Maths pre-requisites for data analysis in neuroscience

1/ Linear Algebra

Arthur Leblois

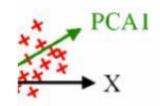
Institut des maladies neurodégénératives (UMR CNRS 5293) Neurocampus, Université de Bordeaux

Ultimate goal: understand and develop tools for the analysis of neural data

$$C_m \frac{dV}{dt} = -g_L(V - E_L) + g_L \Delta_T e^{\frac{V - V_T}{\Delta_T}} - u + I$$

$$\tau_w \frac{du}{dt} = a(V - E_L) - u$$

differential equations and modeling

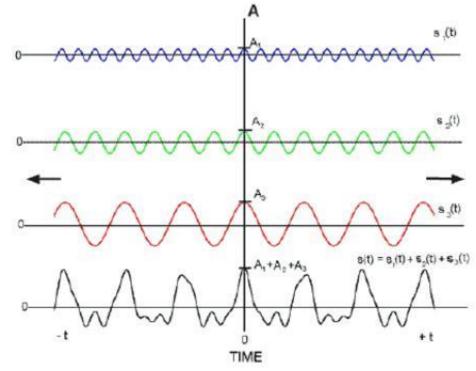


dimensionality reduction

"What is an eigenvector?"

"What exactly is PCA doing?"

"What really is a Fourier transform?"



Fourier transforms, convolutions, and filtering out noise

Many slides from Lane McIntosh & Kiah Hardcastle (NBIO course, Stanford Univ, https://web.stanford.edu/class/nbio228-01/info.html}

1/ Linear Algebra

- When and why is linear algebra useful?
- Vectors and their operations
- Matrices and their operations, special matrices
- Equation systems, matrices and determinants

Why linear algebra?

Why linear algebra?

```
1.63
        5.20
               7.66
                     8.12 3.22
 4.98
        5.90
               8.21
                     9.29 20.10
 10.10
        8.57
               5.73
                     8.17
                            2.22
                     0.93
  0.02
        0.21
               0.14
                            1.40
  9.27
       10.27 13.12
                     8.90
                            9.01
                            7.21
  7.44
        6.98
               5.62
                     8.20
100.10
       8.22
              7.54
                    60.10
                            1.69
40.20
       29.21
              12.45
                            8.90
                     10.41
       21.59
                            2.62
                     4.99
32.33
              10.21
  2.99
        1.67
               1.01
                     0.80
                            0.07
```

Datasets are matrices

	time				
neuron 1	1.63	5.20	7.66	8.12	3.22
neuron 2	4.98	5.90	8.21	9.29	20.10
neuron 3	10.10	8.57	5.73	8.17	2.22
neuron 4	0.02	0.21	0.14	0.93	1.40
neuron 5	9.27	10.27	13.12	8.90	9.01
neuron 6	7.44	6.98	5.62	8.20	7.21
neuron 7	100.10	8.22	7.54	60.10	1.69
neuron 8	40.20	29.21	12.45	10.41	8.90
neuron 9	32.33	21.59	10.21	4.99	2.62
neuron 10	2.99	1.67	1.01	0.80	0.07

Datasets are matrices

		time				
VOX	el 1	1.63	5.20	7.66	8.12	3.22
VOX	el 2	4.98	5.90	8.21	9.29	20.10
VOX	el 3	10.10	8.57	5.73	8.17	2.22
VOX	el 4	0.02	0.21	0.14	0.93	1.40
VOX	el 5	9.27	10.27	13.12	8.90	9.01
VOX	el 6	7.44	6.98	5.62	8.20	7.21
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VOX	el 8	40.20	29.21	12.45	10.41	8.90
VOX	el 9	32.33	21.59	10.21	4.99	2.62
VOX	el 10	2.99	1.67	1.01	0.80	0.07

Datasets are matrices

	patient ——				
gene 1	1.63	5.20	7.66	8.12	3.22
gene 2	4.98	5.90	8.21	9.29	20.10
gene 3	10.10	8.57	5.73	8.17	2.22
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1/ Linear Algebra

A/ Vectors

- Definition and representation
- Basic operations
- Norm and angle
- Products

B/ Matrices

- Definition and basic operations
- Linear transformation M·V
- Matrix rank
- Multiplication
- Special matrices

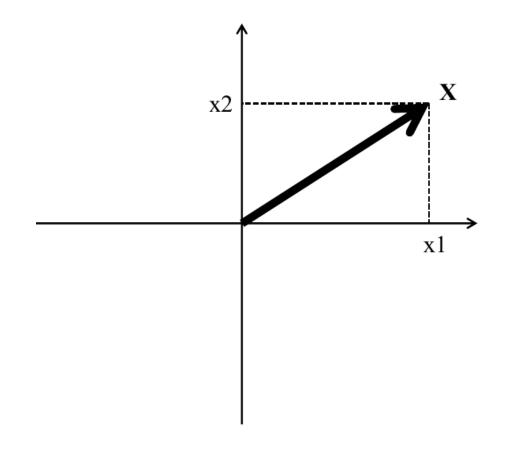
C/ Linear systems, matrices and determinant

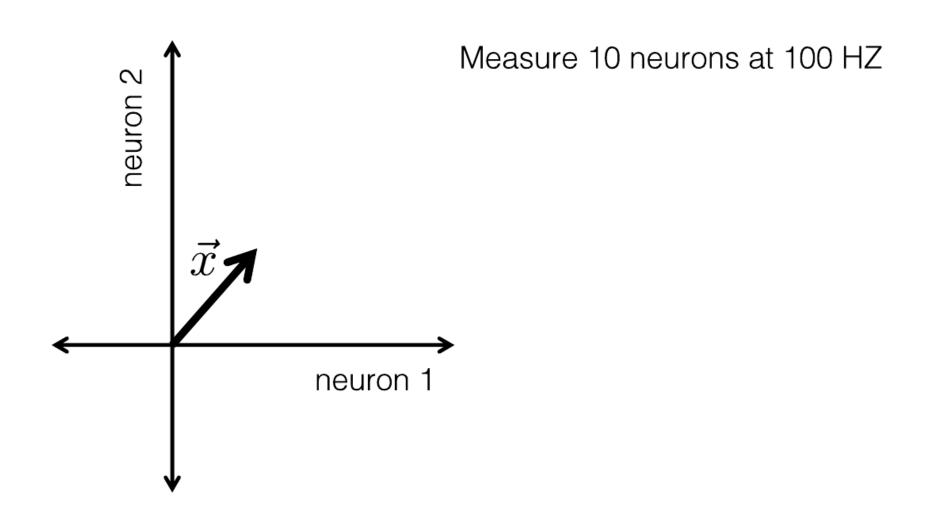
- Linear equation systems
- Inverse matrix
- Determinant: geometry

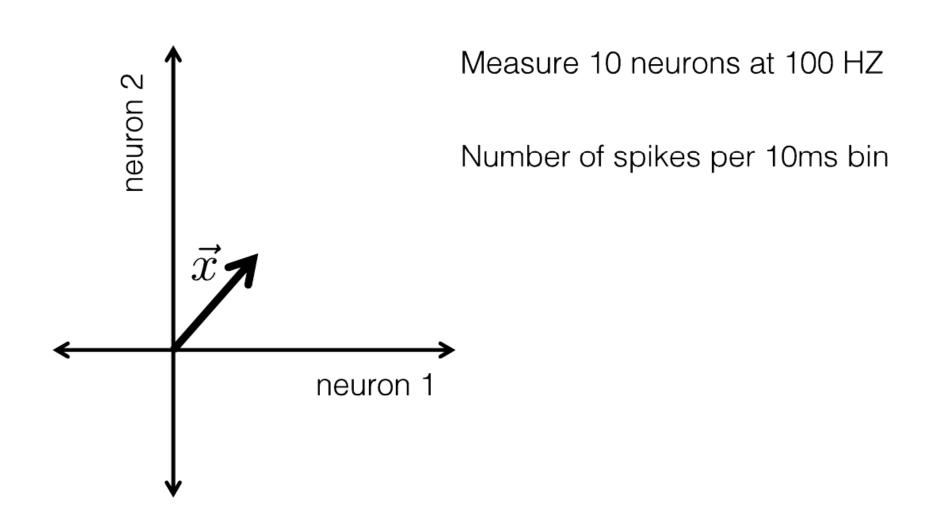
A/ Vectors

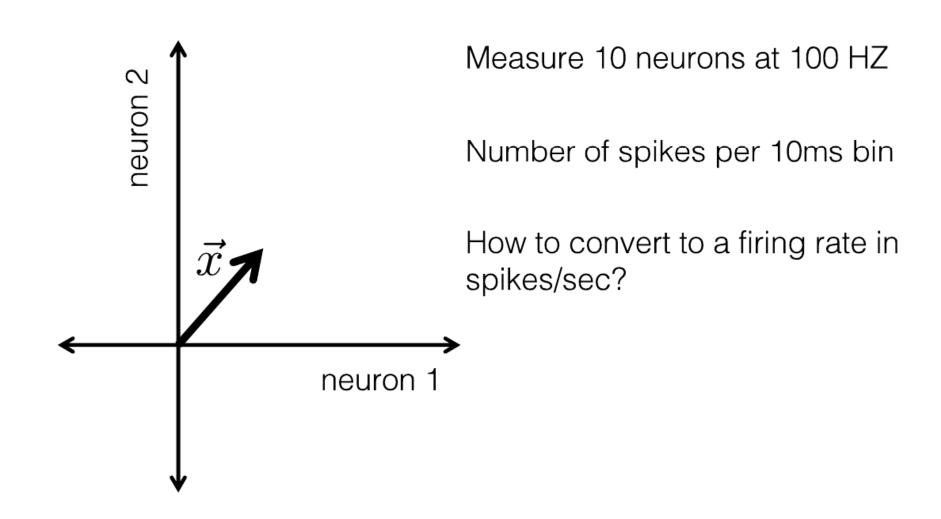
$$\mathbf{x} = (x_1, x_2, \dots, x_n)$$

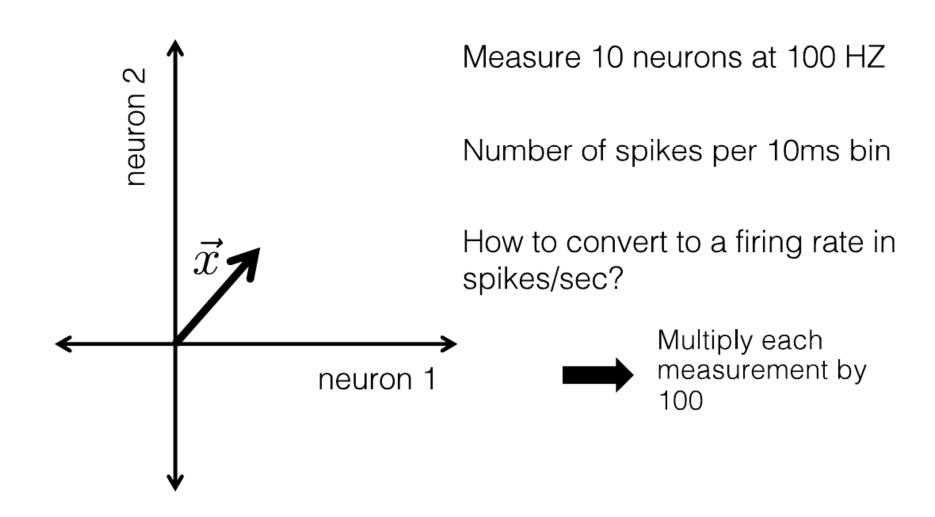
$$\mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}$$

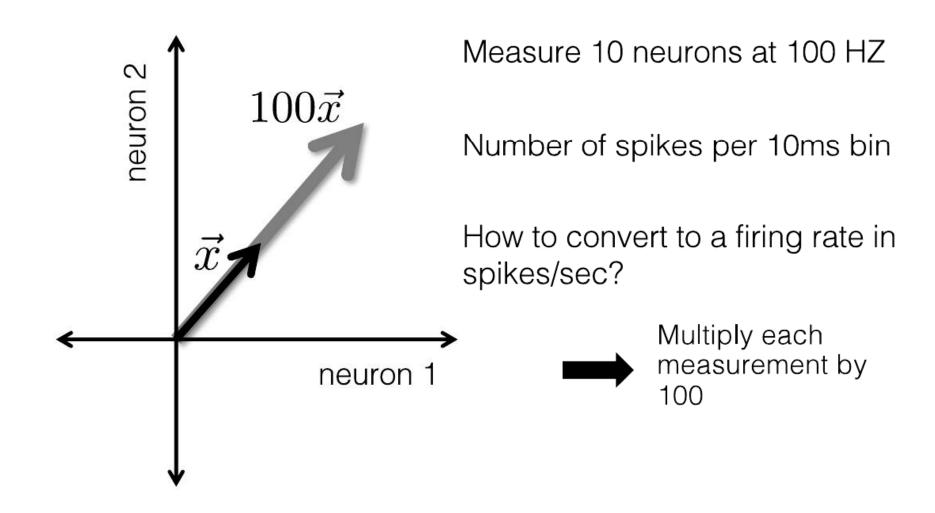


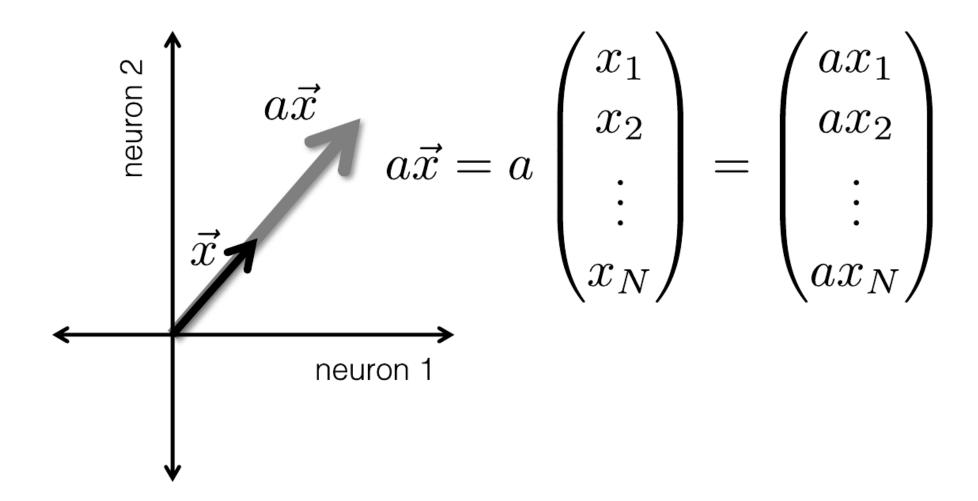










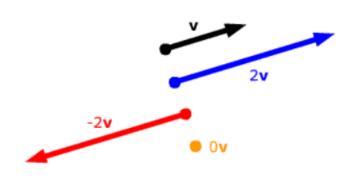


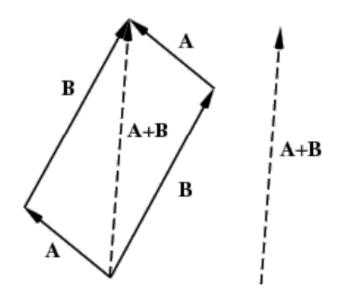
A/ Vectors

Scalar multiplication

Addition

Substraction

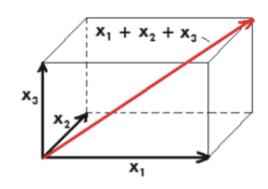




$$\mathbf{A} - \mathbf{B} = \mathbf{A} + (-\mathbf{B}).$$

$$\lambda \mathbf{x} = \lambda \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \equiv \begin{pmatrix} \lambda x_1 \\ \lambda x_2 \\ \vdots \\ \lambda x_n \end{pmatrix}$$

$$\lambda \mathbf{x} = \lambda \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} \equiv \begin{pmatrix} \lambda x_1 \\ \lambda x_2 \\ \vdots \\ \lambda x_n \end{pmatrix} \qquad \mathbf{x} + \mathbf{y} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix} + \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix} \equiv \begin{pmatrix} x_1 + y_1 \\ x_2 + y_2 \\ \vdots \\ x_n + y_n \end{pmatrix}$$

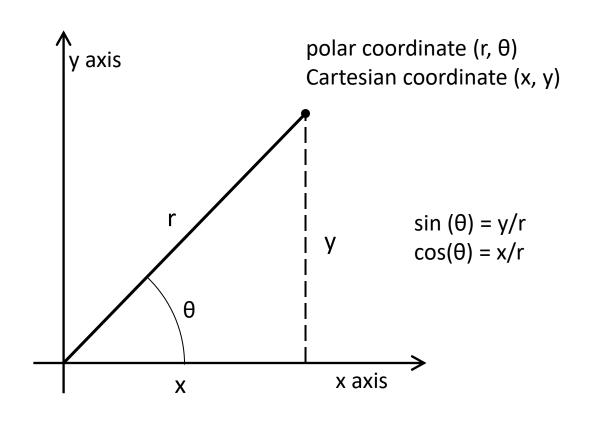


A/ Vectors

Norm (or magnitude): |x| or ||x||

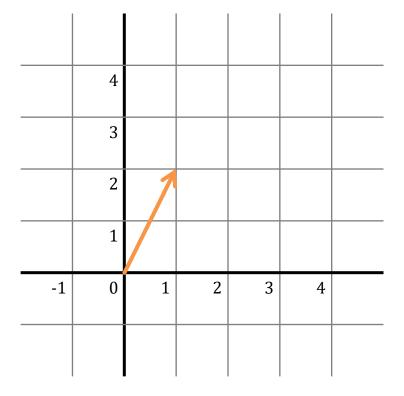
$$\mathbf{x} = (x_1, x_2, \dots, x_n)$$

$$|\mathbf{x}| = \sqrt{x_1^2 + x_2^2 + \dots + x_n^2}$$



Exercises

- 1. Represent the following vectors of \mathbb{R}^2 on a plane with two orthogonal axes:
 - a) [1 2]
 - b) [3 -1]
 - c) 2[1 -3]
 - d) $[2 \ 4] [0 \ -2]$
 - e) $[1 \ 4] + 3[2 \ -1]$
 - f) $5[1 \ 1] + 2[-2 \ 1]$



- 2. Calculate the norm of the following vectors:
 - a) [3 -1]
 - b) [4 3 2]
 - c) $[1 \ 2 \ -1 \ 3 \ 1]$

$$\vec{x} \cdot \vec{y} =$$

$$(x_1 \quad x_2 \quad \dots \quad x_N) \quad \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{pmatrix}$$

$$(x_1 \quad x_2 \quad \dots \quad x_N) \quad \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{pmatrix} = x_1 y_1$$

$$\vec{x} \cdot \vec{y} =$$

$$(x_1 \quad x_2 \quad \dots \quad x_N) \quad \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{pmatrix} = x_1 y_1 + x_2 y_2$$

Dot product (inner product)

$$(x_1 \quad x_2 \quad \dots \quad x_N) \quad \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{pmatrix} = x_1 y_1 + x_2 y_2 + \dots + x_N y_N$$

Dot product (inner product)

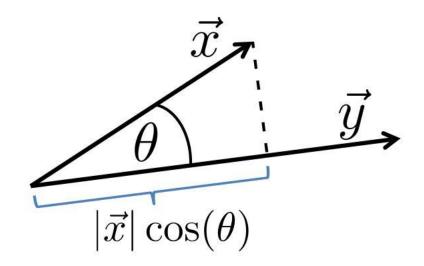
$$(x_1 \quad x_2 \quad \dots \quad x_N) \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{pmatrix} = x_1 y_1 + x_2 y_2 + \dots + x_N y_N$$
$$= \sum_{i=1}^N x_i y_i$$

Dot product (inner product)

$$(x_1 \quad x_2 \quad \dots \quad x_N) \quad \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{pmatrix} = x_1 y_1 + x_2 y_2 + \dots + x_N y_N$$

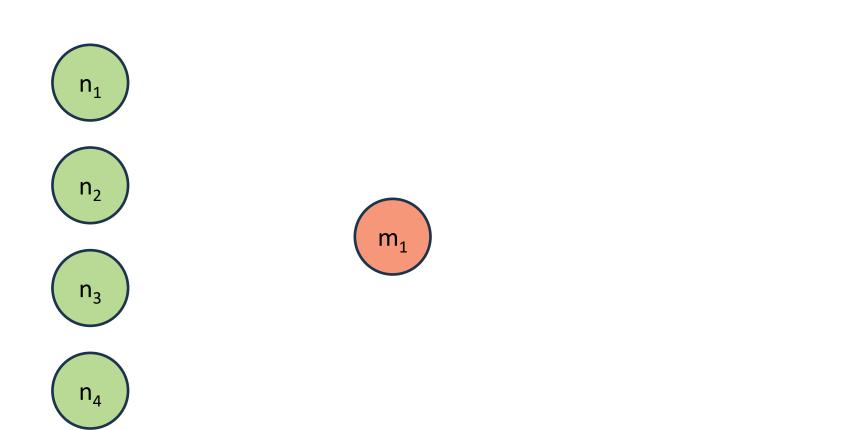
Condition: same inner dimension

Dot product geometric intuition: "Overlap" of 2 vectors

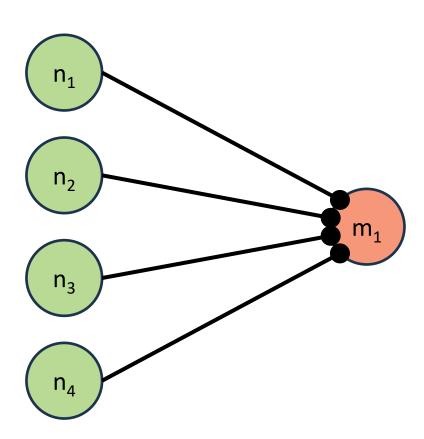


$$\vec{x} \cdot \vec{y} = |\vec{x}| |\vec{y}| \cos(\theta)$$

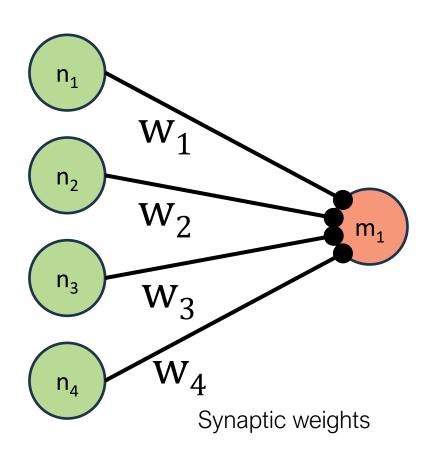
Dot product (inner product) Example 1



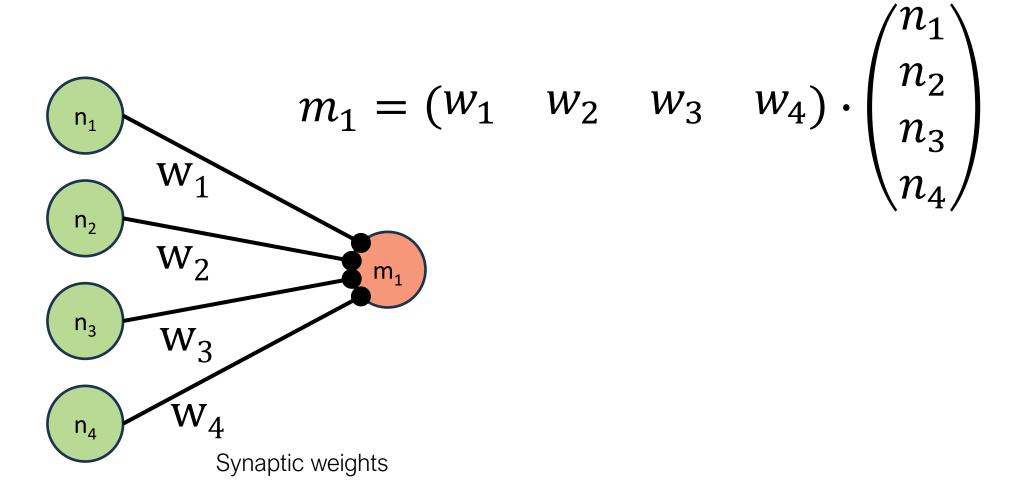
Dot product (inner product) Example 1



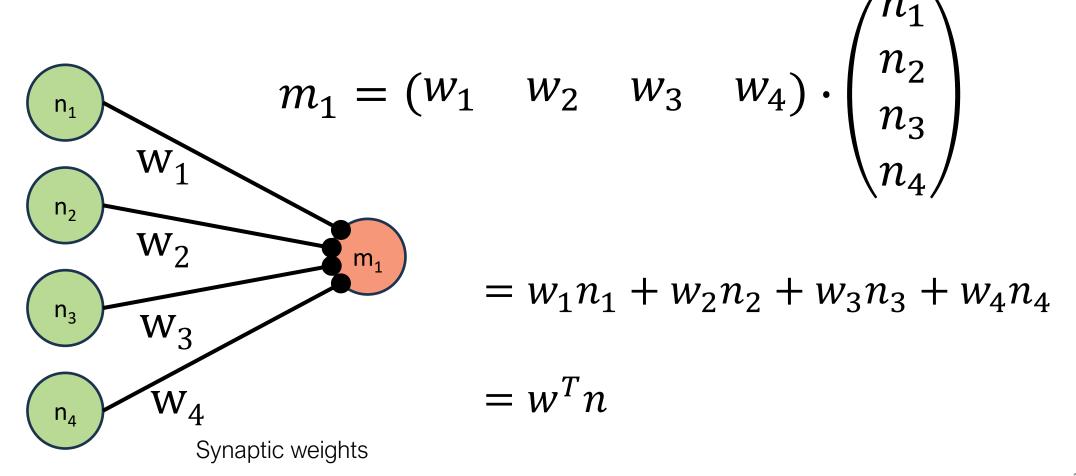
Dot product (inner product) Example 1



Dot product (inner product) Example 1



Dot product (inner product) Example 1



Exercise

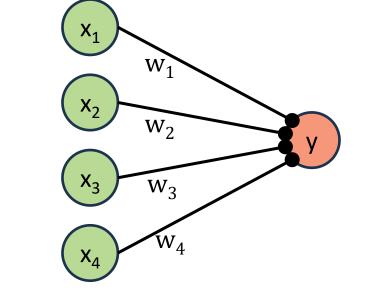
3. Calculate the product of these two vectors:

$$\begin{bmatrix} 1 & 2 & -3 \end{bmatrix} \begin{bmatrix} 4 \\ -5 \\ 6 \end{bmatrix}$$

From vectors to matrices

Let's imagine a linear neuron receiving input from n presynaptic neurons which firing rates $(x_j)_{j=1:n}$ are scaled by synaptic weights $(w_j)_{j=1:n}$ and together determine the firing rate y of the output neuron:

$$y = w_1 x_1 + w_2 x_2 + \cdots + w_n x_n = \sum w_j x_j$$

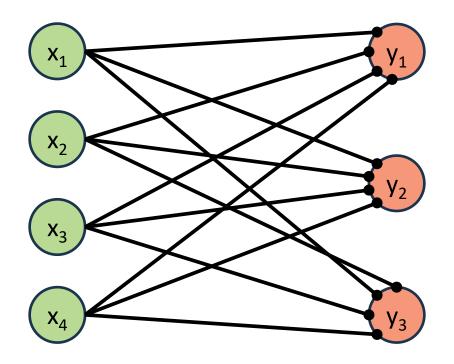


The output can be written as dot product of the weight vector and input vector:

$$y = W \cdot X$$

From vectors to matrices

Now let's suppose we have m output neurons with activities $(y_i)_{i=1:m}$, still given by a linear combination of the firing rates of their inputs neurons $(x_{ij})_{i=1:m, j=1:n}$ scaled by synaptic weights $(w_{ij})_{i=1:m, j=1:n}$



$$y_i = w_{i1}x_{i1} + w_{i2}x_{i2} + \cdots + w_{in}x_{in} = \sum w_{ij}x_{ij}$$

From vectors to matrices

Now let's suppose we have m output neurons with activities $(y_i)_{i=1:m}$, still given by a linear combination of the firing rates of their inputs neurons $(x_{ij})_{i=1:m,j=1:n}$ scaled by synaptic weights $(w_{ij})_{i=1:m, j=1:n}$

n input neurons x *m* output neurons

We can summarize the weights w_{ij} into a matrix W with $m \times n$ values.

$$W = (w_{ij}) = \begin{pmatrix} w_{11} & w_{12} & \dots & w_{1n} \\ w_{21} & w_{22} & \dots & w_{2n} \\ \dots & \dots & \dots & \dots \\ w_{m1} & w_{m2} & \dots & w_{mn} \end{pmatrix}$$

From vectors to matrices

We already know that for each output neuron y_i :

$$y_i = \sum w_{ij} x_{ij}$$

We can generalize this for all the output neurons in the vector *y* with a more compact equation:

$$y = Wx$$

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- Multiplication
- Special matrices

C/ Linear systems, matrices and determinant

- Linear equation systems
- Inverse matrix
- Determinant: geometry

Size of a Matrix

- The size of a matrix is always represented as (# of rows) × (# of columns)
- Example

•
$$A = \begin{bmatrix} 2 & -1 & 0.5 \\ -1 & 1 & 5 \\ 0 & -2 & -1 \end{bmatrix}$$
 is a **3** × **3 matrix**

•
$$B = \begin{bmatrix} 2 & \sqrt{2} \\ -1 & 1 \\ 0 & 0 \end{bmatrix}$$
 is a $\mathbf{3} \times \mathbf{2}$ matrix

- $A_{i,j}$ is the component of A in the *i*-th row and *j*-th column.
 - In the above example, $A_{3.2} = -2$

Matrix representation of vectors

- Vectors can also be considered as matrices.
- Row vectors are $1 \times n$ matrices, where n is the number of components.
- Column vectors are $n \times 1$ matrices, where n is the number of component.
- Examples:
 - Column vector $\begin{bmatrix} 2 \\ -1 \\ 0 \end{bmatrix}$ is a 3 × 1 matrix.
 - Row vector $\begin{bmatrix} 2 \\ 1 \end{bmatrix}$ is a 1×2 matrix.

Basic matrix operations

Multiplication by a scalar

$$-2\begin{bmatrix} 2 & 3 \\ -2 & 1 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} -4 & -6 \\ 4 & -2 \\ 0 & 2 \end{bmatrix}$$

Addition of two matrices

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} + \begin{bmatrix} 4 & 2 \\ 0 & -2 \end{bmatrix} = \begin{bmatrix} 5 & 4 \\ 3 & 2 \end{bmatrix}$$

Matrix addition is commutative and associative

•
$$(A+B)+C = A+(B+C)$$

Transpose of a matrix

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{bmatrix} \text{ has transpose } A^T = \begin{bmatrix} 1 & 3 & 5 \\ 2 & 4 & 6 \end{bmatrix}$$

Subtraction of two matrices

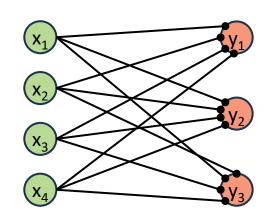
$$A - B = A + (-1)B$$

Vector and Matrix operations

A vector can be multiplied with a matrix in two possible ways:
 Matrix-Vector multiplication or Vector-Matrix multiplication

- Matrix-Vector multiplication: Ab = c
 - Matrix $A_{m \times n}$ can be multiplied with column vector $b_{n \times 1}$ to get a column vector $c_{m \times 1}$.
- Vector-Matrix multiplication: aB = c
 - Row vector $a_{1\times n}$ can be multiplied with matrix $B_{n\times m}$ to get a row vector $c_{1\times m}$.

$$\begin{pmatrix} w_{11} & w_{12} & \dots & w_{1n} \\ w_{21} & w_{22} & \dots & w_{2n} \\ \dots & \dots & \dots & \dots \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \dots \\ x_n \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \\ \dots \\ y_m \end{pmatrix}$$



 $M \times N$

 $N \times 1$

 $M \times 1$

$$\begin{pmatrix} w_{11} & w_{12} & \dots & w_{1n} \\ w_{21} & w_{22} & \dots & w_{2n} \\ \dots & \dots & \dots & \dots \\ w_{m1} & w_{m2} & \dots & w_{mn} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \dots \\ x_n \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \\ \dots \\ y_m \end{pmatrix}$$

Condition: same inner dimension Result: outer dimensions combined

$$\begin{pmatrix} w_{11} & w_{12} & \dots & w_{1n} \\ w_{21} & w_{22} & \dots & w_{2n} \\ \dots & \dots & \dots & \dots \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \dots \\ x_n \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \\ \dots \\ y_m \end{pmatrix}$$

Rule: the ith element of y is the dot product of the ith row of W with x

$$\begin{pmatrix} w_{11} & w_{12} & \dots & w_{1n} \\ w_{21} & w_{22} & \dots & w_{2n} \\ \dots & \dots & \dots & \dots \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \dots \\ x_n \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \\ \dots \\ y_m \end{pmatrix}$$

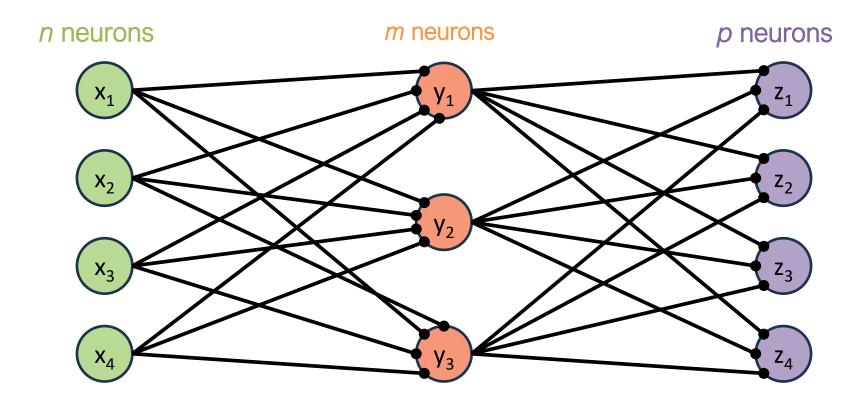
$$y_1 = w_{11}x_1 + w_{12}x_2 + \dots + w_{1n}x_n$$

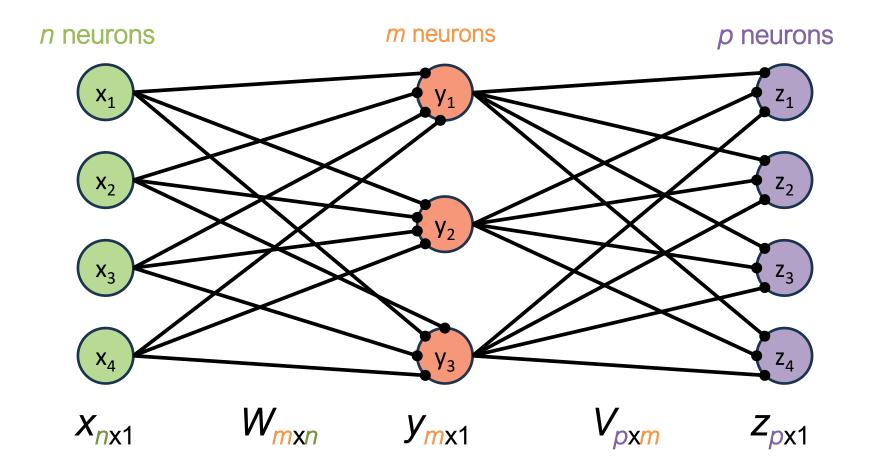
$$\begin{pmatrix} w_{11} & w_{12} & \dots & w_{1n} \\ w_{21} & w_{22} & \dots & w_{2n} \\ \dots & \dots & \dots & \dots \\ w_{m1} & w_{m2} & \dots & w_{mn} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \dots \\ x_n \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \\ \dots \\ y_m \end{pmatrix}$$

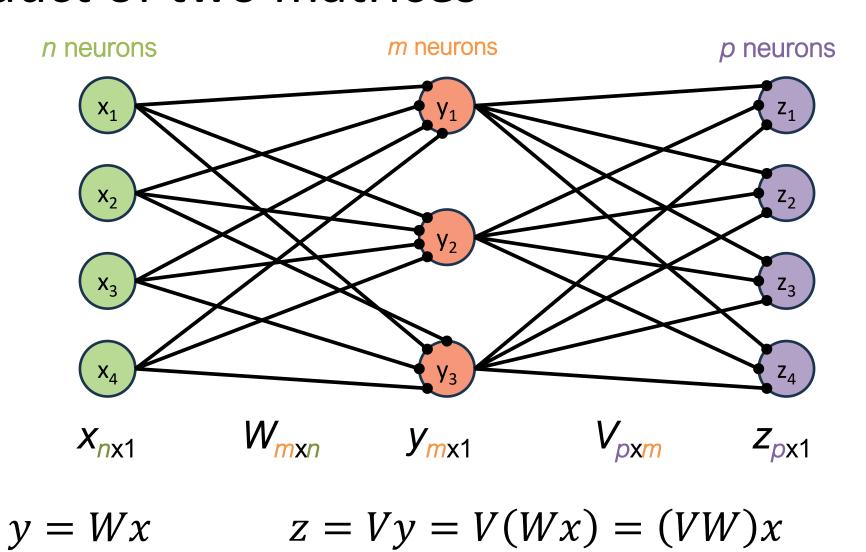
$$y_2 = w_{21}x_1 + w_{22}x_2 + \dots + w_{2n}x_n$$

$$\begin{pmatrix} w_{11} & w_{12} & \dots & w_{1n} \\ w_{21} & w_{22} & \dots & w_{2n} \\ \dots & \dots & \dots & \dots \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ \dots \\ x_n \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \\ \dots \\ y_m \end{pmatrix}$$

$$y_m = w_{m1}x_1 + w_{m2}x_2 + \dots + w_{mn}x_n$$







$$z = (VW)x$$

z = (VW)x let's calculate VW = U

$$\begin{pmatrix} v_{11} & v_{12} & \dots & v_{1m} \\ v_{21} & v_{22} & \dots & v_{2m} \\ \dots & \dots & \dots & \dots \\ v_{p1} & v_{p2} & \dots & v_{pm} \end{pmatrix} \begin{pmatrix} w_{11} & w_{12} & \dots & w_{1n} \\ w_{21} & w_{22} & \dots & w_{2n} \\ \dots & \dots & \dots & \dots \\ w_{m1} & w_{m2} & \dots & w_{mn} \end{pmatrix} = U \longrightarrow ? \times ?$$

$$P \times M$$

$$z = (VW)x$$
 let's calculate $VW = U$

$$\begin{pmatrix} v_{11} & v_{12} & \dots & v_{1m} \\ v_{21} & v_{22} & \dots & v_{2m} \\ \dots & \dots & \dots & \dots \end{pmatrix} \begin{pmatrix} w_{11} & w_{12} & \dots & w_{1n} \\ w_{21} & w_{22} & \dots & w_{2n} \\ \dots & \dots & \dots & \dots \end{pmatrix} = \begin{pmatrix} u_{11} & u_{12} & \dots & u_{1n} \\ u_{21} & u_{22} & \dots & u_{2n} \\ \dots & \dots & \dots & \dots \\ w_{m1} & w_{m2} & \dots & w_{mn} \end{pmatrix} = \begin{pmatrix} u_{11} & u_{12} & \dots & u_{1n} \\ u_{21} & u_{22} & \dots & u_{2n} \\ \dots & \dots & \dots & \dots \\ u_{p1} & u_{p2} & \dots & u_{pn} \end{pmatrix}$$

$$P \times M$$
 $M \times N$ $P \times N$

$$z = (VW)x$$
 let's calculate $VW = U$

$$\begin{pmatrix} v_{11} & v_{12} & \dots & v_{1m} \\ v_{21} & v_{22} & \dots & v_{2m} \\ \dots & \dots & \dots & \dots \\ v_{p1} & v_{p2} & \dots & v_{pm} \end{pmatrix} \begin{pmatrix} w_{11} & w_{12} & \dots & w_{1n} \\ w_{21} & w_{22} & \dots & w_{2n} \\ \dots & \dots & \dots & \dots \\ w_{m1} & w_{m2} & \dots & w_{mn} \end{pmatrix} = \begin{pmatrix} u_{11} & u_{12} & \dots & u_{1n} \\ u_{21} & u_{22} & \dots & u_{2n} \\ \dots & \dots & \dots & \dots \\ u_{p1} & u_{p2} & \dots & u_{pn} \end{pmatrix}$$

$$u_{11} = v_{11}w_{11} + v_{12}w_{21} + \dots + v_{1m}w_{m1}$$

$$z = (VW)x$$
 let's calculate $VW = U$

$$\begin{pmatrix} v_{11} & v_{12} & \dots & v_{1m} \\ v_{21} & v_{22} & \dots & v_{2m} \\ \dots & \dots & \dots & \dots \end{pmatrix} \begin{pmatrix} w_{11} & w_{12} & \dots & w_{1n} \\ w_{21} & w_{22} & \dots & w_{2n} \\ \dots & \dots & \dots & \dots \end{pmatrix} = \begin{pmatrix} u_{11} & u_{12} & \dots & u_{1n} \\ u_{21} & u_{22} & \dots & u_{2n} \\ \dots & \dots & \dots & \dots \\ w_{m1} & w_{m2} & \dots & w_{mn} \end{pmatrix} = \begin{pmatrix} u_{11} & u_{12} & \dots & u_{1n} \\ u_{21} & u_{22} & \dots & u_{2n} \\ \dots & \dots & \dots & \dots \\ u_{p1} & u_{p2} & \dots & u_{pn} \end{pmatrix}$$

$$u_{12} = v_{11}w_{12} + v_{12}w_{22} + \dots + v_{1m}w_{m2}$$

$$z = (VW)x$$
 let's calculate $VW = U$

$$\begin{pmatrix} v_{11} & v_{12} & \dots & v_{1m} \\ v_{21} & v_{22} & \dots & v_{2m} \\ \dots & \dots & \dots & \dots \\ v_{p1} & v_{p2} & \dots & v_{pm} \end{pmatrix} \begin{pmatrix} w_{11} & w_{12} & \dots & w_{1n} \\ w_{21} & w_{22} & \dots & w_{2n} \\ \dots & \dots & \dots & \dots \\ w_{m1} & w_{m2} & \dots & w_{mn} \end{pmatrix} = \begin{pmatrix} u_{11} & u_{12} & \dots & u_{1n} \\ u_{21} & u_{22} & \dots & u_{2n} \\ \dots & \dots & \dots & \dots \\ u_{p1} & u_{p2} & \dots & u_{pn} \end{pmatrix}$$

$$u_{1n} = v_{11}w_{1n} + v_{12}w_{2n} + \dots + v_{1m}w_{mn}$$

$$z = (VW)x$$
 let's calculate $VW = U$

$$\begin{pmatrix} v_{11} & v_{12} & \dots & v_{1m} \\ v_{21} & v_{22} & \dots & v_{2m} \\ \dots & \dots & \dots & \dots \\ v_{p1} & v_{p2} & \dots & v_{pm} \end{pmatrix} \begin{pmatrix} w_{11} & w_{12} & \dots & w_{1n} \\ w_{21} & w_{22} & \dots & w_{2n} \\ \dots & \dots & \dots & \dots \\ w_{m1} & w_{m2} & \dots & w_{mn} \end{pmatrix} = \begin{pmatrix} u_{11} & u_{12} & \dots & u_{1n} \\ u_{21} & u_{22} & \dots & u_{2n} \\ \dots & \dots & \dots & \dots \\ u_{p1} & u_{p2} & \dots & u_{pn} \end{pmatrix}$$

$$u_{21} = v_{21}w_{11} + v_{22}w_{21} + \dots + v_{2m}w_{m1}$$

$$z = (VW)x$$
 let's calculate $VW = U$

$$\begin{pmatrix} v_{11} & v_{12} & \dots & v_{1m} \\ v_{21} & v_{22} & \dots & v_{2m} \\ \dots & \dots & \dots & \dots \\ v_{p1} & v_{p2} & \dots & v_{pm} \end{pmatrix} \begin{pmatrix} w_{11} & w_{12} & \dots & w_{1n} \\ w_{21} & w_{22} & \dots & w_{2n} \\ \dots & \dots & \dots & \dots \\ w_{m1} & w_{m2} & \dots & w_{mn} \end{pmatrix} = \begin{pmatrix} u_{11} & u_{12} & \dots & u_{1n} \\ u_{21} & u_{22} & \dots & u_{2n} \\ \dots & \dots & \dots & \dots \\ u_{p1} & u_{p2} & \dots & u_{pn} \end{pmatrix}$$

$$u_{22} = v_{21}w_{12} + v_{22}w_{22} + \dots + v_{2m}w_{m2}$$

$$z = (VW)x$$
 let's calculate $VW = U$

$$\begin{pmatrix} v_{11} & v_{12} & \dots & v_{1m} \\ v_{21} & v_{22} & \dots & v_{2m} \\ \dots & \dots & \dots & \dots \\ v_{p1} & v_{p2} & \dots & v_{pm} \end{pmatrix} \begin{pmatrix} w_{11} & w_{12} & \dots & w_{1n} \\ w_{21} & w_{22} & \dots & w_{2n} \\ \dots & \dots & \dots & \dots \\ w_{m1} & w_{m2} & \dots & w_{mn} \end{pmatrix} = \begin{pmatrix} u_{11} & u_{12} & \dots & u_{1n} \\ u_{21} & u_{22} & \dots & u_{2n} \\ \dots & \dots & \dots & \dots \\ u_{p1} & u_{p2} & \dots & u_{pn} \end{pmatrix}$$

$$u_{2n} = v_{21}w_{1n} + v_{22}w_{2n} + \dots + v_{2m}w_{mn}$$

$$z = (VW)x$$
 let's calculate $VW = U$

$$\begin{pmatrix} v_{11} & v_{12} & \dots & v_{1m} \\ v_{21} & v_{22} & \dots & v_{2m} \\ \dots & \dots & \dots & \dots \\ v_{p1} & v_{p2} & \dots & v_{pm} \end{pmatrix} \begin{pmatrix} w_{11} & w_{12} & \dots & w_{1n} \\ w_{21} & w_{22} & \dots & w_{2n} \\ \dots & \dots & \dots & \dots \\ w_{m1} & w_{m2} & \dots & w_{mn} \end{pmatrix} = \begin{pmatrix} u_{11} & u_{12} & \dots & u_{1n} \\ u_{21} & u_{22} & \dots & u_{2n} \\ \dots & \dots & \dots & \dots \\ u_{p1} & u_{p2} & \dots & u_{pn} \end{pmatrix}$$

$$u_{p1} = v_{p1}w_{11} + v_{p2}w_{21} + \dots + v_{pm}w_{m1}$$

$$z = (VW)x$$
 let's calculate $VW = U$

$$\begin{pmatrix} v_{11} & v_{12} & \dots & v_{1m} \\ v_{21} & v_{22} & \dots & v_{2m} \\ \dots & \dots & \dots & \dots \end{pmatrix} \begin{pmatrix} w_{11} & w_{12} & \dots & w_{1n} \\ w_{21} & w_{22} & \dots & w_{2n} \\ \dots & \dots & \dots & \dots \end{pmatrix} = \begin{pmatrix} u_{11} & u_{12} & \dots & u_{1n} \\ u_{21} & u_{22} & \dots & u_{2n} \\ \dots & \dots & \dots & \dots \\ w_{m1} & w_{m2} & \dots & w_{mn} \end{pmatrix} = \begin{pmatrix} u_{11} & u_{12} & \dots & u_{1n} \\ u_{21} & u_{22} & \dots & u_{2n} \\ \dots & \dots & \dots & \dots \\ u_{p1} & u_{p2} & \dots & u_{pn} \end{pmatrix}$$

$$u_{p2} = v_{p1}w_{12} + v_{p2}w_{22} + \dots + v_{pm}w_{m2}$$

$$z = (VW)x$$
 let's calculate $VW = U$

$$\begin{pmatrix} v_{11} & v_{12} & \dots & v_{1m} \\ v_{21} & v_{22} & \dots & v_{2m} \\ \dots & \dots & \dots & \dots \end{pmatrix} \begin{pmatrix} w_{11} & w_{12} & \dots & w_{1n} \\ w_{21} & w_{22} & \dots & w_{2n} \\ \dots & \dots & \dots & \dots \end{pmatrix} = \begin{pmatrix} u_{11} & u_{12} & \dots & u_{1n} \\ u_{21} & u_{22} & \dots & u_{2n} \\ \dots & \dots & \dots & \dots \\ w_{m1} & w_{m2} & \dots & w_{mn} \end{pmatrix} = \begin{pmatrix} u_{11} & u_{12} & \dots & u_{1n} \\ u_{21} & u_{22} & \dots & u_{2n} \\ \dots & \dots & \dots & \dots \\ u_{p1} & u_{p2} & \dots & u_{pn} \end{pmatrix}$$

$$u_{pn} = v_{p1}w_{1n} + v_{p2}w_{2n} + \dots + v_{pm}w_{mn}$$

Special matrices: diagonal matrix

$$\overrightarrow{D} = \begin{pmatrix} d_1 & 0 & \dots & 0 \\ 0 & d_2 & \dots & 0 \\ \dots & \dots & \dots & \dots \\ 0 & 0 & \dots & d_n \end{pmatrix}$$

$$\overrightarrow{D}\overrightarrow{x} = \begin{pmatrix} d_1x_1 \\ d_2x_2 \\ \dots \\ d_nx_n \end{pmatrix}$$
 This acts like scalar multiplication

$$\vec{D}\vec{x} = \begin{pmatrix} d_1 x_1 \\ d_2 x_2 \\ \dots \\ d_n x_n \end{pmatrix}$$

Exercises

Represent the following vectors of \mathbb{R}^2 on a plane with two orthogonal axes:

a)
$$\begin{bmatrix} 1 & 3 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} -1 \\ 2 \end{bmatrix}$$

b)
$$\begin{bmatrix} -2 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

c)
$$\begin{bmatrix} 0 & 2 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 3 \\ 1 \end{bmatrix}$$

d)
$$\begin{bmatrix} 1 & 3 \\ 0 & 2 \end{bmatrix} + \begin{bmatrix} -2 & 1 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

Find all possible products among the following matrices:

$$A = [1 \ 2 \ 3],$$

$$A = [1 \ 2 \ 3], \qquad B = \begin{bmatrix} 1 \\ 2 \end{bmatrix}, \qquad C = \begin{bmatrix} 2 & 1 \\ -3 & 0 \\ 1 & 2 \end{bmatrix},$$

$$D = \begin{bmatrix} -2 & 5 \\ 5 & 0 \end{bmatrix}, \qquad E = \begin{bmatrix} -1 & 1 & 3 \\ -1 & -4 & 0 \\ 0 & 2 & 5 \end{bmatrix}$$

Special matrices: identity matrix

for all
$$\overrightarrow{A}$$
, $\overrightarrow{1}\overrightarrow{A} = \overrightarrow{A}\overrightarrow{1} = \overrightarrow{A}$

Special matrices: inverse matrix

$$\overrightarrow{A}\overrightarrow{A}^{-1} = \overrightarrow{A}^{-1}\overrightarrow{A} = \overrightarrow{1}$$

Does the inverse always exist?

C/ Linear systems, matrices and determinants

Linear system

$$w_{11}x_1 + w_{12}x_2 + \dots + w_{1n}x_n = y_1$$

$$w_{21}x_1 + w_{22}x_2 + \dots + w_{2n}x_n = y_2$$

$$\dots$$

$$w_{m1}x_1 + w_{m2}x_2 + \dots + w_{mn}x_n = y_m$$

$$2x + 3y + z = 6$$
$$x - y + z = 1$$
$$x + y + z = 3$$

Matrix formulation

Given
$$W: x \longrightarrow y$$

Find $V: y \longrightarrow x$ such that $x \stackrel{W}{\rightarrow} y \stackrel{V}{\rightarrow} x$
i.e. VWx=x, or VW=I

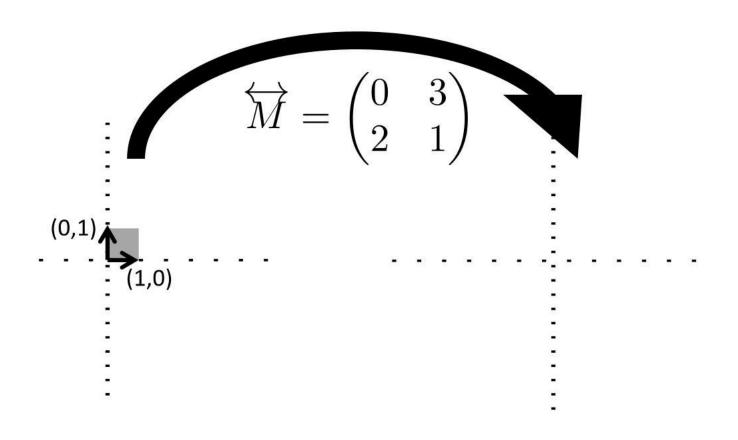
$$W^{-1}(W\mathbf{x}) = \mathbf{x}$$
$$W^{-1}W = WW^{-1} = I$$

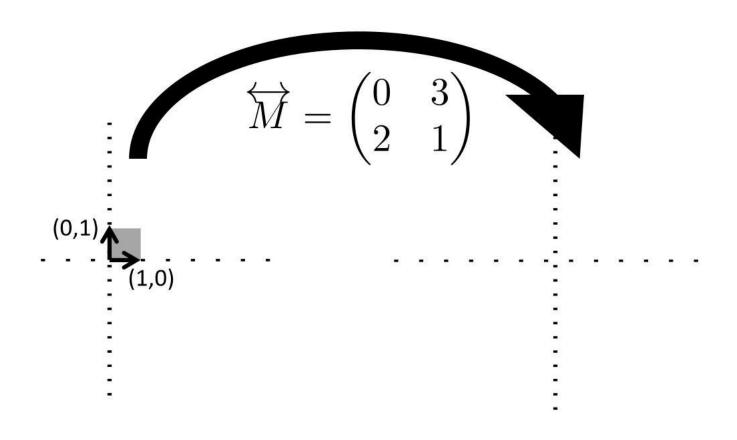
Some square matrices have no inverse and a non-invertible matrix is said to be singular (this is like the exception k=0 for the scalar case). If an inverse does not exist it is for a very good reason. It happens when there is a non-zero vector \mathbf{x} such are two different vectors, 0 and \mathbf{x} , which map to 0 under W, hence W cannot have an inverse (in general a function must be one-to-one to have an inverse).

Another test for singularity of a matrix W is to calculate its determinant, a scalar quantity denoted by det(W) (sometimes |W|) which we will discuss later. A matrix is singular if

$$\det(W) = 0$$







Mx?

