

# Good practice to export and import a report for Fossology

Supported by **ROSIN** - ROS-Industrial Quality-Assured Robot Software Components.

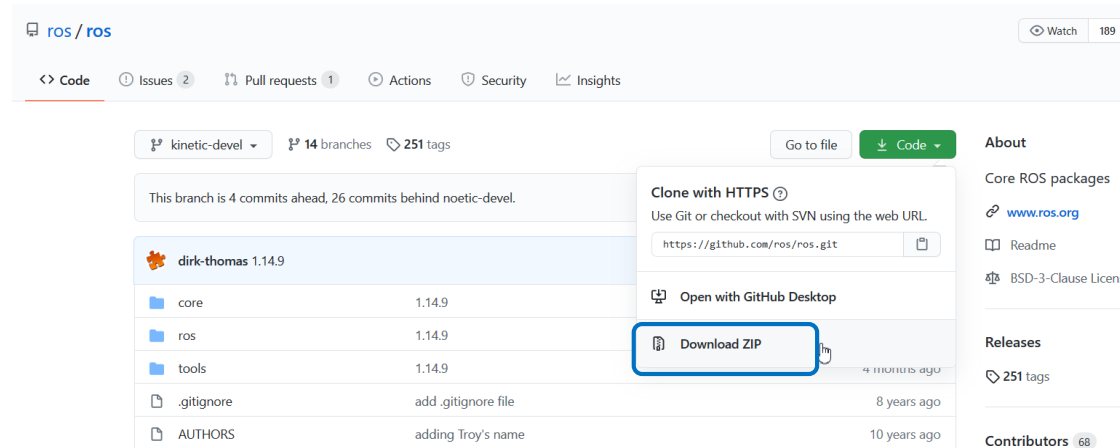
More information: [rosin-project.eu](http://rosin-project.eu)

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# Preparation

# Download a package from GitHub

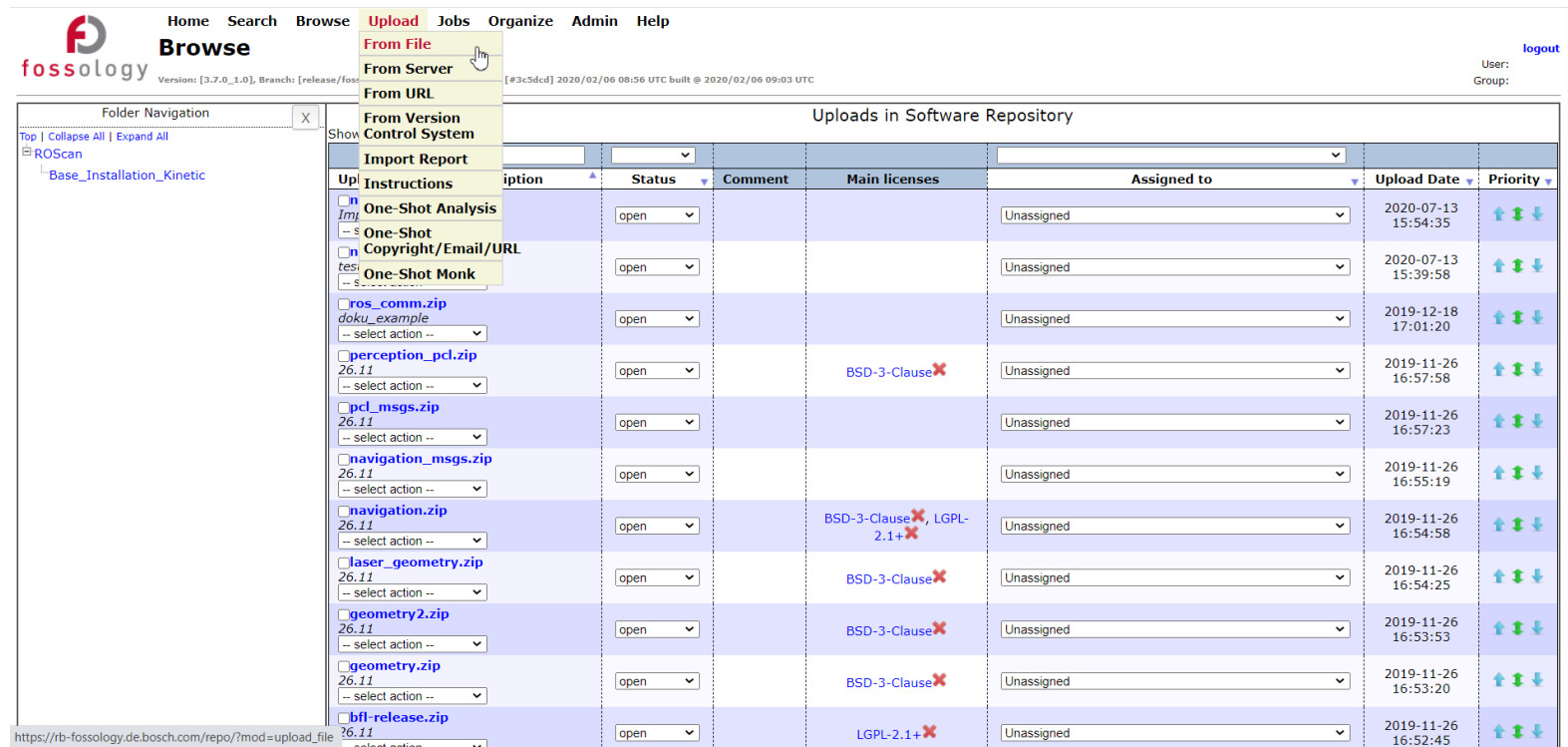


- Download the ROS package you would like to inspect. Download as .zip is helpful, because Fossology uses files in .zip format



- Rename the folder within the downloaded .zip file. (This is needed to match the package and the report structure. For more information s. slide 12)

# Upload the file to Fossology

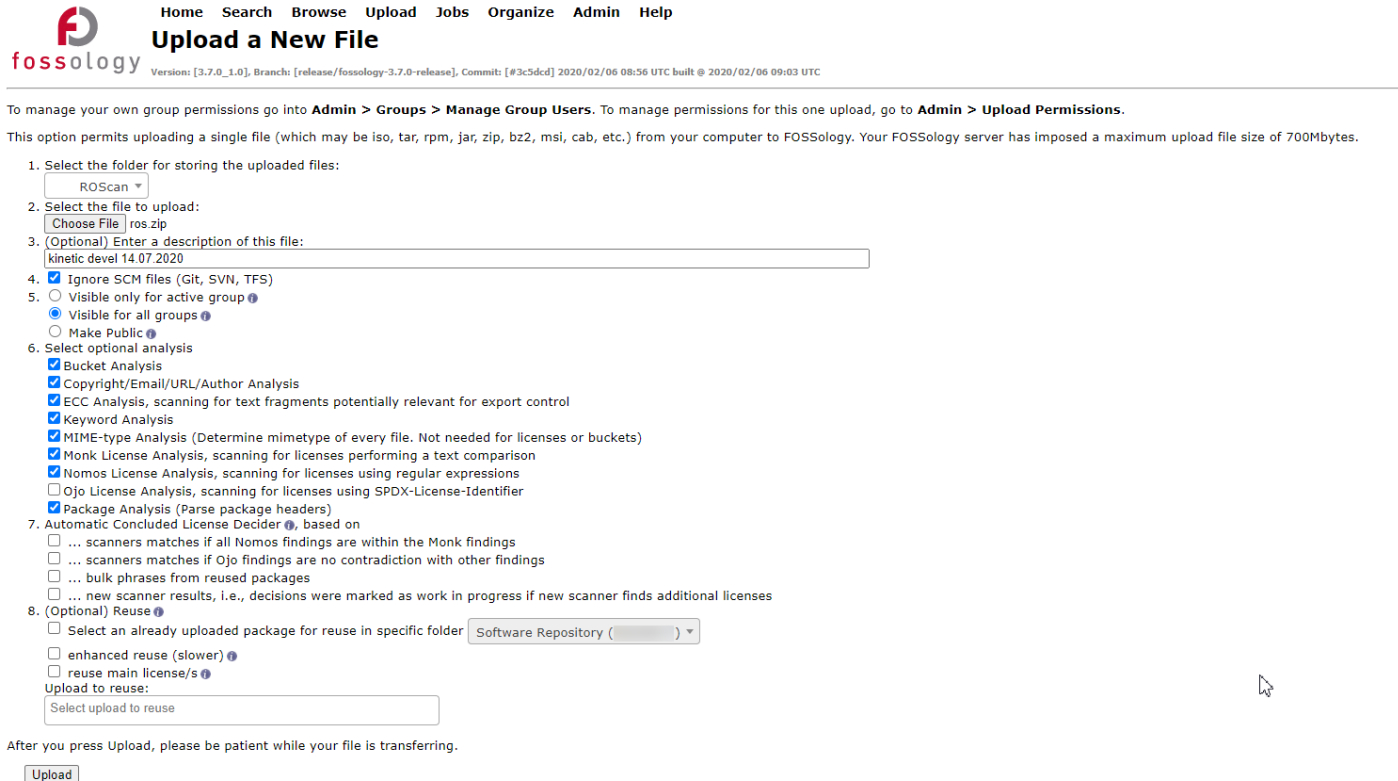


The screenshot shows the Fossology web interface. The top navigation bar includes links for Home, Search, Browse, Upload, Jobs, Organize, Admin, and Help. The 'Upload' menu is open, showing options: From File, From Server, From URL, From Version Control System, and Import Report. The 'From File' option is highlighted. The main content area displays a table titled 'Uploads in Software Repository'. The table has columns for Upload Name, Description, Status, Comment, Main licenses, Assigned to, Upload Date, and Priority. The table lists several files, including 'One-Shot Analysis', 'One-Shot Copyright/Email/URL', 'One-Shot Monk', 'ros\_comm.zip', 'perception\_pcl.zip', 'pcl\_msgs.zip', 'navigation\_msgs.zip', 'navigation.zip', 'laser\_geometry.zip', 'geometry2.zip', 'geometry.zip', and 'bfl-release.zip'. Each row shows the file name, a description, a status of 'open', a comment, the main license (e.g., BSD-3-Clause, LGPL-2.1+), the assigned user (Unassigned), the upload date, and a priority level (indicated by a green arrow icon).

Upload Name	Description	Status	Comment	Main licenses	Assigned to	Upload Date	Priority
One-Shot Analysis	One-Shot	open			Unassigned	2020-07-13 15:54:35	↑ ↓
One-Shot Copyright/Email/URL	One-Shot	open			Unassigned	2020-07-13 15:39:58	↑ ↓
One-Shot Monk	One-Shot	open			Unassigned	2020-07-13 15:39:58	↑ ↓
ros_comm.zip	doku_example	open			Unassigned	2019-12-18 17:01:20	↑ ↓
perception_pcl.zip	26.11	open		BSD-3-Clause	Unassigned	2019-11-26 16:57:58	↑ ↓
pcl_msgs.zip	26.11	open			Unassigned	2019-11-26 16:57:23	↑ ↓
navigation_msgs.zip	26.11	open			Unassigned	2019-11-26 16:55:19	↑ ↓
navigation.zip	26.11	open		BSD-3-Clause, LGPL-2.1+	Unassigned	2019-11-26 16:54:58	↑ ↓
laser_geometry.zip	26.11	open		BSD-3-Clause	Unassigned	2019-11-26 16:54:25	↑ ↓
geometry2.zip	26.11	open		BSD-3-Clause	Unassigned	2019-11-26 16:53:53	↑ ↓
geometry.zip	26.11	open		BSD-3-Clause	Unassigned	2019-11-26 16:53:20	↑ ↓
bfl-release.zip	26.11	open		LGPL-2.1+	Unassigned	2019-11-26 16:52:45	↑ ↓

- Open the Fossology GUI within your browser
- Choose “Upload” -> “From File”

# Load the file to Fossology



The screenshot shows the Fossology web interface for uploading a new file. The header includes the Fossology logo and navigation links: Home, Search, Browse, Upload, Jobs, Organize, Admin, and Help. Below the header, the title 'Upload a New File' is displayed, followed by version and commit information. A note explains that permissions can be managed via 'Admin > Groups > Manage Group Users' or 'Admin > Upload Permissions'. A warning states that only single files (iso, tar, rpm, jar, zip, bz2, msi, cab, etc.) are allowed, with a 700MB limit. The main form consists of eight numbered steps: 1. Select the folder (ROScan selected). 2. Select the file to upload (Choose File button, ros.zip selected). 3. Optional description (kinetic devel 14.07.2020 entered). 4. Ignore SCM files (checked). 5. Visibility (Visible for all groups selected). 6. Optional analysis (multiple checkboxes for various analyses, all checked). 7. Automatic Concluded License Decider (based on various scanner matches, all unchecked). 8. Optional Reuse (unchecked, with a dropdown for 'Software Repository'). An 'Upload' button is at the bottom.

Home Search Browse Upload Jobs Organize Admin Help

## Upload a New File

Version: [3.7.0\_1.0], Branch: [release/fossology-3.7.0-release], Commit: [#3c5dc4] 2020/02/06 08:56 UTC built @ 2020/02/06 09:03 UTC

To manage your own group permissions go into **Admin > Groups > Manage Group Users**. To manage permissions for this one upload, go to **Admin > Upload Permissions**.

This option permits uploading a single file (which may be iso, tar, rpm, jar, zip, bz2, msi, cab, etc.) from your computer to FOSSology. Your FOSSology server has imposed a maximum upload file size of 700Mbytes.

1. Select the folder for storing the uploaded files:  
ROScan
2. Select the file to upload:  
Choose File ros.zip
3. (Optional) Enter a description of this file:  
kinetic devel 14.07.2020
4. ☒ Ignore SCM files (Git, SVN, TFS)
5. ☐ Visible only for active group  
☒ Visible for all groups  
☐ Make Public
6. Select optional analysis  
☒ Bucket Analysis  
☒ Copyright/Email/URL/Author Analysis  
☒ ECC Analysis, scanning for text fragments potentially relevant for export control  
☒ Keyword Analysis  
☒ MIME-type Analysis (Determine mimetype of every file. Not needed for licenses or buckets)  
☒ Monk License Analysis, scanning for licenses performing a text comparison  
☒ Nomos License Analysis, scanning for licenses using regular expressions  
☐ Ojo License Analysis, scanning for licenses using SPDX-License-Identifier  
☒ Package Analysis (Parse package headers)
7. Automatic Concluded License Decider, based on  
☐ ... scanners matches if all Nomos findings are within the Monk findings  
☐ ... scanners matches if Ojo findings are no contradiction with other findings  
☐ ... bulk phrases from reused packages  
☐ ... new scanner results, i.e., decisions were marked as work in progress if new scanner finds additional licenses
8. (Optional) Reuse  
☐ Select an already uploaded package for reuse in specific folder Software Repository  
☐ enhanced reuse (slower)  
☐ reuse main license/s  
Upload to reuse:  
Select upload to reuse

After you press Upload, please be patient while your file is transferring.

Upload

1. Select the folder where to upload the package
2. Choose the file from the download folder
3. Enter some description for the file
6. Select some optional analysis (not needed in case of a later report import)

# Browser view after package upload

**fossology** Home Search Browse Upload Jobs Organize Admin Help  
**Browse**  
Version: [3.7.0\_1.0], Branch: [release/fossology-3.7.0-release], Commit: [#3c5dcd] 2020/02/06 08:56 UTC built @ 2020/02/06 09:03 UTC

User: [logout](#)  
Group:

Folder Navigation X  
Top | Collapse All | Expand All  
ROScan  
Base\_Installation\_Kinetic

Shows 50 entries

Search:						
Upload Name and Description	Status	Comment	Main licenses	Assigned to	Upload Date	Priority
<input type="checkbox"/> <a href="#">ros.zip</a> kinetic devel 14.07.2020 -- select action --	open			Unassigned	2020-07-14 16:52:16	↑ ↓
<input type="checkbox"/> <a href="#">navigation2020.zip</a> Import test2 -- select action --	open			Unassigned	2020-07-13 15:54:35	↑ ↓
<input type="checkbox"/> <a href="#">navigation.zip</a> test for import -- select action --	open			Unassigned	2020-07-13 15:39:58	↑ ↓
<input type="checkbox"/> <a href="#">ros_comm.zip</a> doku_example -- select action --	open			Unassigned	2019-12-18 17:01:20	↑ ↓
<input type="checkbox"/> <a href="#">perception_pcl.zip</a> 26.11 -- select action --	open		BSD-3-Clause	Unassigned	2019-11-26 16:57:58	↑ ↓
<input type="checkbox"/> <a href="#">pcl_msgs.zip</a> 26.11 -- select action --	open			Unassigned	2019-11-26 16:57:23	↑ ↓

The uploaded packages appears at the top. (Sometimes it takes a few minutes until the upload job is executed)

# Download a report

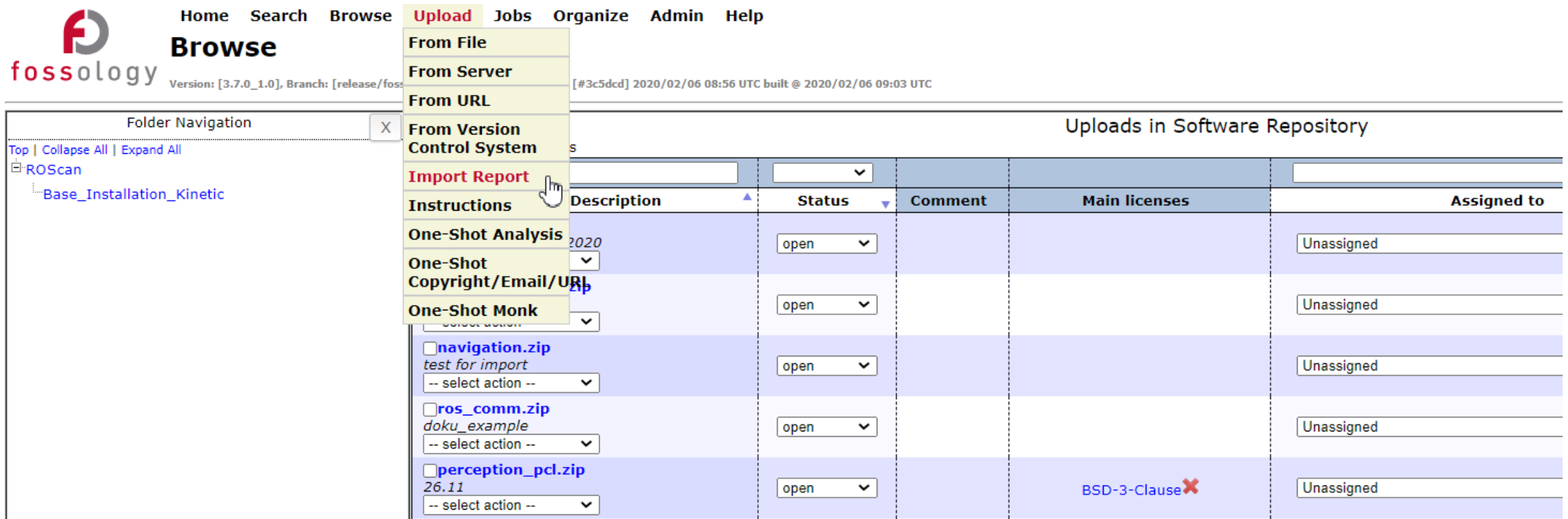
master 1 branch 0 tags			Go to file	Add file	Code
ArneF-oss and ArneF-oss New test ...			34f098e	6 days ago	17 commits
CC BY 4.0 License text.txt	Add CC BY 4.0 license text file	21 days ago			
Empty2.txt	New test	6 days ago			
README.md	Update README.md	23 days ago			
ROScan clearing concept.pdf	Initial upload of the scan results as excel file and scan concept.	9 days ago			
Roscan_all_packages.xlsx	Initial upload of the scan results as excel file and scan concept.	9 days ago			
SPDX2_actionlib.zip_1595001994-spd...	Fix of report path	9 days ago			
SPDX2_ros.zip_1595247747-spd..._exa...	Signed-off-by: ArneF-oss	10 days ago			

- Download a scan report files (e.g. SPDX2\_ros.zip... from a GitHub repository)
- If you downloaded a .zip file -> Unzip it to make it usable for the import tool

# Import a report



# Import a report to a package

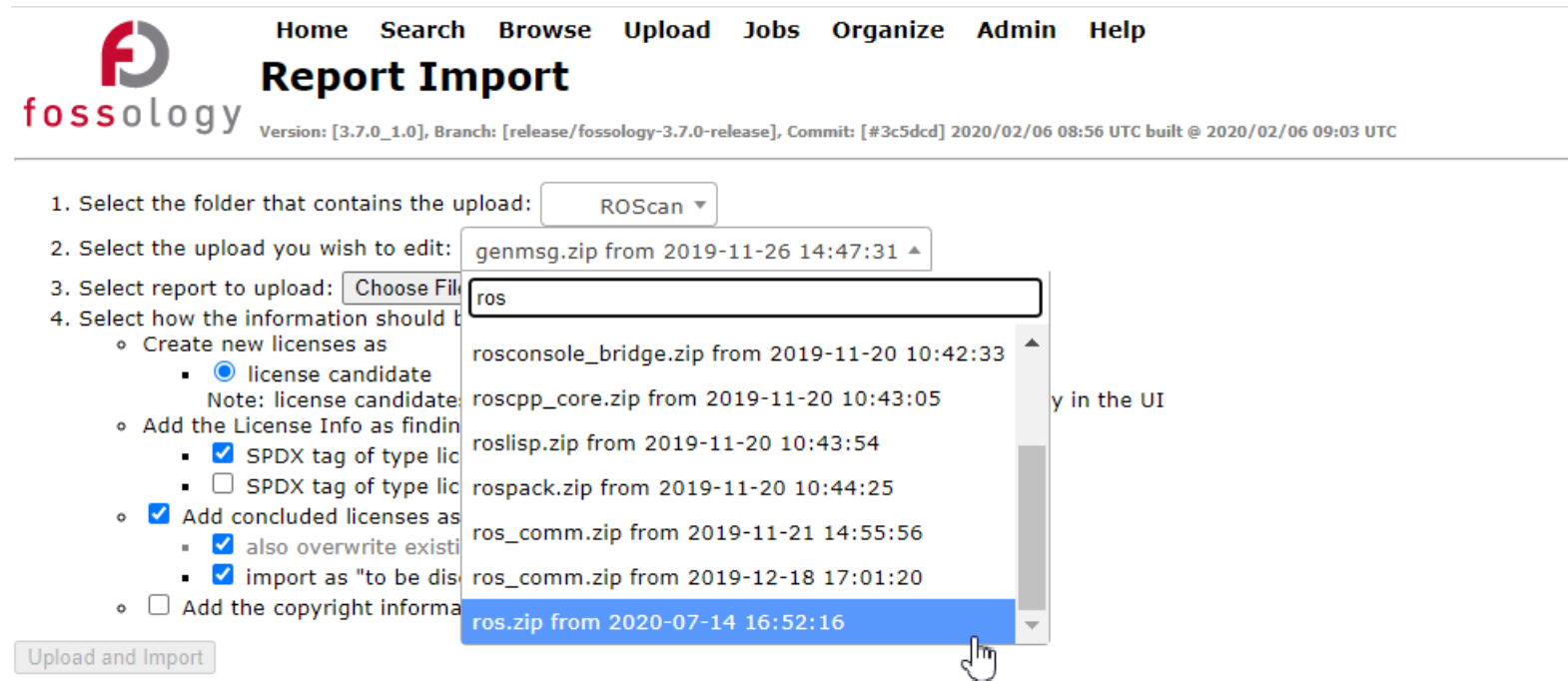


The screenshot shows the Fossology web interface. At the top, there is a navigation bar with links: Home, Search, Browse, Upload, Jobs, Organize, Admin, and Help. The 'Upload' link is highlighted. Below the navigation bar, the 'Browse' section is active, showing a folder navigation tree on the left with 'ROScan' and 'Base\_Installation\_Kinetic'. The main content area displays a table titled 'Uploads in Software Repository'. The table has columns: Description, Status, Comment, Main licenses, and Assigned to. The 'Import Report' menu option is highlighted in the 'Upload' dropdown menu. The table lists several uploads, including 'navigation.zip', 'ros\_comm.zip', and 'perception\_pcl.zip', all with a status of 'open' and 'Assigned to' as 'Unassigned'. The 'Main licenses' column shows 'BSD-3-Clause' for the 'perception\_pcl.zip' upload.

Description	Status	Comment	Main licenses	Assigned to
	open			Unassigned
	open			Unassigned
	open			Unassigned
	open			Unassigned
	open			Unassigned
	open		BSD-3-Clause	Unassigned

- Open the Fossology GUI within your browser
- Choose “Upload” -> “Import Report”

# Import a report to a package



The screenshot shows the Fossology web interface for importing a report. The header includes the Fossology logo and navigation links: Home, Search, Browse, Upload, Jobs, Organize, Admin, and Help. Below the header, the page title is "Report Import" and a version/commit string is displayed: "Version: [3.7.0\_1.0], Branch: [release/fossology-3.7.0-release], Commit: [#3c5dcd] 2020/02/06 08:56 UTC built @ 2020/02/06 09:03 UTC".

The main content area contains four numbered steps:

1. Select the folder that contains the upload:
2. Select the upload you wish to edit:
3. Select report to upload:
4. Select how the information should be handled:
  - Create new licenses as
    - ☒ license candidate
    - Note: license candidate
  - Add the License Info as finding
    - ☒ SPDX tag of type lic
    - ☐ SPDX tag of type lic
  - ☒ Add concluded licenses as
    - ☒ also overwrite existi
    - ☒ import as "to be dis
  - ☐ Add the copyright informa

A dropdown menu is open for step 3, showing a list of reports. The first report, "ros", is selected. The list includes:

- rosconsole\_bridge.zip from 2019-11-20 10:42:33
- roscpp\_core.zip from 2019-11-20 10:43:05
- roslisp.zip from 2019-11-20 10:43:54
- rospack.zip from 2019-11-20 10:44:25
- ros\_comm.zip from 2019-11-21 14:55:56
- ros\_comm.zip from 2019-12-18 17:01:20
- ros.zip from 2020-07-14 16:52:16

An "Upload and Import" button is visible at the bottom left of the form.

1. Select the folder (within Fossology) at which the package to edit is located
2. Choose the package you would like to add the report to
3. Choose the (downloaded) report which should be added

# Import a report to a package



The screenshot shows the Fossology web interface for importing a report. The header includes the Fossology logo, navigation links (Home, Search, Browse, Upload, Jobs, Organize, Admin, Help), and the title "Report Import". Below the header, the version and branch information are displayed. The main form contains four steps for importing a report:

1. Select the folder that contains the upload:
2. Select the upload you wish to edit:
3. Select report to upload:
4. Select how the information should be imported:
  - Create new licenses as
    - ☒ license candidate
    - Note: license candidates as scanner findings are currently not handled correctly in the UI
  - Add the License Info as findings from
    - ☒ SPDX tag of type licenseInfoInFile
    - ☐ SPDX tag of type licenseConcluded
  - ☒ Add concluded licenses as decisions
    - ☒ also overwrite existing decisions
    - ☒ import as "to be discussed"
  - ☐ Add the copyright information as textfindings

At the bottom of the form, there is a button labeled "Upload and Import" with a mouse cursor pointing to it.

- 4. Select how the information (from the report) should be imported
  - > "Add concluded licenses as decisions" will always overwrite existing decisions!

# Import a report to a package - Hint

Folder: **Software Repository/ ROScan/**  
**ros.zip/**ros/ros

Display 25 licenses  Clear

Scanner Count	Concluded License Count	License Name
1	0	BSD

Showing 1 to 1 of 1 licenses Page 1 of 1


Hint: Click on the license name to search for where the license is found in the file listing.

Display 50 files (tree view)

Files	Scanner Res
CMakeLists.txt	
package.xml	BSD [1]

The folder structure of your package at Fossology has to be equal to the folder structure which was used for the report export. This includes also the naming of folders and files.

Otherwise the tool is not able to match report result and belonging file.

 [SPDX2\\_ros.zip\\_1595247747-spx\\_example.rdf](#)

```
<spdx:hasFile>
  <spdx:File rdf:about="SPDX2_ros.zip_1595247747-spx.rdf#SPDXRef-item72122468">
    <spdx:fileName>ros/ros/package.xml</spdx:fileName>
    <spdx:checksum>
      <spdx:Checksum>
        <spdx:algorithm rdf:resource="http://spdx.org/rdf/terms#checksumAlgorithm_sha1" />
        <spdx:checksumValue>c367d97dc39f64c2cee2676595ccd5d80e5ad203</spdx:checksumValue>
      </spdx:Checksum>
    </spdx:checksum>
  </spdx:hasFile>
```

# With and without import as “to be discussed”

## With “To be discussed”

Scanner Count	Concluded License Count	License Name
69	69	BSD-3-Clause
22	0	BSD-possibility
11	0	WebM
9	0	UnclassifiedLicense
8	0	Public-domain
5	0	BSD
1	1	License_info
1	0	not in use GPL-V2-only
1	0	Zlib-license
1	0	Not in use GPL-V2-or-later
1	0	Dual-license

-- filter for scan results --		-- filter for edited results --	<input type="checkbox"/> open		MarkAsIrrelevant
Files	Scanner Results (N: nomos, M: monk, Nk: ninka, I: reportImport, O: ojo)	Edited Results	Clearing Status	Files Cleared	Actions
core	BSD, BSD-3-Clause, BSD-possibility, Dual-license, License_info, No_license_found, not in use GPL-V2-only, Not in use GPL-V2-or-later, Public-domain, UnclassifiedLicense, WebM, Zlib-license	BSD-3-Clause, License_info	●	0/62	[Tag][Edit][Bulk] <input type="checkbox"/>
ros	BSD, No_license_found		●	0/1	[Tag][Edit][Bulk] <input type="checkbox"/>
tools	BSD, BSD-3-Clause, BSD-possibility, Dual-license, No_license_found, not in use GPL-V2-only, Not in use GPL-V2-or-later, Public-domain, WebM, Zlib-license	BSD-3-Clause	●	0/49	[Tag][Edit][Bulk] <input type="checkbox"/>
AUTHORS	No_license_found [N]		●	0/0	[View][Info][Download] [Tag][Edit] <input type="checkbox"/>
LICENSE	BSD-3-Clause [N][I]	BSD-3-Clause	●	0/1	[View][Info][Download] [Tag][Edit] <input type="checkbox"/>
README	No_license_found [N], UnclassifiedLicense [I]		●	0/1	[View][Info][Download] [Tag][Edit] <input type="checkbox"/>

## Without “To be discussed”

Scanner Count	Concluded License Count	License Name
69	69	BSD-3-Clause
22	0	BSD-possibility
11	0	WebM
9	0	UnclassifiedLicense
8	0	Public-domain
5	0	BSD
1	1	License_info
1	0	not in use GPL-V2-only
1	0	Zlib-license
1	0	Not in use GPL-V2-or-later
1	0	Dual-license

-- filter for scan results --		-- filter for edited results --	<input type="checkbox"/> open		MarkAsIrrelevant
Files	Scanner Results (N: nomos, M: monk, Nk: ninka, I: reportImport, O: ojo)	Edited Results	Clearing Status	Files Cleared	Actions
core	BSD, BSD-3-Clause, BSD-possibility, Dual-license, License_info, not in use GPL-V2-only, Not in use GPL-V2-or-later, Public-domain, UnclassifiedLicense, WebM, Zlib-license	BSD-3-Clause, License_info	●	37/62	[Tag][Edit][Bulk] <input type="checkbox"/>
ros	BSD		●	0/1	[Tag][Edit][Bulk] <input type="checkbox"/>
tools	BSD, BSD-3-Clause, BSD-possibility, Dual-license, not in use GPL-V2-only, Not in use GPL-V2-or-later, Public-domain, WebM, Zlib-license	BSD-3-Clause	●	32/49	[Tag][Edit][Bulk] <input type="checkbox"/>
AUTHORS			●	0/0	[View][Info][Download] [Tag][Edit] <input type="checkbox"/>
LICENSE	BSD-3-Clause [I]	BSD-3-Clause	●	1/1	[View][Info][Download] [Tag][Edit] <input type="checkbox"/>
README	UnclassifiedLicense [I]		●	0/1	[View][Info][Download] [Tag][Edit] <input type="checkbox"/>

- If you take over the report without the “to be discussed” flag the imported report results will be directly transferred to your package. So you don’t have to do decision checks for belonging files again, but therefore you have to trust the decisions within the report.

# Job overview



[Home](#) [Search](#) [Browse](#) [Upload](#) [Jobs](#) [Organize](#) [Admin](#) [Help](#)

## Show Jobs

Version: [3.7.0\_1.0], Branch: [release/fossology-3.7.0-release], Commit: [#3c5dcd] 2020/02/06 08:56 UTC built @ 2020/02/06 09:03 UTC

[logout](#)

User:

Group:

1 2 3 [Next] [Last]

ros.zip							
Job/Dependency	Status				Average items/sec	ETA	
255162	Completed	reportimport	47 items	2020-07-14 17:02 - 2020-07-14 17:02	47.000 items/sec	Scanned	[Download uploaded SPDX2 report]
ros.zip							
Job/Dependency	Status				Average items/sec	ETA	
255161	Completed	spdx2	269 items	2020-07-14 16:56 - 2020-07-14 16:56	269.00 items/sec	Scanned	[Download SPDX2 report]
ros.zip							
Job/Dependency	Status				Average items/sec	ETA	
255151	Completed	ununpack	289 items	2020-07-14 16:52 - 2020-07-14 16:52	32.111 items/sec	Scanned	
255152 / 255151	Completed	adj2nest	288 items	2020-07-14 16:52 - 2020-07-14 16:52	288.00 items/sec	Scanned	
255153 / 255152	Completed	nomos	192 items	2020-07-14 16:52 - 2020-07-14 16:52	11.294 items/sec	Scanned	
255154 / 255152	Completed	pkgagent	0 items	2020-07-14 16:52 - 2020-07-14 16:52	0.0000 items/sec	Scanned	
255155 / 255153 / 255154	Completed	buckets	272 items	2020-07-14 16:52 - 2020-07-14 16:52	136.00 items/sec	Scanned	
255156 / 255152	Completed	copyright	195 items	2020-07-14 16:52 - 2020-07-14 16:52	195.00 items/sec	Scanned	
255157 / 255152	Completed	ecc	195 items	2020-07-14 16:52 - 2020-07-14 16:52	195.00 items/sec	Scanned	
255158 / 255152	Completed	keyword	195 items	2020-07-14 16:52 - 2020-07-14 16:52	195.00 items/sec	Scanned	
255159 / 255152	Completed	mimetype	154 items	2020-07-14 16:52 - 2020-07-14 16:52	154.00 items/sec	Scanned	
255160 / 255152	Completed	monk	192 items	2020-07-14 16:52 - 2020-07-14 16:52	192.00 items/sec	Scanned	

Done job for:

- Import
- Export
- Package upload

# Import a new export file

	-- filter for scan results -- ▾	-- filter for edited results -- ▾	<input type="checkbox"/> open		MarkAsIrrelevant
Files ▲	Scanner Results (N: nomos, M: monk, Nk: ninka, I: reportImport, O: ojo)	Edited Results	Clearing Status	Files Cleared	Actions <input type="checkbox"/>
core	BSD, BSD-3-Clause, BSD-possibility, No_license_found, Public-domain		●	0/61	[Tag][Edit][Bulk] <input type="checkbox"/>
ros	BSD, No_license_found		●	0/1	[Tag][Edit][Bulk] <input type="checkbox"/>
tools	BSD, BSD-3-Clause, BSD-possibility, No_license_found, Public-domain		●	0/45	[Tag][Edit][Bulk] <input type="checkbox"/>
AUTHORS	No_license_found [N]		●	0/0	[View][Info][Download] [Tag][Edit] <input type="checkbox"/>
LICENSE	BSD-3-Clause [N]		●	0/1	[View][Info][Download] [Tag][Edit] <input type="checkbox"/>
README	No_license_found [N]		●	0/0	[View][Info][Download] [Tag][Edit] <input type="checkbox"/>

Scanner Count ▾	Concluded License Count ▾	License Name ▾
69	69	BSD-3-Clause
22	0	BSD-possibility
11	0	WebM
9	0	UnclassifiedLicense
8	0	Public-domain
5	0	BSD
1	1	License_info
1	0	not in use GPL-V2-only
1	0	Zlib-license
1	0	Not in use GPL-V2-or-later
1	0	Dual-license

	-- filter for scan results -- ▾	-- filter for edited results -- ▾	<input type="checkbox"/> open		MarkAsIrrelevant
Files ▲	Scanner Results (N: nomos, M: monk, Nk: ninka, I: reportImport, O: ojo)	Edited Results	Clearing Status	Files Cleared	Actions <input type="checkbox"/>
core	BSD, BSD-3-Clause, BSD-possibility, Dual-license, License_info, not in use GPL-V2-only, Not in use GPL-V2-or-later, Public-domain, UnclassifiedLicense, WebM, Zlib-license	BSD-3-Clause, License_info	●	37/62	[Tag][Edit][Bulk] <input type="checkbox"/>
ros	BSD		●	0/1	[Tag][Edit][Bulk] <input type="checkbox"/>
tools	BSD, BSD-3-Clause, BSD-possibility, Dual-license, not in use GPL-V2-only, Not in use GPL-V2-or-later, Public-domain, WebM, Zlib-license	BSD-3-Clause	●	32/49	[Tag][Edit][Bulk] <input type="checkbox"/>
AUTHORS			●	0/0	[View][Info][Download] [Tag][Edit] <input type="checkbox"/>
LICENSE	BSD-3-Clause [I]	BSD-3-Clause	●	1/1	[View][Info][Download] [Tag][Edit] <input type="checkbox"/>
README	UnclassifiedLicense [I]		●	0/1	[View][Info][Download] [Tag][Edit] <input type="checkbox"/>

- If the imported report bases on the same version of the package all decisions (in this case 70) from the report will be connected with the belonging package files

# Import a older export file

Display25licenses

Clear

Scanner Count	Concluded License Count	License Name
69	8	BSD-3-Clause
22	0	BSD-possibility
11	0	WebM
9	0	UnclassifiedLicense
8	0	Public-domain
5	0	BSD
1	0	not in use GPL-V2-only
1	0	Zlib-license
1	0	Not in use GPL-V2-or-later
1	0	Dual-license

Showing 1 to 10 of 10 licenses

Page1of 1

Display50files (tree view or flat)

Clear

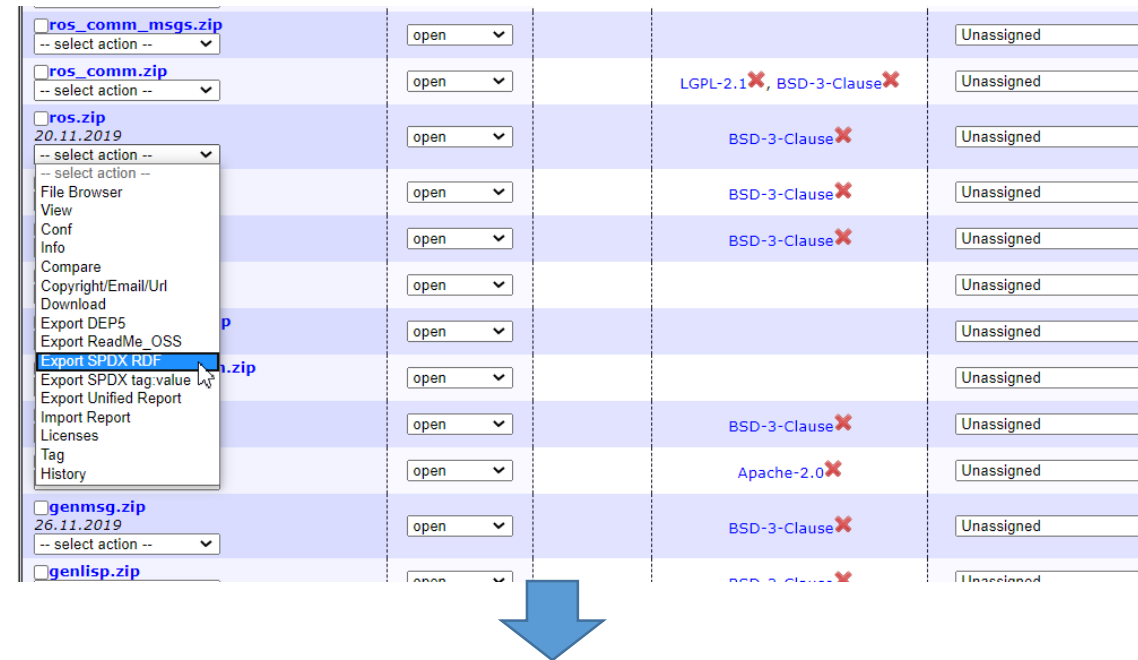
	-- filter for scan results --	-- filter for edited results --	open		MarkAsIrrelevant
Files	Scanner Results (N: nomos, M: monk, Nk: ninka, I: reportImport, O: ojo)	Edited Results	Clearing Status	Files Cleared	Actions
core	BSD, BSD-3-Clause, BSD-possibility, Dual-license, No_license_found, not in use GPL-V2-only, Not in use GPL-V2-or-later, Public-domain, UnclassifiedLicense, WebM, Zlib-license	BSD-3-Clause		0/62	[Tag][Edit][Bulk]
ros	BSD, No_license_found			0/1	[Tag][Edit][Bulk]
tools	BSD, BSD-3-Clause, BSD-possibility, Dual-license, No_license_found, not in use GPL-V2-only, Not in use GPL-V2-or-later, Public-domain, WebM, Zlib-license	BSD-3-Clause		0/49	[Tag][Edit][Bulk]
AUTHORS	No_license_found [N]			0/0	[View][Info][Download][Tag][Edit]
LICENSE	BSD-3-Clause [N][M: 94%]			0/1	[View][Info][Download][Tag][Edit]
README	No_license_found [N], UnclassifiedLicense [I]			0/1	[View][Info][Download][Tag][Edit]

- If the imported report bases on an older version of the package just decisions for unchanged files (in this case 8) will be connected with the belonging package files



# Export

# Export Report



ros.zip							
Job/Dependency	Status	ros.zip			Average items/sec	ETA	
255161	Completed	spdx2	269 items	2020-07-14 16:56 - 2020-07-14 16:56	269.00 items/sec	Scanned	<a href="#">[Download SPDX2 report]</a>

- In case of an export choose the “Export SPDX RDF” item from the drop down list of the belonging package. This triggers a job to create and download the report