

## Part 2

In order to record my voice I used the MATLAB's built in function "audiorecorder" in the following MATLAB code:

```
clc
clear all
Fs = 8192;
record=audiorecorder(Fs,16,1);
disp('started')
recordblocking(record,12);
disp('ended');
x=transpose(getaudiodata(record));
```

My speech was:

*"Hala kapkara su  
Hep aynı derinlikte  
Gökyüzü kadar soğuk  
Sesin duyulmaz olduğunda  
Yüreğim kadar hareketsiz  
Cehennemde donacağım"*

Answers to the questions are below:

$$y(t) = x(t) + \sum_{i=1}^m A_i x(t-t_i)$$

a)  $h(t)$  is the impulse response of the system. So  $x(t) = \delta(t)$

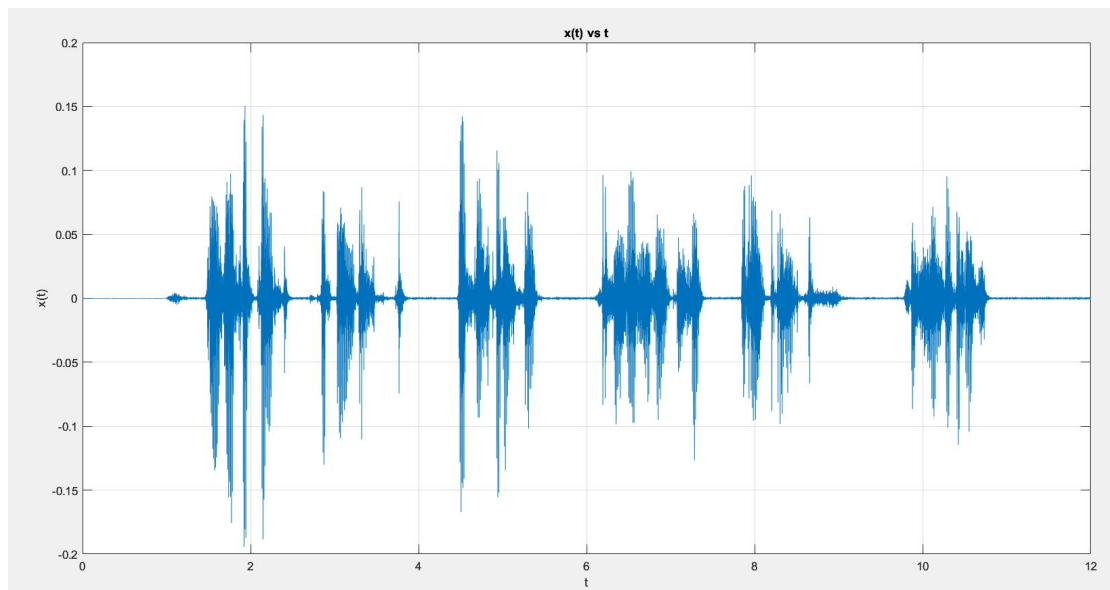
$$h(t) = \delta(t) + \sum_{i=1}^m A_i \delta(t-t_i)$$

b)  $F\{\delta(t)\} = 1$  and time shift in time domain is multiplying complex exponential in frequency domain. FT is linear. Therefore, using this properties FT of  $h(t)$  can be found as:

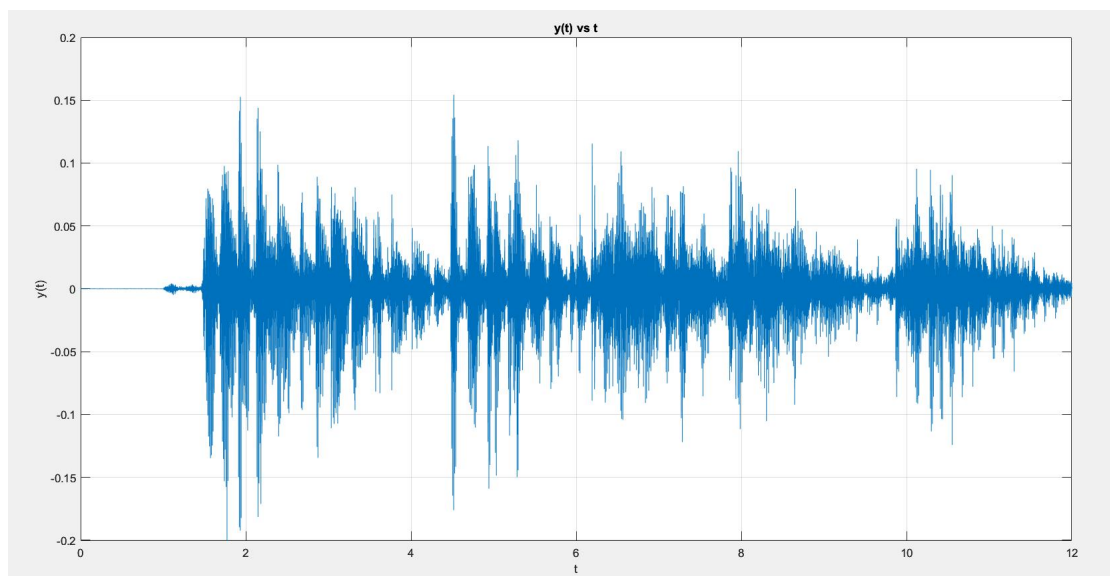
$$H(\omega) = 1 + \sum_{i=1}^m A_i e^{-j\omega t_i}$$

c) Since  $y(t) = x(t) * h(t)$  means  $Y(\omega) = X(\omega) \cdot H(\omega)$  in frequency domain. i.e. convolution in time domain corresponds to multiplication in freq. domain.

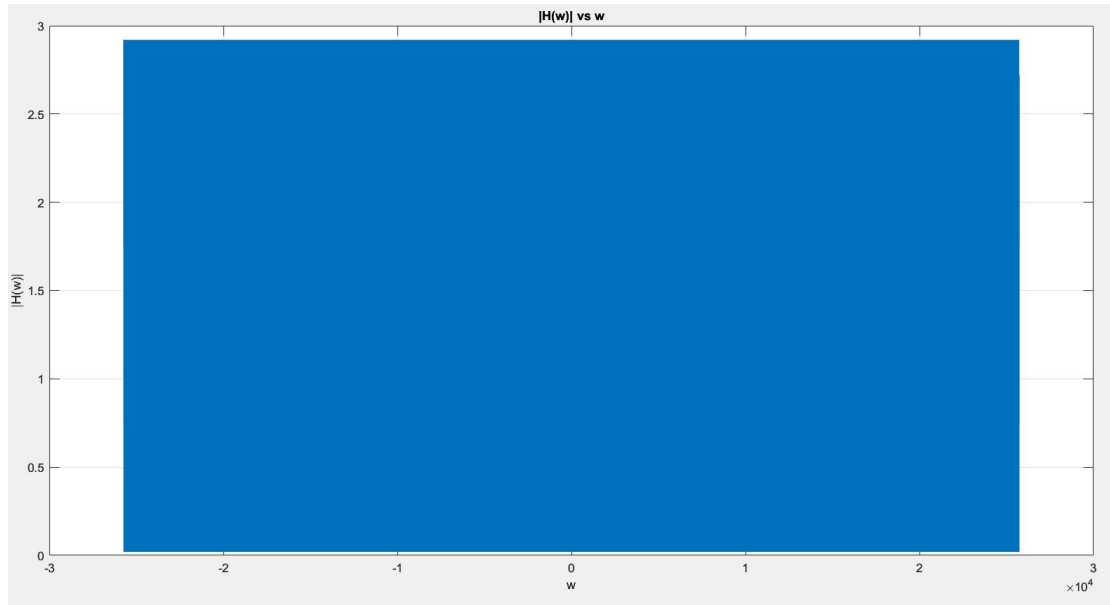
d) So from the result in part c  $X(\omega) = \frac{Y(\omega)}{H(\omega)}$ , this means if we know  $Y(\omega)$  and  $H(\omega)$  we can find  $X(\omega)$ .



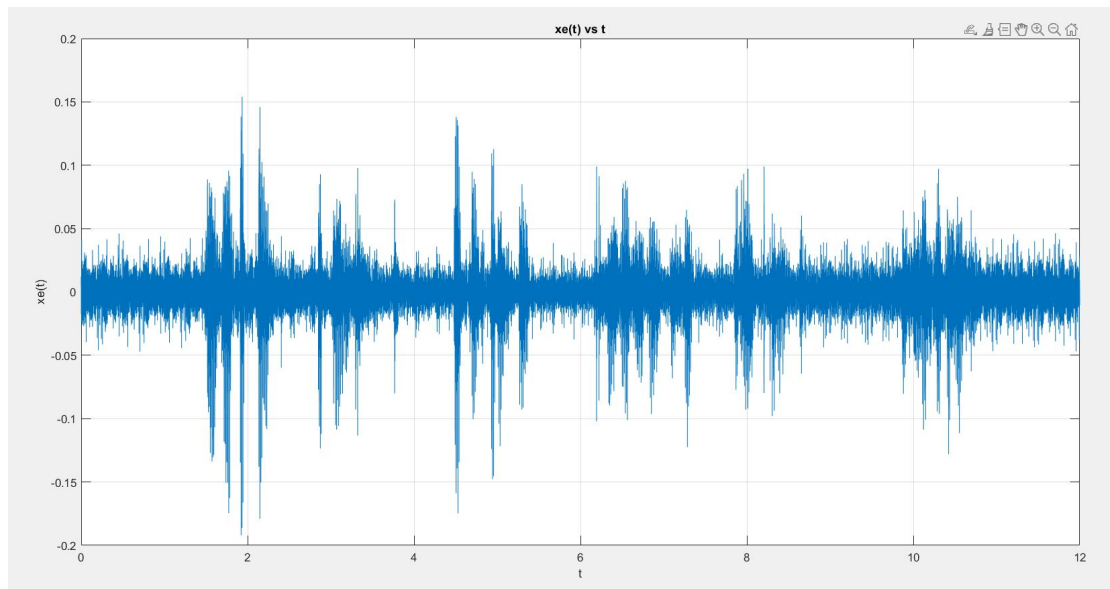
*Figure 4: Plot of array of my speech  $x(t)$  vs  $t$*



*Figure 5: Plot of array of my speech with echo  $y(t)$  vs  $t$*



*Figure 6: Magnitude of frequency response computed over omega*



*Figure 7: Plot of array of my extracted speech  $x_e(t)$  vs  $t$*

When  $y(t)$  is listened, it was the echoed version of my speech, it was hard to understand. When  $x_e(t)$  was listened, even though there were some little noise in the background after the processes, I could understand what I said and the echo and noise were mostly gone. If we compare *Figures 5&7* the general layout of the signal is very similar, also the white noise is also visible in the plot.