AIRLAB
ARTIFICIAL INTELLIGENCE AND ROBOTICS LAB

Exploiting Structure and Uncertainty of Bellman Updates in Markov Decision Processes

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Problem

- Learning is **difficult** in **highly stochastic** environments
- **Uncertainty** in action-value function estimates propagates
- Some algorithms face this problem focusing on the **bias** of the estimate
- Despite empirical evidence, there is **no proof** that focusing on the bias is the solution

Contributions

1. Split the action-value function estimate **two components**:
   - The expected reward $\widetilde{R}(x,u)$
   - The expected next state value function $\widetilde{Q}(x,u)$
2. Use **different learning rates** for the two components
3. We provide **empirical results** showing the effectiveness of our approach

RQ-Learning Algorithm

Idea

Improve accuracy of the estimate exploiting:

Structure of the Bellman update — **Uncertainty of the estimation**

Approach

Split the action-value function in two components

$$\widetilde{R}(x,u) = \mathop{\mathbb{E}}_{x'\sim\mathcal{P}(x'|x,u)}\left[r(x,u,x')\right] \qquad \widetilde{Q}(x,u) = \mathop{\mathbb{E}}_{x'\sim\mathcal{P}(x'|x,u)}\left[\max_{u'} Q^*(x',u')\right]$$

$$Q^*(x,u) = \widetilde{R}(x,u) + \gamma\widetilde{Q}(x,u)$$

Compute the update as follows

$$\widetilde{R}_{t+1}(x,u) \leftarrow \widetilde{R}_t(x,u) + \alpha_t(R(x,u,x') - \widetilde{R}_t(x,u))$$

$$\widetilde{Q}_{t+1}(x,u) \leftarrow \widetilde{Q}_t(x,u) + \beta_t(\max_{u'} Q_t(x',u') - \widetilde{Q}_t(x,u))$$

Q-Learning: $\beta_t = \alpha_t$ **RQ-Learning:** $\beta_t \neq \alpha_t$ **RQ$_\delta$-Learning:** $\beta_t = \alpha_t\delta_t$

Exploit the variance of estimation to set the learning rate

1. Estimate the variance of the estimator $\widetilde{Q}$, using the sample variance of the target:

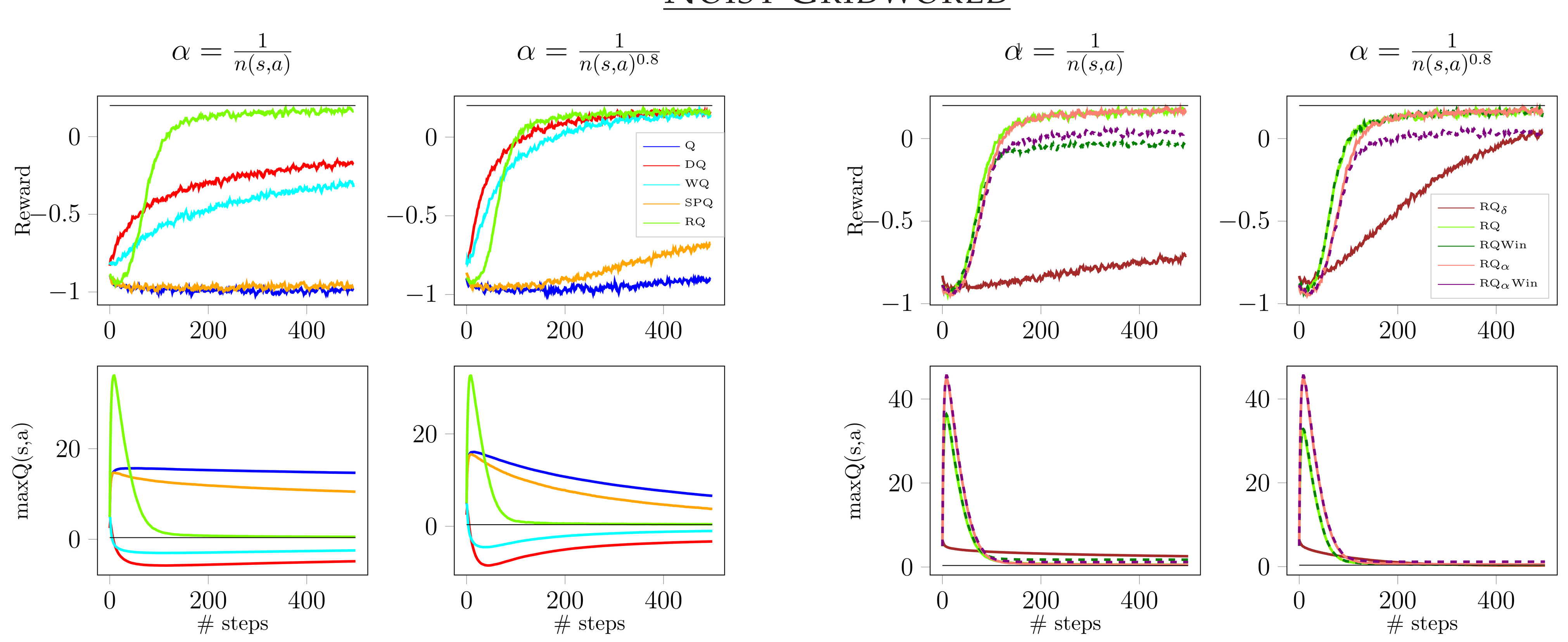
$$\boxed{\mathrm{Var}\left[\widetilde{Q}\right] \approx S_t^2\omega_t} \qquad \boxed{\omega_{t+1} = (1-\beta_t)^2\omega_t + \beta_t^2}$$

2. Compute the learning rate according to the **precision of the estimate**:

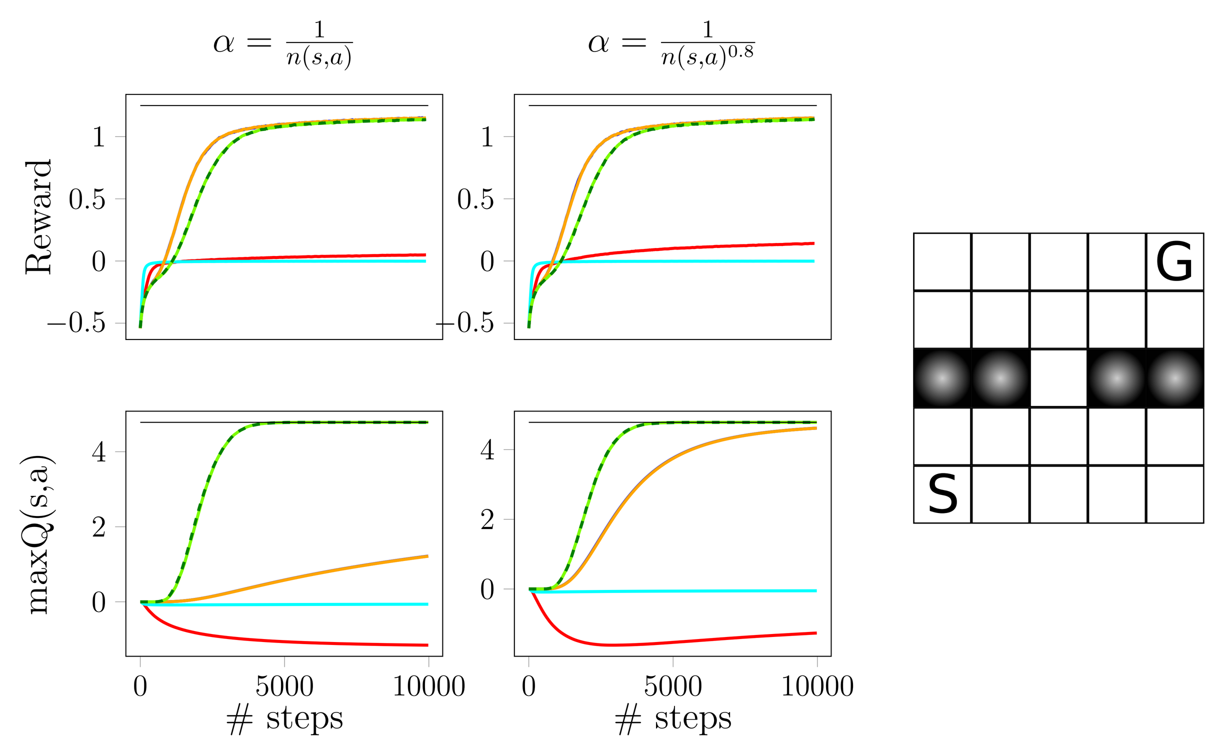
- **Inversely** proportional β: $\boxed{\beta_t = \dfrac{\sigma_e^2(t)}{\sigma_e^2(t)+\eta}}$
- **Directly** proportional δ: $\boxed{\delta_t = e^{\frac{\sigma_e^2}{\eta}\log\frac{1}{2}}}$

Empirical Results

Noisy Gridworld



Gridworld with Holes



Double Chain