

# SE(3) Denoising Score Matching with Neural Euler's Rotation Equation

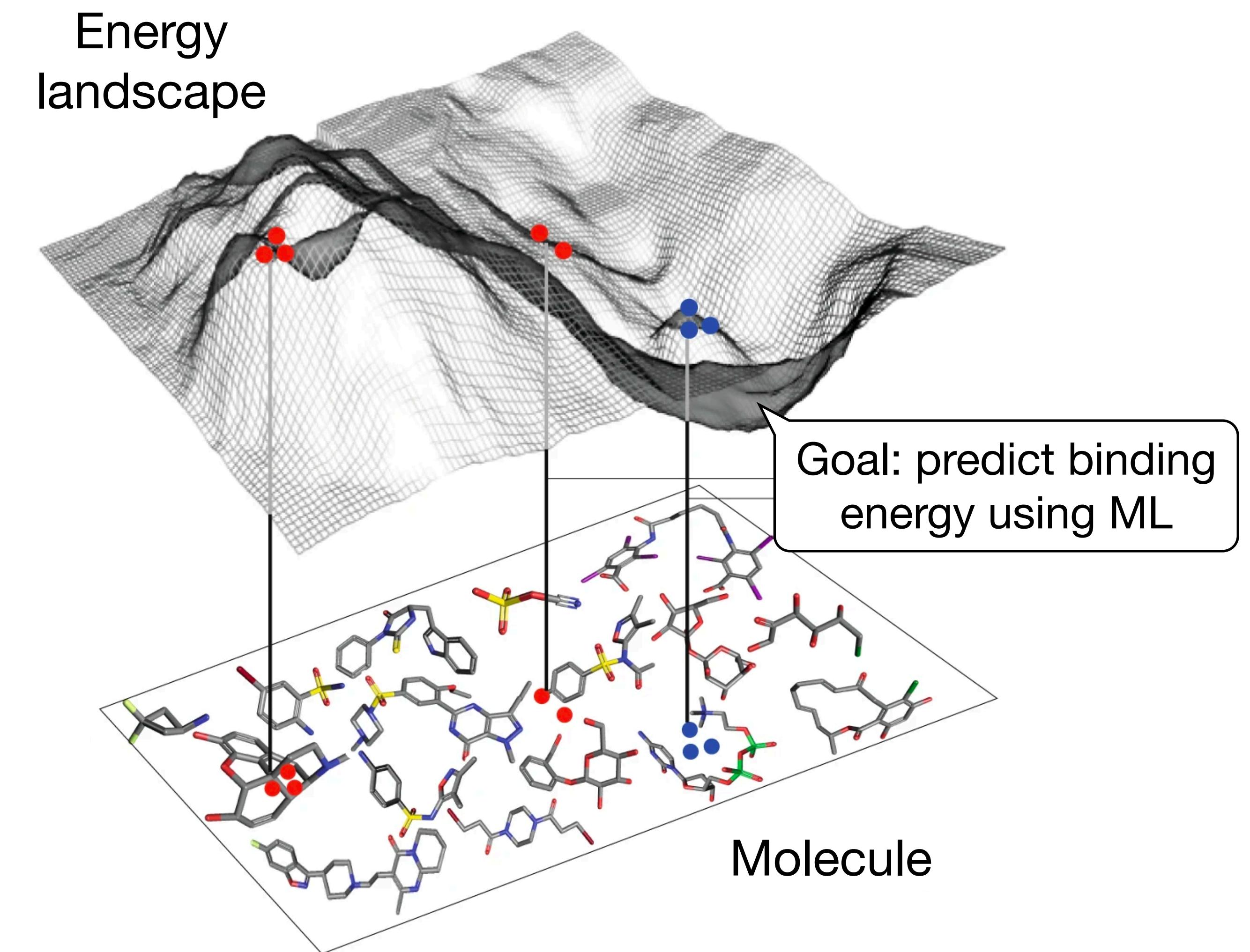
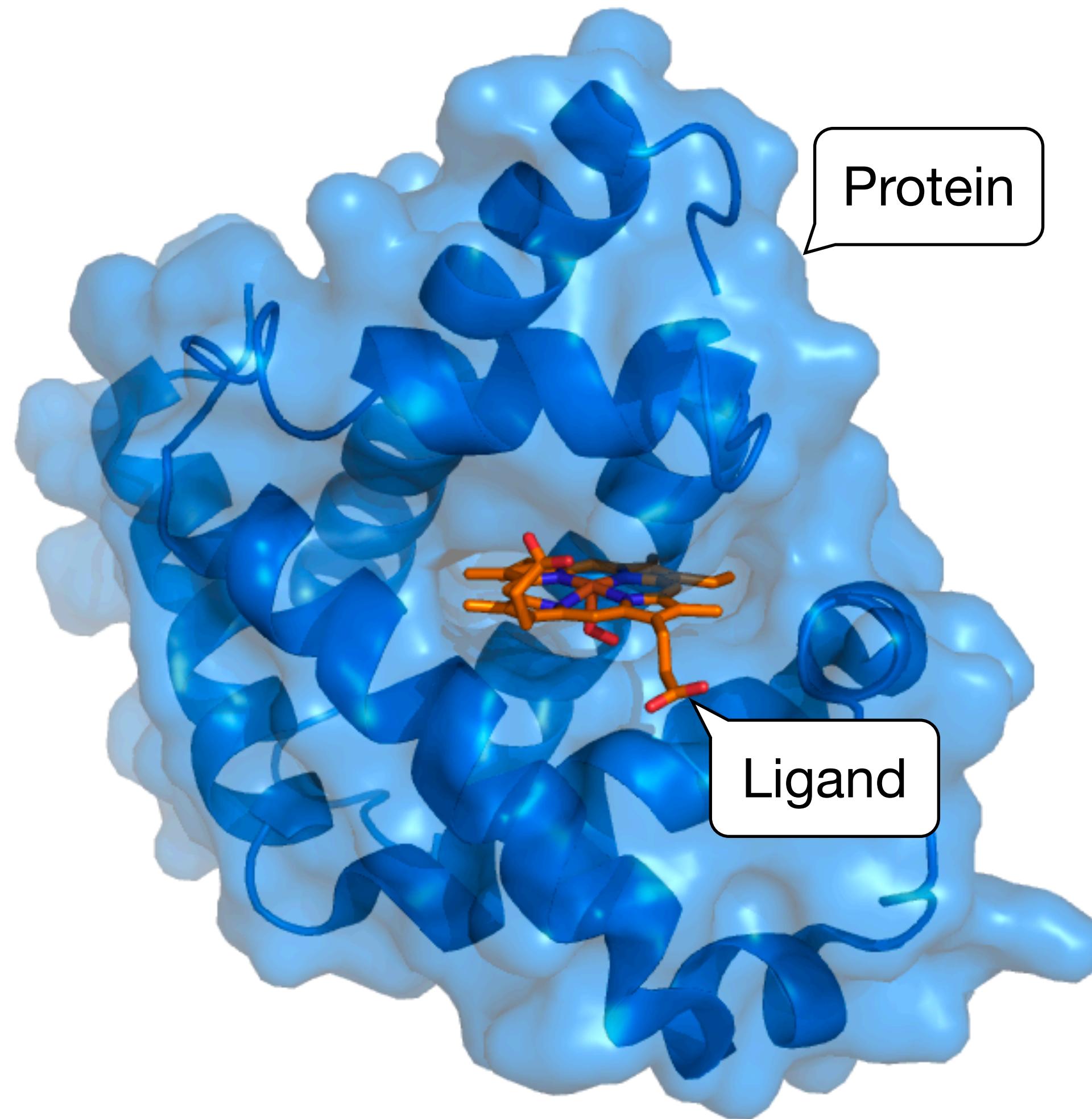
Towards unsupervised models for protein-ligand binding

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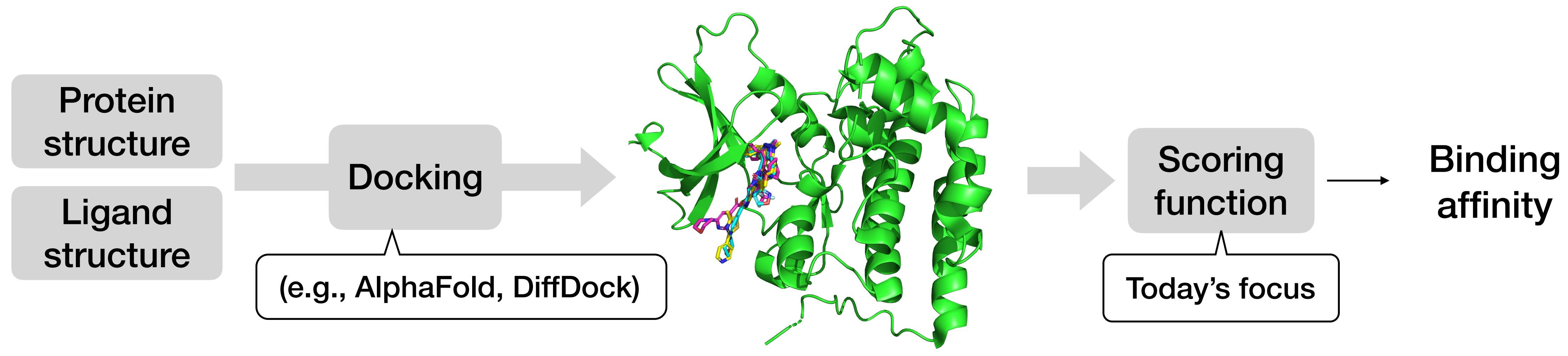
# Protein-ligand binding affinity prediction

## Applications of equivariant neural networks to drug discovery



# Protein-ligand binding affinity prediction

A typical workflow: docking + scoring

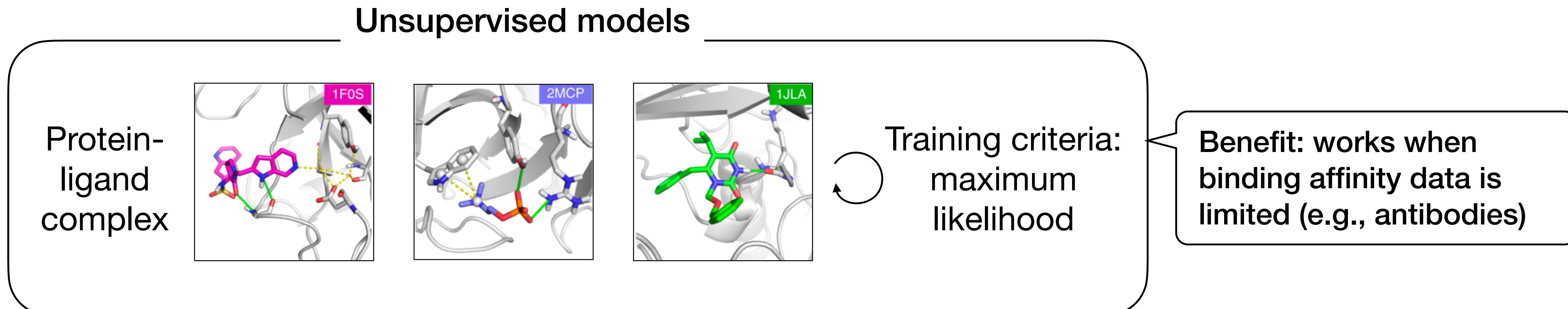
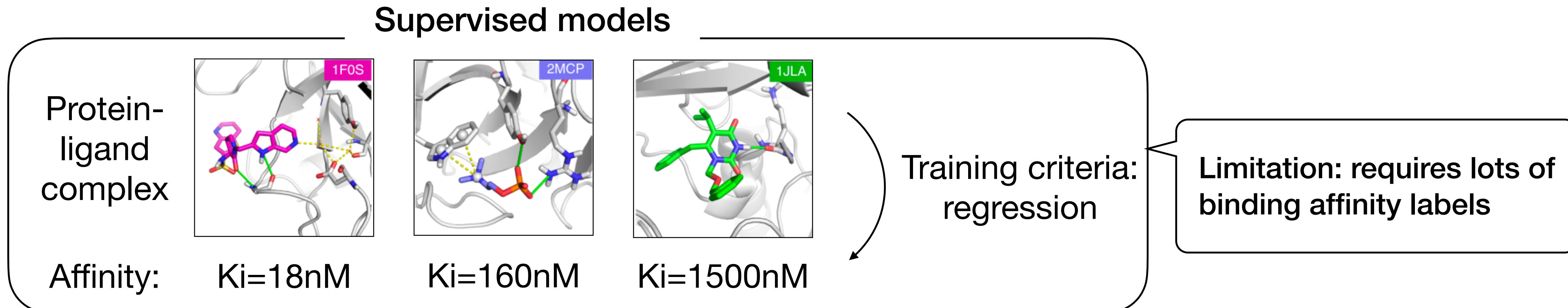


Outline of this talk

1. Formulate binding affinity prediction as a generative modeling problem
2. Train the generative model using SE(3) denoising score matching (DSM)
3. Propose a **simple & equivariant** rotation prediction module for SE(3) DSM

# Protein-ligand binding affinity prediction

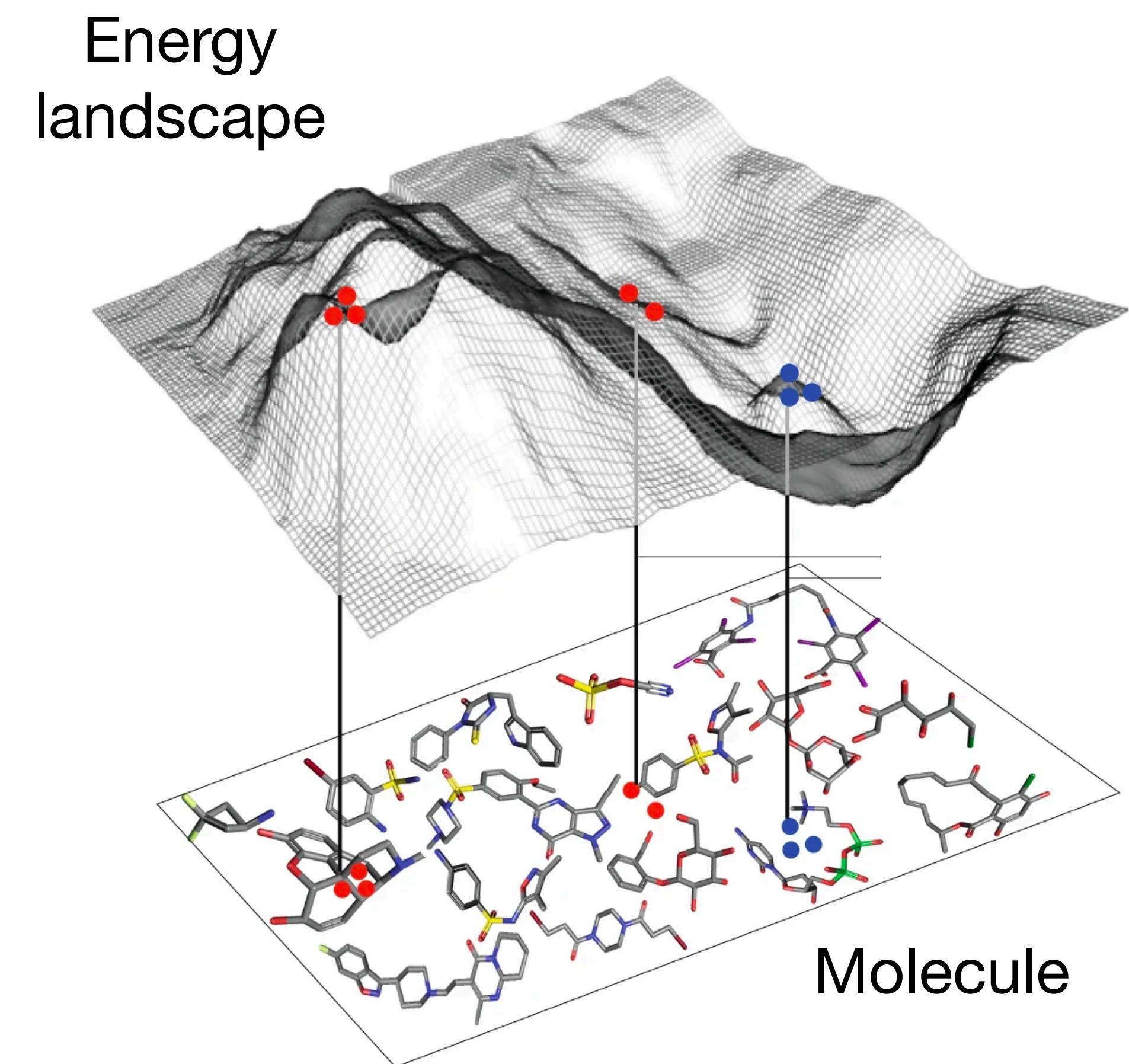
## Background: supervised & unsupervised models



# Protein-ligand binding affinity prediction

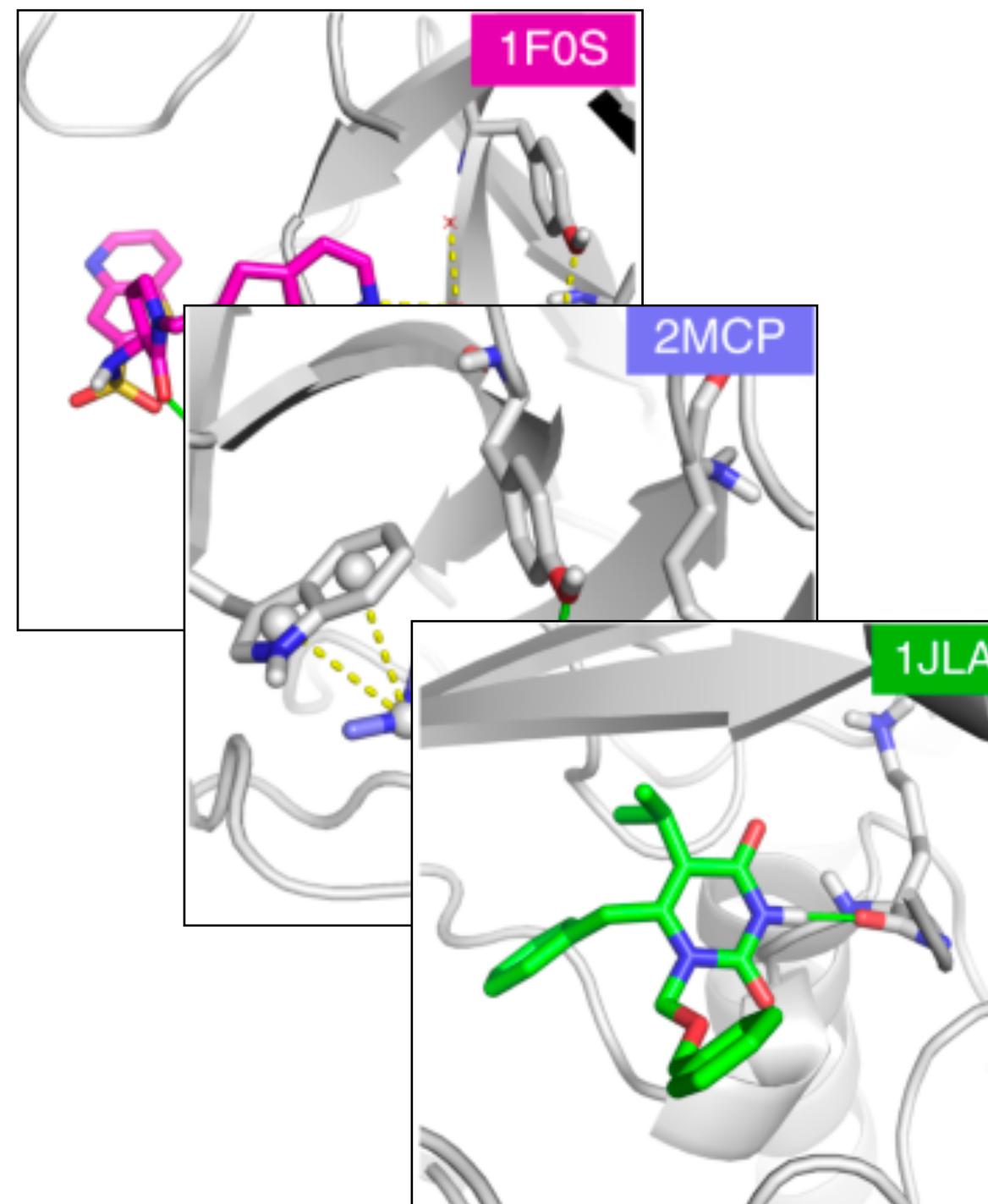
## Background: connection between binding energy and log-likelihood

- **Intuition:** if a protein-ligand complex has a strong binding affinity, it will appear more **often**
- The likelihood of a complex  $p(x) \propto \exp(-E_\theta(x))$ , where  $E_\theta(x)$  is the energy of a complex
- Previous work (e.g., DrugScore2018 [1]) showed log-likelihood is correlated with binding energy
  - $\log p(x) = \sum_{i,j} \log p(D_{ij} = d_{ij})$ , where  $d_{ij}$  is the distance between atom pair  $(i, j)$
  - Model is not expressive due to factorization



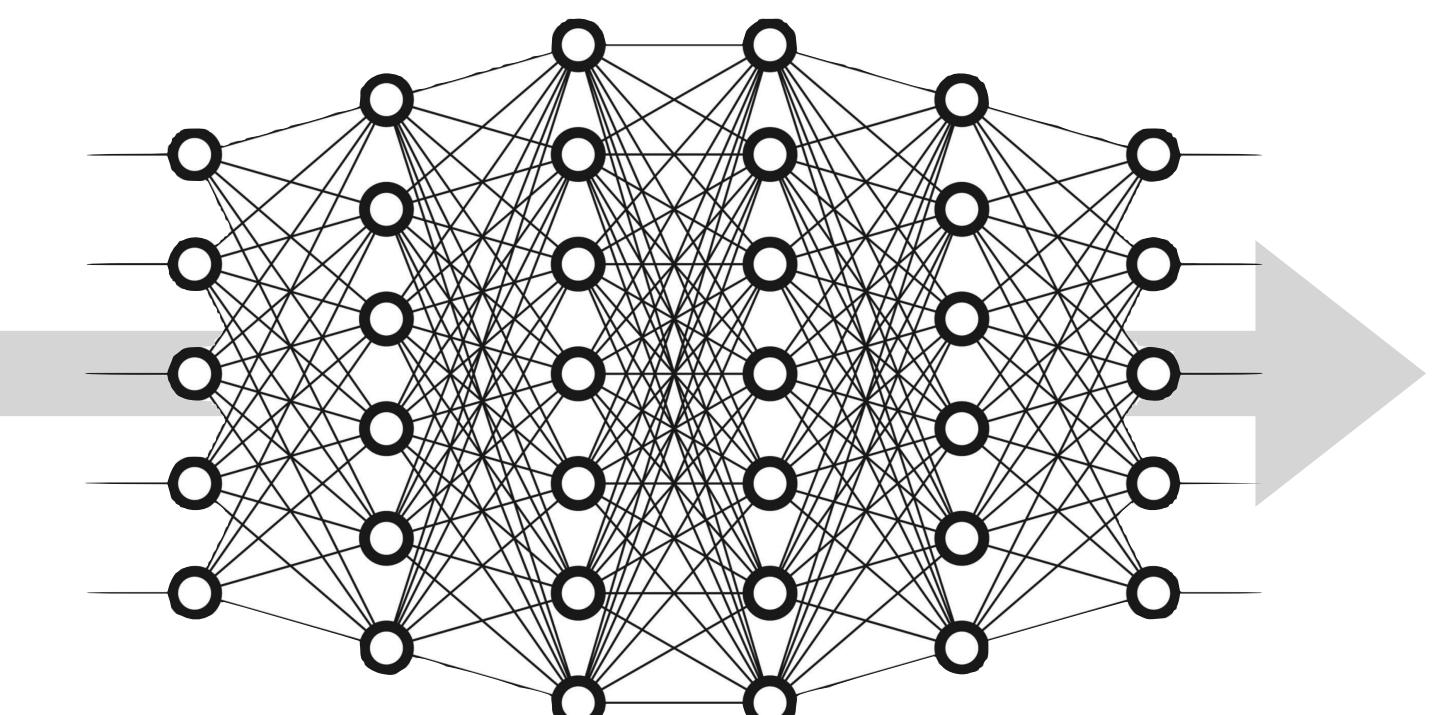
# Our approach: neural network energy models

Learn binding energy from crystal structures (data-driven)

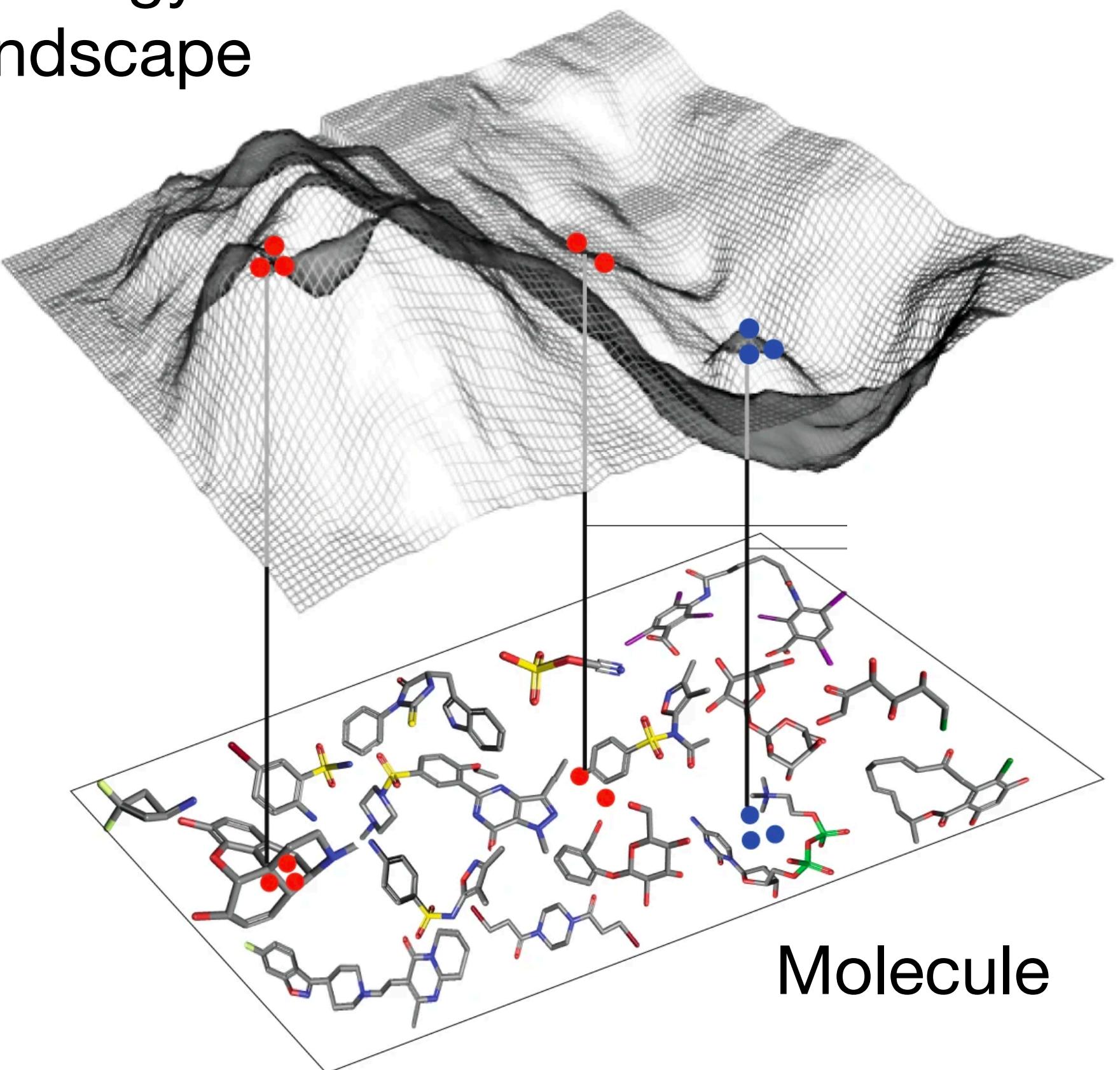


Protein-ligand 3D  
structures

**Energy-based  
Model (EBM)**



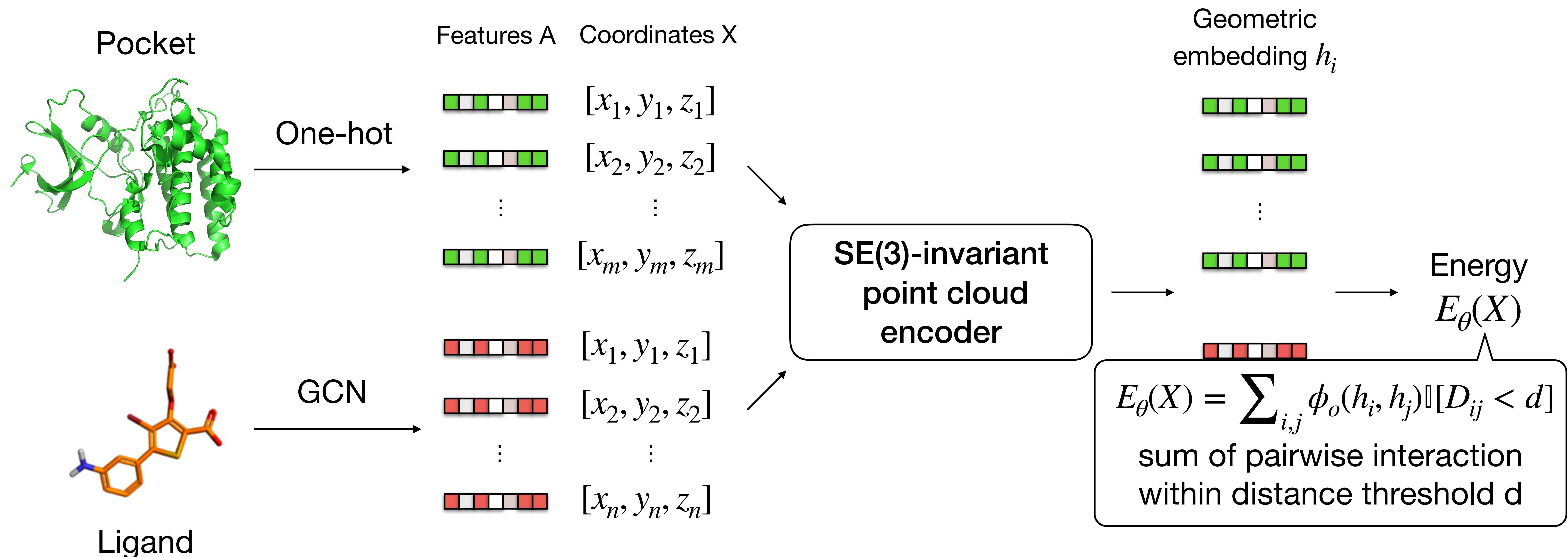
Energy  
landscape



Molecule

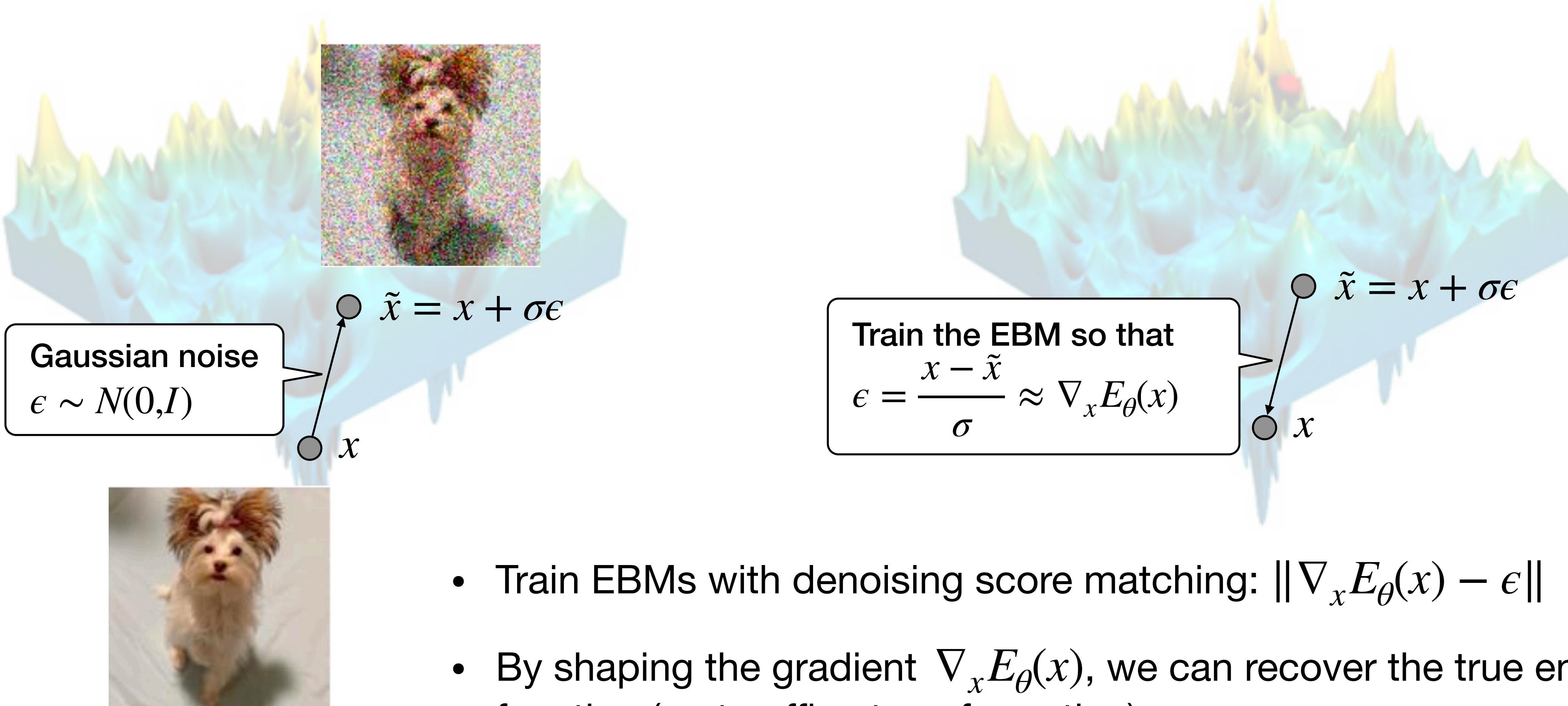
# EBM architecture for protein-ligand binding

Requirement:  $E(X)$  is SE(3)-invariant and differentiable w.r.t.  $X$



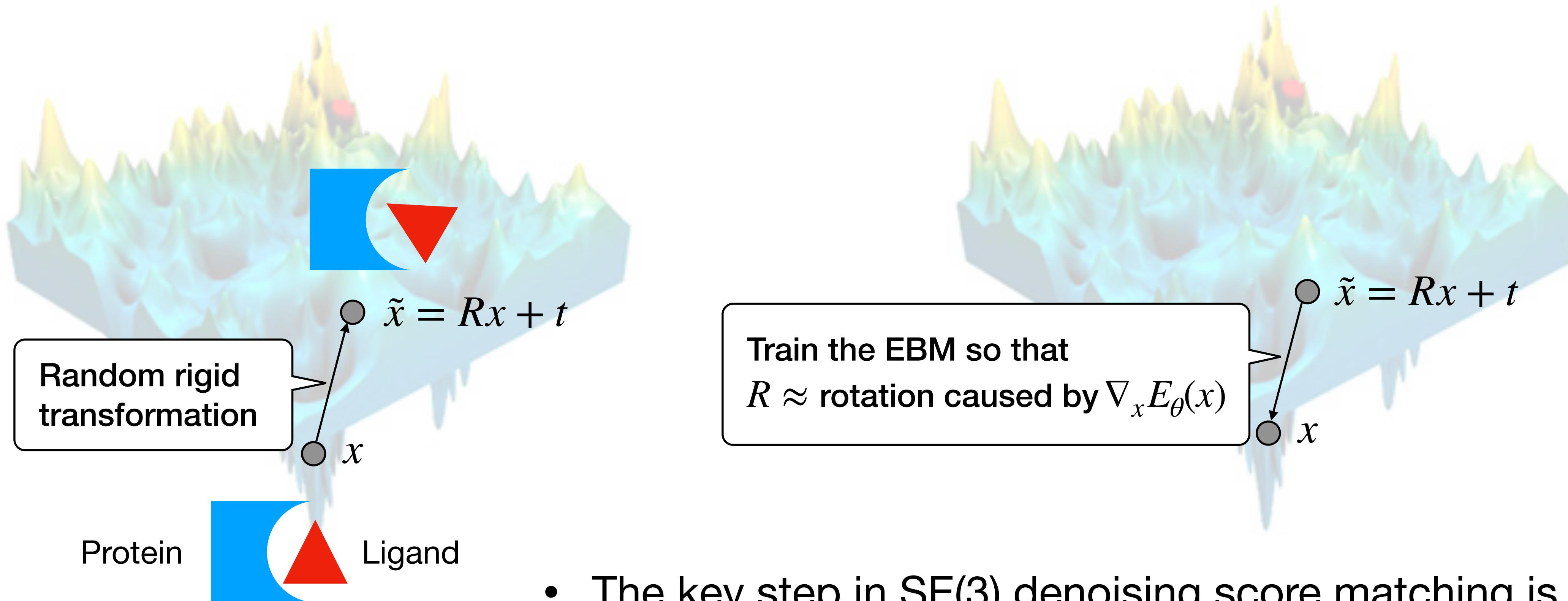
# Training EBMs with denoising score matching

Standard approach: Gaussian noise



# Training EBMs with denoising score matching

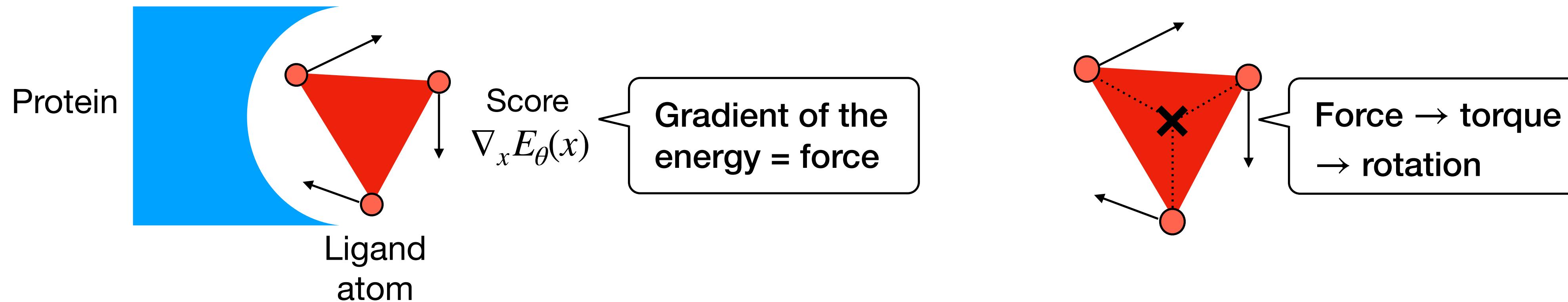
For molecules, we should use rigid transformation noises



- The key step in SE(3) denoising score matching is to infer the rotation induced by the score  $\nabla_x E_\theta(x)$

# Euler's rotation equation

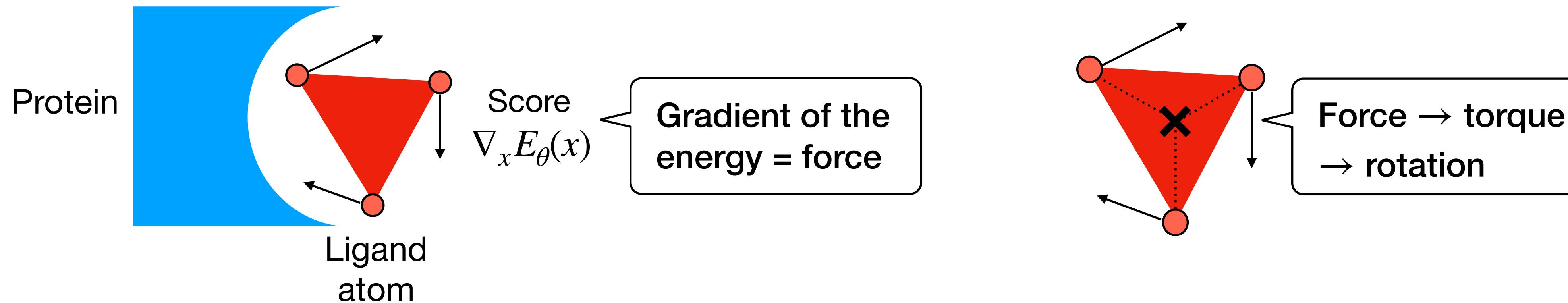
Infer rotation  $R$  from gradient  $\nabla_x E_\theta(x)$  (force)



- The torque applied to the ligand  $\tau = \sum_i (x_i - \mu) \times \nabla_{x_i} E_\theta(x)$
- (**Euler's rotation equation**) Angular acceleration of the ligand  $\alpha = I^{-1}\tau$ , where  $I$  is the inertia matrix
- Angular velocity  $\omega = I^{-1}\tau\Delta t$  for an infinitesimal time  $\Delta t$
- Rotation matrix  $R$  is the exponential of the following matrix  $W(\omega) = \begin{pmatrix} 0 & -\omega_z & \omega_y \\ \omega_z & 0 & -\omega_x \\ -\omega_y & \omega_x & 0 \end{pmatrix}$

# Euler's rotation equation

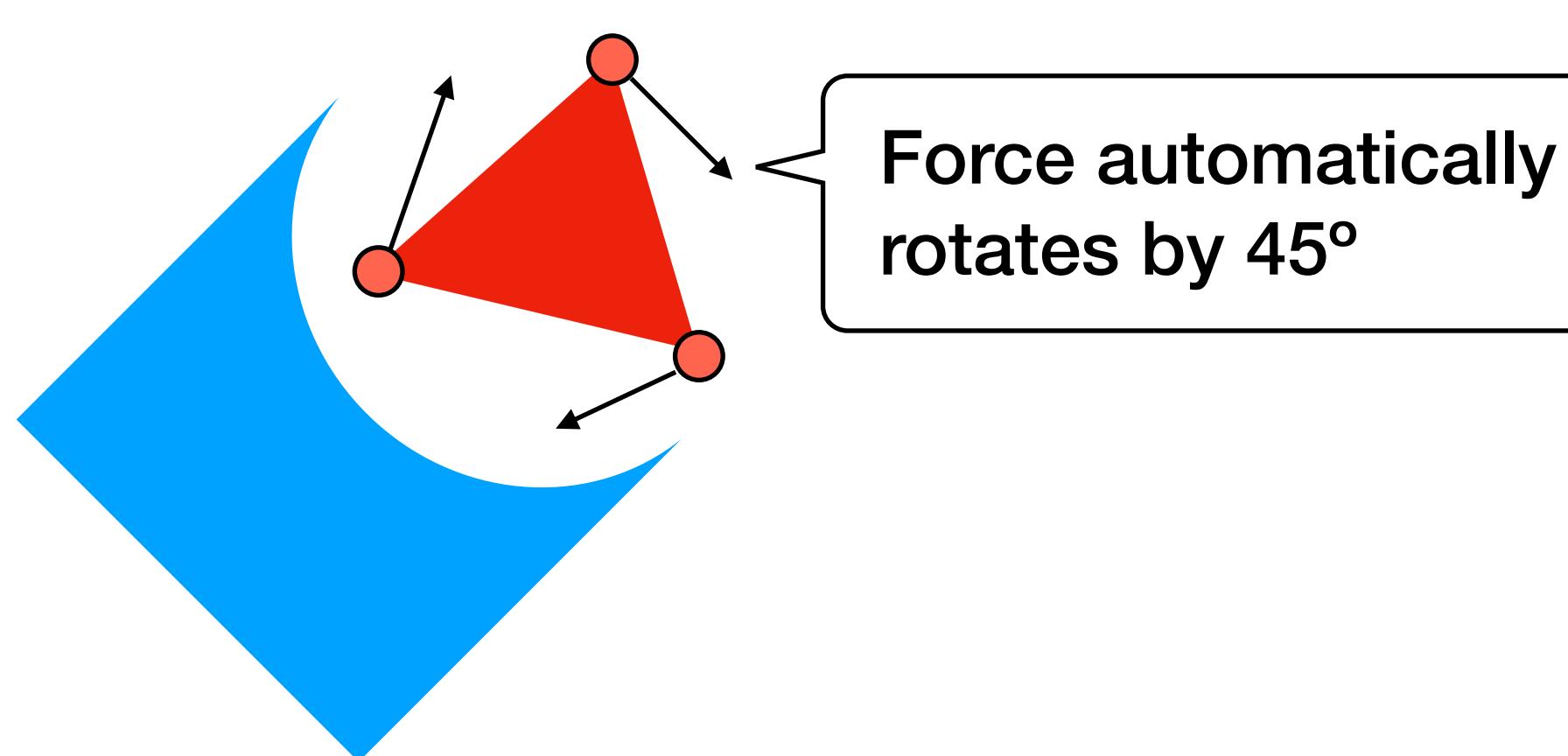
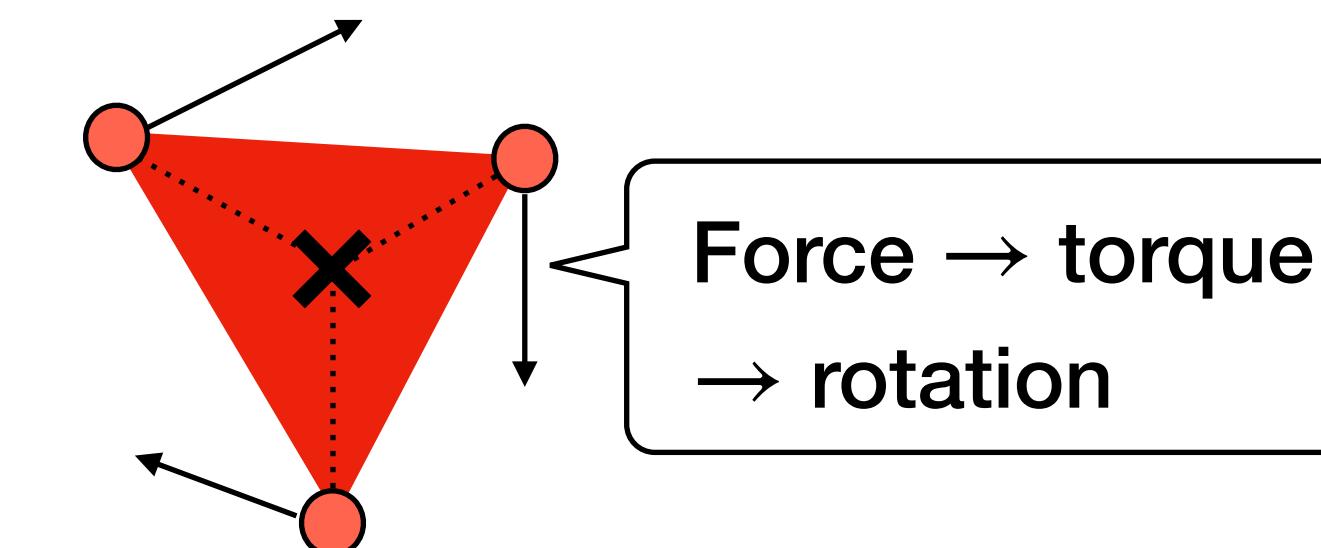
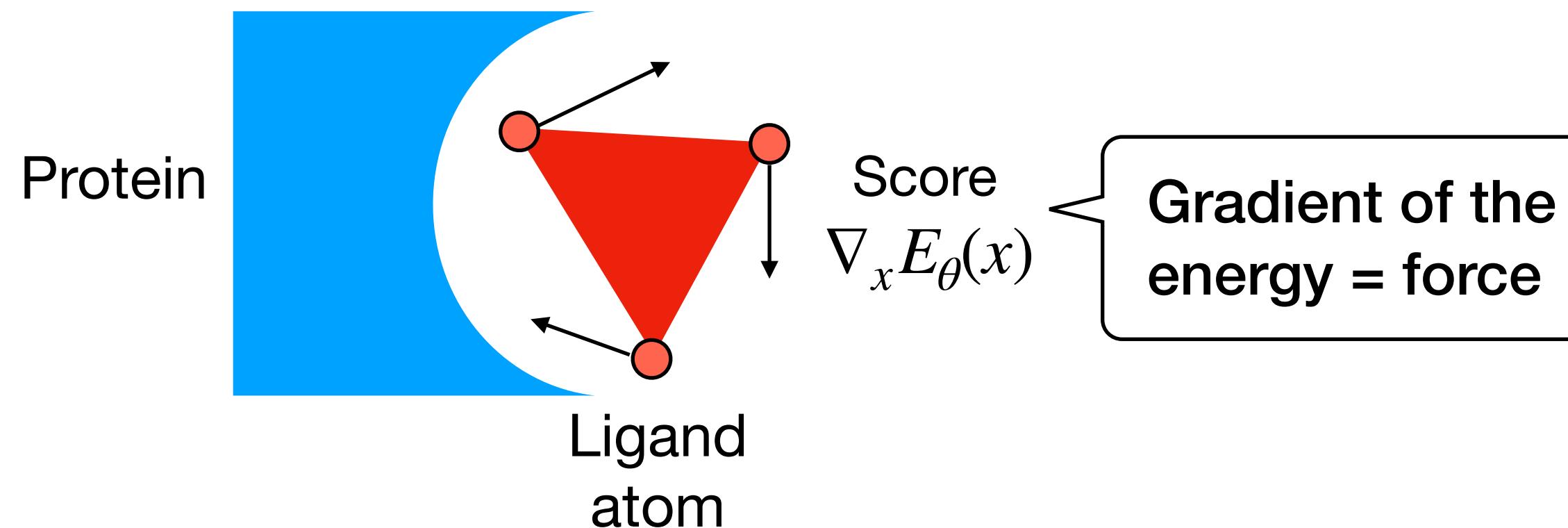
Infer rotation  $R$  from gradient  $\nabla_x E_\theta(x)$  (force)



- The good news is that  $W(\omega)$  is a skew symmetric matrix and its exponential has a closed form
- The rotation operation can be further simplified to  $Rx = e^{W(\omega)}x = x + c_1\omega \times x + c_2\omega \times (\omega \times x)$ , where  $c_1 = \sin \|\omega\|/\|\omega\|$  and  $c_2 = (1 - \cos \|\omega\|)/\|\omega\|^2$
- The above rotation formula only requires vector cross product, which is very efficient.

# Euler's rotation equation as a rotation layer

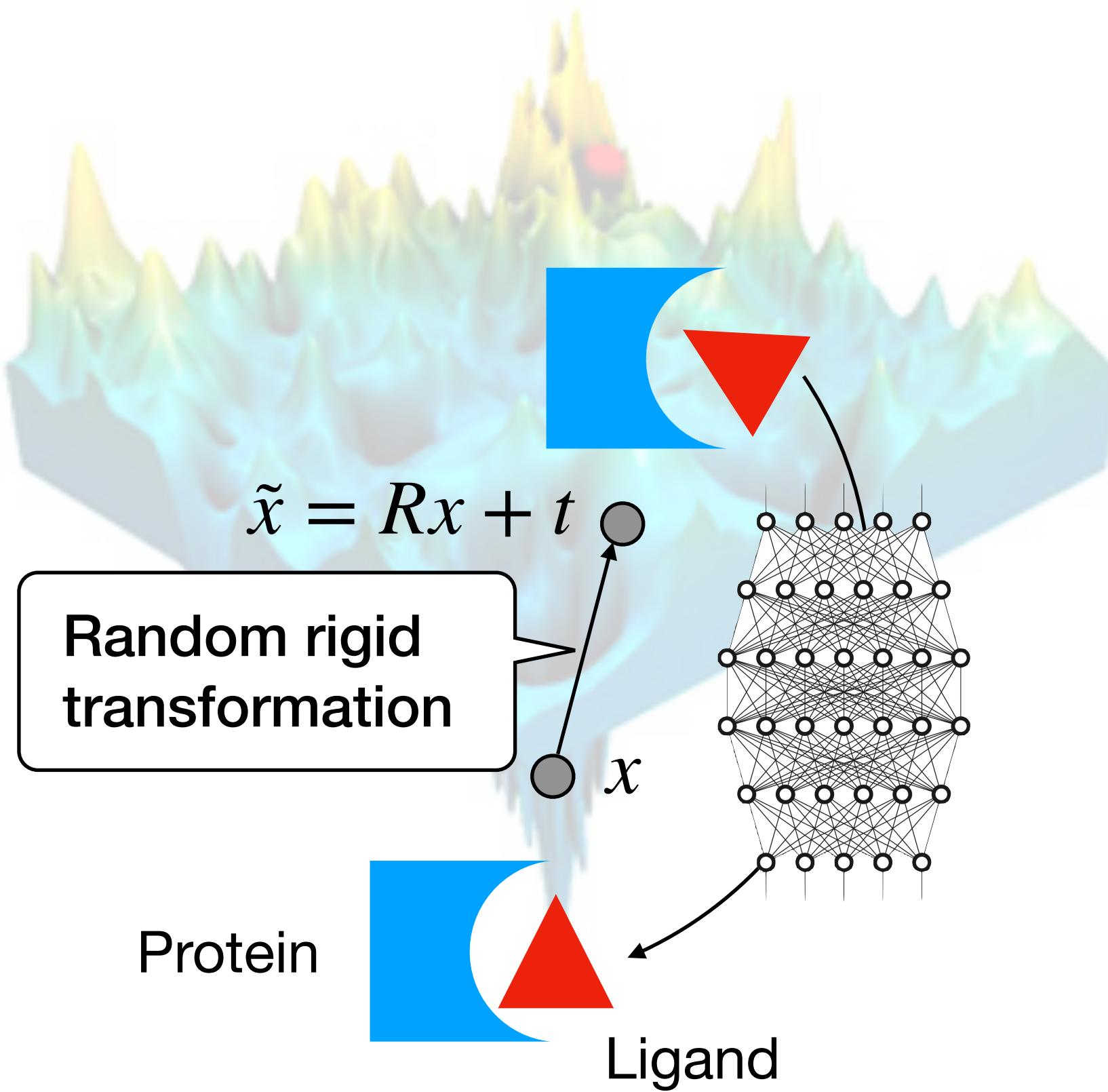
A simple, yet equivariant way to predict rotations



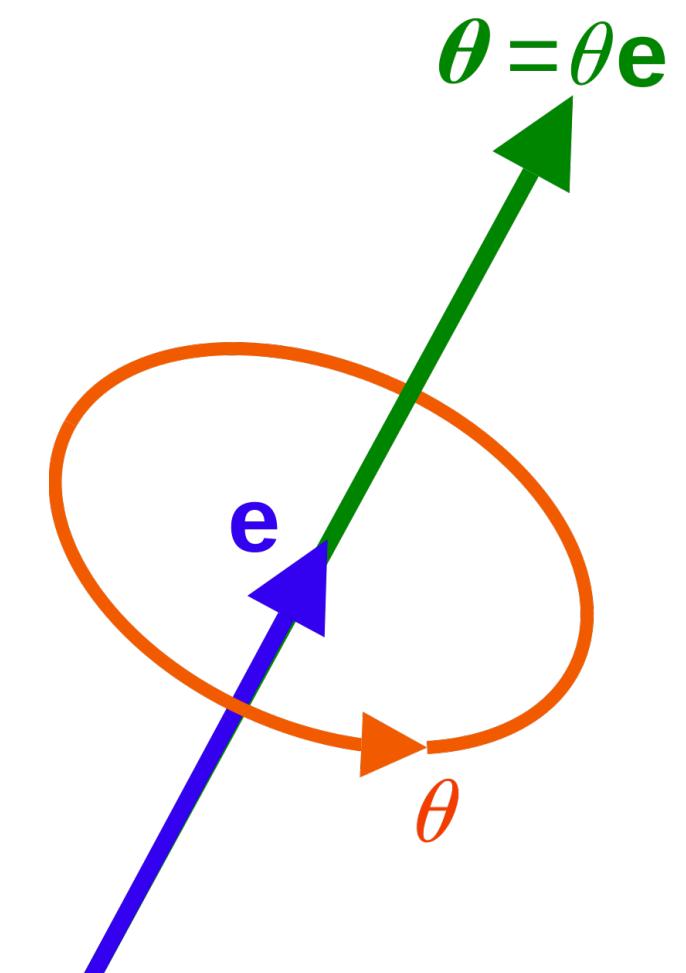
- If we rotate a complex by  $Q$ , we have:
- Torque  $\tau_Q = \sum_i (Qx_i - Q\mu) \times Q \nabla_{x_i} E_\theta(x) = Q\tau$
- Inertia matrix  $I_Q = QIQ^{-1}$
- Angular velocity  $\omega_Q = I_Q^{-1} \tau_Q \Delta t = Q\omega$
- Rotation matrix  $R_Q = QR$

# SE(3) denoising score matching

## Training procedure



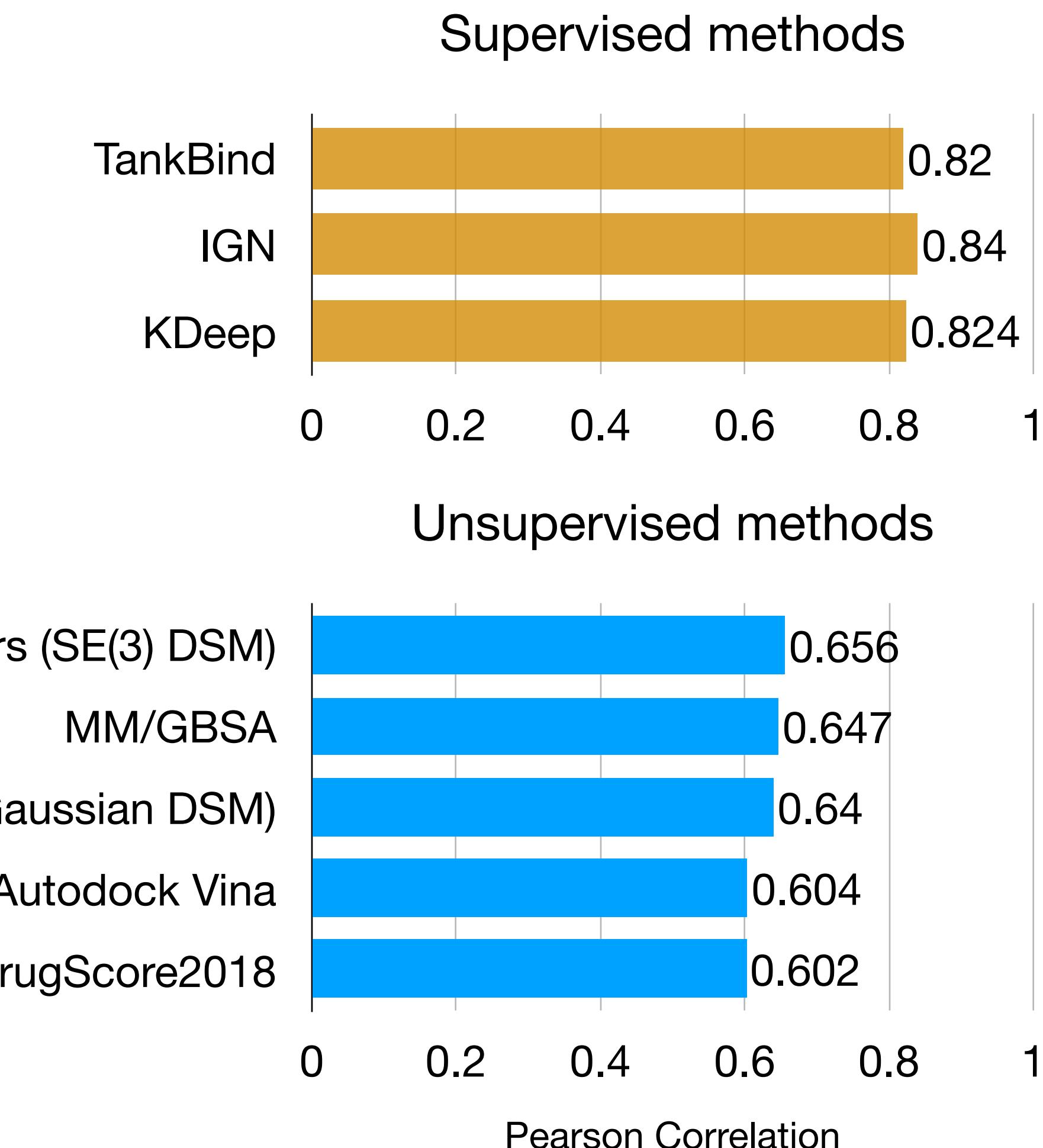
- Step 1: Sample rotation from SO(3) Gaussian distribution  $\mathcal{N}_{SO(3)}$ 
  - Sample a random direction  $e$  from unit sphere
  - Sample an angle  $\theta$  with density  $f(\theta)$  (Isotropic Gaussian)
  - The score of  $\mathcal{N}_{SO(3)}$  is  $\nabla_\theta \log f(\theta) \cdot e$
- Step 2: Calculate the energy  $E_\theta(x)$  and its score  $\nabla_x E_\theta(x)$  (force)
  - Calculate the torque  $\tau$
  - Infer angular velocity  $\omega = I^{-1} \tau \Delta t$
- Step 3: Compute SE(3) DSM Loss
  - $\|\omega - \nabla_\theta \log f(\theta) \cdot e\|$



# Results: protein-ligand binding

## Log-likelihood is strongly correlated with binding affinity

- Training set: 5237 protein-ligand complexes in PDBBind refined set (without using binding affinity data)
- Test set: 285 complexes from CASF challenge evaluation set [1]. Measure the Pearson correlation between predicted and true affinity
- Supervised models are trained on ~18000 binding affinity data in PDBBind
- SE(3) DSM outperforms Gaussian noise DSM and other unsupervised models



# Results: antibody-antigen binding

## Supervised models suffer from lack of binding affinity data

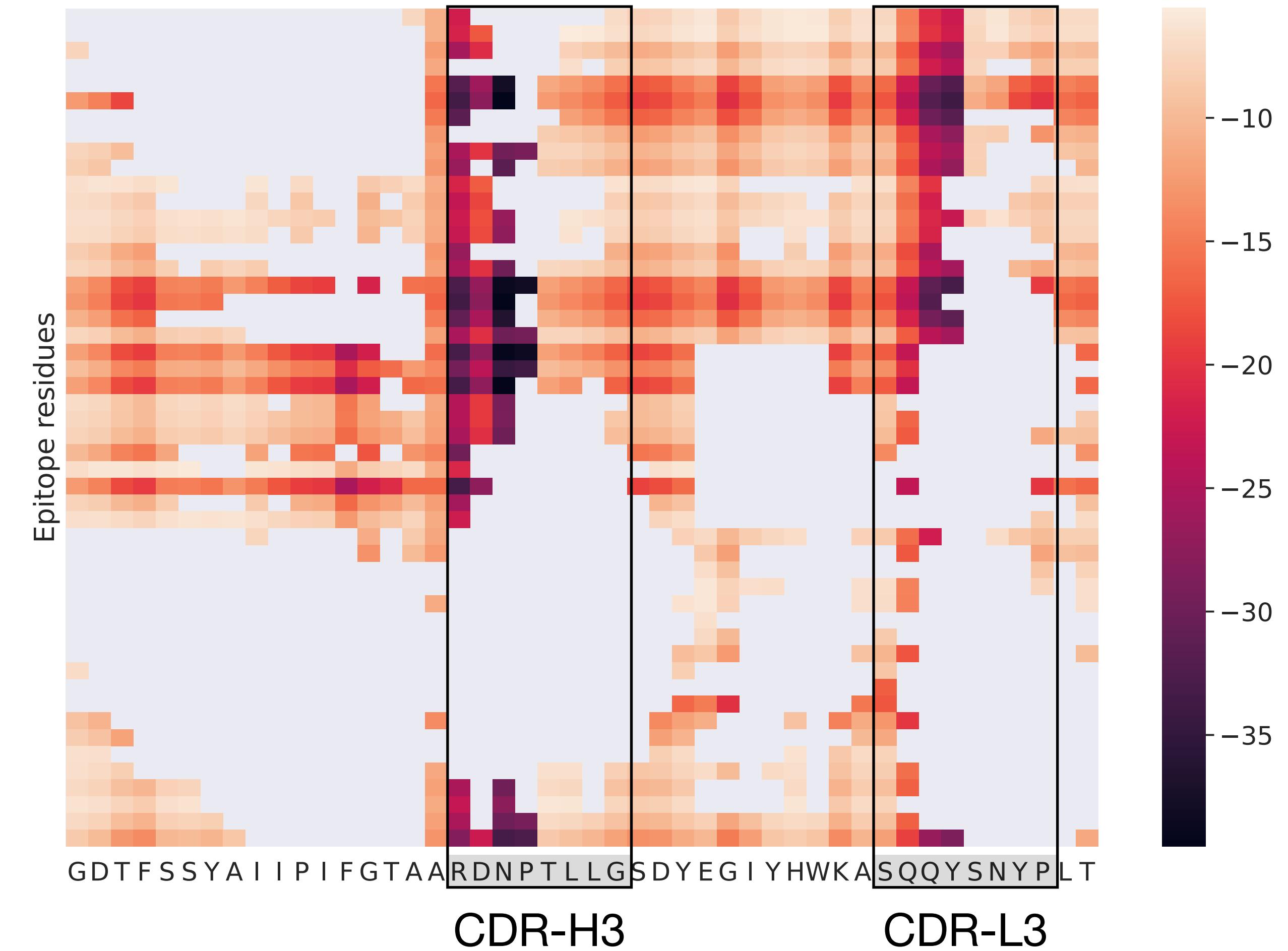
- Training set: 3416 complexes from Structure Antibody Database (SAbDab).
- Test set: 566 complexes from SAbDab that have binding affinity labels
- We compare with several biophysical potentials (unsupervised), and a supervised neural network trained on only 100 binding affinity data points
- We outperform supervised baseline because we can leverage more unlabeled antibody-antigen complexes

	Crystal
ZRANK	0.318
ZRANK2	0.176
RosettaDOCK	0.064
PYDOCK	0.248
SIPPER	-0.138
AP_PISA	0.323
FIREDOCK	0.101
FIREDOCK_AB	0.199
CP_PIE	0.234
NERE (ours)	<b>0.340</b> .029
- standard DSM	0.335.038
Supervised NN	0.295.098

# Visualization: binding energy attention

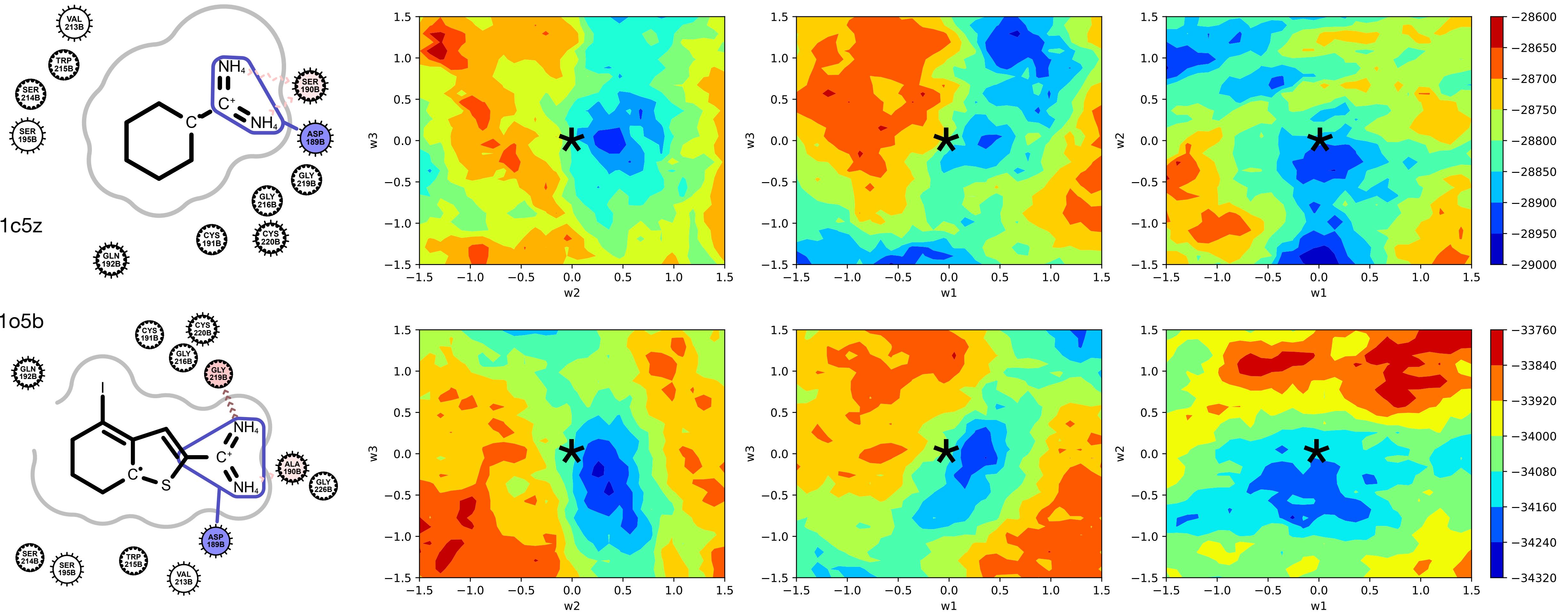
What residues contribute the most?

- $E_\theta(x) = \sum_{i,j} \phi_o(h_i, h_j) \mathbb{I}[D_{ij} < d]$
- $\phi_o(h_i, h_j)$  is the binding energy between two residues
- We plot  $\phi_o(h_i, h_j)$  for all pairs within the distance threshold  $d$
- Interestingly, the model pays the most attention to CDR-H3 and CDR-L3 residues, which are most critical to binding.



# Visualization: binding energy landscape

How binding energy changes with respect to ligand orientation?



# Conclusion & acknowledgements

## Towards unsupervised models for protein-ligand binding

### Main contribution

1. Formulate binding affinity prediction as a generative modeling problem
  - Train the generative model using SE(3) denoising score matching (DSM)
2. Propose a **simple & equivariant** rotation prediction module for SE(3) DSM
  - Embed Euler's rotation equation into neural networks (adding physical prior)

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