Variable discount factor learning in Markov Decision Process

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Abstract—

I. INTRODUCTION

Motivations.

State of the art (Q-Learning [1], SARSA, Double, Weighted, R-Learning)

- A. Subsection Heading Here
 - 1) Subsubsection Heading Here:

II. PRELIMINARIES

A. Decomposition of the TD error

Decompose Q function:

$$Q(x, u) = \mathbb{E}\left[R(x, u, x') + \gamma Q(x', \pi(x'))\right]$$

$$= \mathbb{E}\left[R(x, u, x')\right] + \gamma \mathbb{E}\left[Q(x', \pi(x'))\right]$$

$$= \tilde{R}(x, u) + \gamma \tilde{Q}(x, u)$$
(1)

Decomposed TD update:

$$\tilde{R}(x,u) \leftarrow \tilde{R}(x,u) + \alpha(R(x,u,x') - \tilde{R}(x,u))$$
 (2)

$$\tilde{Q}(x,u) \leftarrow \tilde{Q}(x,u) + \beta(Q(x',\pi(x')) - \tilde{Q}(x,u))$$
 (3)

Update of the Q function:

$$Q(x,u) \leftarrow \tilde{R}(x,u) + \alpha(R(x,u,x') - \tilde{R}(x,u))$$

$$+ \gamma \left(\tilde{Q}(x,u) + \beta(Q(x',\pi(x')) - \tilde{Q}(x,u)) \right)$$

$$= Q(x,u) + \alpha(R(x,u,x') - \tilde{R}(x,u))$$

$$+ \gamma \beta(Q(x',\pi(x')) - \tilde{Q}(x,u))$$
(4)

B. Analysis of the decomposed update

If
$$\alpha = \beta$$

$$Q(x,u) \leftarrow Q(x,u) + \alpha(R(x,u,x') + \gamma Q(x',\pi(x'))) \quad \text{(5)}$$

(6)

That is the classical Q-Learning update

If
$$\beta = \delta \alpha$$

$$Q(x,u) \leftarrow Q(x,u) + \alpha(R(x,u,x') + \gamma \delta Q(x',\pi(x'))$$

$$- \tilde{R}(x,u) + \gamma \delta \tilde{Q}(x,u))$$

$$= Q(x,u) + \alpha(R(x,u,x') + \gamma' Q(x',\pi(x'))$$

$$- \tilde{R}(x,u) + \gamma' \tilde{Q}(x,u))$$

$$= Q(x,u) + \alpha((R(x,u,x') + \gamma' Q(x',\pi(x')))$$

$$- Q'(x,u))$$
(7)

With $\gamma' = \gamma \delta$. Notiche that Q'(x, u) is the current Q function with a different learning rate.

C. Variance dependent learning rate

$$\alpha = \frac{\sigma^2}{\sigma^2 + 1} \tag{8}$$

III. EXPERIMENTAL RESULTS

IV. CONCLUSION

REFERENCES

C. J. Watkins and P. Dayan, "Q-learning," *Machine learning*, vol. 8, no. 3-4, pp. 279–292, 1992.