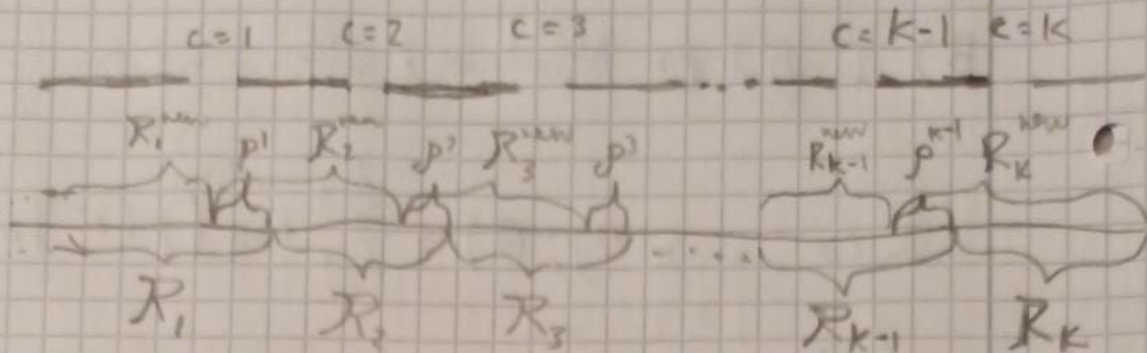


4



A)

$$P_{\text{correct}} = p(x \in R_1, c=1) + \dots + p(x \in R_k, c=k)$$

$$= \sum_{n=1}^k p(x \in R_n, c=n)$$

$$P_{\text{correct}} = \sum_{n=1}^k \int_{R_n} p(x, c=n) \cdot dx$$

$$= \left(\sum_{n=1}^{k-1} \int_{R_n} p(x, c=n) \cdot dx \right) + \int_{R_k} p(x, c=k) \cdot dx$$

When thinking about the optimal R_n^{opt} of each region R , except for regions R_1^{opt} & R_k^{opt} , where the optimal would be:

$$R_1^{\text{opt}} = \{ \vec{x} \mid p(c=1 | \vec{x}) > p(c=2 | \vec{x}) \}$$

$$R_k^{\text{opt}} = \{ \vec{x} \mid p(c=k | \vec{x}) > p(c=k-1 | \vec{x}) \}$$

For the rest of the intermediate regions R , the optimal

should be found not just between one region p , but

between two of them, therefore:
(their side neighbours)

for $R_j \in \{R_2, \dots, R_{k-1}\}$, and $P_j \in \{P_2, \dots, P_{k-1}\}$

$$R_j^{\text{opt}} = \left\{ \vec{x} \mid \left(\underset{P_{j-1}}{p(c=j-1|\vec{x})} < \underset{P_{j-1}}{p(c=j|\vec{x})} \right) \& \left(\underset{P_j}{p(c=j+1|\vec{x})} < \dots \right. \right. \\ \left. \left. \dots < \underset{P_j}{p(c=j|\vec{x})} \right) \right\}$$

B) A given ' R_k ' can be an empty set at some

' R_j ' defined before if the intermediate regions ' P_{j-1} ' & ' P_j ' are both including ~~the~~ all the available for optimality.