Introduction to YNelson (hands-on tutorial)

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Introduction

This document is a hands-on guide to YNelson, Nelson nets and, partially, Ruby language. It is not assumed that the reader is familiar with any of these, though familiarity with Ruby syntax would be an advantage. If you have never heard about Nelson nets, do not wonder: it is a semi-novel concept based on Petri nets crossed with Ted Nelson's ZZ structures. If you follow this guide closely, you will receive a concise and efficient introduction to each of these three (remark: only the Petri net aspect is covered in this version of this guide. ZZ structure aspect will be covered in the future versions of this manual). Newly introduced Ruby keywords and terms are highlighted in red, Petri net terms in green, and YNelson keywords and terms in blue throughout this document.

YNelson is a domain model and a simulator of functional Petri nets living in the ZZ space. The Petri net flavor used in YNelson is similar, but not identical with hybrid functional Petri nets (HFPNs) introduced by Matsuno et al. [2011]. For a recent review of the various flavors of Petri nets, see eg. Bos [2008]. YNelson is implemented in Ruby programming language. It is publicly available as y_nelson gem (gem = Ruby library). YNelson is one of the series of Ruby gems (YPetri, YChem, YCell, Yzz, metrology library SY...), whose design intent is to bring ergonomy to biochemical modeling. Note that YNelson depends on YPetri and Yzz gems, its usage together with SY might be desirable if you are dealing with physical units. Also, YNelson use is not limited to biochemistry, but for all the applications where Petri nets and/or relational databases are used.

YNelson provides a *domain-specific language* (DSL), which you can use in scripts, or access interactively from inferior Ruby interpreter (*irb*). A DSLs can be thought of as APIs with user-friendly syntax. As a believer in robot equality, I dislike the distinction between API and UI (user interface), and prefer common textual command interface (CI) for humanoid as well as cybernetic users.

If you want to seriously work with complicated Petri Nets, no tool can avoid taking you through the process of learning the object model, interface and syntax of the language in which the interface is accessed. GUI tools can be used for simpler tasks (such as drawing arcs between places and transitions), but no tool can avoid using a real script language for the difficult parts, such as functions of the transitions. To operate YNelson, you will be learning powerful and intuitive syntax of a major scripting language. YNelson is open source and gives you freedom. All classes are introspectible and modifiable, even at runtime. Possible bugs or missing features never put the YNelson user in a dead end situation.

Using This Guide, or "The Hard Way Is Easier"

The phrase above is borrowed from the textbook by Zed Shaw named "Learn Ruby the Hard Way" (highly recommended, *hyperlink here*). Apart from being a great shark-jumper, Zed is a great teacher familiar with many programming languages, and I will borrow his teaching method here. Citing Zed, "The title says it's the hard way... but actually it's not." It's only "hard" because of the way people *used* to teach things. YNelson is a language. To learn it and see its usefulness, you will still need to do the incredibly simple things that all language learners do:

- 1. Go through each example.
- 2. Type each sample code exactly.
- 3. Make it run.

That's it. This might feel very difficult at first, but stick with it. It seems stupidly obvious, but, if you have a problem installing YNelson, running irb and typing, you will have a problem learning. If you go through this document without actually doing the exercises, you might as well just not even read it. Do not skip and do not skim. By typing each example exactly, you will be training your brain to focus on the details of what you are doing, as you are doing it. While you do these examples, typing each one in, you will be making mistakes. It's inevitable; humans do make mistakes. By doing so, you will train yourself to notice mistakes and other problems. Do not copy-paste. Type each code sample in, manually. The point is to train your hands, your brain, and your mind in how to read, write and see Ruby and YNelson code. If you skip, skim and copy-paste, you are cheating yourself out of the effectiveness of this guide.

Prerequisites

Most importantly, you will need a working installation of Ruby 1.9 on your computer. Once this condition is met, basic YNelson installation is as simple as typing "gem install y_nelson" in the command prompt. However, YNelson currently uses dependencies (gnuplot gem, graphviz gem...), whose installation may pose challenges. Once YNelson is installed, run *irb* command interpreter, and type:

```
require 'y_nelson'
```

After successful require, type:

```
include YNelson
```

This will augment your irb command session with interactive YNelson command interface (YNelson DSL CI). You have to re-run *irb* from the scratch, and re-type 'require' and 'include' statements before each of the usage examples written below. Please, also notice that this guide itself is alpha stage, so the actual YNelson version you will be using may somewhat differ from this guide. Also, the nucleotide metabolism model in Example 3 is yet to be tuned to be realistic. If something in this guide does not work, please do not hesitate to notify us, we will appreciate your feedback.

Example I: Basics

This example is a gentle introduction to Petri net terminology, YNelson DSL terminology, and Ruby syntax. The most basic capability, that YNelson offers, is that of user-driven token game. We will thus create a small Petri net containing 2 places and play token game with it.

Places

Type:

```
A = Place()
```

Syntactically, this will call *method* 'Place' of YNelson DSL and assign its *return value* to the *constant* A. In this case, the return value is an *object*, which is an *instance* of YNelson::Place *class*. We say that YNelson::Place class *represents* the concept of Petri net places in YNelson *domain model* (and 'Place' method is called a

constructor of YNelson::Place, which is not important.). Whole this object has now been assigned to A. On the screen, you will see the output: #<Place: name: A, marking: nil, default_marking: \$\phi\$>. (This is the inspect string of the object, created by YNelson::Place#inspect method, which is not important.) In the following, screen output will always be written immediately under the code sample, preceded by sherocket (#=>):

```
B = Place()
#=> #<Place: name: B, marking: nil, default_marking: ø>
```

We have so far defined 2 Petri net places named A, B. You can check it by typing:

These have automatically become part of a default Petri net instance (of YNelson::Net class; object id may vary):

```
net()
#=> #<Net: name: Top, 2 pp, 0 tt >
```

Of course, you have full power of Ruby at your disposal. To eg. list only place names as strings, you can use standard Ruby methods:

```
places.map( &:name )
#=> [:A, :B]
```

Here, Ruby map method transforms the *array* of places to the array of their names. The advantage of internal DSLs is, that one retains full power of the language, augmented with human-friendly, domain-specific CI. GUI systems generally sandbox the user inside their interface, with no way to overcome its limitations. But let us go on. Way above, you might have noticed 'nil' in the places' inspect strings. This is because we have specified no *marking* for A, B:

```
A.marking()
#=> nil
places.map( &:marking )
#=> [nil, nil]
```

Let us give these two places some marking:

```
A.marking = 2
#=> 2
B.marking = 5
#=> 5
```

The marking has indeed changed:

```
places.map( &:marking )
#=> [2, 5]
```

In classical Petri nets, this marking is understood as the number of *tokens* in each place, and is always an integer. In this case, A contains 2 tokens, while B contains 5 tokens. Tokens can represent anything: molecules, parts in the production line, trains in the railway network...

Transitions

The behavior of a Petri net is defined by transitions. Each transition defines a single operation: Adding / subtracting some amount of tokens to / from some places. Transition operation can often be expressed by the transition's stoichiometry - a list of places together with the number of tokens added / subtracted when the transition fires. For example, let us define:

```
A2B = Transition( stoichiometry: { A: -1, B: 1 } ) #=> #<Transition: A2B (tS)>
```

Stoichiometry of this transition is given by *hash* { A: -1, B: 1 }. This hash is available from A2B via 's' method:

```
A2B.s()
#=> {:A=>-1, :B=>1}
```

Keys of this hash are place names, values are stoichiometry coefficients. ('Stoichiometry' is a word known from the domain of chemistry, but 'stoicheion' means simply 'element' in Greek, so there is no problem with using it in the domain of general Petri nets.) To see the stoichiometry coefficients of A2B as an array, type:

```
A2B.stoichiometry() #=> [-1. 1]
```

Simply, A2B subtracts 1 token from A, and adds 1 token to B. This can represent conversion of A to B. In classical Petri nets, the arrows connecting places and transitions are called *arcs*. (The term was borrowed from graph theory.) For example, at this moment, our Petri net would contain one arc going from A to A2B, and one arc going from A2B to B. In YNelson domain model, 'arcs' are not first-class citizens. The word is understood simply as a synonym for transitions' connectivity – the list of places connected to each transition:

```
A2B.arcs()
#=> [#<Place: name: A, marking: 2, default_marking: Ø >,
#<Place: name: B, marking: 5, default_marking: Ø >]
The transition A2B is timeless:
```

```
A2B.timeless?()
#=> true
```

'Timeless' means that the transition's firing is not defined in time – it can fire anytime, as long as it is *enabled*. Classical Petri nets are timeless. In classical Petri nets, a transition is enabled whenever its *downstream arcs* allow it to happen. Downstream arcs, or *codomain* of a transition (these two are synonyms) are those places, whose marking can be directly affected by the transition's firing. In this case, both A and B is affected:

```
A2B.downstream_arcs()
[#<Place: name: A, marking: 2, default_marking: Ø>,
    #<Place: name: B, marking: 5, default_marking: Ø>]
A2B.codomain()
[#<Place: name: A, marking: 2, default_marking: Ø>,
    #<Place: name: B, marking: 5, default_marking: Ø>]
```

Since A2B subtracts tokens from A, it will be enabled so long, as there are any tokens left in A.

```
A2B.enabled?() #=> true
```

Token game

After A2B fires, the marking will change:

```
A2B.fire!()
#=> nil
places.map( &:marking )
#=> [1, 6]
A2B.fire!()
#=> nil
places.map( &:marking )
#=> [0, 7]
```

At this point, there are no tokens left in A and A2B becomes disabled:

```
A2B.enabled? #=> false
```

Attempt to fire a disabled transition *raises* an *error* (in Ruby, errors are friendly objects, who, like damsels in distress, are meant to be rescued with a bonus outcome):

```
A2B.fire! #=> RuntimeError: Firing of #<Transition: A2B (tS)> would result in negative marking!
```

Functional transitions and non-integer marking

So far, all the examples were compatible with classical Petri nets. But YNelson goes beyond – it represents functional Petri nets, similar to HFPNs proposed by Matsuno et al. [2011], which was already mentioned in the introduction. YNelson domain model is similar, but not identical. On the side of similarities, YNelson allows non-integer marking of places:

```
C = Place( marking: 7.77 )
#=> #<Place: name: C, marking: 7.77, default_marking: $\phi$</pre>
```

Here, you can notice that marking of places can be specified already upon initialization using ':marking' named argument. Let us now define a timed transition, representing logarithmic decay of C with a rate constant of 0.05:

```
C_decay = Transition( stoichiometry: { C: -1 }, rate: 0.05 )
#=> #<Transition: C_decay (TS)>
C_decay.timed?
#=> true
```

Here, in the transition constructor method, apart from 'stoichiometry:' named argument, another named argument, 'rate:', is introduced. Under 'rate:', it is possible to specify the transition's *function*, which governs its rate. Specifying a function in Ruby requires special syntax (called Ruby *closures*), based on lambda calculus. Ruby closures are easy to learn. But for the moment, in C_decay transition, we are taking use of the convenience, that allows us to pass a numeric value under 'rate:' named argument, and have YNelson create default mass action equation, using the supplied number as its rate constant. For C_decay stoichiometry, { C: -1 }, default mass action will be logarithmic decay with rate constant 0.05. Naturally, when firing timed transitions, the time interval (Δ time) must be specified, for which the transition should be active:

```
C_decay.fire!( 1 )
#=> nil
C.marking
#=> 7.3815
```

```
C_decay.fire! 1
#=> nil
C.marking
#=> 7.012425
C_decay.fire!(0.1)
#=> nil
C.marking
#=> 6.977362875000001
100.times do C_decay.fire! 1 end
#=> 100
C.marking
#=> 0.04130968078231133
```

The penultimate statement was a call of Ruby 'times' method with the integer 100 as the receiver, which results in 100 time repetition of the statement inside do ... end block. Instead of do ... end, it is possible to write a block using curly braces { ... }:

```
100.times { C_decay.fire! 1 }
#=> 100
```

This will cause another 100 time units of C_decay firing. This brings C marking down to almost zero:

```
C.marking
#=> 0.00024457517215434527
```

Four transition types

Thus far, we have demonstrated transitions with stoichiometry, which were either *timed* or not timed (*timeless*). Timed transitions are denoted by capital "T", timeless transitions by small "t". Similarly, stoichiometric transitions are denoted by capital "S", while transitions without stoichiometry (*non-stoichiometric* transitions) by small "s". Together, this gives 4 basic types of transitions: TS, tS, Ts, and ts.

The user can ask the type of a transition by calling the type method:

```
A2B.type #=> :tS
```

Or investigate the type with inquirer methods:

```
A2B.t?
#=> true
A2B.T?
#=> false
A2B.s?
#=> false
A2B.S?
#=> true
A2B. TS?
#=> false
A2B.tS?
#=> true
A2B.Ts?
#=> false
A2B.ts?
#=> false
```

Assignment transitions

In YNelson, there is one more transition type: an assignment transition, denoted by "A". Assignment transitions do not add or subtract tokens from their target, but completely replace the codomain marking with their output. (Again, in YNelson transitions, domain and codomain mean respectively upstream and downstream places.) Transitions other than A transitions can be collectively called non-assignment transitions, denoted by small "a". Note that assignment action is already achievable with plain ts transitions (by subtracting away the previous codomain marking), so A transitions are not strictly needed – their separate existence is just a syntactic convenience

One way to construct assignment transitions is by setting :assignment named argument to true:

```
A_to_42 = Transition codomain: A, assignment: lambda { 42 }
#=> #<Transition: A_to_42 (A Assign.)>
```

Firing this transition results in marking of A being set to 42:

```
A_to_42.fire!

#=> nil

A.marking

#=> 42
```

Assignment transitions are of special type A:

```
A_to_42.type

#=> : A

A_to_42.A?

#=> true

A_to_42.a?

#=> false
```

Example II: Convenience

So far, we have seen only one *constructor method* for transitions: Transition(). Transition() method accepts several different named arguments (:domain, :codomain, :stoichiometry :assignment, :rate, :action, :name...) and depending on their values, returns a YNelson::Transition class object of required type and properties.

Use of whole words in the constructor method makes the YNelson DSL very explicit. But for the cases, where trading readability for brevity is desirable, these syntactic constructs can be shortened. Actually, we have already used this convenience in the earlier examples. We didn't type:

```
Transition( name: "A2B", codomain: [A, B], stoichiometry: [-1, 1] )
A2B = transition( :A2B )

Instead, we just typed
A2B = Transition( stoichiometry: { A: -1, B: 1 } )

Even shorter way to express the same would be:
A2B = Transition s: { A: -1, B: 1 }
```

The above is a timeless transition. But we could think eg. about a more complicated transition, that would transfer tokens from B to A with rate depending on the square root of the product of marking of C and D. Start a new irb session and type:

```
require 'y_nelson'
include YNelson
A = Place( default_marking: 5 )
B = Place m!: 5 # notice "m!" alias for "default marking"
C = Place m!: 1
D = Place m!: 1
Let's check our work:

places.map &:m
#=> [5, 5, 1, 1]
```

Indeed, the net state has been set according to the default markings of the places. Now let's define the transition we want:

To prove that it works, let's fire it for 0.1 time units:

```
B2A.fire! 0.1
#=> nil
places.map &:m
#=> [5.1, 4.9, 1, 1]
```

You can try to change marking of C and D to control the rate:

```
[A, B].each &:reset_marking
C.m = 4
D.m = 9
places.map &:m
#=> [5, 5, 4, 9]
B2A.fire! 0.1
places.map &:m
#=> [5.6, 4.4, 4, 9]
```

We can see that the rate of B2A has risen 6 times as expected (4 * 9 is 36), so B2A works. The question is, could we have written B2A more concisely? For TS transitions (check B2A.type to make sure that it's a TS transition), TS() constructor is available, allowing to express the same transition with a shorter syntactic construct:

```
B2A = TS \text{ domain: } [C, D], A: 1, B: -1 \text{ do } |x, y| (x * y) ** 0.5 \text{ end}
```

Restart the irb session again and use this shorter construct to see that the resulting transition behaves like before. Note the do ... end part of the construct: Using lambda syntax, it defines the rate function of the transition.

One more convenience constructor I want to mention here is AT() constructor for assignment transition. Earlier, we defined:

```
A_to_42 = Transition codomain: A, assignment: lambda { 42 }
```

This can be conveniently rewritten using AT() constructor as:

```
A_{to}_42 = AT A do 42 end
```

In short, syntactic shorthands are less readable than full Transition() statements, but can save a lot of space and typing. In any case, in Ruby, the user can easily defined new aliases and routines that make the frequent tasks easier to type.

Example III: YNelson::Simulation

So far, we have been defining Petri nets and playing the token game using #fire! method, let us now simulate a Petri net inside YNelson::Simulation. Restart your irb session as described in the Prerequisites chapter. We will now define 2 places. Since we are going to use TimedSimulation, the marking owned by YNelson::Place instances is irrelevant. We just need to specify the initial state. One way to do this is by specifying::default_marking named argument:

```
A = Place( default_marking: 0.5 )
#=> #<Place: name: A, marking: 0.5, default_marking: 0.5>
B = Place( default_marking: 0.5 )
#=> #<Place: name: B, marking: 0.5, default_marking: 0.5>
```

Now let us define a transition corresponding to pumping A out of the system at a constant rate 0.005 per time unit.

```
A_pump = Transition( stoichiometry: { A: -1 }, rate: proc { 0.005 } ) #=> #<Transition: A_pump (TS)>
```

Here, proc { 0.005 } is a closure, that defines the rate function. Closure proc { 0.005 } ensures fixed rate 0.005 per time unit regardless of the marking of A. You can notice, that this closure expects no arguments and always outputs 0.005 as its return value. It is the simplest possible way to write a constant function. For comparison,

```
B_decay = Transition( stoichiometry: { B: -1 }, rate: 0.05 )
#=> #<Transition: B_decay (TS)>
```

will behind the scenes automatically create a slightly more complicated mass action closure, which is logarithmic decay of B in this case. (You should remember this from **Example I**.) Now we have created a net of 2 places and 2 transitions:

```
net
#=> #<Net: name: Top, 2 pp, 2 tt>
```

We can execute this Petri net as TimedSimulation simply by typing:

```
run!
#=> 60
```

At this point, run! creates and executes a TimedSimulation instance. The return value is the simulation instance itself (see the inspect string above), which by now has already finished execution and holds the simulation results. This simulation instance is accessible via simulation method.

```
simulation
#=> #<Simulation: time: 60, pp: 2, tt: 2, oid: 75530290>
```

The simulation does not affect the net. The simulation instance works with its own "mental image" of the net, therefore the marking owned by YNelson::Place instances does not change:

```
places.map &:marking #=> [0.5, 0.5]
```

In a general case, it would be necessary to specify the simulation settings (step size, sampling rate, simulation time etc.) before running the simulation. Since we have not specified any, default settings were used:

```
simulation.settings
#=> {:step=>0.1, :sampling=>5, :time=>0..60}
```

We can see sampling done by the simulation by typing:

print_recording #=> : A :B -----0.5000 0.5000 0.4750 0.3892 0.4500 0.3029 0.4250 0.2357 0.4000 0.1835 0.3750 0.1428 0.3500 0.1111 0.3250 0.0865 0.3000 0.0673 0.2750 0.0524 0.2500 0.0408 0.2250 0.0317 0.2000 0.0247 nil

Indeed, A is decreasing at a constant rate, while B undergoes logarithmic decay. In a graphical desktop, we can plot a graph (requires *gnuplot* gem):

```
recording.plot # plots a graph
#=> ""
```

Previous command plots the default feature set, which is marking of the places. We can investigate also features of the recording (gradient or delta of places, firing or flux of the transitions...):

```
recording.gradient.plot
recording.flux.plot
recording.delta( delta_time: 0.1 ).plot
```

The last feature set — delta — requires delta_time named argument to extrapolate the changes (deltas) of the places in the given delta time. As for firing, a feature of tS transitions, the plot would show nothing here, as there are no tS transitions here.

Example IV: A real system.

A highly simplified cell-biological pathway simulated with YNelson::TimedSimulation. Let's first define some assumptions. Type in the following commands (output not shown):

```
require 'y_nelson' and include YNelson
     Pieces_per_microM = 100_000
     set_step 10
     set_sampling 30
     set_target_time 30 * 60
Let's define places corresponding to chemical species first (note that :m! is a synonym for :default_marking)
     AMP = Place m!: 8695.0
     ADP = Place m!: 6521.0
     ATP = Place m!: 3152.0
     DeoxyCytidine = Place m!: 5.0
     DeoxyCTP = Place m!: 20.0
     DeoxyGMP = Place m!: 20.0
     UMP_UDP_pool = Place m!: 2737.0
     DeoxyUMP_DeoxyUDP_pool = Place m!: 10.0
     DeoxyTMP = Place m!: 50.0
     DeoxyTDP_DeoxyTTP_pool = Place m!: 100.0
     Thymidine = Place m!: 10.0
All the places above have their marking in micromolars. The enzyme places below will have their marking in
molecules per cell:
     TK1 = Place m!: 100_000 / Pieces_per_microM
     TYMS = Place m!: 100_000 / Pieces_per_microM
     RNR = Place m!: 100_000 / Pieces_per_microM
     TMPK = Place m!: 100_000 / Pieces_per_microM
Enzyme molecular weights:
     TK1_kDa = 24.8
     TYMS_kDa = 66.0
     RNR_kDa = 140.0
     TMPK_kDa = 50.0
Enzyme specific activities (in micromolar / minute / mg):
     TK1_a = 5.40
     TYMS_a = 3.80
     RNR a = 1.00
     TMPK_a = 0.83
Some species are kept fixed (as simulation-level clamps):
     clamp AMP: 8695.0, ADP: 6521.0, ATP: 3152.0
     clamp DeoxyCytidine: 0.5, DeoxyCTP: 1.0, DeoxyGMP: 1.0
     clamp Thymidine: 0.5
     clamp UMP_UDP_pool: 2737.0
Before defining transitions, let's define some functions first:
     Vmax_per_min_per_enz_molecule =
       lambda { |spec_act_microM_per_min_per_mg, kDa|
                   spec_act_microM_per_min_per_mg * kDa }
     Vmax_per_min =
```

```
lambda { | spec_act, kDa, enz_molecules_per_cell |
                Vmax_per_min_per_enz_molecule.( spec_act, kDa ) *
                  enz_molecules_per_cell }
     Vmax_per_s =
       lambda { |spec_act, kDa, enz_mol_per_cell|
                Vmax_per_min.( spec_act, kDa, enz_mol_per_cell ) / 60 }
      lambda { |km, ki_hash={}|
                ki_hash.map { | c, ki | c / ki }.reduce( 1, :+ ) * km }
     Occupancy =
      lambda { |c, km, compet_inh_w_Ki_hash={}|
                c / ( c + Km_reduced.( km, compet_inh_w_Ki_hash ) ) }
    MM_with_inh_microM_per_second =
       lambda { |c, spec_act, kDa, enz_mol_per_cell, km, ki_hash={}|
                 Vmax_per_s.( spec_act, kDa, enz_mol_per_cell ) *
                   Occupancy.( c, km, ki_hash ) }
    MMi = MM_with_inh_microM_per_second
Michaelis constants:
    TK1_Thymidine_Km = 5.0
     TYMS DeoxvUMP Km = 2.0
    RNR\_UDP\_Km = 1.0
    DNA_creation_speed = 3_000_000_000 / ( 12 * 3600 )
    TMPK_DeoxyTMP_Km = 12.0
And finally, let us define the transitions:
     Transition name: :TK1_Thymidine_DeoxyTMP,
                domain: [ Thymidine, TK1, DeoxyTDP_DeoxyTTP_pool, DeoxyCTP,
                          DeoxyCytidine, AMP, ADP, ATP],
                stoichiometry: { Thymidine: -1, DeoxyTMP: 1 },
                rate: proc { |c, e, pool1, ci2, ci3, master1, master2, master3|
                             ci1 = pool1 * master3 / ( master2 + master3 )
                             MMi.(c, TK1_a, TK1_kDa, e, TK1_Thymidine_Km,
                                   ci1 \Rightarrow 13.5, ci2 \Rightarrow 0.8, ci3 \Rightarrow 40.0)
     Transition name: :TYMS_DeoxyUMP_DeoxyTMP,
                domain: [ DeoxyUMP_DeoxyUDP_pool, TYMS, AMP, ADP, ATP ],
                stoichiometry: { DeoxyUMP_DeoxyUDP_pool: -1, DeoxyTMP: 1 },
                rate: proc { |pool, e, mono, di, tri|
                             c = pool * di / (mono + di)
                               MMi.( c, TYMS_a, TYMS_kDa, e, TYMS_DeoxyUMP_Km ) }
    Transition name: :RNR_UDP_DeoxyUDP,
                domain: [ UMP_UDP_pool, RNR, DeoxyUMP_DeoxyUDP_pool, AMP, ADP, ATP ],
                stoichiometry: { UMP_UDP_pool: -1, DeoxyUMP_DeoxyUDP_pool: 1 },
                rate: proc { | pool, e, mono, di, tri|
                             c = pool * di / (mono + di)
                             MMi.( c, RNR_a, RNR_kDa, e, RNR_UDP_Km ) }
    Transition name: :DNA_polymerase_consumption_of_DeoxyTTP,
                stoichiometry: { DeoxyTDP_DeoxyTTP_pool: -1 },
                rate: proc { DNA_creation_speed / 4 }
     Transition name: :TMPK_DeoxyTMP_DeoxyTDP,
                domain: [ DeoxyTMP, TMPK, DeoxyTDP_DeoxyTTP_pool, DeoxyGMP, AMP, ADP, ATP ],
```

```
stoichiometry: { DeoxyTMP: -1, TMPK: 0, DeoxyTDP_DeoxyTTP_pool: 1 },
                rate: proc { |c, e, pool, ci4, mono, di, tri|
                              ci1 = di
                              ci2 = pool * di / ( di + tri )
                              ci3 = pool * tri / ( di + tri )
                              MMi.(c, TMPK_a, TMPK_kDa, e, TMPK_DeoxyTMP_Km,
                                    ci1 => 250.0, ci2 => 30.0, ci3 => 750, ci4 => 117 ) }
     # require 'mathn'
     Transition name: :PhosphataseI,
                stoichiometry: { DeoxyTMP: -1, Thymidine: 1 },
                rate: 0.04
     Transition name: : PhosphataseII,
                stoichiometry: { DeoxyTDP_DeoxyTTP_pool: -1, DeoxyTMP: 1 },
                rate: 0.01
The created net can be visualized by:
     net.visualize
The simulation should work.
     run!
State recording can be plotted by:
     recording.plot
Flux of the transitions can be plotted by:
     recording.flux.plot
```

Example V: Using SY.

Here, we'll take a look at using YNelson with SY metrology library. If you are experienced with biochemical modeling, then you surely know how big pain in the heel physical units are. Also, in **Example III**, you might have noticed how much attention has been spent on units (in the assumptions, variable names, constant names...) You could have noticed messy unit conversion formulas. The aim of SY is to take care of all this, to relieve the modeler from the task of unit conversion, to clean up the model code, and let the modeler concentrate on the real issue.

SY metrology library

```
SY is publicly available as a Ruby gem 'sy'. After installing it (gem install sy), type:
```

```
require 'sy'
```

Afterwards, your Numeric objects (that is, numbers) should respond to methods representing physical units:

```
1.m
#=> #<±Magnitude: 1.m>
1.s
#=> #<±Magnitude: 1.s>
1.kg.m.s(-2)
#=> #<±Magnitude: 1.N>
1.cm + 1.mm
#=> #<±Magnitude: 0.011.m>
```

The core of the trick is that instead of naked numbers, numbers become magnitudes (SY::Magnitude) of specified physical quantities:

```
1.m.quantity
#=> #<Quantity:Length±>
1.cm.min<sup>-1</sup>.quantity
#=> #<Quantity:Speed±>
```

(You can type 1.cm.min(-1) if you find it difficult to type Unicode superscript characters "-1".) Magnitudes can be converted back to numbers with amount (alias to_f) method:

```
1.km.amount

#=> 1000.0

1.cm.to_f

#=> 0.01
```

Collaboration between SY and YNelson

Enter:

```
A = Place m!: 3.mM
#=> #<Place: name: A, marking: 0.003.M, default_marking: 0.003.M >
B = Place m!: 4.mM
#=> #<Place: name: B, marking: 0.004.M, default_marking: 0.004.M >
A2B = Transition s: { A: -1, B: 1 }, rate: 0.05.s<sup>-1</sup>
#=> #<Transition: A2B (SR) >
B_decay = Transition s: { B: -1 }, rate: 0.002.s<sup>-1</sup>
#=> YNelson::Transition[ B_decay: stoichiometric transition with rate ]
```

Now we have created places and transitions, whose marking and rate closures are defined in physical units. Presently, YNelson::TimedSimulation will not accept such Petri net, so the only thing we can do is play the token game ourselves:

```
fire_both_transitions = proc { |delta_t|
   A2B.fire! delta_t
   B_decay.fire! delta_t
}
#=> #<Proc:0x9b48f1c@(irb):19>
```

Here, we have defined a closure accepting one argument Δt , which it will use to fire! both A2B and B_decay. By calling this closure repeatedly, we can simulate the network without use of TimedSimulation:

```
places.map &:marking
#=> [#<±Magnitude: 0.003.M>, #<±Magnitude: 0.004.M>]
fire_both_transitions.( 1.s )
#=> nil
places.map &:marking
#=> [#<±Magnitude: 0.00285.M>, #<±Magnitude: 0.00414.M>]
100.times do fire_both_transitions.( 1.s ) end
#=> 100
places.map &:marking
#=> [#<±Magnitude: 1.69e-05.M>, #<±Magnitude: 0.0058.M>]
A.marking.in :µM
#=> 16.873508277951963
B.marking.in :µM
#=> 5797.976678013365
```

Example VI: Other simulation methods

At this moment, the default simulation method is implicit Euler (or $pseudo_euler - pseudo$ because timeless transitions and assignment transitions also fire at each step in time). From other simulation methods, Gillespie algorithm is available:

```
require 'y_nelson' and include YNelson
A = Place m!: 10
B = Place m!: 10
AB = Place m!: 0
AB_association = TS A: -1, B: -1, AB: 1, rate: 0.1
AB_dissociation = TS AB: -1, A: 1, B: 1, rate: 0.1
A2B = TS A: -1, B: 1, rate: 0.05
B2A = TS A: 1, B: -1, rate: 0.07
set_step 1
set_target_time 50
set_sampling 1
set_simulation_method :gillespie
run!
print_recording
plot_state
```

The state recording should show the random walk of the system state over 50 time units.

References

- W. Bos. Modeling biological systems using Petri nets. 2008.
- H. Matsuno, Y. Tanaka, H. Aoshima, A. Doi, M. Matsui, and S. Miyano. Biopathways_representation_and_simulation_on_hybrid_functional_petri_net. Stud Health Technol Inform, 162:77-91, 2011. URL http://www.ncbi.nlm.nih.gov/pubmed/ 21685565.