

1.  $\vec{E}_0 = \hat{x} E_0$

$$\vec{E}_{in} = \vec{E} - \vec{E}_{out}$$

$$\vec{P}_{in} = -3\epsilon_0 \vec{E}_{in}$$

$$\vec{D}_{in} = \epsilon_0 \vec{E}_{in} + \vec{P}_{in}$$

2. infinity에서 potential 이 0 이라면,  
point charge  $Q$ 의 에너지는  $W = QV(r)$  이다.

$$U = q(V(\vec{r} + \vec{d}) - V(\vec{r})) = q(V(\vec{r} + \vec{d}) - V(\vec{r}))$$

$$= q \left[ - \int_{\vec{r}}^{\vec{r} + \vec{d}} \vec{E} \cdot d\vec{l} \right]$$

for an ideal dipole,

$$U = -q \vec{E} \cdot \vec{d} = -\vec{p} \cdot \vec{E} \quad (\because \vec{p} = q\vec{d})$$

infinity에서 potential 이 0 이 아니게 하면,

$$W = Q(V(\vec{r}) - V(\vec{r}_0))$$

$$U = q(V(\vec{r} + \vec{d}) - V(\vec{r}_0)) - q(V(\vec{r}) - V(\vec{r}_0))$$

$$= q(V(\vec{r} + \vec{d}) - V(\vec{r})) = -q \vec{E} \cdot \vec{d} = -\vec{p} \cdot \vec{E}$$

3.  $U = -\vec{p}_1 \cdot \vec{E}_2$

$$\vec{E}_2 = \frac{1}{4\pi\epsilon_0} \frac{1}{r^3} (3(\vec{p}_2 \cdot \hat{r})\hat{r} - \vec{p}_2)$$

$$U = \frac{1}{4\pi\epsilon_0} \frac{1}{r^3} (\vec{p}_1 \cdot \vec{p}_2 - 3(\vec{p}_1 \cdot \hat{r})(\vec{p}_2 \cdot \hat{r}))$$



4.

$$i) \rho_b = -\nabla \cdot \vec{P} = -\frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{k}{r} \right) = -\frac{k}{r^2}$$

$$\sigma_b = \vec{P} \cdot \hat{n} = \begin{cases} +\vec{P} \cdot \hat{r} = k/b & (\text{at } r=b) \\ -\vec{P} \cdot \hat{r} = -k/a & (\text{at } r=a) \end{cases}$$

$$\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{Q_{enc}}{r^2} \hat{r}$$

$$\text{for } r < a \quad Q_{enc} = 0, \quad \vec{E} = 0$$

$$\text{for } r > b \quad Q_{enc} = 0 \quad \vec{E} = 0$$

$$\begin{aligned} \text{for } a < r < b \quad Q_{enc} &= -\frac{k}{a} (4\pi a^2) + \int_a^r \left( -\frac{k}{r^2} \right) 4\pi r^2 dr \\ &= -4\pi k a - 4\pi k (r-a) = -4\pi k r \end{aligned}$$

$$\vec{E} = -\frac{k}{\epsilon_0 r} \hat{r}$$

$$ii) \oint \vec{D} \cdot d\vec{a} = Q_{enc} = 0$$

$$\Rightarrow \vec{D} = 0$$

$$\vec{D} = \epsilon_0 \vec{E} + \vec{P} = 0 \Rightarrow \vec{E} = -\frac{1}{\epsilon_0} \vec{P}$$

$$\text{for } r < a \text{ and } r > b, \quad \vec{E} = 0$$

$$\text{for } a < r < b \quad \vec{E} = -\frac{k}{\epsilon_0 r} \hat{r}$$

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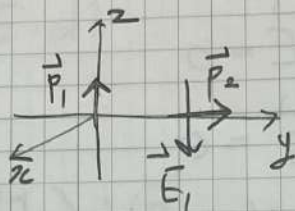
5.

$$(a) \vec{F}_2 = (\vec{p}_2 \cdot \nabla) \vec{E}_1 = p_2 \frac{\partial}{\partial y} \vec{E}_1$$

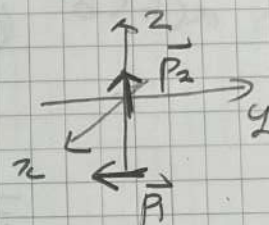
$$\vec{E}_1 = \frac{p_1}{4\pi\epsilon_0 y^3} \hat{y} = -\frac{p_1}{4\pi\epsilon_0 y^3} \hat{z}$$

$$\vec{F}_2 = -\frac{p_1 p_2}{4\pi\epsilon_0} \left( \frac{\partial}{\partial y} \left( \frac{1}{y^3} \right) \right) \hat{z} = \frac{3p_1 p_2}{4\pi\epsilon_0 y^4} \hat{z}$$

$$\text{or} \quad \vec{F}_2 = \frac{3p_1 p_2}{4\pi\epsilon_0 r^4} \hat{z}$$



To calculate  $\vec{F}_1$ , put  $\vec{p}_1$  and  $\vec{p}_2$  like this  $\rightarrow$



$$\vec{F}_1 = (\vec{p}_1 \cdot \nabla) \vec{E}_2 = -p_1 \frac{\partial \vec{E}_2}{\partial y} \Big|_{x=y=0, z=-r}$$

$$\vec{E}_2 = \frac{1}{4\pi\epsilon_0 r^3} \left( \frac{3(\vec{p}_2 \cdot \vec{r})\vec{r}}{r^2} - \vec{p}_2 \right) \text{ where } \vec{r} = x\hat{x} + y\hat{y} + z\hat{z}$$

$$\vec{p}_2 = p_2 \hat{z}$$

$$\vec{E}_2 = \frac{p_2}{4\pi\epsilon_0} \left( \frac{3z(z\hat{x} + y\hat{y} + z\hat{z}) - (x^2 + y^2 + z^2)\hat{z}}{(x^2 + y^2 + z^2)^{3/2}} \right)$$

$$\frac{\partial \vec{E}_2}{\partial y} = \frac{p_2}{4\pi\epsilon_0} \left( -\frac{5}{2} \frac{zy}{r^7} (3xz\hat{x} + 3yz\hat{y} - (x^2 + y^2 - 2z^2)\hat{z}) + \frac{1}{r^5} (3z\hat{y} - 2yz\hat{z}) \right)$$

$$\frac{\partial \vec{E}_2}{\partial y} \Big|_{(0,0)} = \frac{p_2}{4\pi\epsilon_0} \frac{3z}{r^5} \hat{y}, \quad \vec{F}_1 = -p_1 \left( \frac{p_2}{4\pi\epsilon_0} \frac{3r}{r^5} \hat{y} \right) = \frac{3p_1 p_2}{4\pi\epsilon_0 r^4} \hat{y}$$

$\hat{y}$  is correspond to  $-\hat{z}$  in the original system, so

these results are consistent with  $\vec{F}_1 = -\vec{F}_2$  (Newton's third law)



$$(b) \quad \vec{N}_2 = (\vec{p}_2 \times \vec{E}_1) + (\vec{r} \times \vec{F}_2)$$

$$\vec{p}_2 \times \vec{E}_1 = \frac{p_1 p_2}{4\pi\epsilon_0 r^3} (-\hat{x}) \quad (\text{in Prob. 4.5})$$

$$\vec{r} \times \vec{F}_2 = (\hat{y}) \times \left( \frac{3p_1 p_2}{4\pi\epsilon_0 r^4} \hat{z} \right) = \frac{3p_1 p_2}{4\pi\epsilon_0 r^3} \hat{x}$$

$$\vec{N}_2 = \frac{2p_1 p_2}{4\pi\epsilon_0 r^3} \hat{x}$$

this is equal and opposite direction to the torque on  $\vec{p}_1$  due to  $\vec{p}_2$ .

$$6. (a) \quad \vec{F} = \alpha (\vec{E} \cdot \nabla) \vec{E}$$

$$\nabla E^2 = \nabla (\vec{E} \cdot \vec{E}) = 2\vec{E} \times (\nabla \times \vec{E}) + 2(\vec{E} \cdot \nabla) \vec{E}$$

$$\nabla \times \vec{E} = 0 \Rightarrow (\vec{E} \cdot \nabla) \vec{E} = \frac{1}{2} \nabla (E^2)$$

$$\vec{F} = \frac{1}{2} \alpha \nabla (E^2)$$

(b) suppose  $E^2$  has a local maximum at point P.

Then, there's a sphere about P such that  $E^2(P') < E^2(P)$

and  $|\vec{E}(P')| < |\vec{E}(P)|$  for all points on the surface.

But, if there's no charge inside sphere, the average field is equal to field at center,

$$\frac{1}{4\pi R^2} \oint \vec{E} \cdot d\vec{a} = \vec{E}(P)$$

$$\frac{1}{4\pi R^2} \int E_z \, da = E(P) \quad (\text{choosing the } z \text{ axis to lie along } \vec{E}(P))$$

$E^2$  is max at P,

$$\int E_z \, da \leq \int |\vec{E}| \, da < \int |\vec{E}(P)| \, da = 4\pi R^2 E(P) \Rightarrow \underline{E(P) < E(P)} \quad \text{contradiction!}$$



7.  $\vec{E}^{\parallel}$  is continuous,  $D_{\perp}$  is continuous,

$$E_{x1} = E_{x2}, \quad P_{y1} = P_{y2}$$

$$\epsilon_1 E_{y1} = \epsilon_2 E_{y2}$$

$$\text{So, } \frac{\tan \theta_2}{\tan \theta_1} = \frac{E_{x2}/E_{y2}}{E_{x1}/E_{y1}} = \frac{E_{y1}}{E_{y2}} = \frac{\epsilon_2}{\epsilon_1}$$

8. the net dipole moment at the center is,

$$\vec{p}' = \vec{p} - \frac{\chi_e}{1+\chi_e} \vec{p} = \frac{1}{1+\chi_e} \vec{p} = \frac{1}{\epsilon_r} \vec{p}$$

We want the potential produced by  $\vec{p}'$  and  $G_b$

Using separation of variables,

$$\left\{ \begin{array}{l} \text{Outside } V(r, \theta) = \sum_{l=0}^{\infty} \frac{B_l}{r^{l+1}} P_l(\cos \theta) \\ \text{Inside } V(r, \theta) = \frac{1}{4\pi\epsilon_0} \frac{p \cos \theta}{\epsilon_r r^2} + \sum_{l=0}^{\infty} A_l r^l P_l(\cos \theta) \end{array} \right\}$$

$$V \text{ continuous at } R \Rightarrow \left\{ \begin{array}{l} \frac{B_l}{R^{l+1}} = A_l R^l \\ \frac{B_l}{R^2} = \frac{1}{4\pi\epsilon_0} \frac{p}{\epsilon_r R^2} + A_l R \end{array} \right.$$

$$\begin{aligned} \left. \frac{\partial V}{\partial r} \right|_{R+} - \left. \frac{\partial V}{\partial r} \right|_{R-} &= -\sum (2l+1) \frac{B_l}{R^{l+2}} P_l(\cos \theta) + \frac{1}{4\pi\epsilon_0} \frac{2p \cos \theta}{\epsilon_r R^3} \\ &\quad - \sum 2A_l R^{l-1} P_l(\cos \theta) = -\frac{1}{\epsilon_0} G_b \\ &= -\frac{1}{\epsilon_0} \vec{p}' \cdot \hat{r} = -\frac{1}{\epsilon_0} (\epsilon_0 \chi_e \vec{E} \cdot \hat{r}) = \chi_e \left. \frac{\partial V}{\partial r} \right|_{R-} \\ &= \chi_e \left( -\frac{1}{4\pi\epsilon_0} \frac{2p \cos \theta}{\epsilon_r R^3} + \sum 2A_l R^{l-1} P_l(\cos \theta) \right) \end{aligned}$$



$$-(2l+1) \frac{B_2}{R^{2l+2}} - 2A_2 R^{2l-1} = \chi_e 2A_2 R^{2l-1} (2l+1)$$

or

$$-(2l+1)A_2 R^{2l-1} = \chi_e 2A_2 R^{2l-1} \Rightarrow A_2 = 0 \quad (l \neq 1)$$

For  $l=1$ ,

$$-2 \frac{B_1}{R^3} + \frac{1}{4\pi\epsilon_0} \frac{2p}{\epsilon_r R^3} - A_1 = \chi_e \left( -\frac{1}{4\pi\epsilon_0} \frac{2p}{\epsilon_r R^3} + A_1 \right) - B_1 + \frac{p}{4\pi\epsilon_0 \epsilon_r} - \frac{A_1 R^3}{2}$$

$$= -\frac{1}{4\pi\epsilon_0} \frac{\chi_e p}{\epsilon_r} + \chi_e \frac{A_1 R^3}{2}$$

$$-\frac{p}{4\pi\epsilon_0 \epsilon_r} - A_1 R^3 + \frac{p}{4\pi\epsilon_0 \epsilon_r} - \frac{A_1 R^3}{2} = -\frac{1}{4\pi\epsilon_0} \frac{\chi_e p}{\epsilon_r} + \chi_e \frac{A_1 R^3}{2}$$

$$\Rightarrow \frac{A_1 R^3}{2} (3 + \chi_e) = \frac{1}{4\pi\epsilon_0} \frac{\chi_e p}{\epsilon_r}$$

$$\Rightarrow A_1 = \frac{1}{4\pi\epsilon_0} \frac{2\chi_e p}{R^3 \epsilon_r (3 + \chi_e)} = \frac{1}{4\pi\epsilon_0} \frac{2(\epsilon_r - 1)p}{R^3 \epsilon_r (\epsilon_r + 2)}$$

$$B_1 = \frac{p}{4\pi\epsilon_0 \epsilon_r} \left( 1 + \frac{2(\epsilon_r - 1)}{\epsilon_r + 2} \right) = \frac{p}{4\pi\epsilon_0 \epsilon_r} \frac{3\epsilon_r}{\epsilon_r + 2}$$

$$V(r, \theta) = \left( \frac{p \cos \theta}{4\pi\epsilon_0 r^2} \right) \left( \frac{3}{\epsilon_r + 2} \right) \quad (r \geq R)$$

$$\text{for } r \leq R, \quad V(r, \theta) = \frac{1}{4\pi\epsilon_0} \frac{p \cos \theta}{\epsilon_r r^2} + \frac{1}{4\pi\epsilon_0} \frac{p \cos \theta}{R^3} \frac{2(\epsilon_r - 1)}{\epsilon_r (\epsilon_r + 2)}$$

$$= \frac{p \cos \theta}{4\pi\epsilon_0 r^2 \epsilon_r} \left( 1 + 2 \left( \frac{\epsilon_r - 1}{\epsilon_r + 2} \right) \frac{r^3}{R^3} \right) \quad (r \leq R)$$