

The text website has an Appendix A on it that describes some methods, Cramer's Rule and Linear Algebra. I have put the Web Appendix A on the Black board site under Course Materials.

Cramer's Rule:

Given an array equation:

$$G V = S$$

$$\begin{pmatrix} G_{11} & G_{12} \\ G_{21} & G_{22} \end{pmatrix} \begin{pmatrix} V_1 \\ V_2 \end{pmatrix} = \begin{pmatrix} S_1 \\ S_2 \end{pmatrix}$$

then $V_i = \frac{\Delta_i}{\Delta}$

where $\Delta = |G|$ and $\Delta_i = \begin{vmatrix} G_{11} & G_{12} \\ S_1 & S_2 \end{vmatrix}$ with
S in place
of the i^{th}
column

$$\Delta = \begin{vmatrix} G_{11} & G_{12} \\ G_{21} & G_{22} \end{vmatrix} = (G_{11}G_{22} - G_{12}G_{21})$$

$$\Delta_1 = \begin{vmatrix} S_1 & G_{12} \\ S_2 & G_{22} \end{vmatrix} = S_1G_{22} - S_2G_{12}$$

and ~~Δ_2~~ $\Delta_2 = \begin{vmatrix} G_{11} & S_1 \\ G_{21} & S_2 \end{vmatrix} = (G_{11}S_2 - G_{21}S_1)$

Then $V_1 = \frac{\Delta_1}{\Delta} = \frac{S_1G_{22} - S_2G_{12}}{G_{11}G_{22} - G_{12}G_{21}}$

$V_2 = \frac{\Delta_2}{\Delta} = \dots$

The larger an array becomes, the more complicated the determinant is. I'm

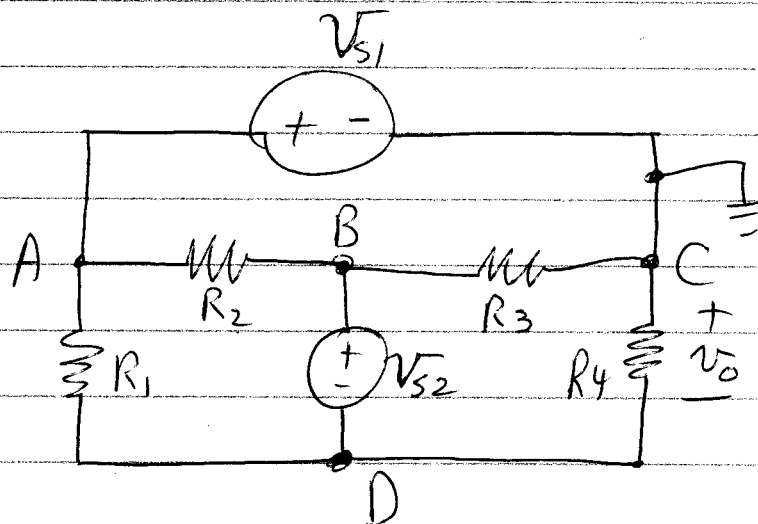
not going to go further now. Many calculators, and Excel, Matlab, ^{Wolfram Alpha} etc,

and CircuitLab will do them for you.

Page 91 of text has a pretty good summary of Node-Voltage Analysis, look it over, good idea to develop your own, prime candidate for an exam.

Let's do another example, I'm going to do Ex 3-7 from text, but with a twist:

Ckt:



With $R_1 = R_4 = 2\text{k}\Omega$ and $R_2 = R_3 = 4\text{k}\Omega$

In text, they selected D as reference,

as I usually would, and got $v_o = v_c = \frac{v_{S2}}{3} - \frac{v_{S1}}{2}$

To show that any choice works, I'm going to select C as the reference (mark) and solve:

① Now - $v_o = v_c - v_d = 0 - v_d = -v_d \leftarrow D.O$

② Count - 4 Node Voltages $v_A = v_{s1}$ $v_c = 0$
 $v_B = ?$ $v_d = ?$
 2 unknowns, need 2 equations

③ V source supernodes:

① v_{s1} includes reference, so
 $v_A = v_{s1}$

② v_{s2} includes B + D, so
 $v_B - v_D = v_{s2}$

(B+D) $\frac{v_B - v_A}{R_2} + \frac{v_D - v_A}{R_1} + \frac{v_D}{R_4} + \frac{v_B}{R_3} = 0$

$(-\frac{1}{R_2} - \frac{1}{R_1})v_A + (\frac{1}{R_2} + \frac{1}{R_3})v_B + (\frac{1}{R_1} + \frac{1}{R_4})v_D = 0$

Insert values: $(-\frac{1}{4k} - \frac{1}{2k})v_A + (\frac{1}{4k} + \frac{1}{4k})v_B + (\frac{1}{2k} + \frac{1}{2k})v_D = 0$

$\times 4k :$ $(-1-2)v_A + (1+1)v_B + (2+2)v_D = 0$
 $-3v_A + 2v_B + 4v_D = 0$

Use $\underline{v_A = v_{s1}} + \underline{v_B = v_D + v_{s2}}$

$$-3v_{s1} + 2(v_D + v_{s2}) + 4v_D = 0$$

$$6v_D = 3v_{s1} - 2v_{s2}$$

$$v_D = \frac{1}{2}v_{s1} - \frac{1}{3}v_{s2}$$

So $\underline{v_o = -v_D = \frac{1}{3}v_{s2} - \frac{1}{2}v_{s1}}$ ✓

Could I write as matrix?

Put in $v_A = v_{s1}$ to start:

~~$-3 \quad 2 \quad 4$~~ ~~v_A~~

$$2v_B + 4v_D = 3v_{s1}$$

$$v_B - v_D = v_{s2}$$

Becomes:
$$\begin{pmatrix} 2 & 4 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} v_B \\ v_D \end{pmatrix} = \begin{pmatrix} 3v_{s1} \\ v_{s2} \end{pmatrix}$$

$$v_D = \frac{\Delta_2}{\Delta} = \frac{\begin{vmatrix} 2 & 3v_{s1} \\ 1 & v_{s2} \end{vmatrix}}{\begin{vmatrix} 2 & 4 \\ 1 & -1 \end{vmatrix}} = \frac{2v_{s2} - 3v_{s1}}{(2 \times -1) - (1 \times 4)}$$

$$= \frac{2v_{s2} - 3v_{s1}}{-2 - 4} = \frac{2v_{s2} - 3v_{s1}}{-6}$$

$$= -\frac{1}{3}v_{s2} + \frac{1}{2}v_{s1}$$