

Grid Saliency for Context Explanations of Semantic Segmentation

BOSCH Invented for life

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Motivation

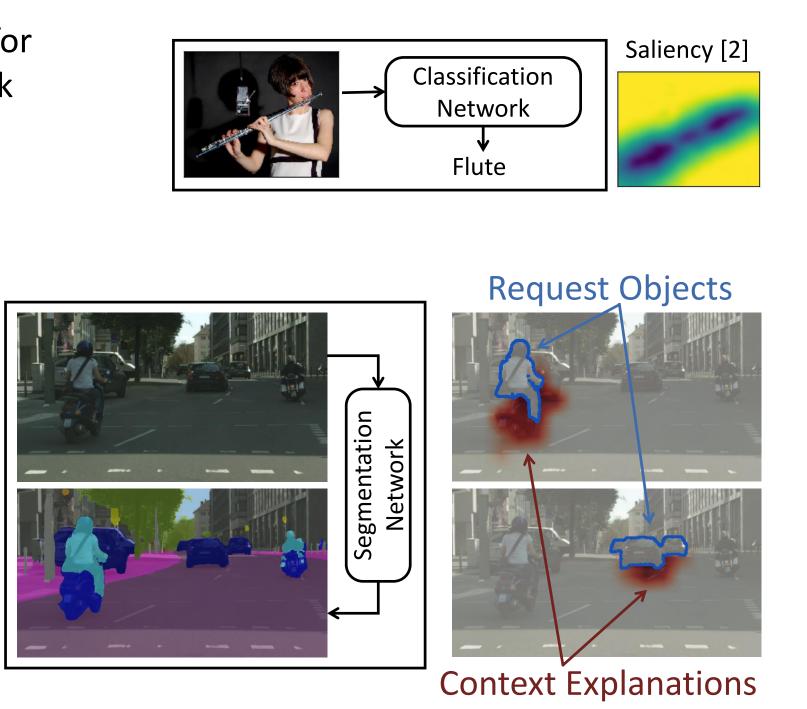
Prior work: Saliency maps are used for visual explanations of neural network image classifications [1,2,3,4]

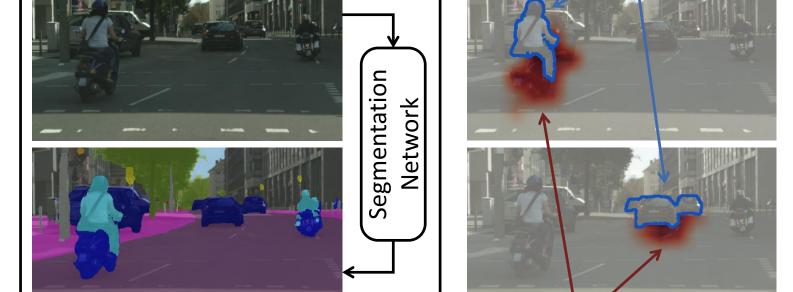


Our approach: Grid Saliencies for dense prediction tasks

Contributions:

- Context explanations for semantic segmentation
- Synthetic benchmark
- Real-world data analysis

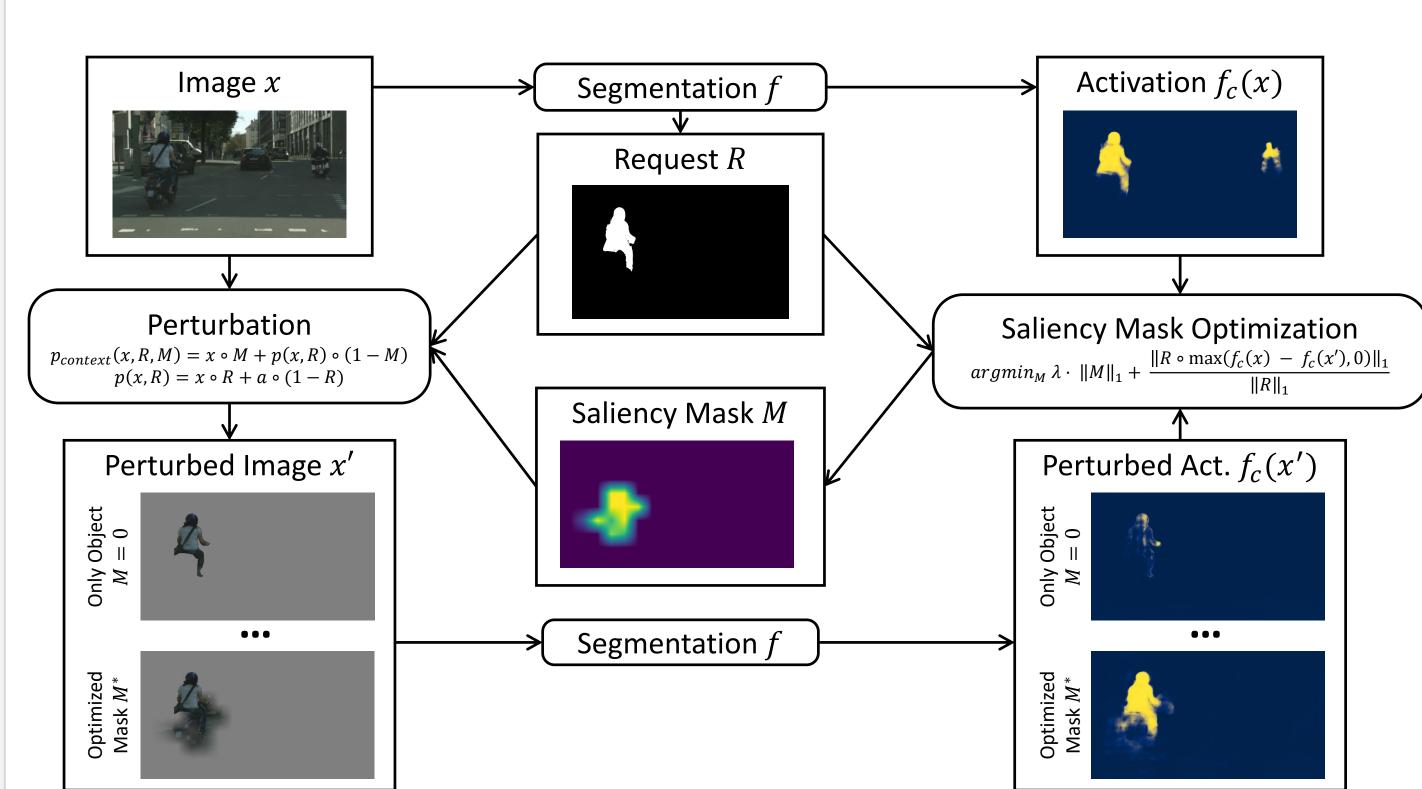




Perturbation-Based Grid Saliency

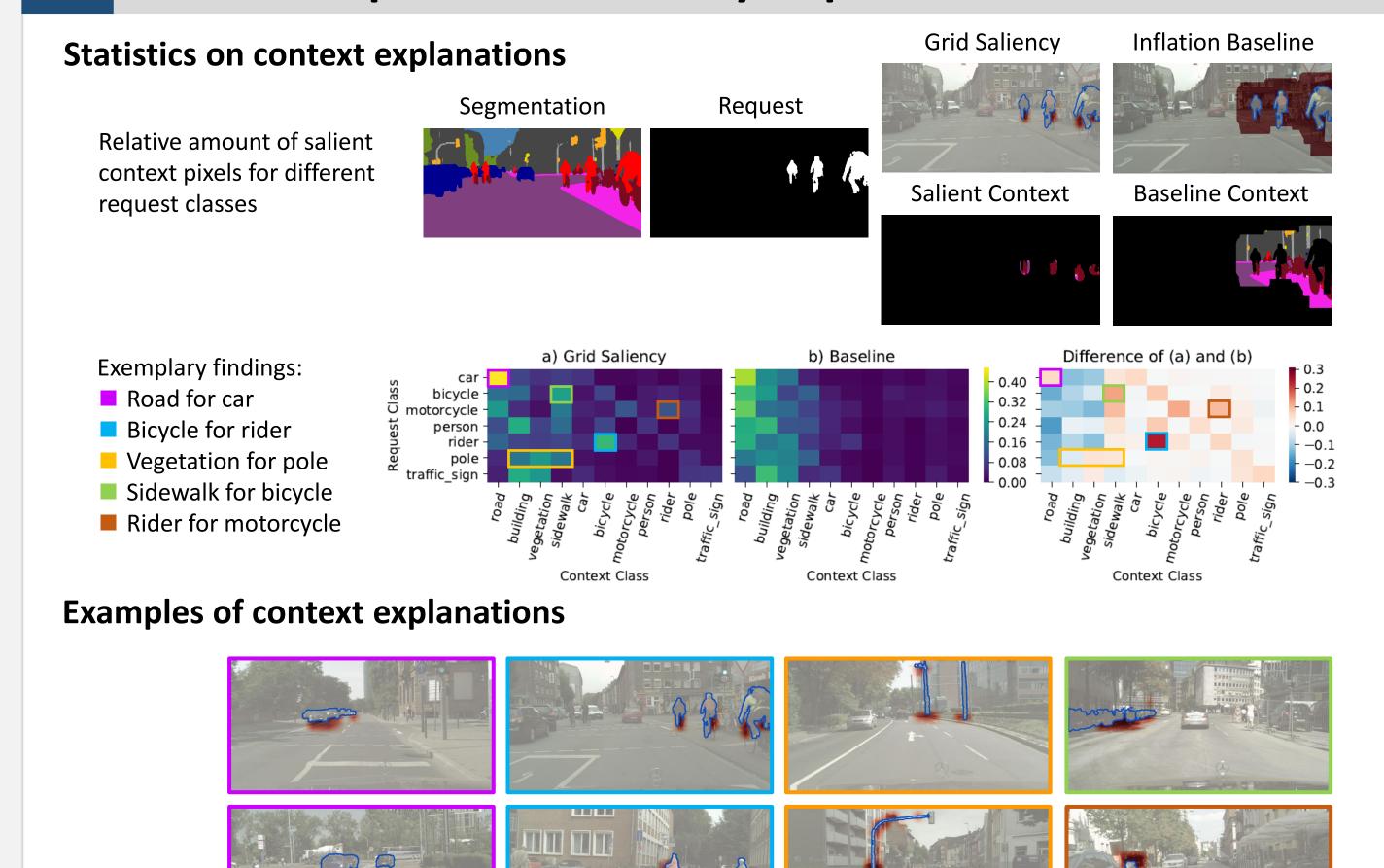
Context saliency map optimization

- Perturb as much context as possible
- Retain network predictions inside a request region



Grid Saliency Use Cases Error case analysis Pedestrian classified as rider → arm pose salient Rider classified as pedestrian → bicycle not salient **Network generalization Architecture comparison** MobileNet v2 misclassified backbone The cow is Xception W/o context correctly backbone

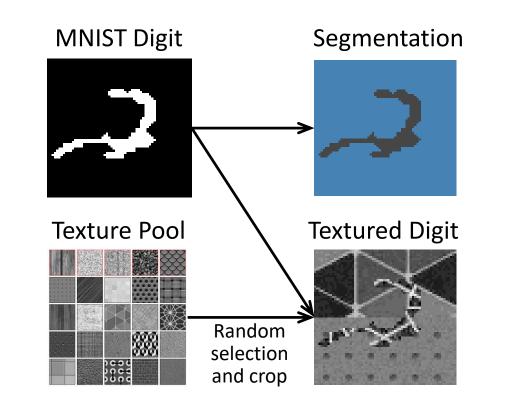
Context Explanations on Cityscapes



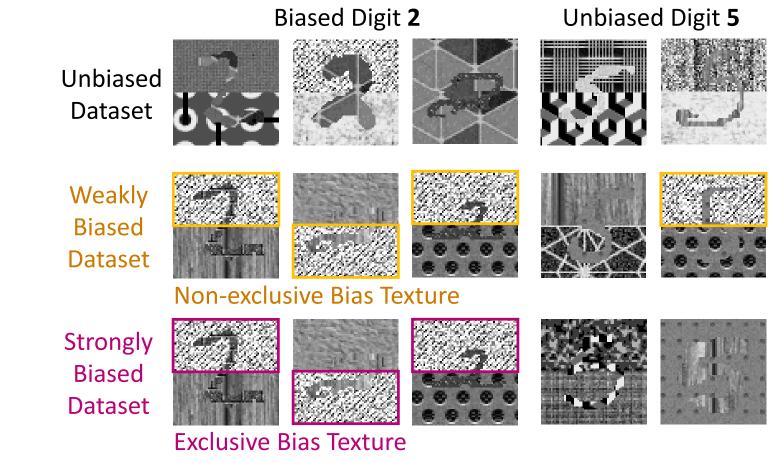
Synthetic Data for Benchmarking Saliencies

Generation of the dataset with induced bias

MNIST digits are combined with random fore- and background textures

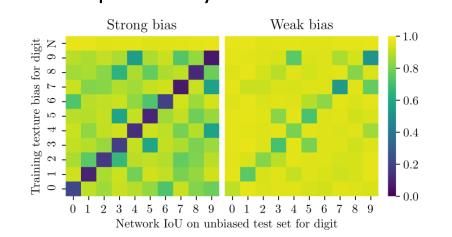


Context bias is induced into the dataset by choosing the same background texture for a specific digit

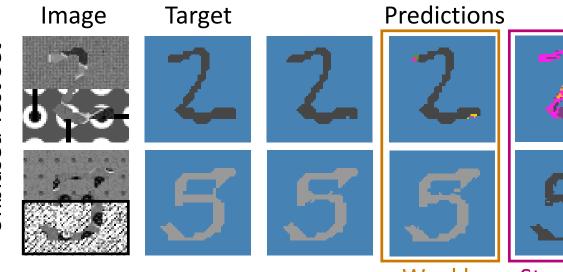


Has the network picked up the bias?

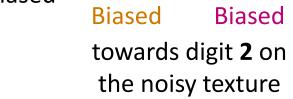
Test a potentially biased network on an unbiased dataset



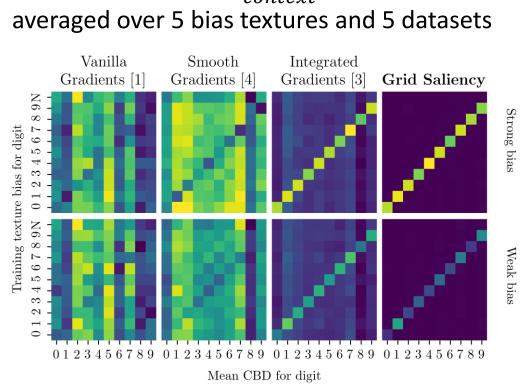
Drop in segmentation IoU for biased digits → Network has picked up the bias



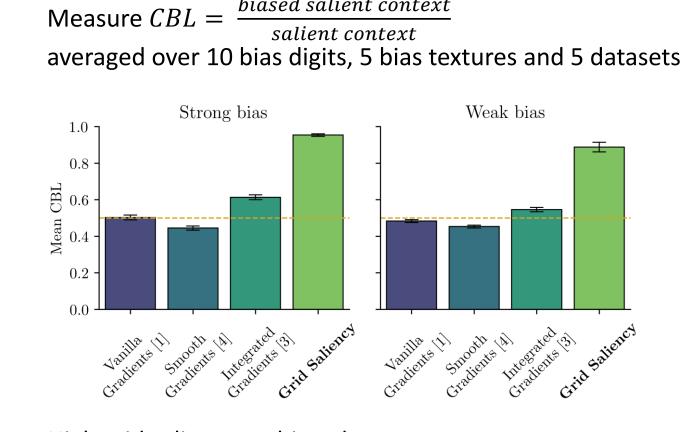
Network trained on: Unbiased



Can the saliency detect biased samples and localize the bias?



High grid saliency on biased digits → Biased samples can be detected



High grid saliency on biased context → Bias can be localized

References

[1] Simonyan et al. Deep inside convolutional networks: Visualising image classification models and saliency maps. In International Conference on Learning Representations, 2013. [2] Fong et al. Interpretable explanations of black boxes by meaningful perturbation. In Proceedings of the IEEE International Conference on Computer Vision, 2017.

[3] Sundararajan et al. Axiomatic attribution for deep networks. In International Conference on Machine Learning, 2017.

[4] Smilkov et al. Smoothgrad: removing noise by adding noise. arXiv:1706.03825, 2017