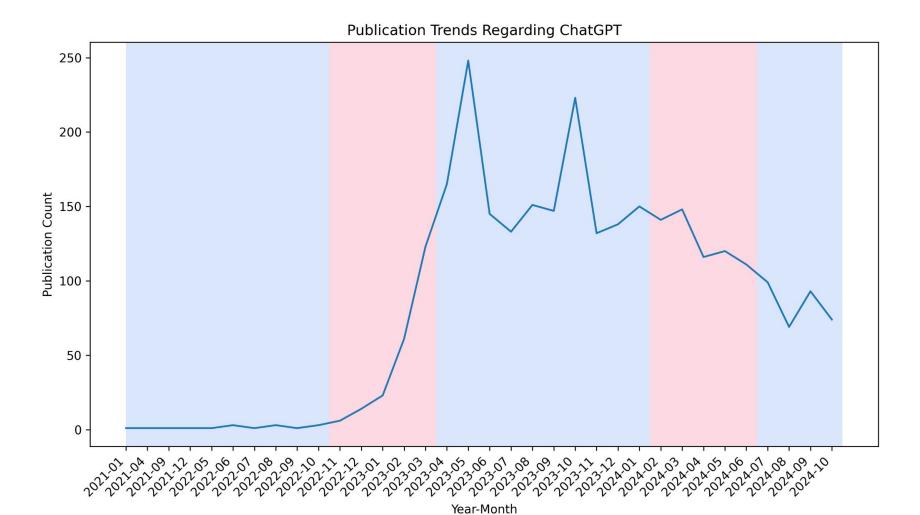
Math x Al Hackathon ∞



Signal Select

Can VLMs evaluate change point detection models?



Change Point Detection

Change point detection is a statistical technique used to identify points in a time series where the underlying statistical properties of the data change significantly. In simple mathematical notation, we can describe change point detection as follows:

Let $X=\{x_1,x_2,\ldots,x_n\}$ be a time series of length n. The goal of change point detection is to find a set of change points $\tau=\{\tau_1,\tau_2,\ldots,\tau_m\}$ where $1<\tau_1<\tau_2<\cdots<\tau_m< n$. These change points divide the time series into m+1 segments:

$$[1, au_1),[au_1, au_2),\ldots,[au_m,n]$$

https://github.com/deepcharles/ruptures

PELT: Pruned Exact Linear Time

Because the enumeration of all possible partitions impossible, the algorithm relies on a pruning rule. Many indexes are discarded, greatly reducing the computational cost while retaining the ability to find the optimal segmentation. The implementation follows [Killick2012]. In addition, under certain conditions on the change point repartition, the avarage computational complexity is of the order of $\mathcal{O}(CKn)$, where K is the number of change points to detect, n the number of samples and C the complexity of calling the considered cost function on one sub-signal.

PELT

Mathematical Formulation

PELT aims to minimize a penalized cost function:

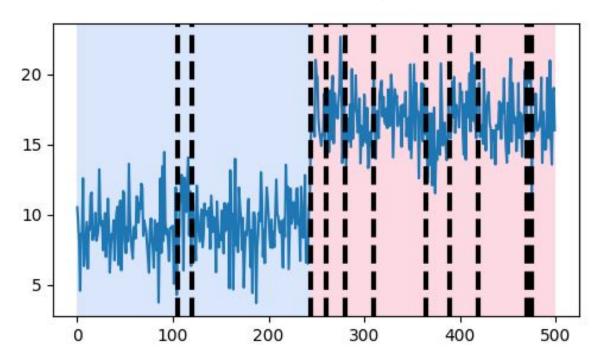
$$\min_{K, au_1,..., au_K} \left[\sum_{i=1}^{K+1} \mathcal{C}(x_{(au_{i-1}+1): au_i}) + eta K
ight]$$

Where:

- *K* is the number of change points
- $\tau_1, ..., \tau_K$ are the positions of the change points
- $\mathcal{C}(\cdot)$ is a cost function for a segment
- ullet eta is a penalty to prevent overfitting

The algorithm efficiently solves this optimization problem by using dynamic programming and applying a pruning rule to reduce the search space.

Hyperparameter Tuning can be a Challenge!

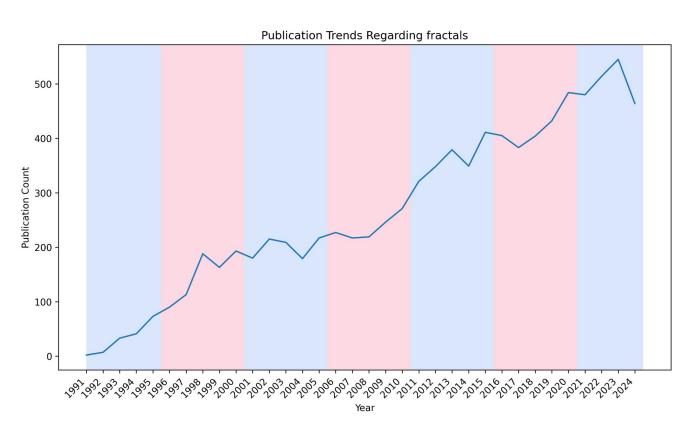


- 1. **Number of Dotted Lines**: There appear to be multiple dotted lines, which suggests that there may be multiple change points identified. For binary segmentation, ideally, there should only be one dotted line.
- 2. **Location of Dotted Lines**: The placement of the dotted lines should ideally separate the two segments clearly. It seems like the lines are spread across the range rather than demarcating a clear change.

Based on these observations, I would rate the appropriateness of the change point detection as a **2 out of 10**. The detection is poor because it does not adhere to the requirement for change point segmentation.

Final score: **0** (indicating that the change point detection was poor).

PELT can be Informative



"evaluation": {

"dotted lines placement": "The dotted lines appear to delineate segments that show differing trends in the data, indicating potential change points.", "trend_shift": "A noticeable trend shift occurs at the segments, with increasing values in later segments." "final evaluation": 8, "binary_indicator": 1