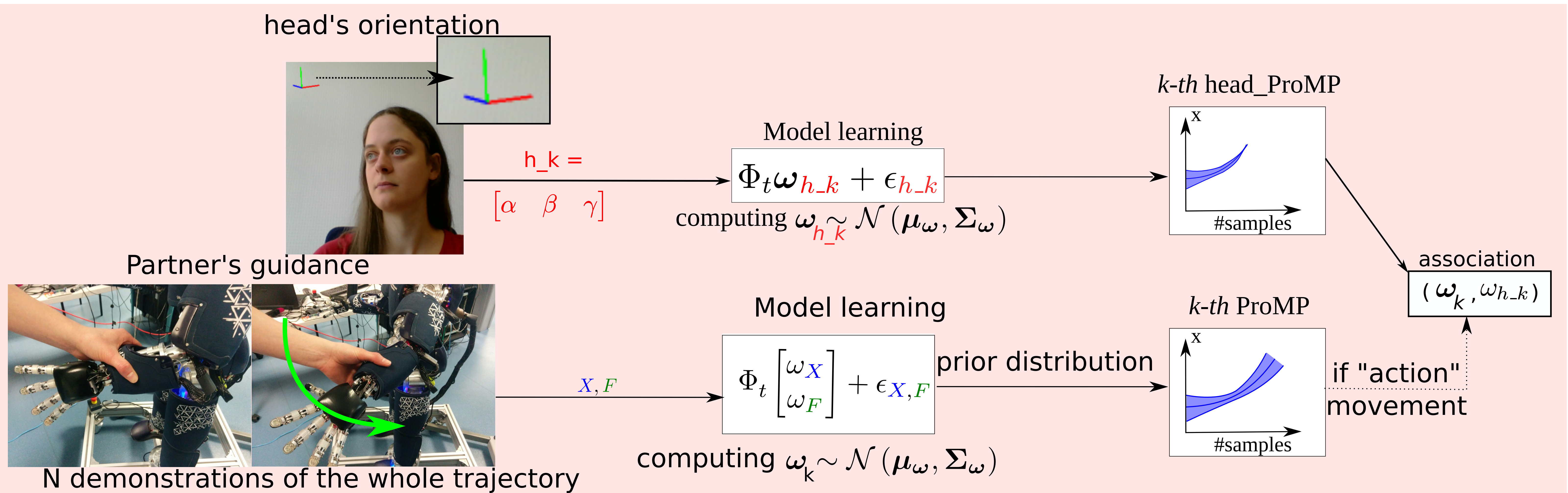
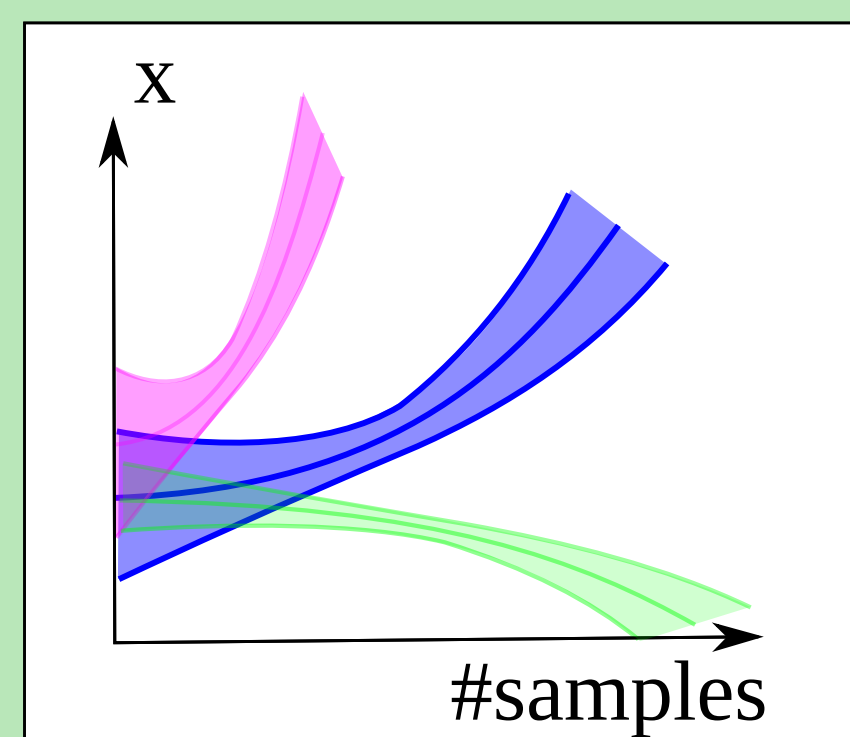


Training the k-th trajectory



Learned grasp: ProMPs



Learned action: ProMPs

