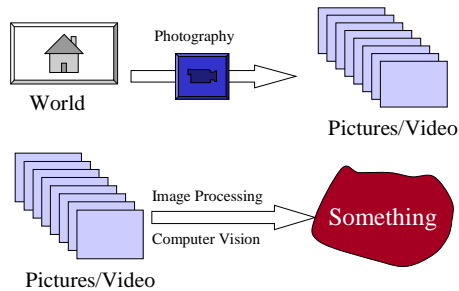


Image Processing (Computer Vision)

“Inverse Photography”



Stages in Computer Vision

- **Physics:** Image Formation (Light, Reflectance)
- **Physics:** Cameras: Optics (Lens), Sensors (CCD, CMOS)
- **Image Processing:** Coding (Transmission, Compression)
- **Image Processing:** Enhancement (Noise Cleaning, Colors)
- **IP-CV:** Feature Detection (Objects, Actions, Motion)
- **Computer Vision:** Scene recovery (3D, Reflectance)
- **Computer Vision:** Object Recognition
- **Human and Machine Vision:** Visual Perception
- **Robotics:** Control Action (autonomous driving)

Vision in Nature = Smart, Moving

- Only smart and moving organisms see!
 - Plants do not have eyes
- Visual recognition at early development
 - Babies recognize and track the mother very early
- Most of the brain is involved in vision processing

Application: Recognition



1984

2000

National Geographics: “Afghan Girl”

Panoramic Stereo Mosaics (Last Exercise)



Image Processing: 2005/2006

Teacher: Shmuel Peleg <peleg@cs.huji.ac.il>

Assistant: Yael Pritch <yaelpri@cs.huji.ac.il>

Ozer Horaa: ?????? <???@cs.huji.ac.il>

Textbook:

Gonzalez & Woods, Digital Image Processing (2nd Ed.), Addison Wesley, 2002.

Jain, Pratt, Rosenfeld,....

Expected Work:

4 Written Exercises

4 individual computer exercises (**MATLAB**)

Grading:

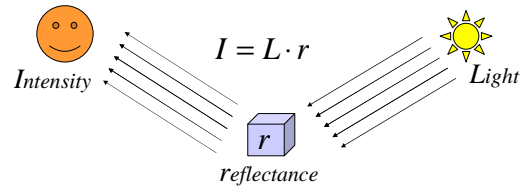
Exam: 60-70%; Exercises: 30-40%

Relevant Computer Vision Courses

- Image Processing (Peleg)
 - Computer Vision Seminar (Sundays 10-12)
 - Computer Graphics (Sun 12-14, Wed 16-18, Lischinski)
 - Introduction to Machine Learning (Mon 08-10, Tue 14-16, Shashua)
 - Mathematical Methods in IP, CV, and CG (Thu 10-12)
-
- Computer Vision (Peleg-Shashua-Weinshall)
 - Image Sequence Analysis (Seminar, Peleg)
 - Medical Image Processing & Robotics (Joskowicz)

Image Formation

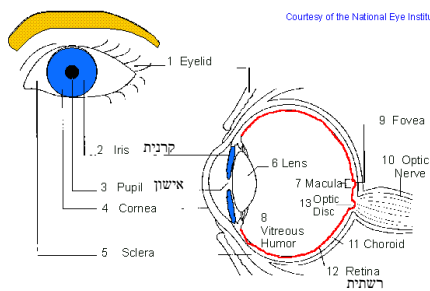
- Light is emitted by light source
- Light is reflected from objects
- Reflected light is sensed by eye or by camera



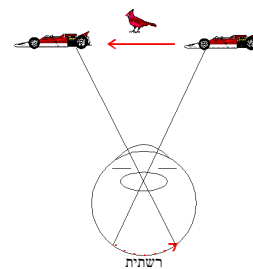
The Human Eye (2.1)

<http://www.yorku.ca/research/vision/eye/>

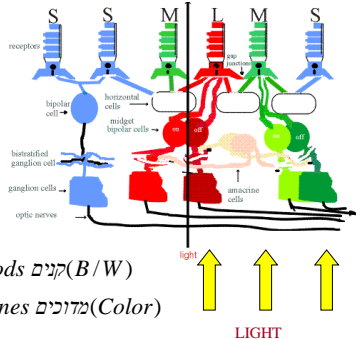
Courtesy of the National Eye Institute



World to Retina Projection



The Retina

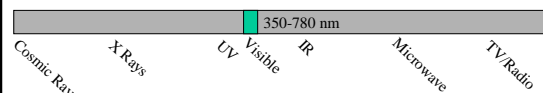
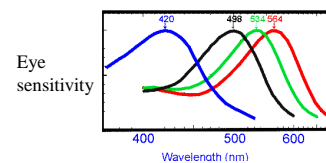


$120 \cdot 10^6$ Rods קנים (B/W)

$7 \cdot 10^6$ Cones גזוזים (Color)

$\approx 10^4$ Nerves

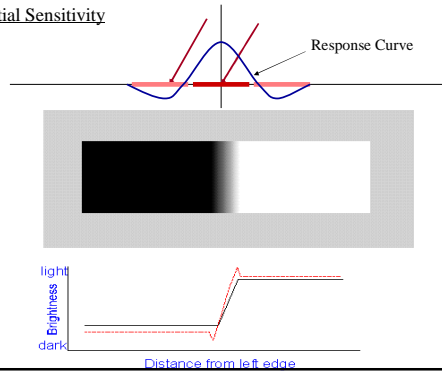
Colors - Electromagnetic Radiation



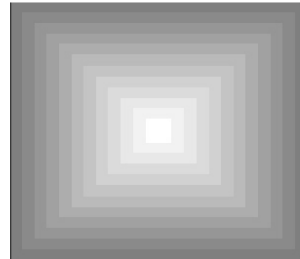
- Maximum Sun Energy: 450 nm
- Best Atmospheric Transmittance: Visible Range

Mach Bands (1)

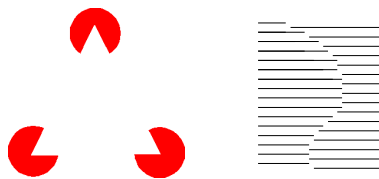
Spatial Sensitivity



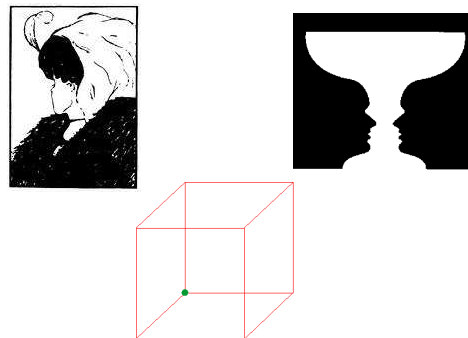
Mach Bands (2)



Visual Illusions



Dual Interpretations



What is That?



Image Digitization (2.3)

- Transforming the 3D world into 2D image
 - Perspective Projection (Optics)
- Sampling the Image Plane
 - Finite number of **Pixels**
- Quantizing the color/gray-level
 - Finite number of colors

Perspective Projection (2.5.2)

- Transforming the 3D world into 2D image
 - Continuous Perspective Projection
 - optics

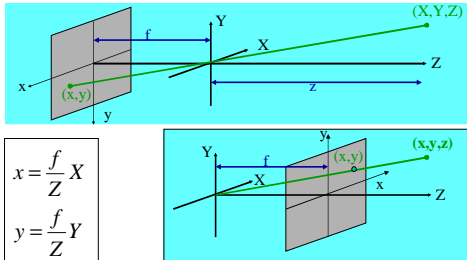
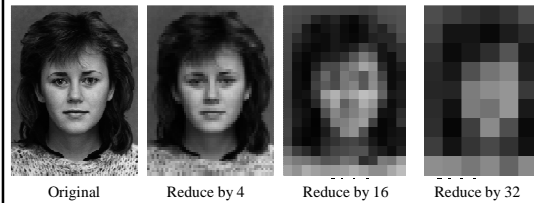


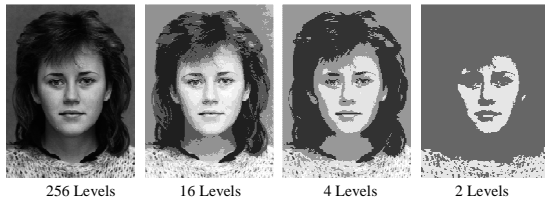
Image Sampling

- Sampling the Image Plane
 - Finite number of **Pixels**



Color/Grey-level Quantization

- Quantizing the color/gray-level
 - Finite number of colors

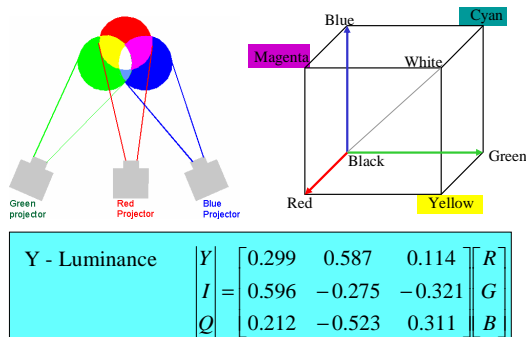


Digital Pictures

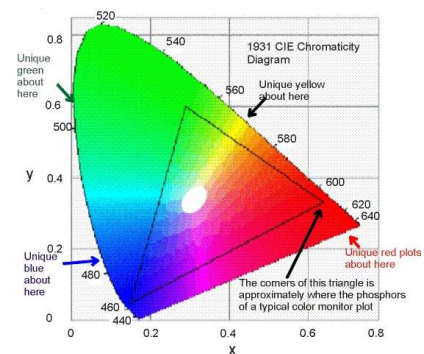
- A Matrix of numbers (B/W)
- A Matrix of triplets (RGB Color, etc.)

1	2	3	4	5	6	7	8	9	10	9	8	7	6	5
2	4	5	6	7	8	9	10	11	12	11	10	9	8	7
3	5	6	7	8	9	10	11	12	13	12	11	10	9	8
4	6	7	8	9	10	11	12	13	14	13	12	11	10	9
5	7	8	9	10	11	12	13	14	15	14	13	12	11	10
6	8	9	10	11	12	13	14	15	16	15	14	13	12	11
7	9	10	11	12	13	14	15	16	17	16	15	14	13	12
8	10	11	12	13	14	15	16	17	18	17	16	15	14	13
9	11	12	13	14	15	16	17	18	19	18	17	16	15	14
10	12	13	14	15	16	17	18	19	20	19	18	17	16	15
9	11	12	13	14	15	16	17	18	19	18	17	16	15	14
8	10	11	12	13	14	15	16	17	18	17	16	15	14	13
7	9	10	11	12	13	14	15	16	17	16	15	14	13	12
6	8	9	10	11	12	13	14	15	16	15	14	13	12	11
5	7	8	9	10	11	12	13	14	15	14	13	12	11	10
4	6	7	8	9	10	11	12	13	14	13	12	11	10	9
3	5	6	7	8	9	10	11	12	13	12	11	10	9	8
2	4	5	6	7	8	9	10	11	12	11	10	9	8	7
1	3	4	5	6	7	8	9	10	11	10	9	8	7	6

Color Spaces (4.6)

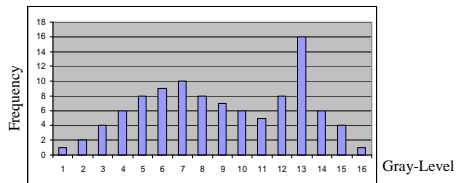


CIE Chromaticity Diagram (1931)



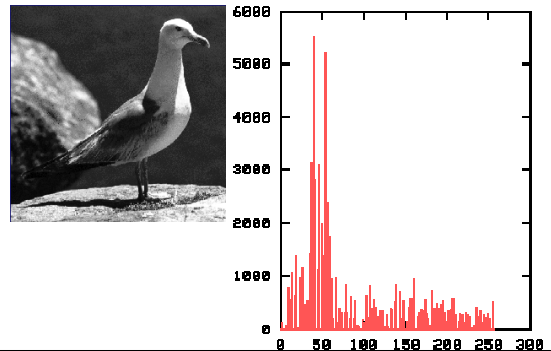
The Histogram

- Frequency counting of gray levels



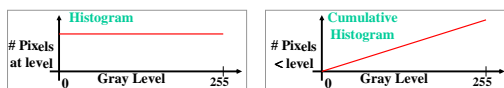
- In continuous intensities:
a continuous probability distribution $p(g)$

Histogram - Example

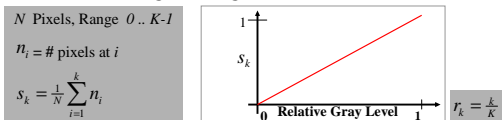


Histogram Equalization

- Equal usage of all gray levels



- Normalizing to range 0..1

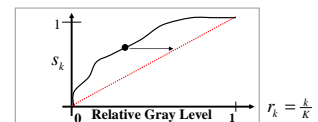
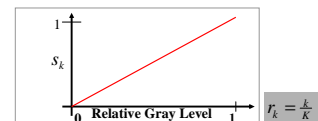


Histogram Equalization

N Pixels, Range $0 \dots K-1$

$n_i = \# \text{ pixels at } i$

$$S_k = \frac{1}{N} \sum_{i=1}^k n_i$$



Histogram Equalization (cont.)

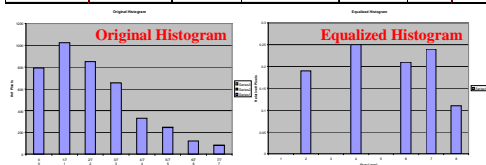
N Pixels, Range $0 \dots K-1$ $n_i = \# \text{ pixels at } i$

Normalized Cumulative Occurrence: $s_j = \frac{1}{N} \sum_{i=1}^j n_i$

- For every original level j :
Change its gray level to $S_j \cdot (K-1)$
- Stretch gray levels back to $[0 \dots K-1]$

Equalization Example

Gray Level (k)	Normalized (n)	# Pixels (n)	Normalized (n/N)	Cumulative	Approx	Result
0	0	790	0.19	0.19	1/7	1
1	1/7	1023	0.25	0.44	3/7	3
2	2/7	850	0.21	0.65	5/7	5
3	3/7	656	0.16	0.81	6/7	6
4	4/7	329	0.08	0.89	6/7	6
5	5/7	245	0.06	0.95	1	7
6	6/7	122	0.03	0.98	1	7
7	7/7	81	0.02	1.00	1	7
Total:		4096	1			



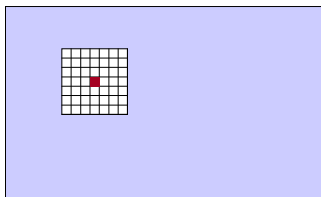
Examples for Equalization



Adaptive Histogram Equalization

- Different regions in a single image
 - Example: Coin on white paper
- Poor result for Histogram Equalization
 - Do the coins and paper separately
 - How to segment?
- Compute histogram in local regions around each pixel

Adaptive Equalization



- For each pixel
 - Compute Histogram in Neighborhood
 - Transform only the center pixel
- Go to next pixel

Color Quantization

- 24 bits/pixel - 8 bits/color - 256³ Colors
- 8 bits/pixel - 256 colors
 - 3-3-2 bits for R-G-B
 - General Quantization - Look Up Table (LUT)
 - LUT can be for **R****G****B** or for **YUV**

LUT	0	1	2	k	254	255
R	...	R ₁	...	R _k	...	R ₂₅₅
G	...	G ₁	...	G _k	...	G ₂₅₅
B	...	B ₁	...	B _k	...	B ₂₅₅

Quantization Error

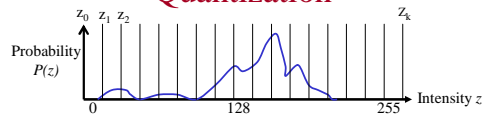
LUT	0	1	2	k	254	255
R	...	R ₁	...	R _k	...	R ₂₅₅
G	...	G ₁	...	G _k	...	G ₂₅₅
B	...	B ₁	...	B _k	...	B ₂₅₅

- If pixel p with color (r, g, b) is coded by k , a possible quantization error for p is:

$$E_p^2 = (r - R_k)^2 + (g - G_k)^2 + (b - B_k)^2$$
- The total error introduced by a LUT is:

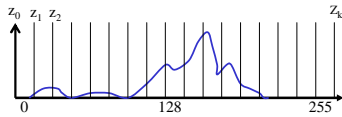
$$E^2 = \sum_p E_p^2$$
- Unknowns: $(r, g, b) \rightarrow k, k \rightarrow (R_k, G_k, B_k)$

Quantization



- Map the continuous intensities to $\{q_0, \dots, q_{k-1}\}$
 - Borders of segments: $z_0, z_1, z_2, \dots, z_k$
 - Represent each segment $[z_{i-1}, z_i]$ by intensity q_{i-1}
- Uniform Quantization: $q_i = (z_i + z_{i+1}) / 2$
 $z_{i+1} - z_i = (z_k - z_0) / k$
- Prior Mappings (e.g. Gamma Correction)

Optimal Quantization (6.5.1)



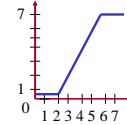
- Minimize the error:
$$\sum_{i=0}^{k-1} \int_{z_i}^{z_{i+1}} (q_i - z)^2 p(z) dz$$
- Solution (Prove!):

$$q_i = \frac{\int_{z_i}^{z_{i+1}} z \cdot p(z) dz}{\int_{z_i}^{z_{i+1}} p(z) dz} \quad z_i = \frac{q_{i-1} + q_i}{2}$$

Operation with LUT (4.2)

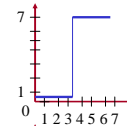
- Stretch

0	1	2	3	4	5	6	7
0	0	0	2	4	6	7	7



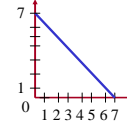
- Threshold

0	1	2	3	4	5	6	7
0	0	0	0	7	7	7	7



- Negative

0	1	2	3	4	5	6	7
7	6	5	4	3	2	1	0



1-D Discrete Convolution

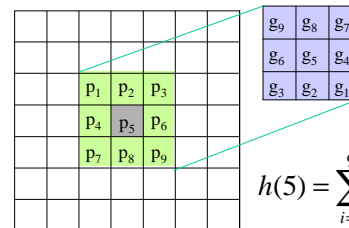
$$h(i) = (f * g)(i) = \sum_{k=1}^n f(k) g(i-k)$$

$$f = (0 \ 0 \ 1 \ 0 \ 0) \quad g = (0 \ 0 \ 1 \ -1 \ 0)$$

$$h(6) = \sum_{k=1}^5 f(k) \cdot g(6-k) = f(3) \cdot g(3) = 1$$

$$h(7) = \sum_{k=1}^5 f(k) \cdot g(7-k) = f(3) \cdot g(4) = -1$$

2D Discrete Convolution



2-D Discrete Convolution

$$h = f * g$$

$$h(i, j) = \sum_{k=1}^n \sum_{l=1}^m f(k, l) g(i-k, j-l)$$

Question: What is the complexity of convolution

Convolutions: Smoothing

Q: What is the average gray level after convolution?

Smoothing

$$\frac{1}{9} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \quad \frac{1}{16} \begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{bmatrix}$$



Original Image



Corrupted Image



Filtered Image

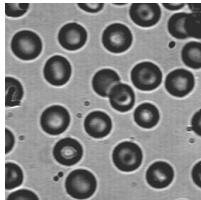
Convolutions: Edge-Detection

Q: What is the average gray level after convolution?

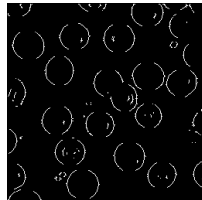
Edge
Detection

$$\begin{bmatrix} 1 & 0 & -1 \\ 1 & 0 & -1 \\ 1 & 0 & -1 \end{bmatrix}$$

$$\begin{bmatrix} -1 & 1 \\ -1 & 1 \end{bmatrix}$$



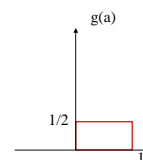
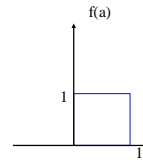
Original Blood Image



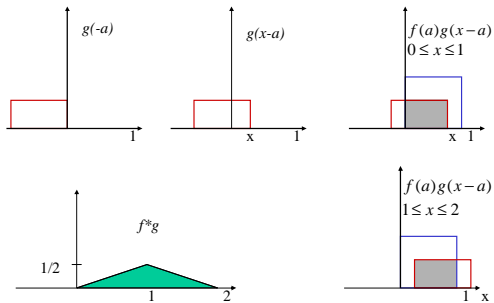
Edge Map

Convolution (Continuous)

$$(f * g)(x) = \int_{-\infty}^{\infty} f(a)g(x-a)da$$



$$(f * g)(x) = \int_{-\infty}^{\infty} f(a)g(x-a)da$$



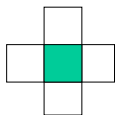
Properties of Convolution

Commutative: $f * g = g * f$

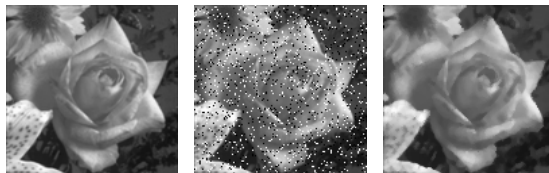
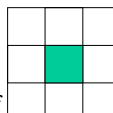
Transitive: $f * (g * h) = (f * g) * h$

Associative: $f * (g + h) = f * g + f * h$

Median Filtering



- Replace the value of a pixel with the MEDIAN of its neighborhood
- Depends on the definition of "neighborhood"

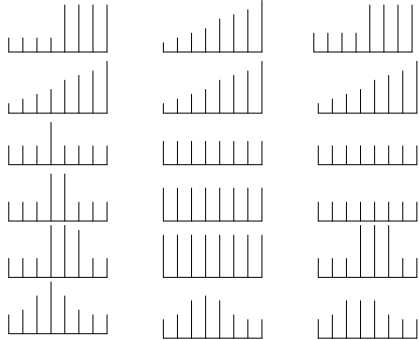


Noise Cleaning

- Averaging / Smoothing - Loss of Detail
- Median - Blockiness
- Min, Max, Min/Max, etc.



Compare: Average Median



An Approximation to Derivatives

$$\frac{\partial}{\partial x} f(i, j) \cong f(i, j) - f(i-1, j) \quad \begin{pmatrix} 1 & -1 \end{pmatrix}$$

$$\frac{\partial}{\partial y} f(i, j) \cong f(i, j) - f(i, j-1) \quad \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

$$\begin{aligned} \frac{\partial^2}{\partial x^2} f(i, j) &\cong \frac{\partial}{\partial x} f(i+1, j) - \frac{\partial}{\partial x} f(i, j) = \\ &= f(i-1, j) + f(i+1, j) - 2f(i, j) \end{aligned}$$

$$\begin{pmatrix} 1 & -2 & 1 \end{pmatrix}$$

Laplacian

Equation: $\nabla^2 f = \frac{\partial}{\partial x^2} f + \frac{\partial}{\partial y^2} f$

Convolution: $(1 \ -2 \ 1) + \begin{pmatrix} 1 \\ -2 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 \\ 1 & -4 & 1 \\ 0 & 1 & 0 \end{pmatrix}$

Subtracting the Laplacian:

$$\begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} - \begin{pmatrix} 0 & 1 & 0 \\ 1 & -4 & 1 \\ 0 & 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & -1 & 0 \\ -1 & 5 & -1 \\ 0 & -1 & 0 \end{pmatrix}$$

Subtracting The Laplacian

