

# Boshen Zhang

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## RESEARCH INTERESTS

I am interested in Artificial Intelligence, particularly in the development of decision-making agents capable of adaptive, rapid, and robust operations within cooperative environments. My objective is to develop decision-making methodologies with applications in robotics. The following key areas currently shape my research endeavors:

- Multi-Agent Systems
- Robot Learning
- Human Robot Interaction
- Foundation Models

## EDUCATION

**University of Southern California**, GPA: 3.60/4.0

Jun 2023 - Dec 2024

*Master of Science*, Computer Science

Coursework: Robot Learning, Robotics, Autonomous Decision-Making, Computational Human-Robot Interaction, Algorithm Analysis, Machine Learning, Linear Programming and Extensions

**Virginia Tech**, GPA: 3.60/4.0

Aug 2018 - Dec 2022

*Bachelor of Science*, Computer Science & Applied Mathematics

## RESEARCH EXPERIENCE

**Interactive and Collaborative Autonomous Robotics Lab (ICAROS)**

Los Angeles, CA

University of Southern California

Dec 2023 - Present

*Research Assistant* / Advisor: **Stefanos Nikolaidis**

- Investigating diverse human behavior emulation with LLM-aided Quality Diversity (QD) optimization approach in multi-agent collaborative system.
- Developed LLM-based agent framework enabling agents' communication and collaboration in real time.
- Created an advanced multi-agent Steakhouse environment for agents and human interaction.
- Integrated SGLang with QD experiment framework on High-Performing Computing (HPC) platform, reducing experiment batch inference latency
- Investigating LLM embedding mutation strategy with CMA-ME on poetry evaluation domain.

**Computational Human-Robot Interaction Course Project**

Los Angeles, CA

University of Southern California

Jan 2024 - Present

*Research Lead* / Advisor: **Stefanos Nikolaidis**

- Enhanced agent real time adaptability to human behavior by utilizing LLMs for lower-level planning and benchmarking agent adaptability in proposed reactive scenarios.
- Finetuned llama3-8B model using LoRA based on trajectory from existing PPO algorithm and human experts
- Distilled Llama3-1B model with knowledge from GPT-4o to achieve lower latency and higher team fluency for proposed framework.
- Conducted user study and data analysis for different interaction styles between human and LLM powered agents and measured user satisfaction, perceived agent intelligence, and task efficiency under different teaming styles.

**Prof Hooshangi's Research Group**

*Research Assistant* / Advisor: **Sara Hooshangi**

Aug 2022 - Dec 2022

- Processed and lemmatized over 750 open-ended responses utilizing Natural Language Toolkit (NLTK), then leveraged Pandas to organize and analyze student feedback and identified recurring themes.
- Analyzed student responses using sentiment analysis, examined emotional insights and visualized sentiment patterns.

## PUBLICATIONS

**Boshen Zhang\***, Shipeng Liu\*, Zhehui Huang. 2024. Benchmark Real-time Adaptation and Communication Capabilities of Embodied Agent in Collaborative Scenario. In the Workshop on Planning in the Era of Large Language Models at the AAAI 2025(LM4Plan @ AAAI2025). Posted at <https://arxiv.org/abs/2412.00435>

PRESENTATIONS

Southern California Robotics Symposium. 2024. (Oral)

Riverside, CA

Benchmarking Reactive Human-AI Collaboration Powered by Foundation Models

COMPUTER SKILLS

Languages: Python, Java, JavaScript, C, Swift, MATLAB, Mathematica, Bash, LaTeX

Libraries: PyTorch, NumPy, Matplotlib, Pandas, Hugging Face

Other: ROS, Linux, PyBullet, SLURM, Robosuite

AWARDS & ACHIEVEMENTS

- Overall 2nd place for VTHacks IX Hackathon (387 participants)2022
- IISE DAIS Mobile/Web App Competition Finalist2022
- IISE Annual Conference & Expo, 4<sup>th</sup> place in final presentation2022

ACADEMIC PROJECTS

Steakhouse-AI

Feb - May 2024

Multi-agent Reinforcement learning testbed built on Overcooked environment

- Added 5 medium level actions and 4 unique dishes on top of Overcooked testbed.
- Developed an interactive game interface using Pygame for human-agent gameplay and communication

Fetch Arm Manipulation

Jan 2024

Scripts for Fetch robot objects manipulation in iGibson simulated environment.

- Implemented Inverse Kinematics for precise robot configurations in response to target positions
- Implemented RRT algorithms to manipulate objects while avoiding collisions

Semantic Search

Mar 2022

Chrome extension enabling search contents in form of synonyms, images, and videos. Alternative for Ctrl + F

- Achieved ~90% search accuracy by building a Chrome extension for synonyms and image recognition and highlighting features with JavaScript.
- Developed website object detection framework using YOLO and launched with google cloud

WORK EXPERIENCE

Prof. Weijun Xie’s Research Group

Blacksburg, VA

Software Engineer

Aug 2021 - May 2022

- Implemented a website with JavaScript, Express.js, jQuery, Bootstrap, specifically designed to manipulate and showcase behavior of a drunk driver linear model built in Pyomo
- Processed asynchronous HTTP requests using Ajax and maintained/analyzed user data with MySQL, enabling data analysis for 500+ users.

Share App

Remote

Full Stack Developer Intern

Jun 2021- Aug 2021

- Developed and integrated a user system with APIs, facilitating database access and processing diverse client requests and Migrated dataset from MongoDB to DynamoDB

LANGUAGE

Chinese (Native), English (Full-professional), Japanese (Elementary)