

# Incremental (Combinatorial) Voronoi Diagrams

Boris Zolotov, Mag. 1

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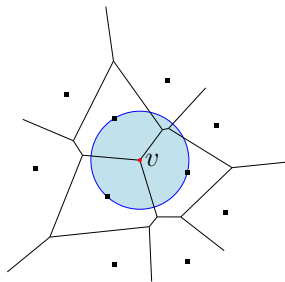
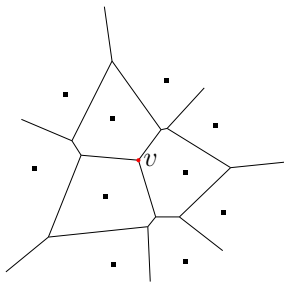
# Voronoi Diagrams

## Definition

*Voronoi diagram* of set  $S \subset \mathbb{R}^2$  of  $n$  points is the subdivision of the plane into  $n$  cells, one for each site in  $S$ , with the property that a point  $q$  lies in the cell corresponding to a site  $s_i$  if and only if

$$\text{dist}(q, s_i) < \text{dist}(q, s_j)$$

for each  $s_j \in S$  with  $j \neq i$ .



# Algorithms for Voronoi Diagram

- 1 Calculate whole Voronoi diagram —  $O(n \log n)$ : sweep line, divide-and-conquer.
- 2 (And no better: sorting reduces to Voronoi.)
- 3 Update the diagram when a new site came —  $O(n)$  — *literally any* possible way.
- 4 (And no better: *should draw an example here*. There can be that many changes.)
- 5 But what if we consider *the graph* of a diagram...

# Results today

- 1  $O(\sqrt{n})$ ,  $\Omega(\sqrt{n})$  edge insertions / removals — even if the diagram is a tree.

This is in contrast to  $O(n)$  geometric changes and  $O(\log n)$  (amortised, existential) combinatorial changes in case of inserting in clockwise order.

- 2 *Algorithm* for insertion of sites in convex position, in arbitrary order —  $O(\sqrt{n} \text{ polylog})$ .

# Links and Cuts

*Link* is the addition of an edge, *cut* is the removal of an edge. We count only them. All other operations are thought to have no cost. For example, addition of a vertex.

How many links / cuts are there in our example?

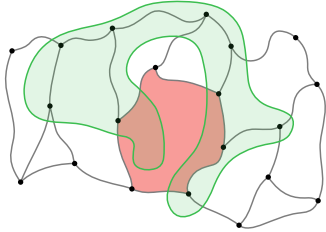
# Chan's structure

Can be used for:

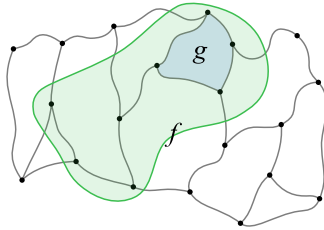
- 1 Search of nearest neighbor;
- 2 Reporting extreme point in given direction.

Makes use of *shallow cuttings*. (Was presented at CG seminar.) Time complexity:

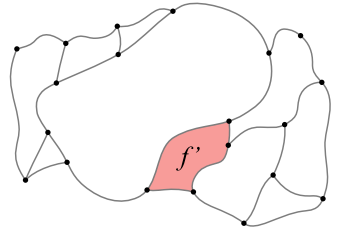
- 1 Insertion:  $O(\log^3 n)$ ;
- 2 Deletion:  $O(\log^7 n)$  (improved to  $^5$ );
- 3 Query:  $O(\log^2 n)$ .



(a) This curve is not flarbable



(b) This curve is flarbable



(c) Result of applying flarb operation

Fleeq-edges: those intersecting  $\mathcal{C}$ . Note that in a real Voronoi diagram there can be no such cells as  $g$ .

# Flarb: Results

## Theorem

*$\mathcal{G}(G, \mathcal{C})$  has at most two more vertices than  $G$  (3-regular graph inside).*

## Theorem

*$\mathcal{G}(G, \mathcal{C})$  contains one more face than  $G$  (if it comes to Voronoi diagrams).*

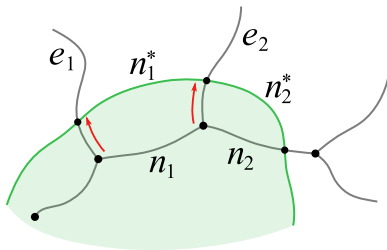
## Theorem

*For any new point, there exists a curve such that the changes the graph of  $V. D.$  undergoes can be represented by Flarb.*



# Preserving operation

Sometimes no links and cuts are needed.



$\mathcal{P}(G, \mathcal{C})$  — the set of *preserved* faces.  $\mathcal{B}(G, \mathcal{C})$  — faces wholly inside  $\mathcal{C}$ .

$\mathcal{A}(G, \mathcal{C})$  — augmented,  $\mathcal{S}(G, \mathcal{C})$  — shrinking.

Thank you for your attention

*Some contents here maybe*