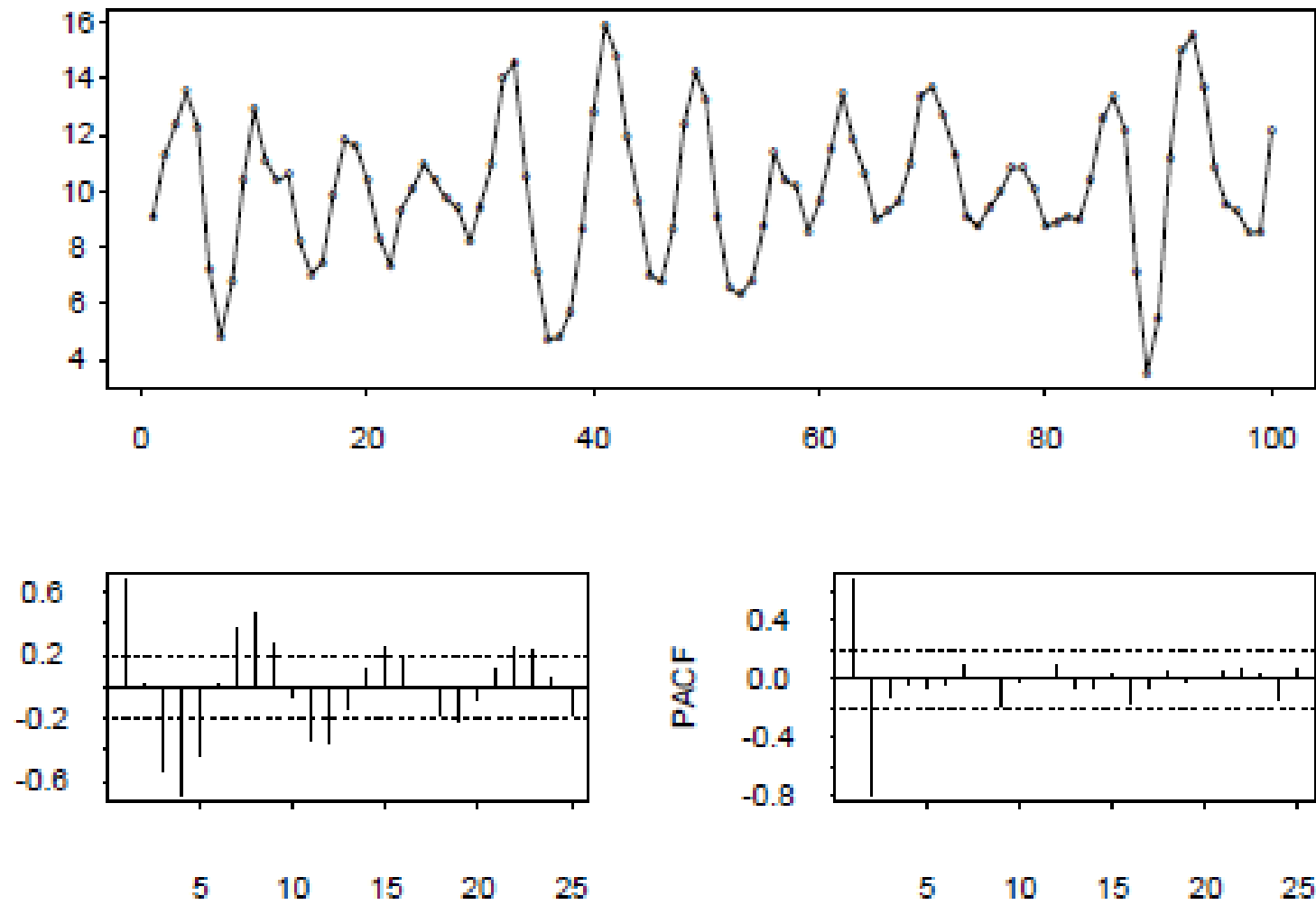
MA(1) ACF-PCF patterns

Randomly Generated Data: MA(1) with $\theta_1 = -0.7$.



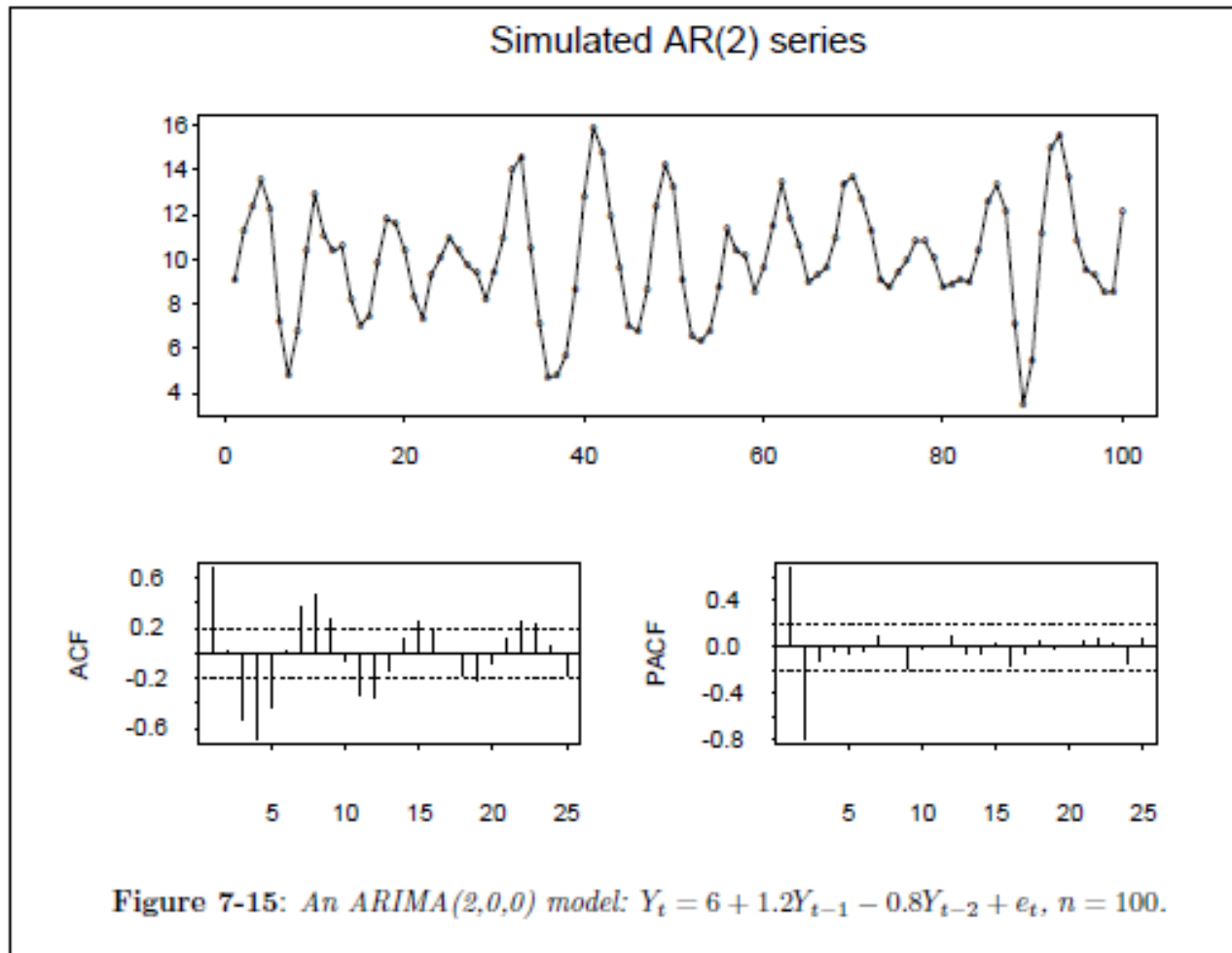
Note the geometric decrease in the PAC this time.

Poll 2



Poll Example: AR (2)

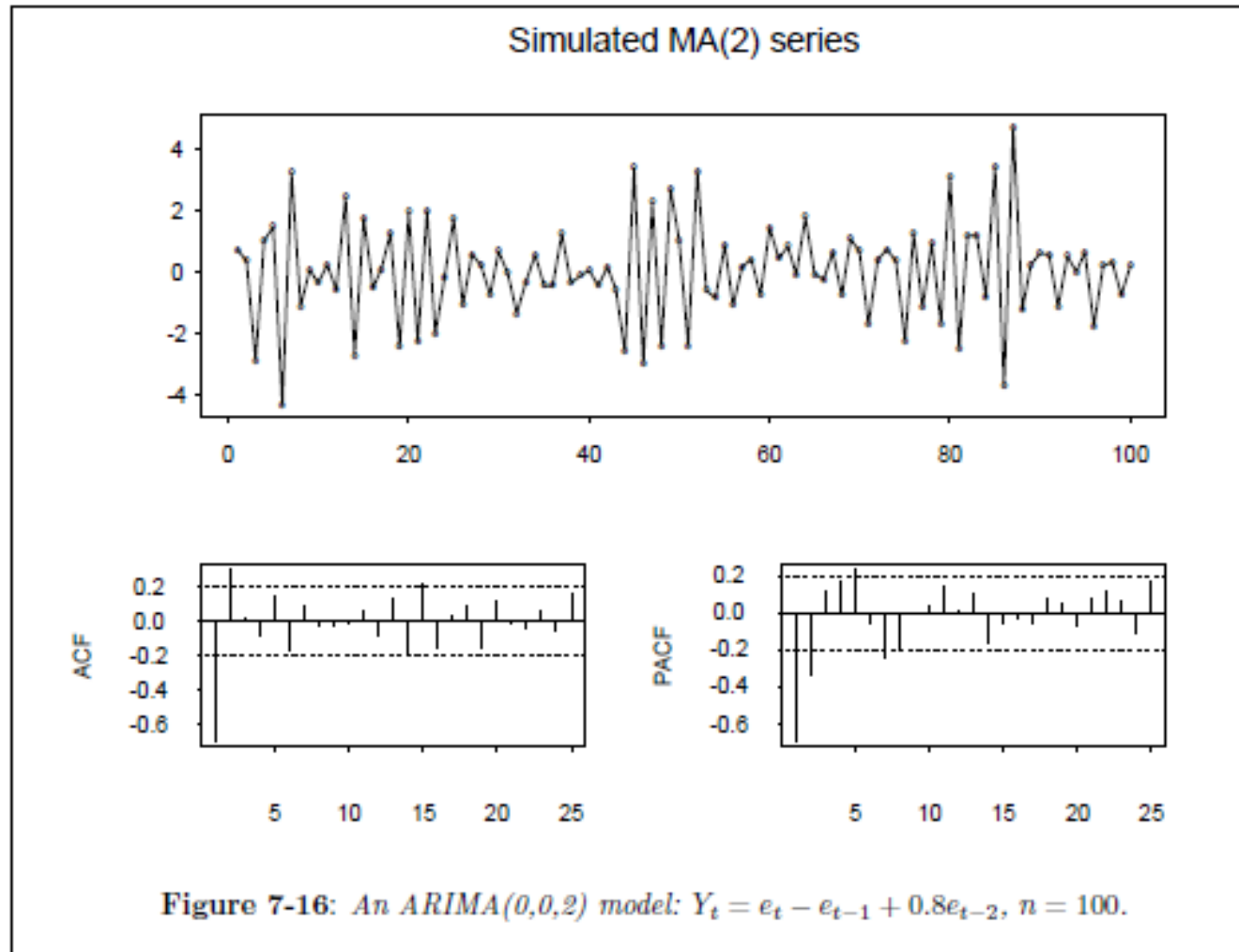
$$Y_t = 6 + 1.2Y_{t-1} - 0.8Y_{t-2} + e_t,$$



It's hard to tell from the ACF, this is AR(2) but with help from PACF we can conclude that it is likely to be AR(2) (two spikes at lags 1 and 2 but no decreasing behavior).

Example: MA (2)

$$Y_t = e_t - e_{t-1} + 0.8e_{t-2}.$$



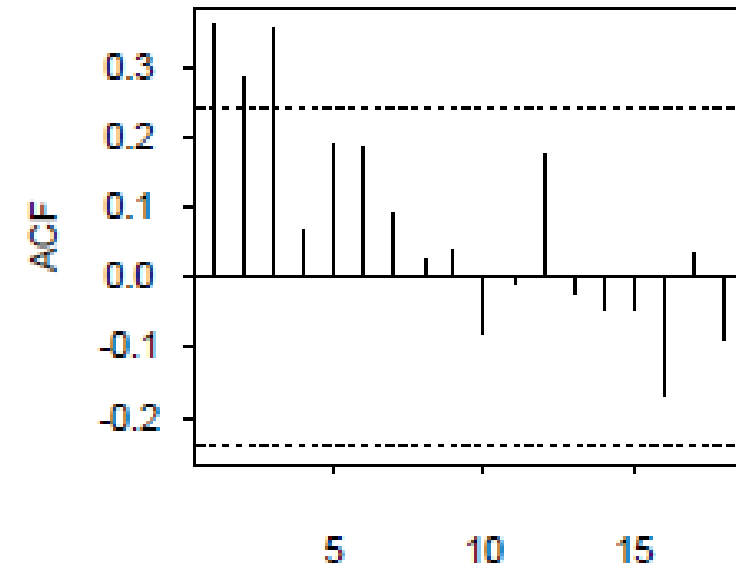
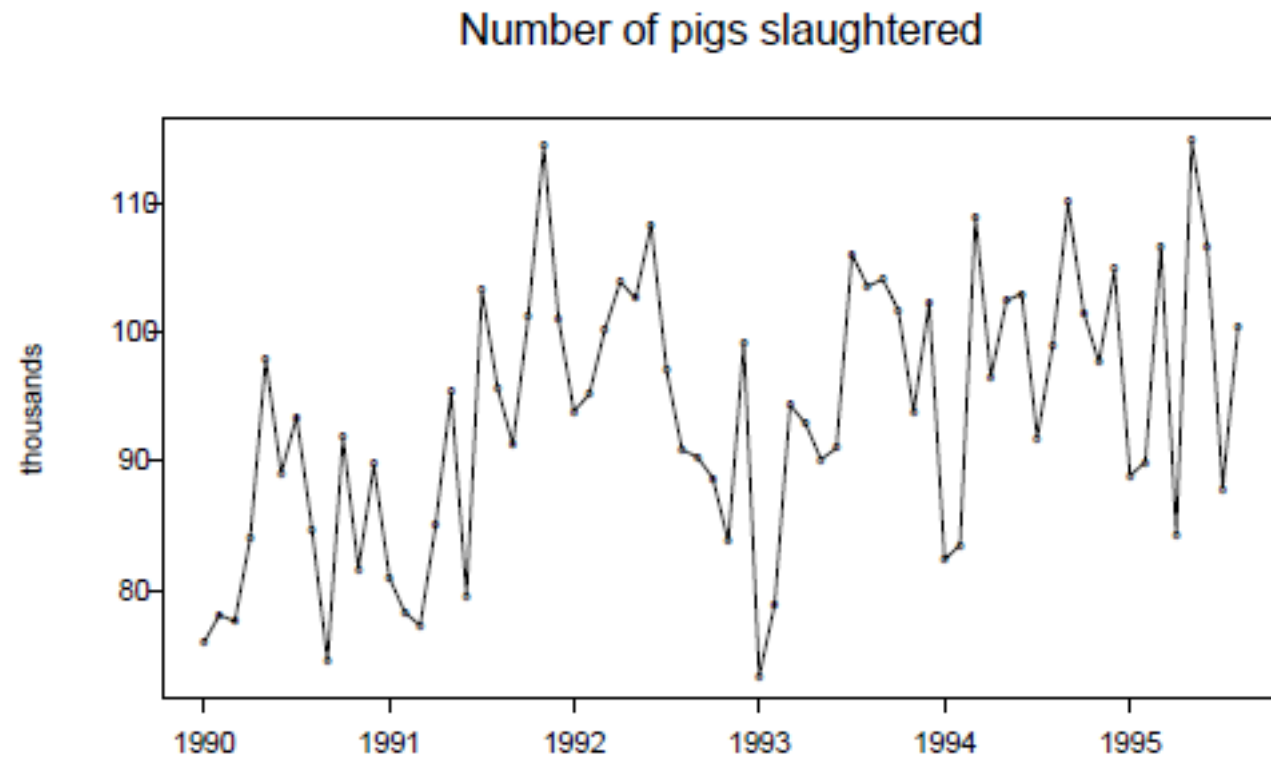
This time the ACF is more helpful.

Summary of ACF and PACF patterns for simple AR and MA models

Process	ACF	PACF
AR(1)	Exponential decay: on positive side if $\phi_1 > 0$ and alternating in sign starting on negative side if $\phi_1 < 0$.	Spike at lag 1, then cuts off to zero: spike positive if $\phi_1 > 0$, negative if $\phi_1 < 0$.
AR(p)	Exponential decay or damped sine-wave. The exact pattern depends on the signs and sizes of ϕ_1, \dots, ϕ_p .	Spikes at lags 1 to p , then cuts off to zero.
MA(1)	Spike at lag 1 then cuts off to zero: spike positive if $\theta_1 < 0$, negative if $\theta_1 > 0$.	Exponential decay: on negative side if $\theta_1 > 0$ and alternating in sign starting on positive side if $\theta_1 < 0$.
MA(q)	Spikes at lags 1 to q , then cuts off to zero.	Exponential decay or damped sine-wave. The exact pattern depends on the signs and sizes of $\theta_1, \dots, \theta_q$.

Table 7-2: *Expected patterns in the ACF and PACF for simple AR and MA models.*

Example: Number of Pigs Slaughtered



Maybe:

But the PACF would be helpful