Week 07 Lectures

Similarity-based Selection

Similarity-based Selection

2/89

Selection in SQL ...

- is precise on structured objects
- · objects are tuples, under a schema
- · query finds tuples satisfying logical properties
- satisfaction determined by evaluating a boolean expression

Similarity-based selection ...

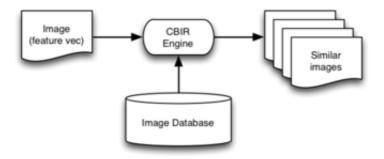
- is approximate on unstructured objects
- objects are typically media objects (e.g. text, images, audio, ...)
- query finds objects that are similar to a query object
- similarity determined by measuring distance between objects

Example: Content-based Image Retrieval

3/89

User supplies a description or sample of desired image.

System returns a ranked list of "matching" images from database.



... Example: Content-based Image Retrieval

4/89

At the SQL level, this might appear as ...

where (imaginary) ~~ operator measures how "alike" images are

Similarity-based Retrieval

5/89

Database contains media objects, but also tuples, e.g.

- id to uniquely identify object (e.g. PostgreSQL oid)
- metadata (e.g. artist, title, genre, date taken, ...)
- value of object itself (e.g. PostgreSQL BLOB or bytea)

BLOB = Binary Large OBject

- BLOB stored in separate file; tuple contains reference (cf. TOAST)
- BLOBs are typically MB in size (1MB..2GB)

... Similarity-based Retrieval

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Similarity-based retrieval requires a distance measure

• $dist(x,y) \in 0..1$, dist(x,x) = 0, dist(x,y) = dist(y,x)

where *x* and *y* are two objects (in the database)

Note: distance calculation often requires substantial computational effort

How to restrict solution set to only the "most similar" objects:

- threshold d_{max} (only objects t such that $dist(t,q) \le d_{max}$)
- count k (k closest objects (k nearest neighbours))

BUT both above methods require knowing distance between query object and all objects in DB

... Similarity-based Retrieval

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Naive approach to similarity-based retrieval

```
q = ...  // query object
dmax = ...  // dmax > 0 => using threshold
knn = ...  // knn > 0 => using nearest-neighbours
Dists = []  // empty list
foreach tuple t in R {
    d = dist(t.val, q)
    insert (t.oid,d) into Dists  // sorted on d
}
n = 0; Results = []
foreach (i,d) in Dists {
    if (dmax > 0 && d > dmax) break;
    if (knn > 0 && ++n > knn) break;
    insert (i,d) into Results  // sorted on d
}
return Results;
```

Cost = fetch all r objects + compute distance() for each

... Similarity-based Retrieval

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For some applications, Cost(dist(x,y)) is comparable to T_r

⇒ computing dist(t.val,q) for every tuple t is infeasible.

To improve this ...

- compute feature vector to capture "critical" object properties
- store feature vectors "in parallel" with objects (cf. signatures)
- compute distance using feature vectors (not objects)

i.e. replace dist(t,q) by dist'(vec(t),vec(q)) in previous algorithm.

Further optimisation: dimension-reduction to make vectors smaller

... Similarity-based Retrieval

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Feature vectors ...

- often use multiple features, concatenated into single vector
- represent points in a very high-dimensional (vh-dim) space

Content of feature vectors depends on application ...

- image ... colour histogram (e.g. 100's of values/dimensions)
- music ... loudness/pitch/tone (e.g. 100's of values/dimensions)
- text ... term frequencies (e.g. 1000's of values/dimensions)

Query: feature vector representing one point in vh-dim space

Answer: list of objects "near to" query object in this space

... Similarity-based Retrieval

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Inputs to content-based similarity-retrieval:

- a database of r objects (obj₁, obj₂, ..., obj_r) plus associated ...
- r x n-dimensional feature vectors (v_{obj1}, v_{obj2}, ..., v_{objr})
- a query image q with associated n-dimensional vector (v_q)
- a distance measure $D(v_i, v_j) : [0..1)$ $(D=0 \rightarrow v_i=v_j)$

Outputs from content-based similarity-retrieval:

- a list of the *k* nearest objects in the database $[a_1, a_2, \dots a_k]$
- ordered by distance $D(v_{a_1}, v_q) \le D(v_{a_2}, v_q) \le \dots \le D(v_{a_k}, v_q)$

Approaches to kNN Retrieval

11/89

Partition-based

- use auxiliary data structure to identify candidates
- space/data-partitioning methods: e.g. k-d-B-tree, R-tree, ...
- unfortunately, such methods "fail" when #dims > 10..20
- absolute upper bound on d before linear scan is best d = 610

Approximation-based

- use approximating data structure to identify candidates
- signatures: VA-files
- projections: iDistance, LSH, MedRank, CurveIX, Pyramid

... Approaches to kNN Retrieval

12/89

Above approaches try to reduce number of objects considered.

cf. indexes in relational databases

Other optimisations to make kNN retrieval faster

- reduce I/O by reducing size of vectors (compression, d-reduction)
- reduce I/O by placing "similar" records together (clustering)
- reduce I/O by remembering previous pages (caching)
- reduce cpu by making distance computation faster

Similarity Retrieval in PostgreSQL

13/89

PostgreSQL has always supported simple "similarity" on strings

```
-- for most SQL implementations
select * from Students where name like '%oo%';
-- and PostgreSQL-specific
select * from Students where name ~ '[Ss]mit';
```

Also provides support for ranked similarity on text values

- using tsvector data type (stemmed, stopped feature vector for text)
- using tsquery data type (stemmed, stopped feature vector for strings)
- using @@ similarity operator

... Similarity Retrieval in PostgreSQL

14/89

Example of PostgreSQL text retrieval:

For more details, see PostgreSQL documentation, Chapter 12.

Signature-based Selection

Indexing with Signatures

16/89

Signature-based indexing:

- designed for *pmr* queries (conjunction of equalities)
- does not try to achieve better than O(n) performance
- attempts to provide an "efficient" linear scan

Each tuple is associated with a signature

- a compact (lossy) descriptor for the tuple
- formed by combining information from multiple attributes
- stored in a signature file, parallel to data file

Instead of scanning/testing tuples, do pre-filtering via signatures.

... Indexing with Signatures

17/89

File organisation for signature indexing (two files)



One signature slot per tuple slot; unused signature slots are zeroed.

Signatures do not determine record placement \Rightarrow can use with other indexing.

Signatures

A signature "summarises" the data in one tuple

A tuple consists of N attribute values $A_1 ... A_n$

A codeword $cw(A_i)$ is

- a bit-string, m bits long, where k bits are set to 1 (k « m)
- derived from the value of a single attribute A_i

A tuple descriptor (signature) is built by combining $cw(A_i)$, i=1...n

- could combine by overlaying (or concatenating) codewords
- · aim to have roughly half of the bits set to 1

Generating Codewords

19/89

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Generating a k-in-m codeword for attribute A_i

bits codeword(char *attr_value, int m, int k)

```
int nbits = 0;  // count of set bits
bits cword = 0;  // assuming m <= 32 bits
srandom(hash(attr_value));
while (nbits < k) {
   int i = random() % m;
   if (((1 << i) & cword) == 0) {
      cword |= (1 << i);
      nbits++;
   }
}
return cword;  // m-bits with k 1-bits and m-k 0-bits
}</pre>
```

Superimposed Codewords (SIMC)

20/89

21/89

In a superimposed codewords (simc) indexing scheme

· a tuple descriptor is formed by overlaying attribute codewords

A tuple descriptor desc(r) is

- a bit-string, m bits long, where $j \le nk$ bits are set to 1
- $desc(r) = cw(A_1)$ OR $cw(A_2)$ OR ... OR $cw(A_n)$

Method (assuming all *n* attributes are used in descriptor):

```
bits desc = 0
for (i = 1; i <= n; i++) {
   bits cw = codeword(A[i])
   desc = desc | cw
}</pre>
```

SIMC Example

Consider the following tuple (from bank deposit database)

Branch	AcctNo	Name	Amount
Perryridge	102	Hayes	400

It has the following codewords/descriptor (for m = 12, k = 2)

A_i	cw(A _i)
Perryridge	010000000001
102	00000000011
Hayes	000001000100
400	000010000100
desc(r)	010011000111

SIMC Queries 22/89

To answer query q in SIMC

- first generate a query descriptor desc(q)
- then use the query descriptor to search the signature file

desc(q) is formed by OR of codewords for known attributes.

E.g. consider the query (Perryridge, ?, ?, ?).

```
      Ai
      cw(Ai)

      Perryridge
      01000000001

      ?
      00000000000

      ?
      00000000000

      ?
      00000000000

      desc(q)
      010000000001
```

... SIMC Queries 23/89

Once we have a query descriptor, we search the signature file:

Example SIMC Query

24/89

Consider the guery and the example database:

Signature	Deposit Record
010000000001	(Perryridge,?,?,?)
100101001001	(Brighton,217,Green,750)
010011000111	(Perryridge,102,Hayes,400)
101001001001	(Downtown,101,Johnshon,512)
101100000011	(Mianus,215,Smith,700)

010101010101 (Clearview,117,Throggs,295)

10010101011 (Redwood, 222, Lindsay, 695)

Gives two matches: one true match, one false match.

SIMC Parameters

25/89

False match probablity p_F = likelihood of a false match

How to reduce likelihood of false matches?

- use different hash function for each attribute (h_i for A_i)
- increase descriptor size (m)
- choose k so that \approx half of bits are set

Larger m means reading more descriptor data.

Having k too high \Rightarrow increased overlapping.

Having k too low \Rightarrow increased hash collisions.

... SIMC Parameters 26/89

How to determine "optimal" m and k?

- 1. start by choosing acceptable p_F (e.g. $p_F \le 10^{-5}$ i.e. one false match in 10,000)
- 2. then choose m and k to achieve no more than this p_F .

Formulae to derive m and k given p_F and n:

$$k = 1/log_e 2 \cdot log_e (1/p_F)$$

 $m = (1/log_e 2)^2 \cdot n \cdot log_e (1/p_F)$

Query Cost for SIMC

27/89

Cost to answer *pmr* query: $Cost_{pmr} = b_D + b_q$

- read r descriptors on b_D descriptor pages
- then read b_q data pages and check for matches

 $b_D = ceil(r/c_D)$ and $c_D = floor(B/ceil(m/8))$

E.g.
$$m=64$$
, $B=8192$, $r=10^4 \Rightarrow c_D = 1024$, $b_D=10$

 b_q includes pages with r_q matching tuples and r_F false matches

Expected false matches = $r_F = (r - r_q).p_F \approx r.p_F$ if $r_q \ll r$

E.g. Worst $b_q = r_q + r_F$, Best $b_q = 1$, Avg $b_q = ceil(b(r_q + r_F)/r)$

Exercise 1: SIMC Query Cost

Consider a SIMC-indexed database with the following properties

- all pages are B = 8192 bytes
- tuple descriptors have m = 64 bits (= 8 bytes)
- total records r = 102,400, records/page c = 100
- false match probability p_F = 1/1000
- answer set has 1000 tuples from 100 pages
- 90% of false matches occur on data pages with true match
- 10% of false matches are distributed 1 per page

Calculate the total number of pages read in answering the query.

Page-level SIMC

29/89

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SIMC has one descriptor per tuple ... potentially inefficient.

Alternative approach: one descriptor for each data page.

Every attribute of every tuple in page contributes to descriptor.

Size of page descriptor (PD) (clearly larger than tuple descriptor):

• use above formulae but with c.n "attributes"

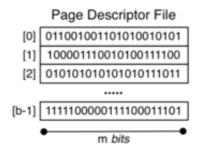
E.g.
$$n = 4$$
, $c = 128$, $p_F = 10^{-3} \implies m \approx 7000 bits \approx 900 bytes$

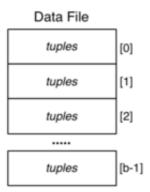
Typically, pages are 1..8KB \Rightarrow 8..64 PD/page (N_{PD}).

Page-Level SIMC Files

30/89

File organisation for page-level superimposed codeword index





Exercise 2: Page-level SIMC Query Cost

31/89

Consider a SIMC-indexed database with the following properties

- all pages are B = 8192 bytes
- page descriptors have m = 4096 bits (= 512 bytes)

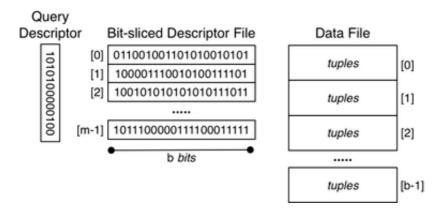
- total records r = 102,400, records/page c = 100
- false match probability p_F = 1/1000
- answer set has 1000 tuples from 100 pages
- 90% of false matches occur on data pages with true match
- 10% of false matches are distributed 1 per page

Calculate the total number of pages read in answering the query.

... Page-Level SIMC Files

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Improvement: store *b m*-bit page descriptors as *m b*-bit "bit-slices"



... Page-Level SIMC Files 33/89

At query time

```
matches = ~0  //all ones
for each bit i set to 1 in desc(q) {
    slice = fetch bit-slice i
    matches = matches & slice
}
for each bit i set to 1 in matches {
    fetch page i
    scan page for matching records
}
```

Effective because desc(q) typically has less than half bits set to 1

Exercise 3: Bit-sliced SIMC Query Cost

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Consider a SIMC-indexed database with the following properties

- all pages are B = 8192 bytes
- r = 102,400, c = 100, b = 1024
- page descriptors have m = 4096 bits (= 512 bytes)
- bit-slices have *b* = 1024 bits (= 128 bytes)
- false match probability p_F = 1/1000
- query descriptor has k = 10 bits set to 1
- answer set has 1000 tuples from 100 pages

- 90% of false matches occur on data pages with true match
- 10% of false matches are distributed 1 per page

Calculate the total number of pages read in answering the guery.

Implementing Join

Join 36/89

DBMSs are engines to store, combine and filter information.

Join (\bowtie) is the primary means of *combining* information.

Join is important and potentially expensive

Most common join condition: equijoin, e.g. (R.pk = S.fk)

Join varieties (natural, inner, outer, semi, anti) all behave similarly.

We consider three strategies for implementing join

- nested loop ... simple, widely applicable, inefficient without buffering
- sort-merge ... works best if tables are sorted on join attributes
- hash-based ... requires good hash function and sufficient buffering

Join Example 37/89

Consider a university database with the schema:

```
create table Student(
   id   integer primary key,
   name   text, ...
);
create table Enrolled(
   stude integer references Student(id),
   subj   text references Subject(code), ...
);
create table Subject(
   code   text primary key,
   title   text, ...
);
```

... Join Example 38/89

List names of students in all subjects, arranged by subject.

SQL query to provide this information:

```
select E.subj, S.name
from Student S, Enrolled E
where S.id = E.stude
order by E.subj, S.name;
```

And its relational algebra equivalent:

Sort[subj] (Project[subj,name] (Join[id=stude](Student,Enrolled)))

To simplify formulae, we denote Student by S and Enrolled by E

... Join Example 39/89

Some database statistics:

Sym	Meaning	Value
rs	# student records	20,000
r _E	# enrollment records	80,000
c_S	Student records/page	20
c _E	Enrolled records/page	40
bs	# data pages in Student	1,000
bE	# data pages in Enrolled	2,000

Also, in cost analyses below, N = number of memory buffers.

... Join Example 40/89

Out = Student \bowtie Enrolled relation statistics:

Sym	Meaning	Value
r _{Out}	# tuples in result	80,000
C _{Out}	result records/page	80
b _{Out}	# data pages in result	1,000

Notes:

- r_{Out} ... one result tuple for each Enrolled tuple
- C_{Out} ... result tuples have only subj and name
- in analyses, ignore cost of writing result ... same in all methods

Nested Loop Join

Basic strategy (R.a ⋈ S.b):

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Needs input buffers for R and S, output buffer for "joined" tuples

Terminology: R is outer relation, S is inner relation

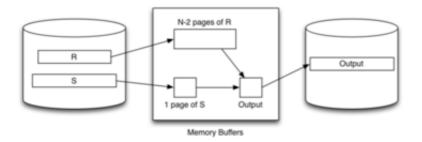
Cost = $b_R \cdot b_S$... ouch!

Block Nested Loop Join

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Method (for N memory buffers):

- read N-2-page chunk of R into memory buffers
- for each S page check join condition on all (t_R,t_S) pairs in buffers
- repeat for all N-2-page chunks of R



... Block Nested Loop Join

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Best-case scenario: $b_R \le N-2$

- read b_R pages of relation R into buffers
- while whole R is buffered, read b_S pages of S

 $Cost = b_R + b_S$

Typical-case scenario: $b_R > N-2$

- read ceil(b_R/(N-2)) chunks of pages from R
- for each chunk, read b_S pages of S

Cost = $b_R + b_S \cdot ceil(b_R/N-2)$

Note: always requires $r_R.r_S$ checks of the join condition

Exercise 4: Nested Loop Join Cost

44/89

Compute the cost (# pages fetched) of $(S \bowtie E)$

Sym	Meaning	Value
	# student records	20,000

rs		
rE	# enrollment records	80,000
c_S	Student records/page	20
c _E	Enrolled records/page	40
b_S	# data pages in Student	1,000
b _E	# data pages in Enrolled	2,000

for N = 22, 202, 2002 and different inner/outer combinations

If the query in the above example was:

how would this change the previous analysis?

What join combinations are there?

Assume 2000 subjects, with $c_J = 10$

How large would the intermediate tuples be? What assumptions?

Compute the cost (# pages fetched, # pages written) for N = 202

... Block Nested Loop Join

46/89

Why block nested loop join is actually useful in practice ...

Many queries have the form

```
select * from R,S where r.i=s.j and r.x=k
```

This would typically be evaluated as

Join
$$[i=i]$$
 ((Sel[r.x=k](R)), S)

If Sel[r.x=k](R) is small \Rightarrow may fit in memory (in small #buffers)

Index Nested Loop Join

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A problem with nested-loop join:

needs repeated scans of entire inner relation S

If there is an index on S, we can avoid such repeated scanning.

Consider Join[i=j](R,S):

```
for each tuple r in relation R {
   use index to select tuples
```

```
from S where s.j = r.i
for each selected tuple s from S {
    add (r,s) to result
}
```

... Index Nested Loop Join

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This method requires:

- one scan of R relation (b_R)
 - only one buffer needed, since we use R tuple-at-a-time
- for each tuple in R (r_R), one index lookup on S
 - · cost depends on type of index and number of results
 - best case is when each R.i matches few S tuples

```
Cost = b_R + r_R \cdot Sel_S (Sel_S is the cost of performing a select on S).
```

Typical $Sel_S = 1-2$ (hashing) .. b_q (unclustered index)

Trade-off: $r_R.Sel_S$ vs $b_R.b_S$, where $b_R \ll r_R$ and $Sel_S \ll b_S$

Exercise 5: Index Nested Loop Join Cost

49/89

Consider executing Join[i=j](S,T) with the following parameters:

- $r_S = 1000$, $b_S = 50$, $r_T = 3000$, $b_T = 600$
- S.i is primary key, and T has index on T.i
- T is sorted on T.j, each S tuple joins with 2 T tuples
- DBMS has N = 12 buffers available for the join

Calculate the costs for evaluating the above join

- using block nested loop join
- · using index nested loop join

Cost_r = # pages read and Cost_i = # join-condition checks

Sort-Merge Join

50/89

Basic approach:

- sort both relations on join attribute (reminder: Join [i=j] (R,S))
- scan together using merge to form result (r,s) tuples

Advantages:

- no need to deal with "entire" S relation for each r tuple
- deal with runs of matching R and S tuples

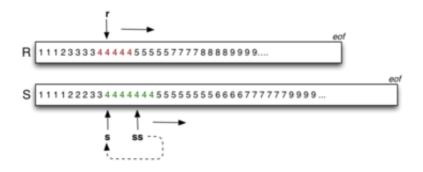
Disadvantages:

- cost of sorting both relations (already sorted on join key?)
- some rescanning required when long runs of S tuples

... Sort-Merge Join

Method requires several cursors to scan sorted relations:

- r = current record in R relation
- s = start of current run in S relation
- ss = current record in current run in S relation



... Sort-Merge Join 52/89

Algorithm using query iterators/scanners:

... Sort-Merge Join 53/89

```
// remember start of current run in S
TupleID startRun = scanCurrent(si)
// scan common run, generating result tuples
while (r != NULL && r.i == s.j) {
    while (s != NULL and s.j == r.i) {
        addTuple(outbuf, combine(r,s));
        if (isFull(outbuf)) {
            writePage(outf, outp++, outbuf);
            clearBuf(outbuf);
        }
        s = nextTuple(si);
    }
    r = nextTuple(ri);
    setScan(si, startRun);
}
```

... Sort-Merge Join 54/89

Buffer requirements:

- · for sort phase:
 - as many as possible (remembering that cost is $O(log_N)$)
 - if insufficient buffers, sorting cost can dominate
- for merge phase:
 - one output buffer for result
 - one input buffer for relation R
 - (preferably) enough buffers for longest run in S

... Sort-Merge Join 55/89

Cost of sort-merge join.

Step 1: sort each relation (if not already sorted):

• Cost = $2.b_R (1 + log_{N-1}(b_R/N)) + 2.b_S (1 + log_{N-1}(b_S/N))$ (where N = number of memory buffers)

Step 2: merge sorted relations:

- if every run of values in S fits completely in buffers, merge requires single scan, Cost = b_R + b_S
- if some runs in of values in S are larger than buffers, need to re-scan run for each corresponding value from R

Sort-Merge Join on Example

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Case 1: Join[id=stude](Student,Enrolled)

- relations are not sorted on id#
- memory buffers *N=32*; all runs are of length < 30

Cost =
$$sort(S) + sort(E) + b_S + b_E$$

$$= 2b_S(1+log_{31}(b_S/32)) + 2b_E(1+log_{31}(b_E/32)) + b_S + b_E$$

$$= 2 \times 1000 \times (1+2) + 2 \times 2000 \times (1+2) + 1000 + 2000$$

- = 6000 + 12000 + 1000 + 2000
- = 21.000

... Sort-Merge Join on Example

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Case 2: Join[id=stude](Student, Enrolled)

- Student and Enrolled already sorted on id#
- memory buffers N=4 (S input, 2 × E input, output)
- 5% of the "runs" in E span two pages
- there are no "runs" in S, since id# is a primary key

For the above, no re-scans of E runs are ever needed

Cost = 2,000 + 1,000 = 3,000 (regardless of which relation is outer)

Exercise 6: Sort-merge Join Cost

58/89

Consider executing Join[i=j](S,T) with the following parameters:

- $r_S = 1000$, $b_S = 50$, $r_T = 3000$, $b_T = 150$
- S.i is primary key, and T has index on T.j
- T is sorted on T.j, each S tuple joins with 2 T tuples
- DBMS has N = 42 buffers available for the join

Calculate the cost for evaluating the above join

- using sort-merge join
- compute #pages read/written
- compute #join-condition checks performed

Hash Join 59/89

Basic idea:

- use hashing as a technique to partition relations
- · to avoid having to consider all pairs of tuples

Requires sufficent memory buffers

- to hold substantial portions of partitions
- · (preferably) to hold largest partition of outer relation

Other issues:

- works only for equijoin R.i=S.j (but this is a common case)
- susceptible to data skew (or poor hash function)

Variations: simple, grace, hybrid.

Simple Hash Join

Basic approach:

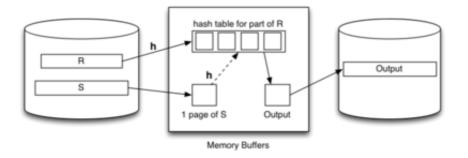
- hash part of outer relation R into memory buffers (build)
- scan inner relation S, using hash to search (probe)
 - if R.i=S.j, then h(R.i)=h(S.j) (hash to same buffer)
 - only need to check one memory buffer for each S tuple
- repeat until whole of R has been processed

No overflows allowed in in-memory hash table

- · works best with uniform hash function
- can be adversely affected by data/hash skew

... Simple Hash Join 61/89

Data flow:



... Simple Hash Join 62/89

Algorithm for simple hash join *Join[R.i=S.j](R,S)*:

```
for each tuple r in relation R {
   if (buffer[h(R.i)] is full) {
      for each tuple s in relation S {
        for each tuple rr in buffer[h(S.j)] {
            if ((rr,s) satisfies join condition) {
                add (rr,s) to result
            }      }
      clear all hash table buffers
   }
   insert r into buffer[h(R.i)]
}
```

Best case: # join tests $\leq r_S.c_R$ (cf. nested-loop $r_S.r_R$)

... Simple Hash Join 63/89

Cost for simple hash join ...

Best case: all tuples of R fit in the hash table

- Cost = b_R + b_R
- Same page reads as block nested loop, but less join tests

Good case: refill hash table m times (where $m \ge ceil(b_R / (N-2))$)

- Cost = $b_R + m.b_R$
- More page reads that block nested loop, but less join tests

Worst case: everything hashes to same page

• Cost = $b_R + b_R.b_S$

Exercise 7: Simple Hash Join Cost

64/89

Consider executing *Join[i=j](R,S)* with the following parameters:

- $r_R = 1000$, $b_R = 50$, $r_S = 3000$, $b_S = 150$, $c_{Res} = 30$
- R.i is primary key, each R tuple joins with 2 S tuples
- DBMS has N = 42 buffers available for the join

data + hash have uniform distribution

Calculate the cost for evaluating the above join

- using simple hash join
- compute #pages read/written
- compute #join-condition checks performed
- assume that hash table has L=0.75 for each partition

Grace Hash Join 65/89

Basic approach (for $R \bowtie S$):

- partition both relations on join attribute using hashing (h1)
- load each partition of *R* into N-buffer hash table (*h2*)
- scan through corresponding partition of S to form results
- · repeat until all partitions exhausted

For best-case cost $(O(b_R + b_S))$:

• need $\geq \sqrt{b_R}$ buffers to hold largest partition of outer relation

If $<\sqrt{b_B}$ buffers or poor hash distribution

• need to scan some partitions of S multiple times

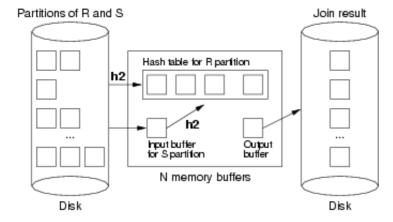
... Grace Hash Join 66/89

Partition phase (applied to both *R* and *S*):

[Diagram:Pics/join/grace-hash1-small.png]

... Grace Hash Join 67/89

Probe/join phase:



The second hash function (h2) simply speeds up the matching process. Without it, would need to scan entire R partition for each record in S partition.

... Grace Hash Join 68/89

Cost of grace hash join:

- #pages in all partition files of Rel ≅ b_{Rel} (maybe slightly more)
- partition relation R ... Cost = b_R.T_r + b_R.T_w = 2b_R
- partition relation S ... Cost = $b_S T_r + b_S T_w = 2b_S$
- probe/join requires one scan of each (partitioned) relation
 Cost = b_R + b_S
- all hashing and comparison occurs in memory ⇒ ≅0 cost

Total Cost = $2b_R + 2b_S + b_R + b_S = 3(b_R + b_S)$

Exercise 8: Grace Hash Join Cost

69/89

Consider executing Join[i=j](R,S) with the following parameters:

- $r_R = 1000$, $b_R = 50$, $r_S = 3000$, $b_S = 150$, $c_{Res} = 30$
- R.i is primary key, each R tuple joins with 2 S tuples
- DBMS has N = 43 buffers available for the join
- data + hash have reasonably uniform distribution

Calculate the cost for evaluating the above join

- using Grace hash join
- compute #pages read/written
- compute #join-condition checks performed
- assume that no R partition is larger than 40 pages

Exercise 9: Grace Hash Join Cost

70/89

Consider executing Join[i=i](R,S) with the following parameters:

- $r_B = 1000$, $b_B = 50$, $r_S = 3000$, $b_S = 150$, $c_{Bes} = 30$
- R.i is primary key, each R tuple joins with 2 S tuples
- DBMS has N = 42 buffers available for the join
- data + hash have reasonably uniform distribution

Calculate the cost for evaluating the above join

- using Grace hash join
- compute #pages read/written
- compute #join-condition checks performed
- assume that one R partition has 50 pages, others < 40 pages
- assume that the corresponding S partition has 30 pages

Hybrid Hash Join

71/89

A variant of grace join if we have $\sqrt{b_R} < N < b_R + 2$

- create *k*«*N* partitions, *m* in memory, *k-m* on disk
- buffers: 1 input, k-m output, p = N-(k-m)-1 for in-memory partitions

When we come to scan and partition S relation

- any tuple with hash in range 0..m-1 can be resolved
- other tuples are written to one of k partition files for S

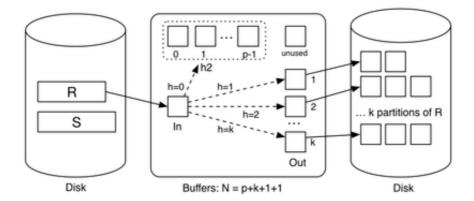
Final phase is same as grace join, but with only *k* partitions.

Comparison:

- grace hash join creates N-1 partitions on disk
- hybrid hash join creates *m* (memory) + *k* (disk) partitions

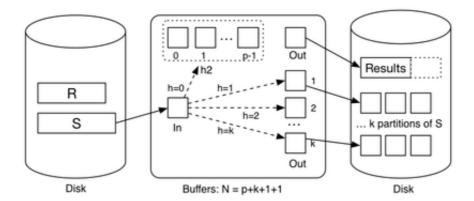
... Hybrid Hash Join 72/89

First phase of hybrid hash join with m=1 (partitioning R):



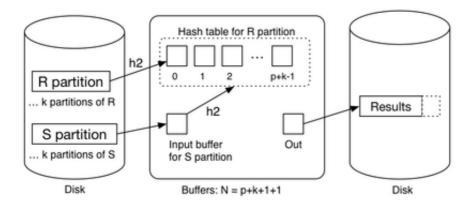
... Hybrid Hash Join 73/89

Next phase of hybrid hash join with m=1 (partitioning S):



... Hybrid Hash Join 74/89

Final phase of hybrid hash join with m=1 (finishing join):



... Hybrid Hash Join 75/89

Some observations:

- with k partitions, each partition has expected size b_R/k
- holding m partitions in memory needs \(\int mb_P \)/k \(\frac{1}{2} \) buffers
- trade-off between in-memory partition space and #partitions

Best-cost scenario:

• m = 1, $k = \lceil b_B/N \rceil$ (satisfying above constraint)

Other notes:

- if $N = b_B + 2$, using block nested loop join is simpler
- cost depends on N (but less than grace hash join)

Exercise 10: Hybrid Hash Join Cost

76/89

Consider executing Join[i=i](R,S) with the following parameters:

- $r_R = 1000$, $b_R = 50$, $r_S = 3000$, $b_S = 150$, $c_{Res} = 30$
- R.i is primary key, each R tuple joins with 2 S tuples
- DBMS has N = 42 buffers available for the join
- data + hash have reasonably uniform distribution

Calculate the cost for evaluating the above join

- using hybrid hash join with *m*=1, *p*=40
- compute #pages read/written
- compute #join-condition checks performed
- assume that no R partition is larger than 40 pages

Join Summary 77/89

No single join algorithm is superior in some overall sense.

Which algorithm is best for a given query depends on:

- sizes of relations being joined, size of buffer pool
- any indexing on relations, whether relations are sorted

- · which attributes and operations are used in the query
- number of tuples in S matching each tuple in R
- distribution of data values (uniform, skew, ...)

Choosing the "best" join algorithm is critical because the cost difference between best and worst case can be very large.

E.g. Join[id=stude](Student,Enrolled): 3,000 ... 2,000,000

Join in PostgreSQL

78/89

Join implementations are under: src/backend/executor

PostgreSQL suports three kinds of join:

- nested loop join (nodeNestloop.c)
- sort-merge join (nodeMergejoin.c)
- hash join (nodeHashjoin.c) (hybrid hash join)

Query optimiser chooses appropriate join, by considering

- · physical characteristics of tables being joined
- estimated selectivity (likely number of result tuples)

Exercise 11: Outer Join?

79/89

Above discussion was all in terms of theta inner-join.

How would the algorithms above adapt to outer join?

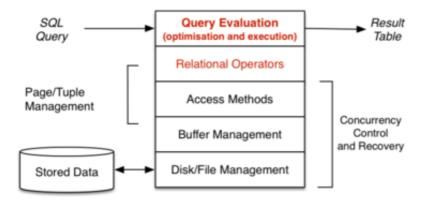
Consider the following ...

```
select *
from R left outer join S on (R.i = S.j)
select *
from R right outer join S on (R.i = S.j)
select *
from R full outer join S on (R.i = S.j)
```

Query Evaluation

Query Evaluation

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... Query Evaluation 82/89

A query in SQL:

- states what kind of answers are required (declarative)
- does not say how they should be computed (procedural)

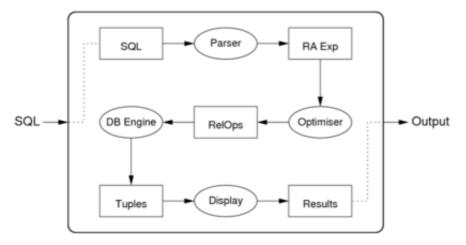
A query evaluator/processor:

- takes declarative description of query (in SQL)
- parses query to internal representation (relational algebra)
- determines plan for answering query (expressed as DBMS ops)
- executes method via DBMS engine (to produce result tuples)

Some DBMSs can save query plans for later re-use.

... Query Evaluation 83/89

Internals of the query evaluation "black-box":



... Query Evaluation 84/89

DBMSs provide several "flavours" of each RA operation.

For example:

- several "versions" of selection (σ) are available
- each version is effective for a particular kind of selection, e.g.

```
select * from R where id = 100 \, -- hashing select * from S \, -- Btree index where age > 18 and age < 35 select * from T \, -- MALH file where a = 1 and b = 'a' and c = 1.4
```

Similarly, π and \bowtie have versions to match specific query types.

... Query Evaluation 85/89

We call these specialised version of RA operations RelOps.

One major task of the query processor:

- given a RA expression to be evaluated
- · find a combination of RelOps to do this efficiently

Requires the query translator/optimiser to consider

- information about relations (e.g. sizes, primary keys, ...)
- information about operations (e.g. selection reduces size)

RelOps are realised at execution time

- as a collection of inter-communicating nodes
- · communicating either via pipelines or temporary relations

Terminology Variations

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Relational algebra expression of SQL query

- intermediate query representation
- · logical query plan

Execution plan as collection of RelOps

- query evaluation plan
- query execution plan
- physical query plan

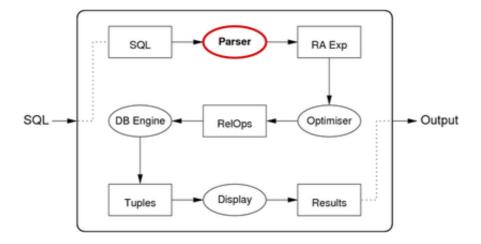
Representation of RA operators and expressions

- σ = Select = Sel, π = Project = Proj
- $R \bowtie S = R \text{ Join } S = \text{Join}(R,S), \quad \land = \&, \quad \lor = I$

Query Translation

87/89

Query translation: SQL statement text → RA expression



Query Translation

88/89

Translation step: SQL text → RA expression

Example:

```
SQL: select name from Students where id=7654321;
-- is translated to
RA: Proj[name](Sel[id=7654321]Students)
```

Processes: lexer/parser, mapping rules, rewriting rules.

Mapping from SQL to RA may include some optimisations, e.g.

```
select * from Students where id = 54321 and age > 50;
-- is translated to
Sel[age>50](Sel[id=54321]Students)
-- rather than ... because of index on id
Sel[id=54321&age>50](Students)
```

Parsing SQL

89/89

Parsing task is similar to that for programming languages.

Language elements:

```
keywords: create, select, from, where, ...
identifiers: Students, name, id, CourseCode, ...
operators: +, -, =, <, >, AND, OR, NOT, IN, ...
constants: 'abc', 123, 3.1, '01-jan-1970', ...
```

PostgreSQL parser ...

- implemented via lex/yacc (src/backend/parser)
- maps all identifiers to lower-case (A-Z → a-z)
- needs to handle user-extendable operator set
- makes extensive use of catalog (src/backend/catalog)

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