

In [1]:

```
%matplotlib inline
```

In [78]:

```
import numpy as np
import matplotlib.pyplot as plt

class Solow_Swan():

    def __init__(self, n=0.02, # population growth rate
                  s=0.20, # savings rate
                  δ=0.10, # depreciation rate
                  α=0.36, # share of labor
                  z=1.00, # technology constant
                  k=0.01): # initial capital stock

        self.n, self.s, self.δ, self.α, self.z = n, s, δ, α, z
        self.k = k

    def steady_state(self):
        # Unpack parameters
        n, s, δ, α, z = self.n, self.s, self.δ, self.α, self.z
        # Compute and return steady-state level of capital per worker, output per worker, and
        capital_per_output
        capital_per_worker_steady_state = ((s * z) / (δ + n))**(1 / (1 - α))
        output_per_worker_steady_state = (z * (s / (δ + n))**α)**(1 / (1 - α))
        capital_per_output_steady_state = α / (δ + n)
        return capital_per_worker_steady_state, output_per_worker_steady_state,
        capital_per_output_steady_state

    def random_process(self, t):
        # Generate and return random process of length t
        process = np.zeros(t)
        for i in range(t):
            process[i] = np.random.randn()
        return process

    def log_deviation_coefficients(self):
        # Unpack parameters
        n, δ, α = self.n, self.δ, self.α
        # Compute and return coefficients ρ1 and ρ2
        ρ1 = (1 + α * n - δ * (1 - α)) / (1 + n)
        ρ2 = (δ + n) / (1 + n)
        return ρ1, ρ2

    def output_per_worker(self, random_process):
        # Unpack parameters
        α, z, k = self.α, self.z, self.k
        # Generate random process of length t for level of technology
        technology_process = z * np.exp(random_process)
        # Generate and return output per worker
        return technology_process * k**α

    def capital_per_worker(self, random_process):
        # Unpack parameters
        n, s, δ, α, z = self.n, self.s, self.δ, self.α, self.z
        # Update capital per worker
        return (s * self.output_per_worker(random_process) + (1 - δ) * self.k) / (1 + n)

    def capital_per_worker_update(self, random_process):
        # Update current state of capital per worker
        self.k = self.capital_per_worker(random_process)

    def capital_per_output(self, random_process):
        # Generate and return capital per output
        return self.capital_per_worker(random_process) / self.output_per_worker(random_process)

    def capital_per_worker_log_deviation(self, t, random_process):
        # Unpack parameter
        k = self.k
        # Unpack steady-state level of capital per worker
```

```

p1, p2 = self.log_deviation_coefficients()
# Generate addends for summation of log deviations of capital per worker from steady state
of length t
if t == 0:
    capital_per_worker_log_deviation_addend = np.log(k / capital_per_worker_steady_state)
else:
    capital_per_worker_log_deviation_addend = np.zeros(t)
    for i in range(t-1):
        capital_per_worker_log_deviation_addend[i] = p2 * p1**i * random_process[(t-1)-i]
# Generate and return log deviation of output per worker from steady state
capital_per_worker_log_deviation = np.sum(capital_per_worker_log_deviation_addend)
return capital_per_worker_log_deviation

def output_per_worker_log_deviation(self, t, random_process):
    #Unpack parameter
    alpha = self.alpha
    # Unpack coefficients p1 and p2
    p1, p2 = self.log_deviation_coefficients()
    # Generate and return log deviation of output per worker from steady state
    output_per_worker_log_deviation = random_process[t] + alpha *
self.capital_per_worker_log_deviation(t, random_process)
return output_per_worker_log_deviation

def sequence(self, t):
    # Unpack parameters
    n, s, delta, alpha, z = self.n, self.s, self.delta, self.alpha, self.z
    # Unpack coefficients p1 and p2
    p1, p2 = self.log_deviation_coefficients()
    # Generate time series of length t for capital per worker, output per worker, and capital
per worker
    capital_per_worker_path = np.zeros(t)
    output_per_worker_path = np.zeros(t)
    capital_per_output_path = np.zeros(t)
    # Generate time series of length t for log deviations of capital per worker and output per
worker from steady state
    capital_per_worker_log_deviation_path = np.zeros(t)
    output_per_worker_log_deviation_path = np.zeros(t)
    # Generate random process of length t for level of technology
    random_process = self.random_process(t)
    technology_process = z * np.exp(random_process)
    for i in range(t):
        # Compute current level of capital per output, output per worker, and capital per output
t
        capital_per_worker_path[i] = self.k
        output_per_worker_path[i] = self.output_per_worker(random_process[i])
        capital_per_output_path[i] = capital_per_worker_path[i] / output_per_worker_path[i]
        # Update current state of capital per worker
        self.capital_per_worker_update(random_process[i])
        # Compute current level of log deviations of capital per output, output per worker, and
capital per output from steady state
        capital_per_worker_log_deviation_path[i] = self.capital_per_worker_log_deviation(i, random_process)
        output_per_worker_log_deviation_path[i] = self.output_per_worker_log_deviation(i, random_process)
    return capital_per_worker_path, output_per_worker_path, capital_per_output_path, capital_per_worker_log_deviation_path, output_per_worker_log_deviation_path, random_process

```

In [79]:

```
solow = Solow_Swan()
```

In [98]:

```
t = 150
x = list(range(t))
```

In [99]:

```
solow.steady_state()
```

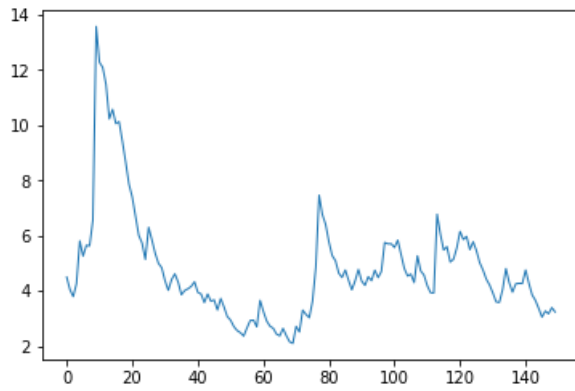
Out[99]:

In [100]:

```
k, y, ky, k_deviation, y_deviation, random_process = solow.sequence(t)
```

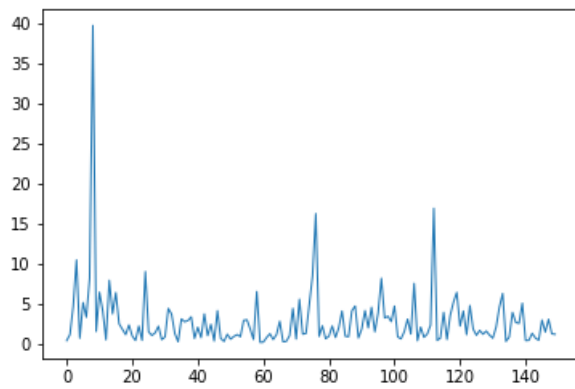
In [101]:

```
fig, ax = plt.subplots()
ax.plot(x, k, linewidth=1)
plt.show()
```



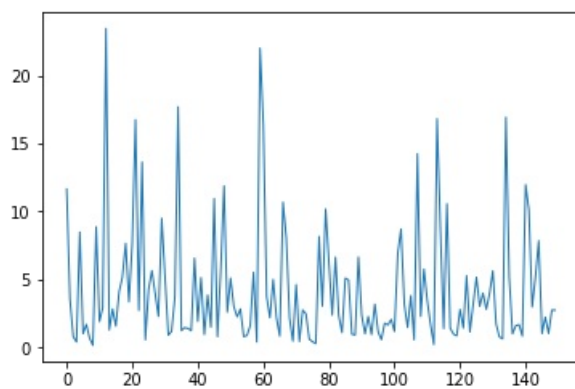
In [102]:

```
fig, ax = plt.subplots()
ax.plot(x, y, linewidth=1)
plt.show()
```



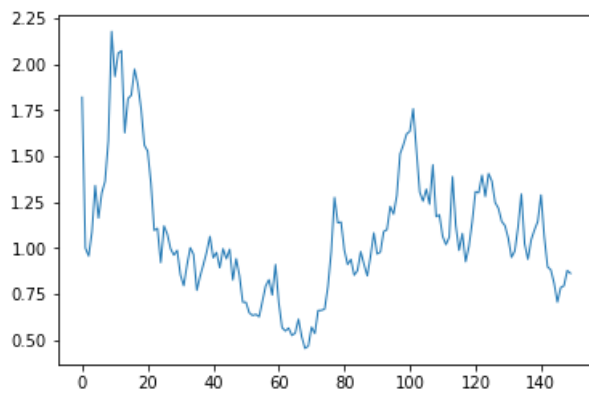
In [103]:

```
fig, ax = plt.subplots()
ax.plot(x, ky, linewidth=1)
plt.show()
```



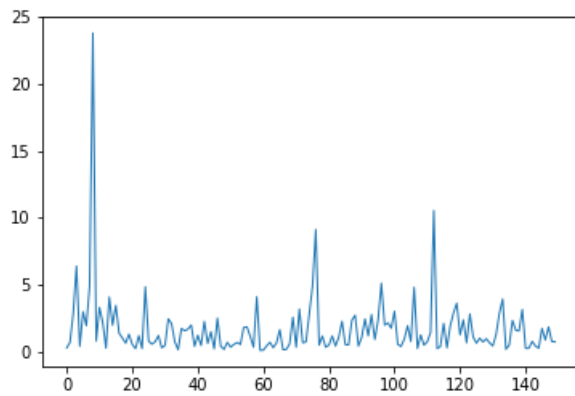
In [104]:

```
ax.plot(x, np.exp(x_deviation), linewidth=1)  
plt.show()
```



In [105]:

```
fig, ax = plt.subplots()  
ax.plot(x, np.exp(y_deviation), linewidth=1)  
plt.show()
```



In [106]:

```
fig, ax = plt.subplots()  
ax.plot(x, random_process, linewidth=1)  
plt.show()
```

