

Introduction to Machine Learning

Linear Regression

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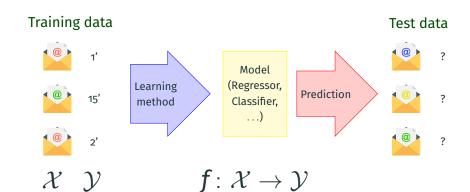
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Credit: Slides based on the IML Lectures by Sebastian Tschiatschek and Andreas Krause

Summary so far

- · Two basic forms of learning:
 - Supervised vs. Unsupervised learning
- Key challenge in ML:
 - · Trading goodness of fit and model complexity
- Representation of data is of key importance

Supervised Learning Pipeline



Representation

Model fitting

Prediction and Generalization

Regression

- · Instance of supervised learning
- Goal: Predict real valued labels (possibly vectors)
- · Examples:

```
\mathcal{X} \mathcal{Y} Flight routes delay (minutes)
```

Real estate objects price

Patient & drug treatment effectiveness

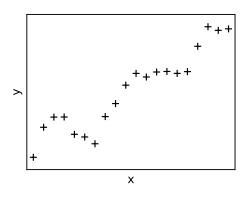
. . .

More concrete real-world example: Diabetes

[Efron et al '04]

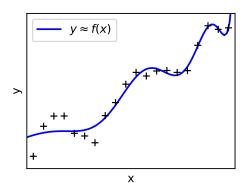
- Features \mathcal{X} :
 - Age
 - Sex
 - · Body mass index
 - Average blood pressure
 - Six blood serum measurements (S1-S6)
- Label (target) \mathcal{Y} :
 - · Quantitative measure of disease progression

Regression



• Goal: learn real valued mapping $f\colon \mathbb{R}^d o \mathbb{R}$

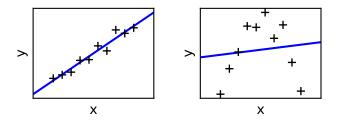
Regression



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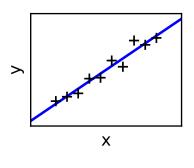
Important choices in regression

1 What types of functions *f* should we consider? Examples:



2 How should we measure goodness of fit?

Example: Linear Regression



Goal: $y \approx f(x)$

Linear functions:

- 1-dim: f(x) = ax + b
- 2-dim: $f(x_1, x_2) = ax_1 + bx_2 + c$
- . . .
- d-dim: $f(\mathbf{x}) = w_1 x_1 + w_2 x_2 + \cdots + w_d x_d + w_0 = \mathbf{w}^T \mathbf{x} + w_0$

Homogeneous Representation

Goal: Simplify $\mathbf{w}^T \mathbf{x} + w_0$ by removing the term w_0 Idea: Augment input data \mathbf{x} by adding a component $x_0 = 1$

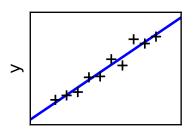
$$\mathbf{w}^{T}\mathbf{x} + w_{o} = \widetilde{\mathbf{w}}^{T}\widetilde{\mathbf{x}}$$

$$\mathbf{x} = (x_{1}, \dots, x_{d})^{T} \qquad \widetilde{\mathbf{x}} = (1, x_{1}, \dots, x_{d})^{T}$$

$$\mathbf{w} = (w_{1}, \dots, w_{d})^{T} \qquad \widetilde{\mathbf{w}} = (w_{o}, w_{1}, \dots, w_{d})^{T}$$

Quantifying goodness of fit

$$\mathcal{D} = \{(\boldsymbol{x}_1, y_1), \dots, (\boldsymbol{x}_n, y_n)\} \qquad \boldsymbol{x}_i \in \mathbb{R}^d, y_i \in \mathbb{R}$$



Χ

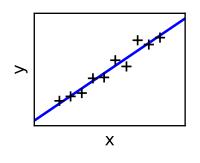
$$\mathbf{x}_i \in \mathbb{R}^d, y_i \in \mathbb{R}$$

Error at point i: $r_i = y_i - \mathbf{w}^\mathsf{T} \mathbf{x}_i$

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Error at point *i*: $r_i = y_i - \mathbf{w}^\mathsf{T} \mathbf{x}_i$

- Measure squared error per data point: $(y_i \mathbf{w}^T \mathbf{x}_i)^2$
- Sum of errors

$$\hat{R}(\mathbf{w}) = \sum_{i=1}^{n} (y_i - \mathbf{w}^\mathsf{T} \mathbf{x}_i)^2$$

Least-squares linear regression optimization

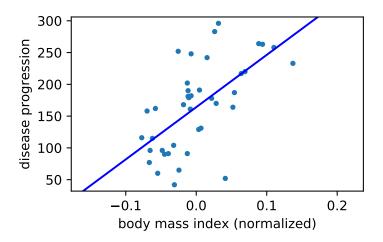
[Legendre 1805, Gauss 1809]

- Given a dataset $\mathcal{D} = \{(\boldsymbol{x}_1, y_1), \dots, (\boldsymbol{x}_n, y_n)\} \dots$
- ... how do we find the optimal weight vector?

$$\hat{\mathbf{w}} = \arg\min_{\mathbf{w}} \sum_{i=1}^{n} (y_i - \mathbf{w}^T \mathbf{x}_i)^2$$

How to solve? Example: Scikit Learn

```
# Create linear regression object
regr = linear_model.LinearRegression()
# Train the model using the training set
regr.fit(X_train, Y_train)
# Make predictions on the testing set
Y_pred = regr.predict(X_test)
```



Method 1: Closed form solution

- Setting: $\mathcal{D} = \{(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_n, y_n)\}$ $\mathbf{x}_i \in \mathbb{R}^d, y_i \in \mathbb{R}$
- The problem

$$\hat{\mathbf{w}} = \arg\min_{\mathbf{w}} \sum_{i=1}^{n} (y_i - \mathbf{w}^T \mathbf{x}_i)^2$$

can be solved in closed form:

$$\hat{\mathbf{w}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y},$$

where:

$$\mathbf{X} = \begin{pmatrix} \mathbf{x}_1^T \\ \mathbf{x}_2^T \\ \vdots \\ \mathbf{x}_n^T \end{pmatrix} = \begin{pmatrix} x_{1,1} & x_{1,2} & \dots & x_{1,d} \\ x_{2,1} & x_{2,2} & \dots & x_{2,d} \\ \vdots & \vdots & \ddots & \vdots \\ x_{n,1} & x_{n,2} & \dots & x_{n,d} \end{pmatrix} \qquad \mathbf{y} = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}$$

Method 1: Closed form solution - Derivation

How to derive the closed form solution?

$$\hat{\mathbf{w}} = \arg\min_{\mathbf{w}} \sum_{i=1}^{n} (y_i - \mathbf{w}^T \mathbf{x}_i)^2 = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

$$\hat{R}(\mathbf{w}) = \sum_{i=1}^{n} (y_i - \mathbf{w}^T \mathbf{x}_i)^2$$

$$= \sum_{i=1}^{n} (\mathbf{y} - \mathbf{X} \mathbf{w})_i^2 = (\mathbf{y} - \mathbf{X} \mathbf{w})^T (\mathbf{y} - \mathbf{X} \mathbf{w})$$

$$= \mathbf{y}^T \mathbf{y} - 2\mathbf{y}^T \mathbf{X} \mathbf{w} + \mathbf{w}^T \mathbf{X}^T \mathbf{X} \mathbf{w}$$

$$\nabla_{\mathbf{w}} \hat{R}(\mathbf{w}) = \mathbf{0} - 2\mathbf{X}^T \mathbf{y} + 2\mathbf{X}^T \mathbf{X} \mathbf{w}$$

$$\nabla_{\mathbf{w}} \hat{R}(\mathbf{w}) = \mathbf{0} \iff \mathbf{X}^T \mathbf{X} \mathbf{w} = \mathbf{X}^T \mathbf{y}$$

$$\implies \hat{\mathbf{w}} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

Method 2: Optimization

The objective function

$$\hat{R}(\mathbf{w}) = \sum_{i=1}^{n} (y_i - \mathbf{w}^\mathsf{T} \mathbf{x}_i)^2$$

is convex!

• A function $f: \mathbb{R}^d \to \mathbb{R}$ is convex iff $\forall \mathbf{x}, \mathbf{x}' \in \mathbb{R}^d, \lambda \in [0, 1]$, it holds that

$$f(\lambda \mathbf{x} + (1 - \lambda)\mathbf{x}') \le \lambda f(\mathbf{x}) + (1 - \lambda)f(\mathbf{x}').$$

Gradient Descent

Gradient Descent

- Start at an arbitrary $\mathbf{w}_0 \in \mathbb{R}^d$
- For t = 0, 1, 2, ..., do

•
$$\mathbf{w}_{t+1} = \mathbf{w}_t - \eta_t \nabla \hat{R}(\mathbf{w_t})$$

• Hereby, η_t is called learning rate or step rate

Convergence of gradient descent

- Under mild assumptions, if step size sufficiently small, gradient descent converges to a stationary point (gradient = 0)
- For convex objectives, it therefore finds the optimal solution!
- In the case of the squared loss, linear convergence for properly chosen constant stepsize.

Computing the gradient

$$\nabla \hat{R}(\boldsymbol{w}) = \left[\frac{\partial}{\partial w_1} \hat{R}(\boldsymbol{w}), \frac{\partial}{\partial w_2} \hat{R}(\boldsymbol{w}), \dots, \frac{\partial}{\partial w_d} \hat{R}(\boldsymbol{w}) \right]$$

1-dim:
$$\nabla \hat{R}(w) = \frac{\partial}{\partial w} \hat{R}(w) = \frac{\partial}{\partial w} \sum_{i=1}^{n} (y_i - wx_i)^2$$

$$= \sum_{i=1}^{n} \frac{\partial}{\partial w} (y_i - wx_i)^2 \quad \text{e.g., via chain rule}$$

$$= \sum_{i=1}^{n} 2(\underbrace{y_i - wx_i}_{=r_i})(-x_i) = -2 \sum_{i=1}^{n} r_i x_i$$

$$d\text{-dim: } \nabla \hat{R}(w) = \dots = \sum_{i=1}^{n} 2(y_i - w^T x_i)(-x_i) = -2 \sum_{i=1}^{n} r_i x_i$$

Demo: Gradient descent

Choosing a stepsize

What happens if we choose a poor stepsize?

Adaptive step size

- Can update the step size adaptively. For example:
 - (a) Via line search (optimizing step size every step):

```
Suppose that at iteration t, we have \mathbf{w}_t, \mathbf{g}_t = \nabla \hat{R}(\mathbf{w}_t) Define: \eta_t^* = \arg\min_{\eta \in [0,\infty]} \hat{R}(\mathbf{w}_t - \eta \mathbf{g}_t)
```

- (b) "Bold driver" heuristic:
 - Initial learning rate η_0 .
 - If function decreases, increase step size:

If
$$\hat{R}(\mathbf{w}_{t+1}) < \hat{R}(\mathbf{w}_t)$$
 then $\eta_{t+1} = \eta_t c_+$ with $c_+ > 1$.

· If function increases, decrease step size:

If
$$\hat{R}(\mathbf{w}_{t+1}) > \hat{R}(\mathbf{w}_t)$$
 then $\eta_{t+1} = \eta_t c_-$ with $c_- < 1$.

Demo: Gradient Descent for Linear Regression

Why would one ever consider performing gradient descent, when it is possible to find closed form solution?

Closed form:

$$\hat{\boldsymbol{w}} = (\boldsymbol{X}^T\boldsymbol{X})^{-1}\boldsymbol{X}^T\boldsymbol{y}$$

Gradient descent:

$$\nabla \hat{R}(\mathbf{w}) = \sum_{i=1}^{n} (y_i - \mathbf{w}^T \mathbf{x}_i) \mathbf{x}_i$$

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Computational complexity

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- · Computational complexity
- · May not need an optimal solution

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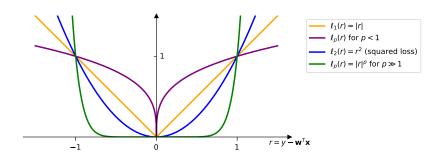
Gradient descent:

$$\nabla \hat{R}(\mathbf{w}) = \sum_{i=1}^{n} (y_i - \mathbf{w}^T \mathbf{x}_i) \mathbf{x}_i$$

- · Computational complexity
- · May not need an optimal solution
- · Many problems don't admit closed form solution

Other Loss Functions

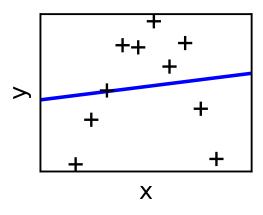
- So far: Measure goodness of fit via squared error
- Many other loss functions possible (and sensible!)



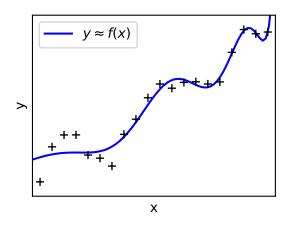
Supervised learning summary so far

Representation/ features	Linear hypotheses
Model/ objective	Loss-function (squared loss, ℓ_p loss)
Method	Exact solution, Gradient Descent
Evaluation metric	Empirical risk = (mean) squared error

Outlook: Fitting nonlinear functions



Outlook: Fitting nonlinear functions



Outlook: Linear regression for polynomials

We can fit non-linear functions via linear regression, using nonlinear features of our data (basis functions):

$$f(\mathbf{x}) = \sum_{i=1}^{D} w_i \phi_i(\mathbf{x})$$