Algorithms

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Lesson #8:

All-Pairs Shortest Paths



All-Pairs Shortest Paths

- Given:
 - Directed graph G = (V, E)
 - Weight function $w : E \rightarrow R$
- Compute:
 - The shortest paths between all pairs of vertices in a graph
 - Representation of the result: an $n \times n$ matrix of shortest-path distances $\delta(u, v)$

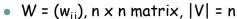
All-Pairs Shortest Paths - Solutions



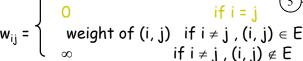
- Run BELLMAN-FORD once from each vertex:
 - $O(|V|^2|E|)$, which is $O(|V|^4)$ if the graph is dense
- If no negative-weight edges, could run **Dijkstra's** algorithm once from each vertex:
 - $O(|V|^3)$ if the graph is dense.
 - O(|V||E||g|V|) if the graph is sparse.

All-Pairs Shortest Paths

 Assume the graph (G) is given as adjacency matrix of weights



• Vertices numbered 1 to n



- Output the result in an n x n matrix $D = (d_{ij})$, where $d_{ij} = \delta(i, j)$
- Note: negative weights are allowed but for now no negative cycles.

2 4 8 3 4 8 3 1 -5 6 4

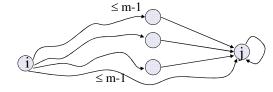
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Dynamic Programming



• $d_{ij}^{(m)}$ = weight from i to j with \leq m edges $d_{ij}^{(0)}$ = 0 if i = j and $d_{ij}^{(0)}$ = ∞ if i \neq j $d_{ij}^{(m)}$ = min($d_{ij}^{(m-1)}$, min_k{ $d_{ik}^{(m-1)}$ + w_{kj}})= = min_k{ $d_{ik}^{(m-1)}$ + w_{kj}} (Why?)

• Runtime = $O(n^4)$



Matrix Multiplication



• Similar: $C = A \cdot B$, two n × n matrices $c_{ij} = \sum_k a_{ik} \cdot b_{kj}$ $O(n^3)$ operations

• $c_{ij} = \min_k \{a_{ik} + b_{kj}\}$

D⁽¹⁾=W

• $D^{(m)} = D^{(m-1)} \cdot W = W^m$

• Time is $O(n \cdot n^3) = O(n^4)$

• Repeated squaring: $W^{2n} = W^n \times W^n$ Compute W, W^2 , W^4 ,..., W^{2k} , k= log n, $O(n^3 \log n)$

Floyd-Warshall Algorithm

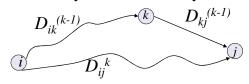


- Vertices in G are given by V = {1, 2, ..., n}
- Consider a path $p = \langle v_1, v_2, ..., v_k \rangle$
 - An intermediate vertex of p is any vertex in the set $\{v_2, v_3, ..., v_{k-1}\}$

Floyd-Warshall Algorithm



- $d_{ij}^{(k)}$ = length of shortest path from i to j with intermediate vertices from $\{1, 2, ..., k\}$:
- $\delta(i, j) = d_{ii}^{(n)}$
- Dynamic Programming: recurrence
 - $d_{ij}^{(0)} = w_{ij}$
 - $d_{ij}^{(k)} = \min\{d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)}\}$



intermediate nodes in {1, 2, ..., k}

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Example

 $d_{ii}(k)$ = the weight of a shortest path from vertex i to vertex j with all intermediary vertices drawn from $\{1, 2, ..., k\}$

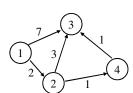
•
$$d_{13}^{(0)} =$$

•
$$d_{13}^{(1)} =$$

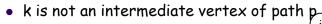
•
$$d_{13}^{(2)} =$$

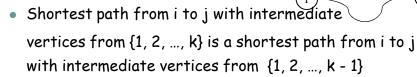
•
$$d_{13}^{(3)} =$$

•
$$d_{13}^{(4)} =$$



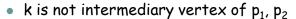
The Structure of a Shortest Path





• k is an intermediate vertex of path p

- p₁ is a shortest path from i to k
- p₂ is a shortest path from k to j



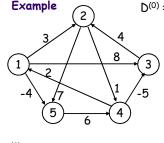
• p₁ and p₂ are shortest paths from i to k with vertices from {1,2,...,k-1}

FLOYD-WARSHALL(W)

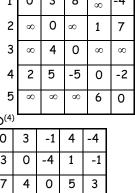


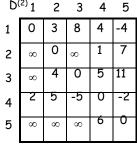
- $D^{(0)} \leftarrow W$ for $k \leftarrow 1$ to n do for $i \leftarrow 1$ to n do for $j \leftarrow 1$ to n **do** $d_{ij}^{(k)} \leftarrow \min (d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)})$ 5.
- return D(n)
- Running time: $\Theta(n^3)$

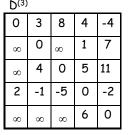
$d_{ij}^{(k)} = \min \{d_{ij}^{(k-1)}, d_{ik}^{(k-1)} + d_{kj}^{(k-1)}\}$

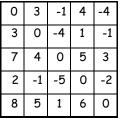


D ₍₀₎	= V	V ₁	2	3	4	5	D ⁽¹⁾ 1 2 3 4 1 0 3 8			
	1	0	3	8	8	-4	1	0	3	8
(3)	2	8	0	×	1	7	2	8	0	∞
-5	3	8	4	0	×	∞	3	8	4	0
•	4	2	8	-5	0	8	4	2	5	-5
	5	∞	8	∞	6	0	5	8	8	∞
~ (A)										



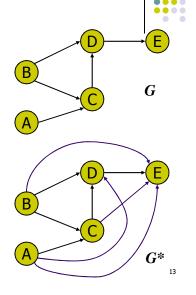






Question

A Transitive Closure of a graph
 G = (V,E) is the graph
 G*=(V,E*) where
 E*={(i,j)/ there exist a path from i to j in G.}
 Given a graph G, use Floyd-Warshall's algorithm to compute the closure of G



Summary- Single Source Shortest Path



Type of Graph	Algorithm	Time
No weights	BFS	O(V + E)
Non negative weights	Dijkstra	O(V ²)/O(E log V)
Weighted graph	Belman-Ford	O(V E)

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Summary- All-Pairs Shortest Paths



Type of Graph	Algorithm	Time		
No weights	V times BFS	O(V (E + V))		
Non negative weights	V times Dijkstra	O(V ³)/O(V E log V)		
Weighted graph	V times Belman-Ford	$O(V ^2 E)$		
Weighted graphs No negative cycles	Floyd-Warshall	O(V ³)		

Sparse graphs



- What if the graph is sparse?
 - If no negative edges run repeated Dijkstra's
 - If negative edges let us somehow change the weights of all edges (to w) and then run repeated Dijkstra's
- Requirements for *reweighting*.
 - Non-negativity: for each (u,v), $w'(u,v) \ge 0$
 - Shortest-path equivalence: for all pairs of vertices u and v, a path p is a shortest path from u to v using weights w if and only if p is a shortest path from u to v using weights w'.

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Reweighting theorem

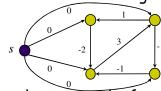


- Rweighting does not change shortest paths
 - Let $h: V \to \mathbf{R}$ be any function
 - For each (u,v)∈ E, define
 w'(u,v) = w(u,v) + h(u) h(v).
 - Let $p = (v_1, v_2, ..., v_k)$ be any path from v_1 to v_k
 - Then: $w(p) = \delta(v_1, v_k) \Leftrightarrow w'(p) = \delta'(v_1, v_k)$

Choosing reweighting function



- How to choose function h?
- The idea of Johnson:
 - 1. Augment the graph by adding vertex s and edges (s, v) for each vertex v with 0 weights.



- 2. Compute the shortest paths from s in the augmented graph (using Belman-Ford).
- = 3. Make $h(v) = \delta(s, v)$

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Johnson's algorithm



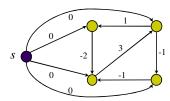
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- Why does it work?
 - By definition of the shortest path: for all edges (u,v), $h(v) \le h(u) + w(u,v)$
 - Thus, $w(u,v) + h(u) h(v) \ge 0$
- Johnson's algorithm:
 - 1. Construct augmented graph
 - 2. Run Bellman-Ford (possibly report a negative cycle), to find $h(v) = \delta(s, v)$ for each vertex v
 - 3. Reweight all edges:
 - $w'(u,v) \leftarrow w(u,v) + h(u) h(v).$
 - 4. For each vertex ω
 - Run Dijkstra's from u, to find $\delta(u, v)$ for each v
 - For each vertex $v: D[u][v] \leftarrow \delta(u, v) + h(v) h(u)$

Example, Analysis



• Do the reweighting on this example:



What is the running time of Johnson's?