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11/06- 2x2 Systems
    DE. x'=Ax where A: [a b]
     Q- how to solve?
       assistication of nxn matrix

1. two distinct eigenvalues (real)

2. complex eigenvalues (\lambda, \overline{\lambda})

[\lambda, 0] \lambda, \lambda \in \mathbb{R}
[\lambda, 0] = Q^{-1}AQ
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    Classification of nxn matrix
     Determine the Case
         check det (XI-A)
                                                                                          trace(A) = sum
                                                                                          of diagonal
                 = \det \begin{pmatrix} \begin{bmatrix} \lambda - a & -b \\ -c & \lambda - d \end{pmatrix} \end{pmatrix} = (\lambda - a)(\lambda - d) - bc
                                                = \lambda^2 - a\lambda - d\lambda + ad-bc
                                                 = x2 - (a-d)>+ (ad-bc)
                                                 = \lambda^2 - tr(A)\lambda + det(A)
         discriminant \Delta = (tr(A))^2 - 4 \det(A)
            1) \Delta > 0 \Rightarrow 2 distinct real eigenvalues
            2) \Delta<0 \Rightarrow 2 complex conjugate eigenvalues
            3\Delta=0 \Rightarrow 1 real eigenvalues
      thm - e^{\lambda,t}\vec{v},(t) = \hat{x},(t) and e^{\lambda,t}\vec{v}_{2}(t) = \hat{x}_{2}(t) are lin. ind.
      proof - by the prop, we only have to show that when t=0
                $,(0) and $,20) are lin ind
       lemma- then v, v, oure lin. ind.
       proof by contradiction
             suppose \vec{v}_1, \vec{v}_2 are lin dep \iff \vec{v}_2 = c_1 \vec{v}_1, \vec{v}_1 = c_2 \vec{v}_2
             without loss of openerality (WLOG) assume v.=cv,
             1) Av. = 2v.
                                                         \lambda, \vec{v}_1 = \lambda_2 \vec{v}_1
             2) Av. = A(cv.) = c(Av.)
                                                  So √, =0
                                   = c(\lambda_3 \vec{v}_2) contradiction!
                                    = 22(6,7)
                                                         v., v. are lin ind.
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 $=\lambda, \vec{\nabla}$

step 1:
$$\lambda I - A = \begin{bmatrix} \lambda+5 & -1 \\ 2 & \lambda+2 \end{bmatrix}$$

$$d(\lambda I - A) = (\lambda+5)(\lambda+2) + 2$$

$$= \lambda^2 + 7\lambda + 12$$

$$= (\lambda+4)(\lambda+3) \qquad \lambda = -4 \cdot \lambda = -3$$

x(b)=cx,(t)+(2x2(t)

step 2: find v., v2

$$\vec{V}_{1}: \begin{bmatrix} -4+5 & -1 \\ 2 & -4+2 \end{bmatrix} \vec{V}_{1} = 0 \Rightarrow \begin{bmatrix} 1 & -1 \\ 2 & -2 \end{bmatrix} \begin{bmatrix} a_{1} \\ b_{1} \end{bmatrix} \Rightarrow \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} a_{1} \\ b_{1} \end{bmatrix} \Rightarrow \vec{V}_{1}: \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\vec{V}_{2}: \begin{bmatrix} -3+5 & -1 \\ 2 & -3+2 \end{bmatrix} \vec{V}_{2} = 0 \Rightarrow \begin{bmatrix} 2 & -1 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} a_{1} \\ b_{1} \end{bmatrix} \Rightarrow 2a_{1} = b_{1} \Rightarrow \vec{V}_{2} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\text{Step 3:} \quad \vec{X}_{1}(t) = e^{\lambda_{1}t} \vec{V}_{2}(t) = e^{-\lambda_{1}t} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} e^{-\lambda_{1}t} \\ e^{-\lambda_{2}t} \end{bmatrix}$$

$$\vec{X}_{2}(t) = e^{\lambda_{2}t} \vec{V}_{2}(t) = e^{-\lambda_{2}t} \begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} e^{-\lambda_{1}t} \\ 2e^{-\lambda_{2}t} \end{bmatrix}$$