

Phyiscal Scene

encode
→

Graph Structured Representation

Interaction Network

$$O = \begin{bmatrix} o_1^{(t)} & \dots & o_{N_O}^{(t)} \end{bmatrix}, X = \begin{bmatrix} x_1^{(t)} & \dots & x_{N_O}^{(t)} \end{bmatrix}, R = \langle R_r, R_s, R_a \rangle$$

$$m(O, R) = \begin{bmatrix} OR_r & OR_s & R_a \end{bmatrix}^T = \begin{bmatrix} b_1 & \dots & b_{N_R} \end{bmatrix} = B$$

$$\phi_R(B) = \begin{bmatrix} f_R(b_1) & \dots & f_R(b_{N_R}) \end{bmatrix} = \begin{bmatrix} e_1 & \dots & e_{N_R} \end{bmatrix} = E$$

$$a(O, R, X, E) = \begin{bmatrix} O & X & ER_r^T \end{bmatrix}^T = \begin{bmatrix} c_1 & \dots & c_{N_O} \end{bmatrix} = C$$

$$\phi_O(C) = \begin{bmatrix} f_O(c_1) & \dots & f_O(c_{N_O}) \end{bmatrix} = \begin{bmatrix} o_1^{(t+1)} & \dots & o_{N_O}^{(t+1)} \end{bmatrix}$$

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