

# Adversarial Search

Chapter 5

# Outline

- ▣ Optimal decisions
- ▣ MiniMax
- ▣  $\alpha$ - $\beta$  pruning
- ▣ Imperfect, real-time decisions

# Games vs. search problems

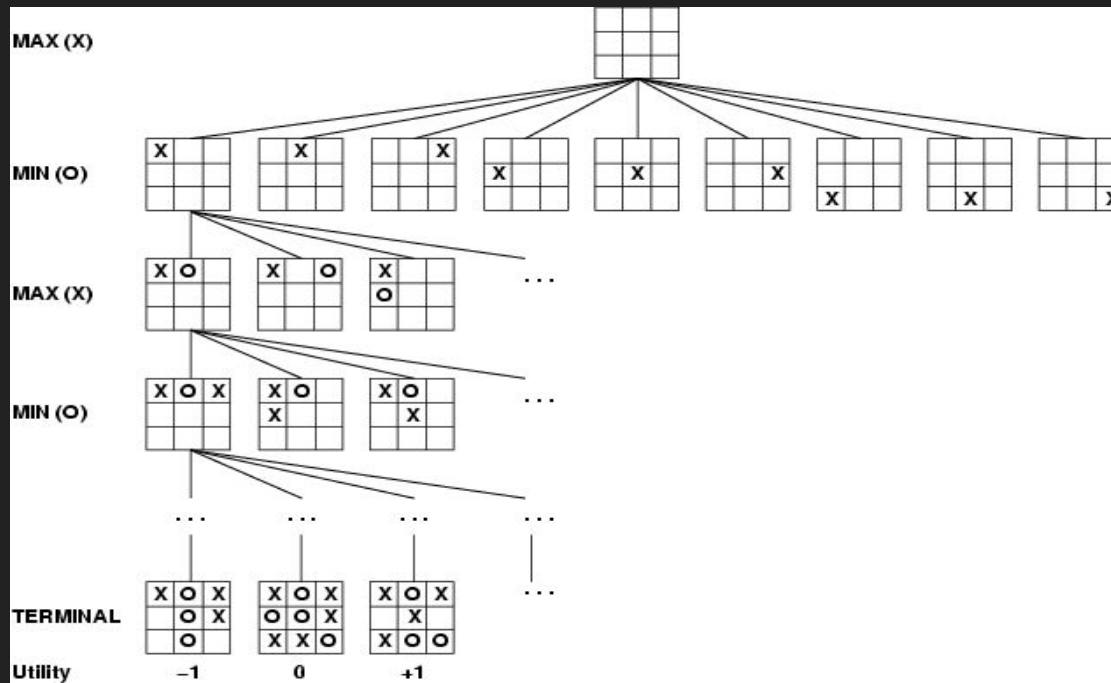
- "Unpredictable" opponent □ specifying a move for every possible opponent reply
- prisoner dilemma

A\B	betray	persist
betray	0\0	1\ -1
persist	\1	2\2

- Time limits ( $35^{100}$ ) □ unlikely to find goal, must approximate

# Game tree (2-player, deterministic, turns)

tic-tac-toe



# Minimax

- Perfect play for deterministic games
- Idea: choose move to position with highest **minimax value**  
= best achievable payoff against best play
- E.g., 2-ply game:

# Minimax algorithm

**function** MINIMAX-DECISION(*state*) *returns an action*

$v \leftarrow \text{MAX-VALUE}(\text{state})$

**return** the *action* in SUCCESSORS(*state*) with value *v*

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**function** MAX-VALUE(*state*) *returns a utility value*

**if** TERMINAL-TEST(*state*) **then return** UTILITY(*state*)

$v \leftarrow -\infty$

**for** *a, s* in SUCCESSORS(*state*) **do**

$v \leftarrow \text{MAX}(v, \text{MIN-VALUE}(s))$

**return** *v*

---

**function** MIN-VALUE(*state*) *returns a utility value*

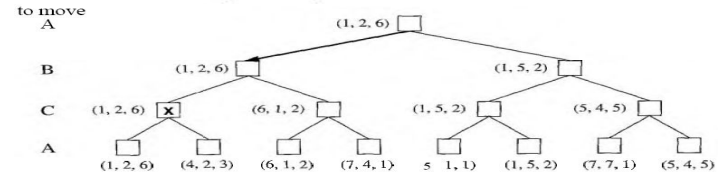
**if** TERMINAL-TEST(*state*) **then return** UTILITY(*state*)

$v \leftarrow \infty$

**for** *a, s* in SUCCESSORS(*state*) **do**

$v \leftarrow \text{MIN}(v, \text{MAX-VALUE}(s))$

**return** *v*



# Properties of minimax

- Complete? Yes (if tree is finite)
- Optimal? Yes (against an optimal opponent)
- Time complexity?  $O(b^m)$
- Space complexity?  $O(bm)$  (depth-first exploration)
- For chess,  $b \approx 35$ ,  $m \approx 100$  for "reasonable" games
  - exact solution completely infeasible

# OPTIMAL STRATEGIES

-Find the contingent *strategy* for MAX assuming an infallible MIN opponent.

-**Assumption**: Both players play optimally !!

Given a game tree, the optimal strategy can be determined by using the minimax value of each node:

-**MINIMAX-VALUE**( $n$ )=

UTILITY( $n$ )

If  $n$  is a terminal

$\max_{s \in \text{successors}(n)} \text{MINIMAX-VALUE}(s)$  If  $n$  is a max then

$\min_{s \in \text{successors}(n)} \text{MINIMAX-VALUE}(s)$  If  $n$  is a min node



# MINIMAX ALGORITHM

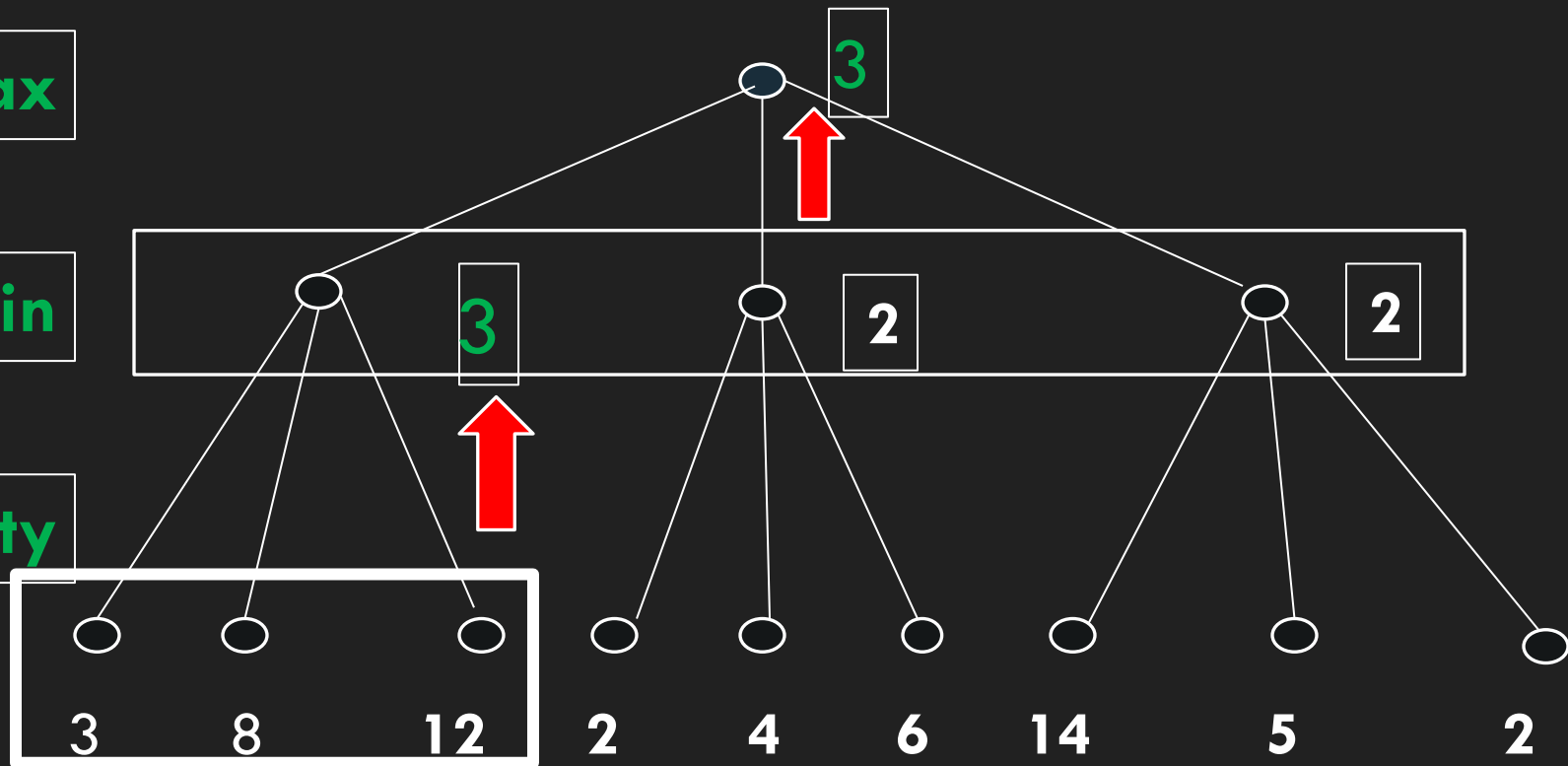
- Minimax is a decision rule algorithm, which is represented as a game-tree.
- It has applications in decision theory, game theory , statistics and philosophy.
- Minimax is applied in two player games. The one is the min and the other is the max player.
- By agreement the root of the game-tree represents the max player.
- It is assumed that each player aims to do the best move for himself and therefore the worst move for his opponent in order to win the game.

# Example

Max

Min

Utility

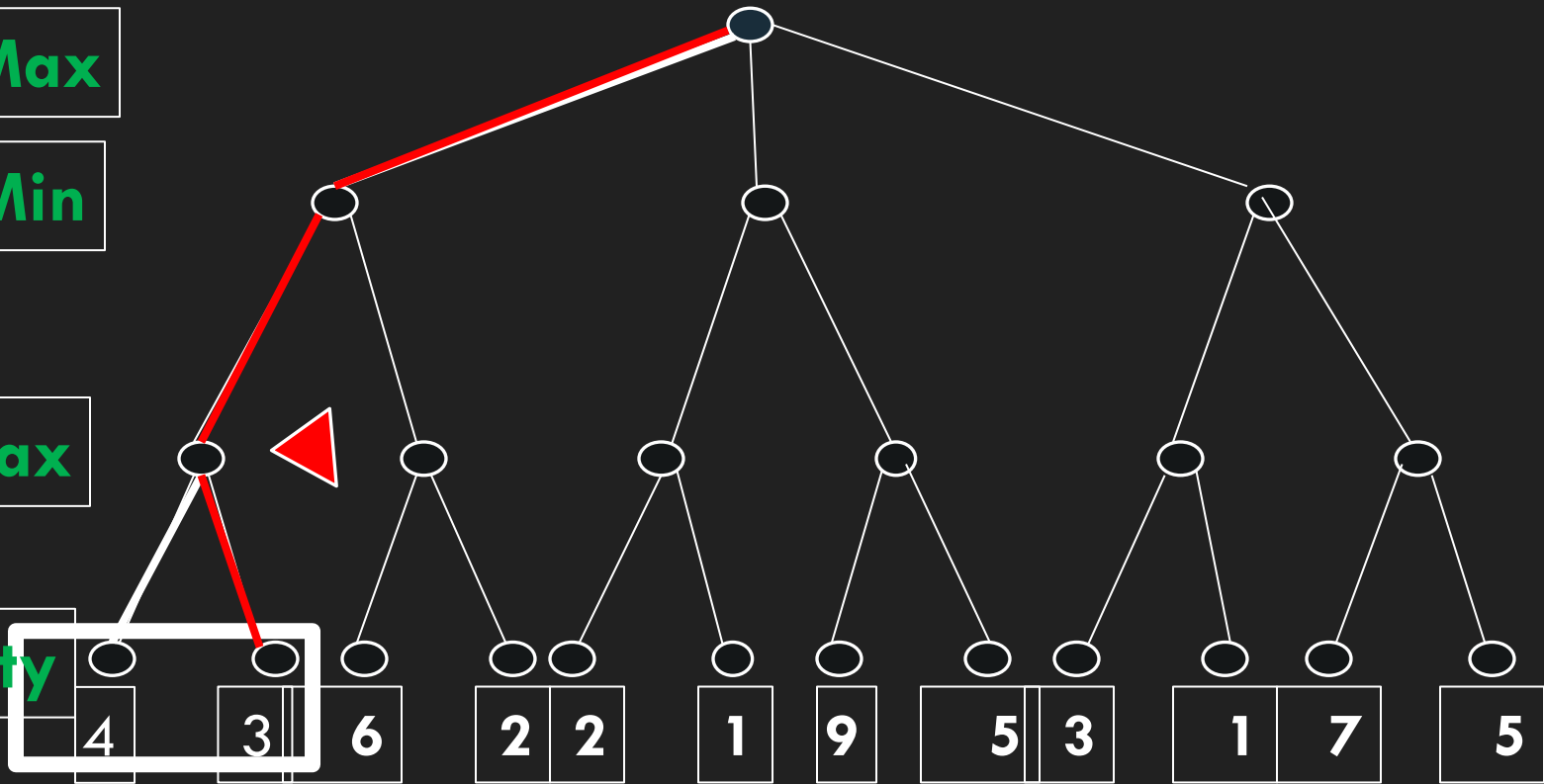


**Max**

Min

**Max**

## Utility

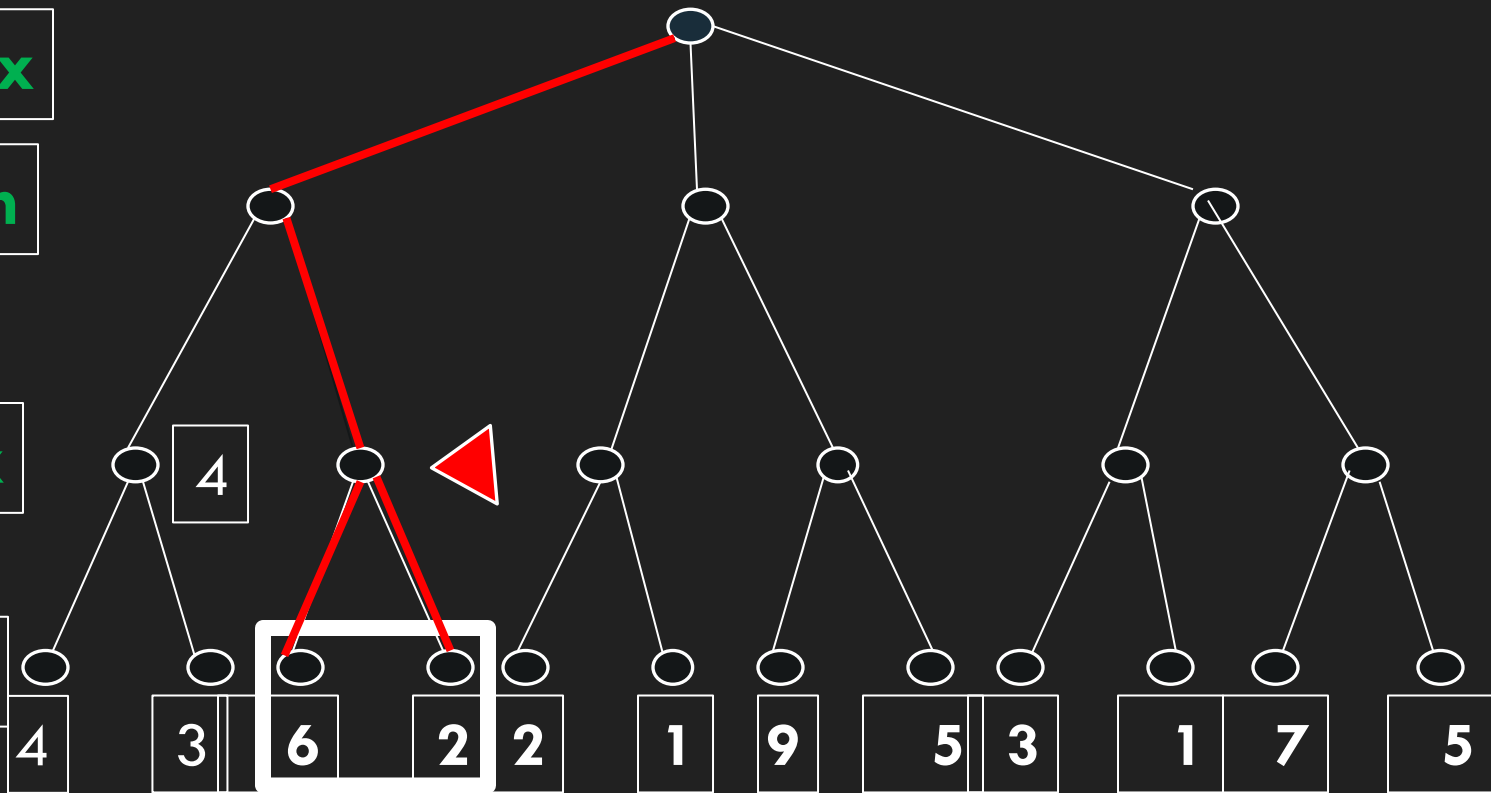


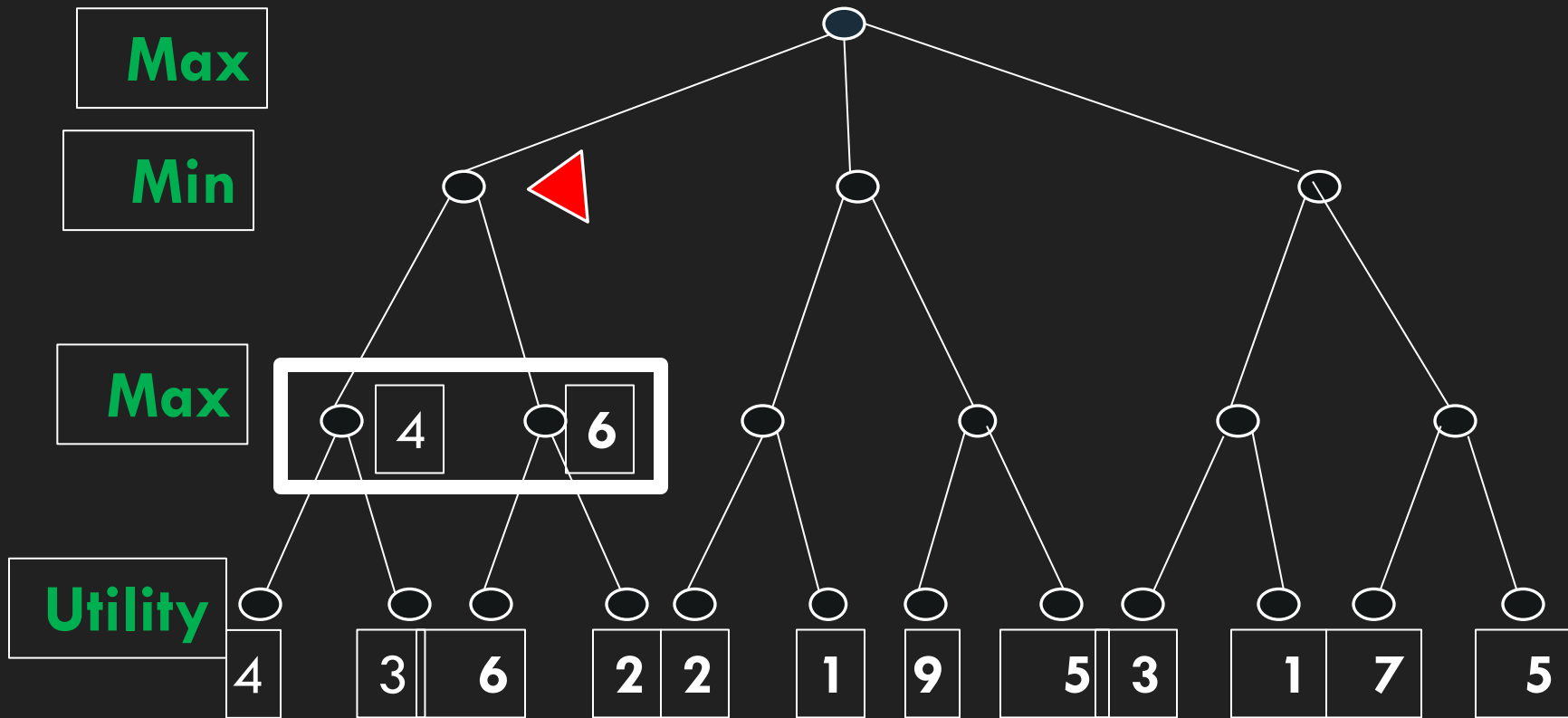
**Max**

Min

**Max**

## Utility



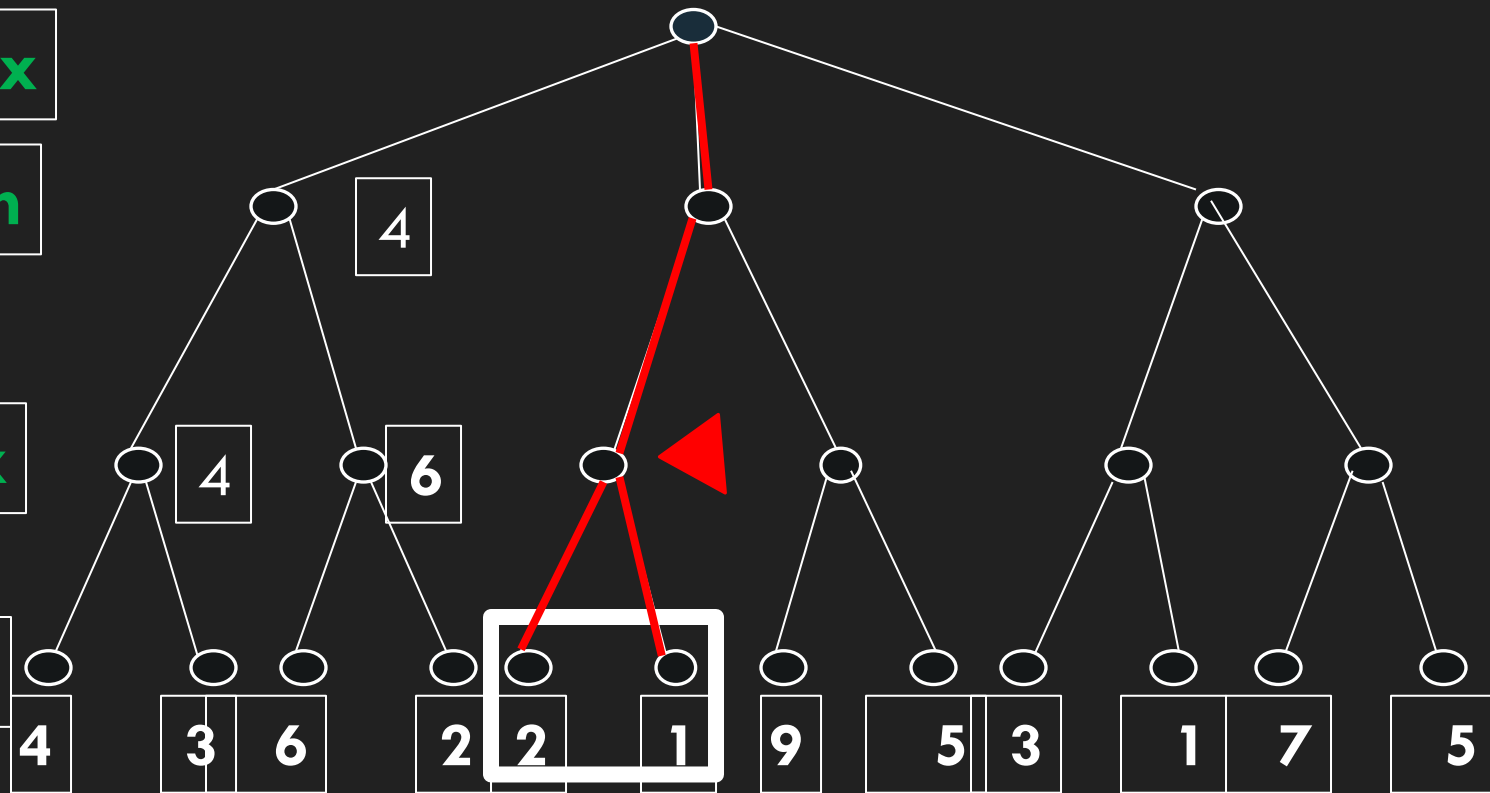


Max

Min

Max

Utility

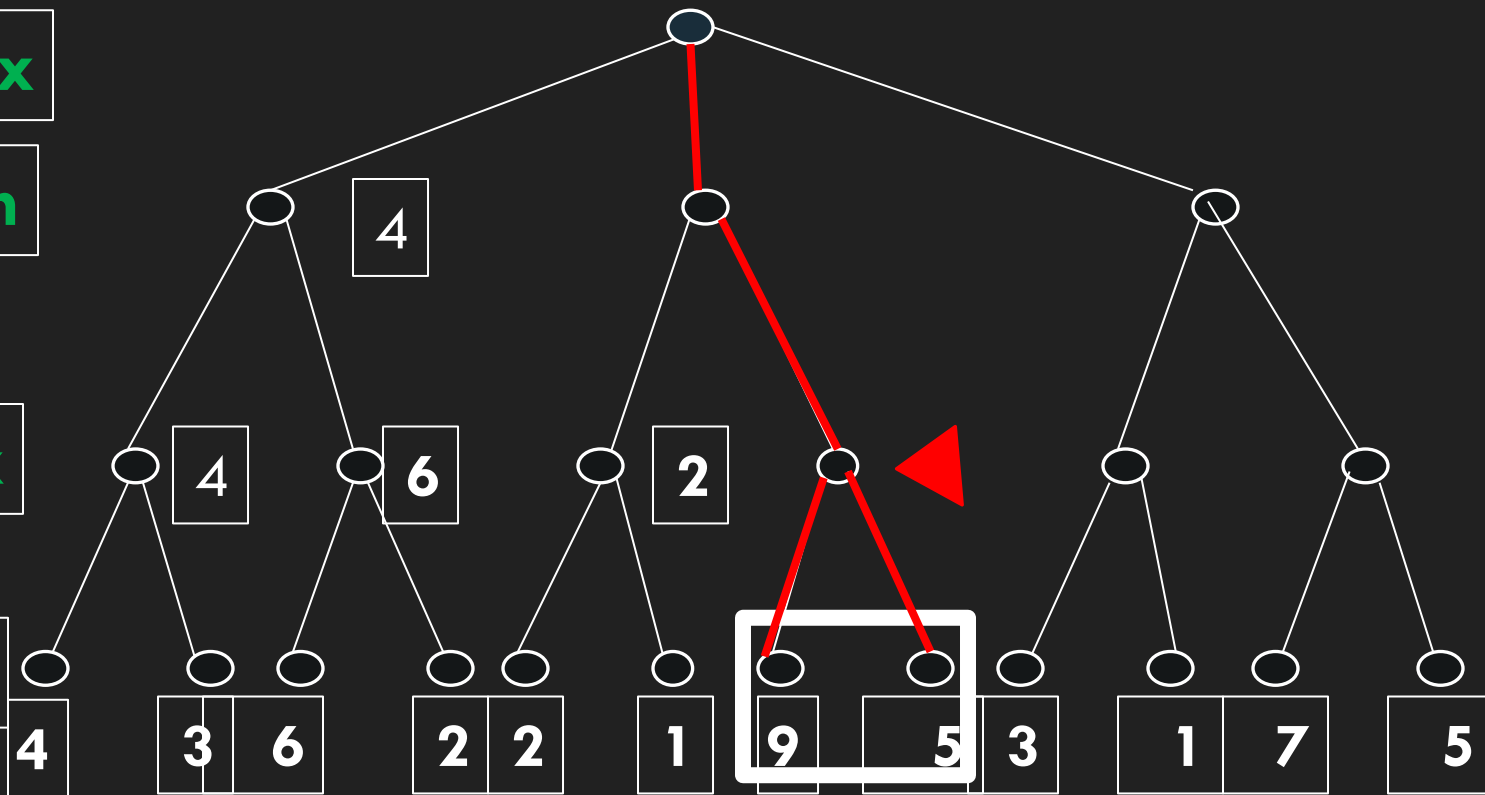


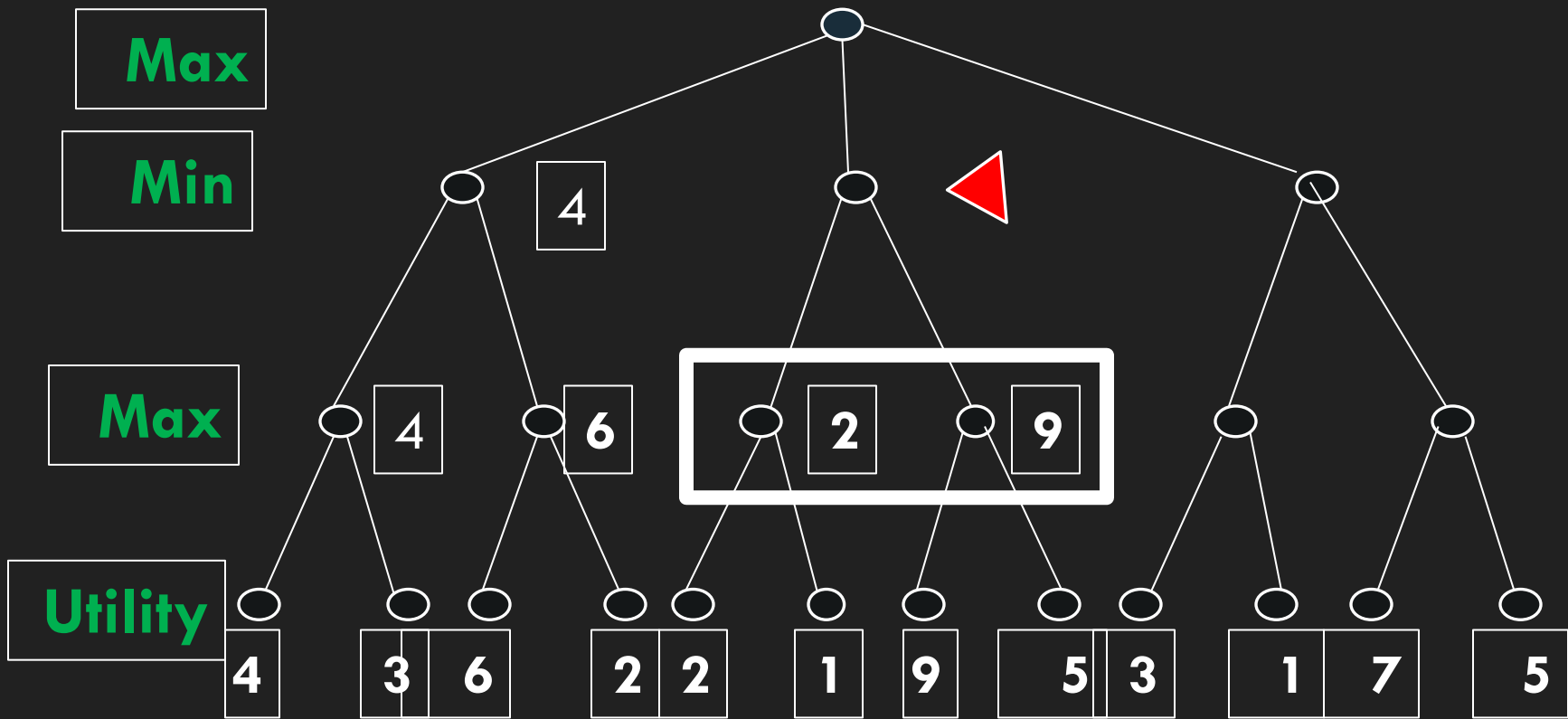
Max

Min

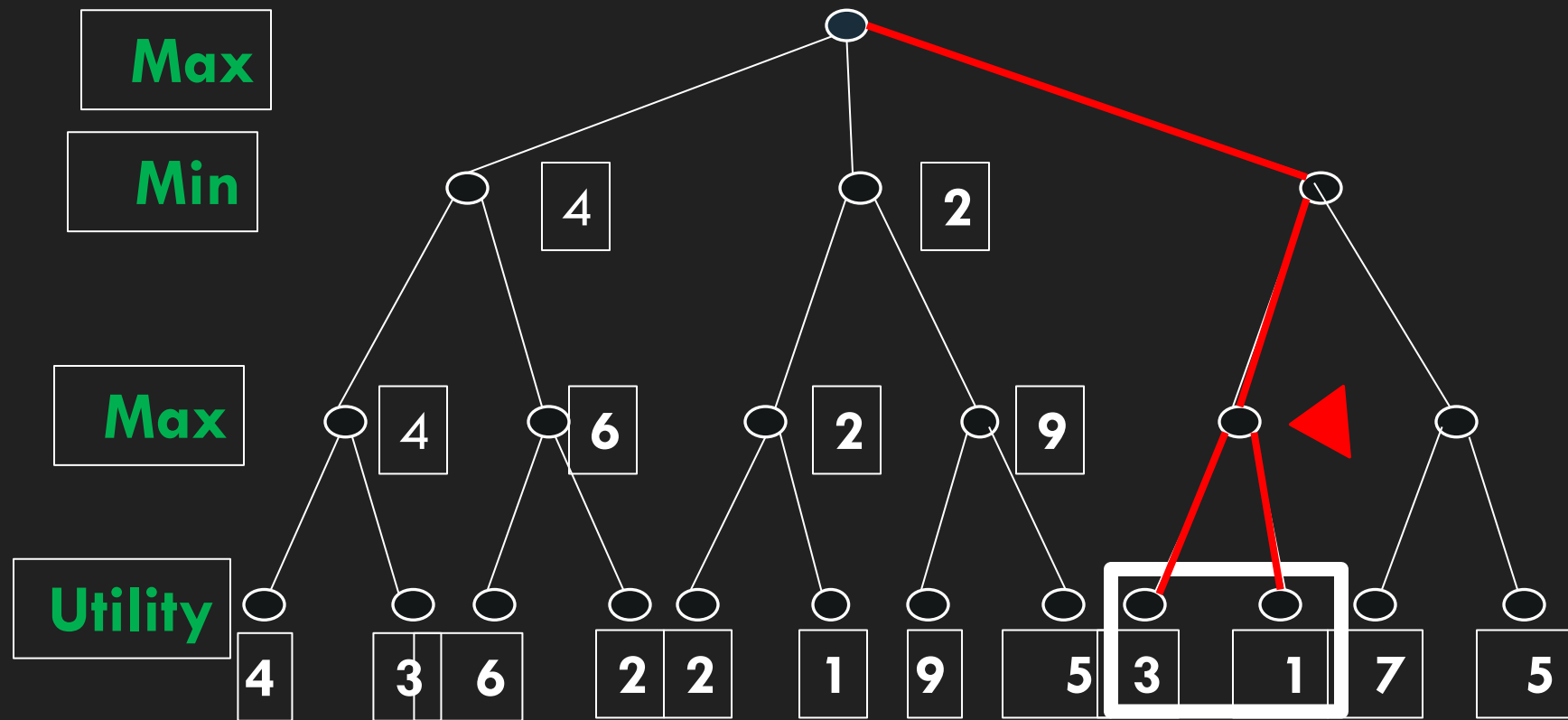
Max

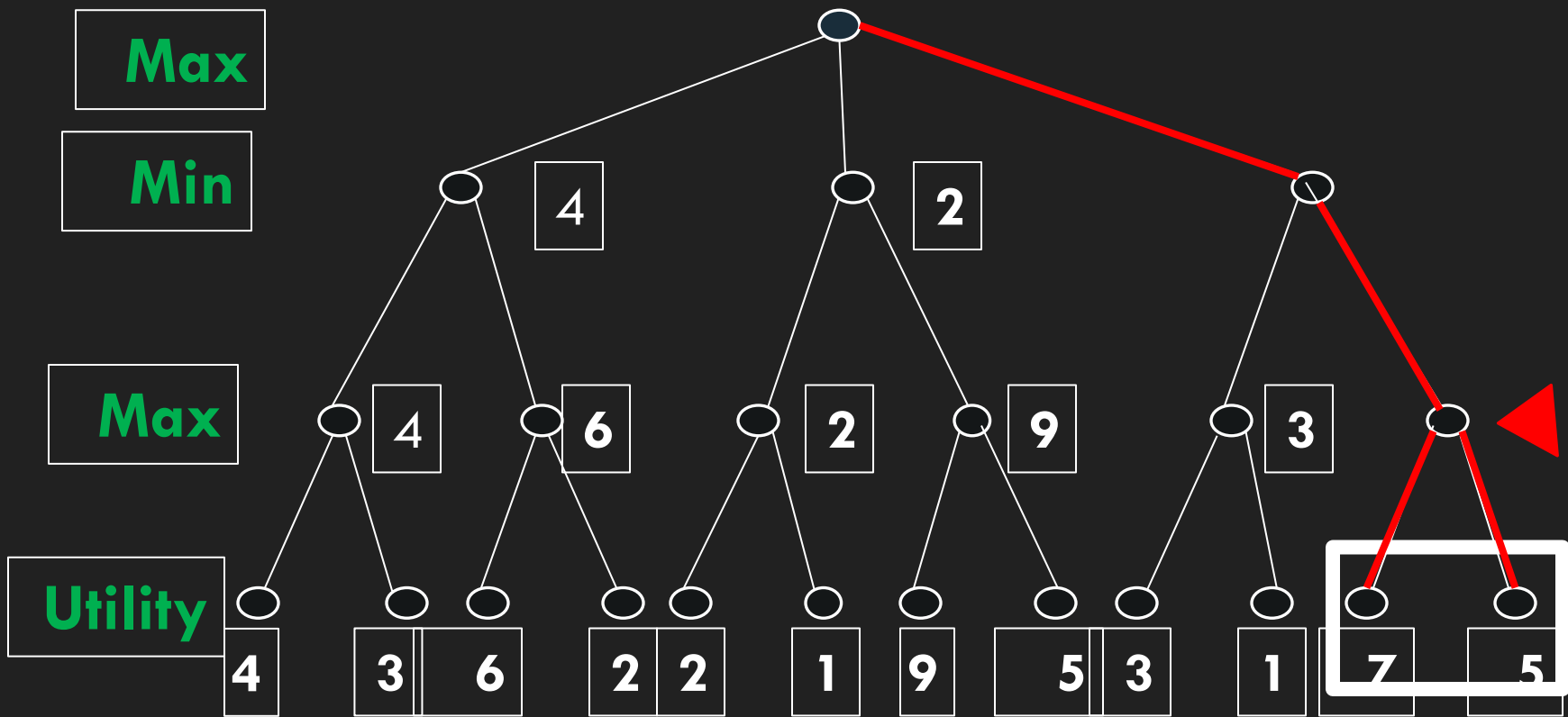
Utility









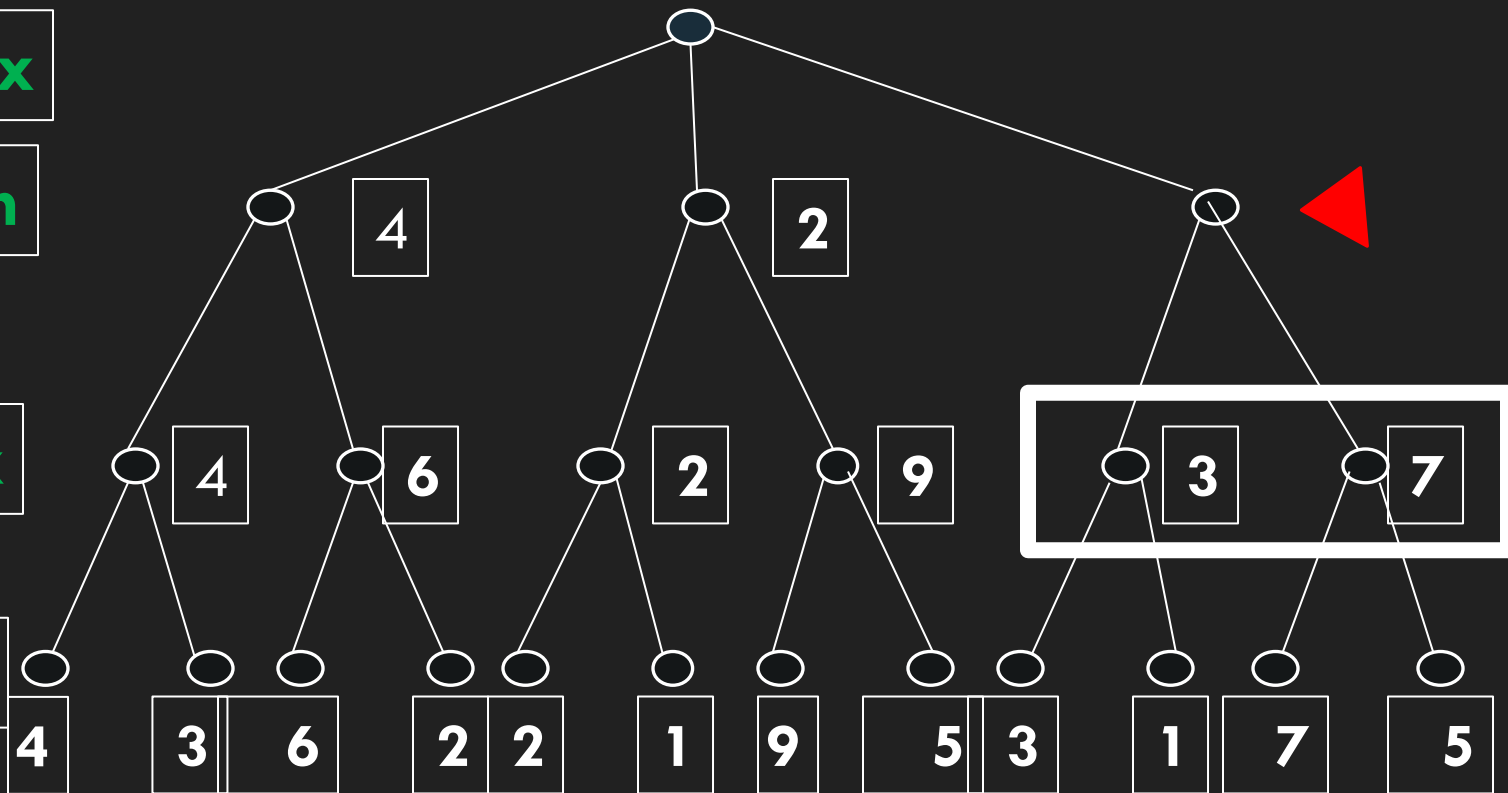


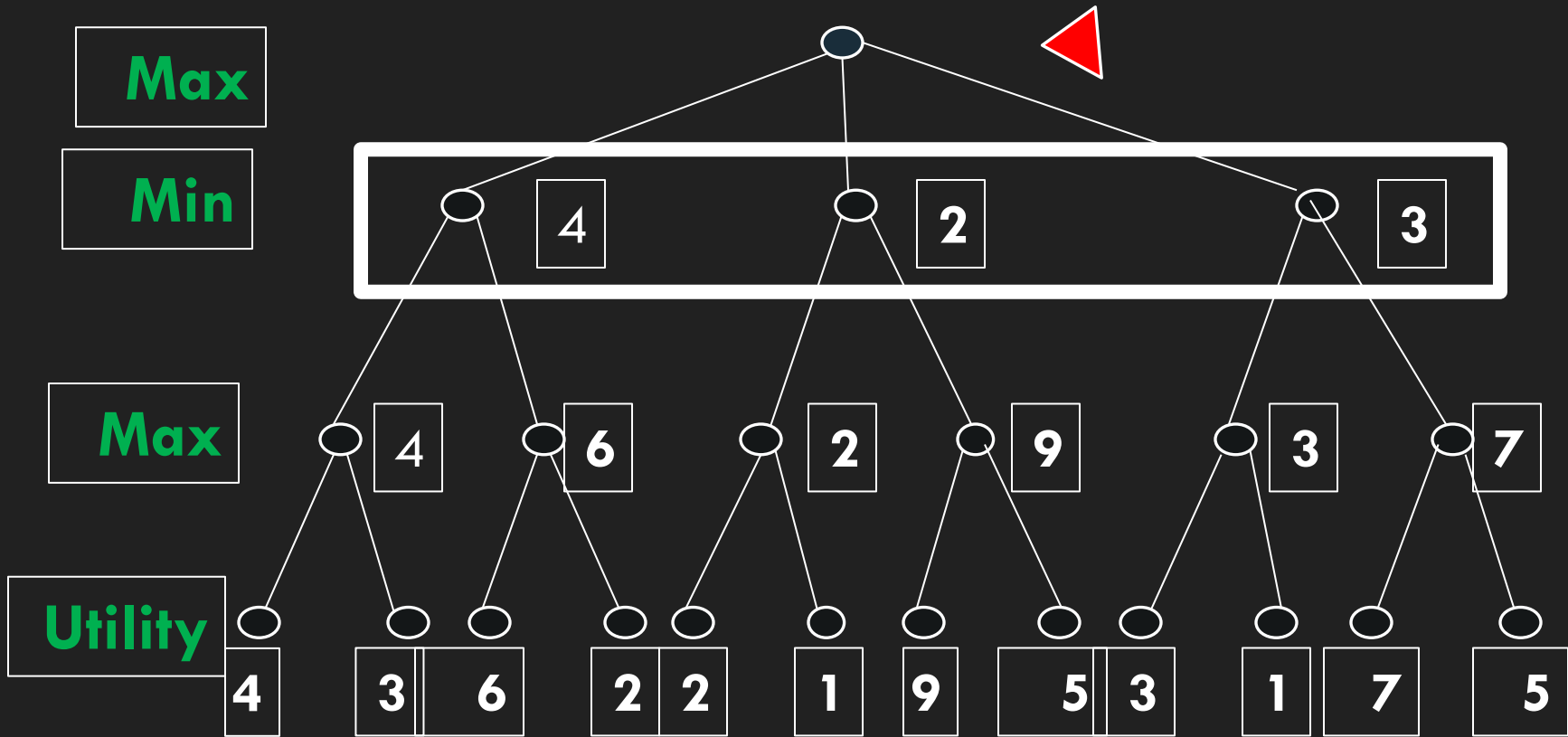
Max

Min

Max

Utility





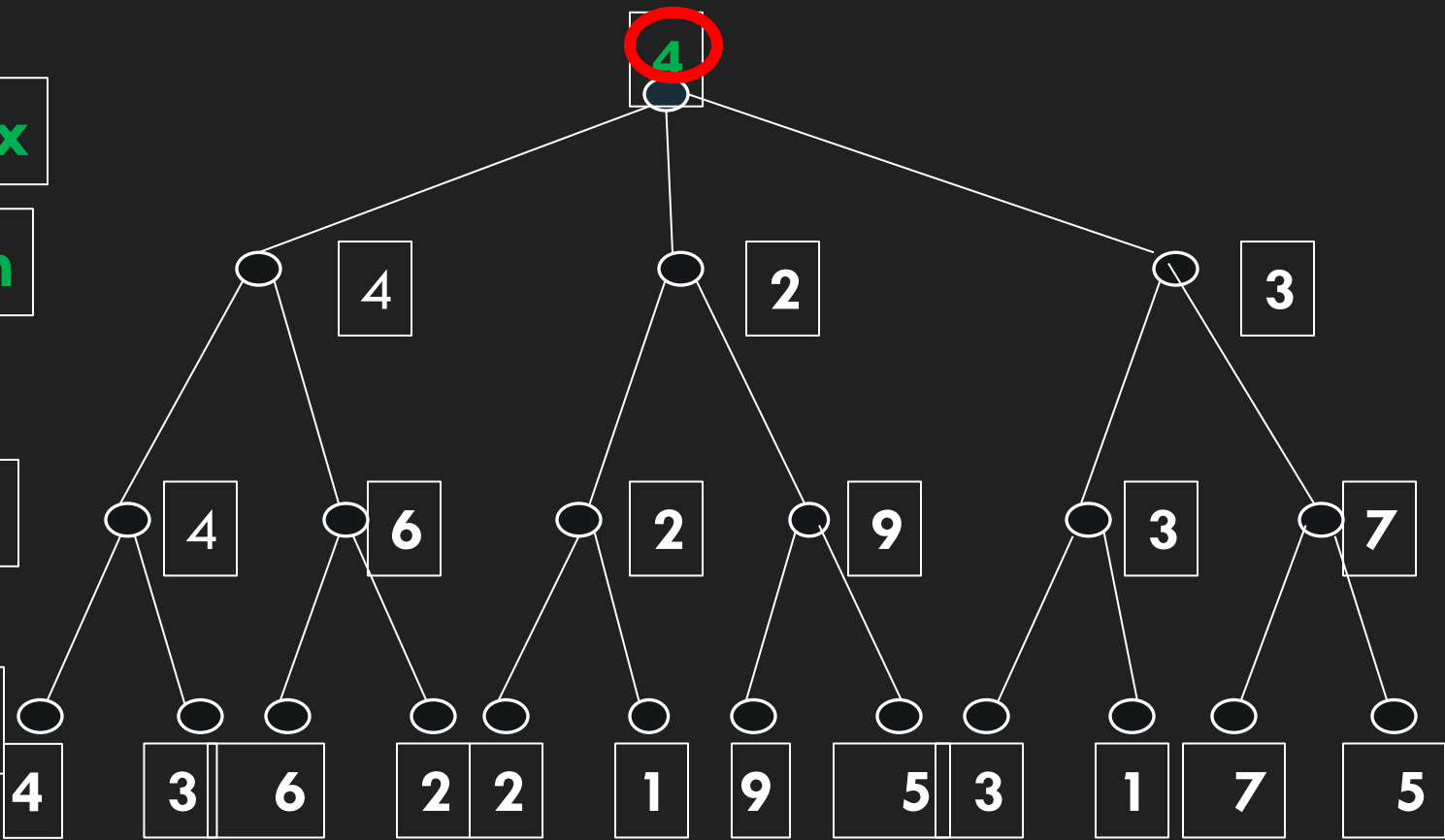
4

Max

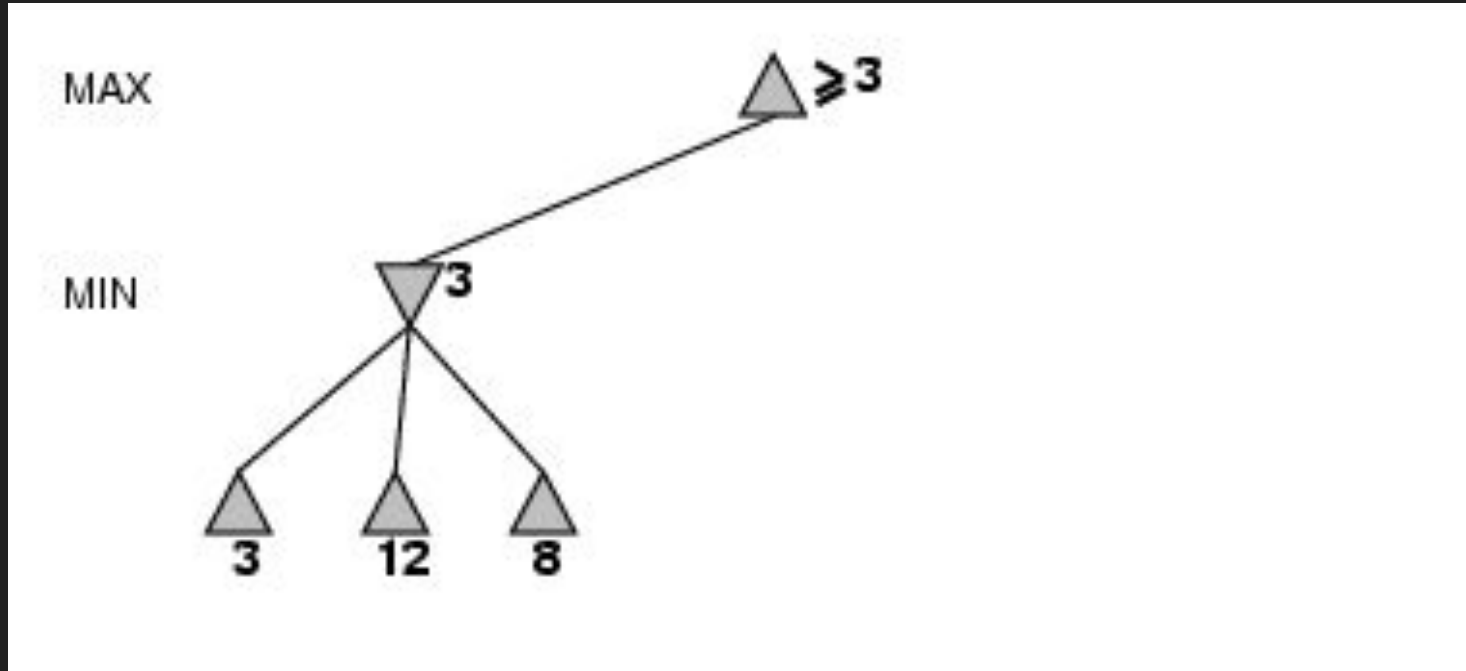
Min

Max

Utility



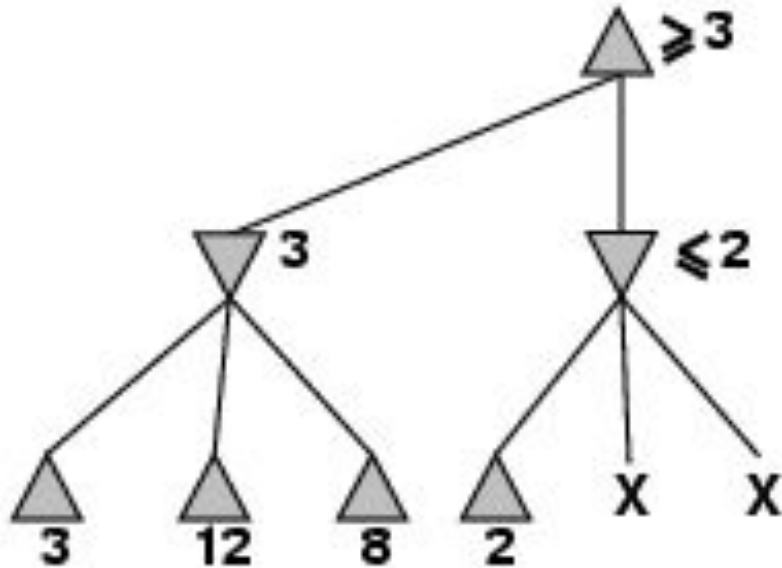
# $\alpha$ - $\beta$ pruning example



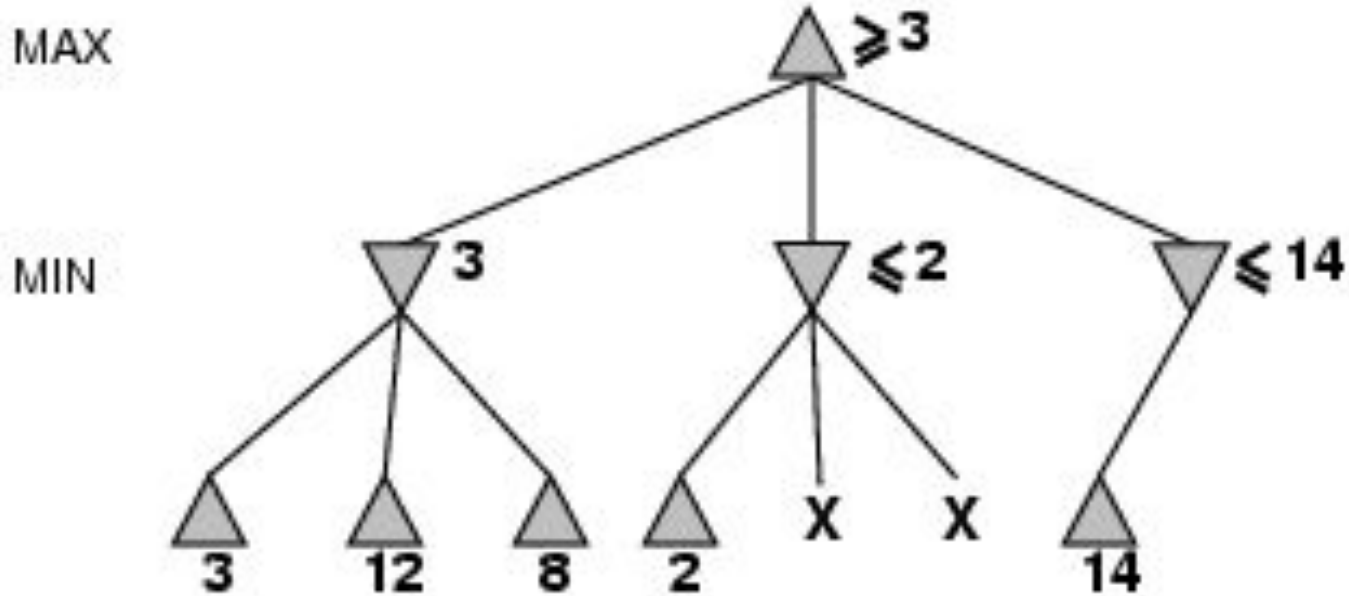
# $\alpha$ - $\beta$ pruning example

MAX

MIN

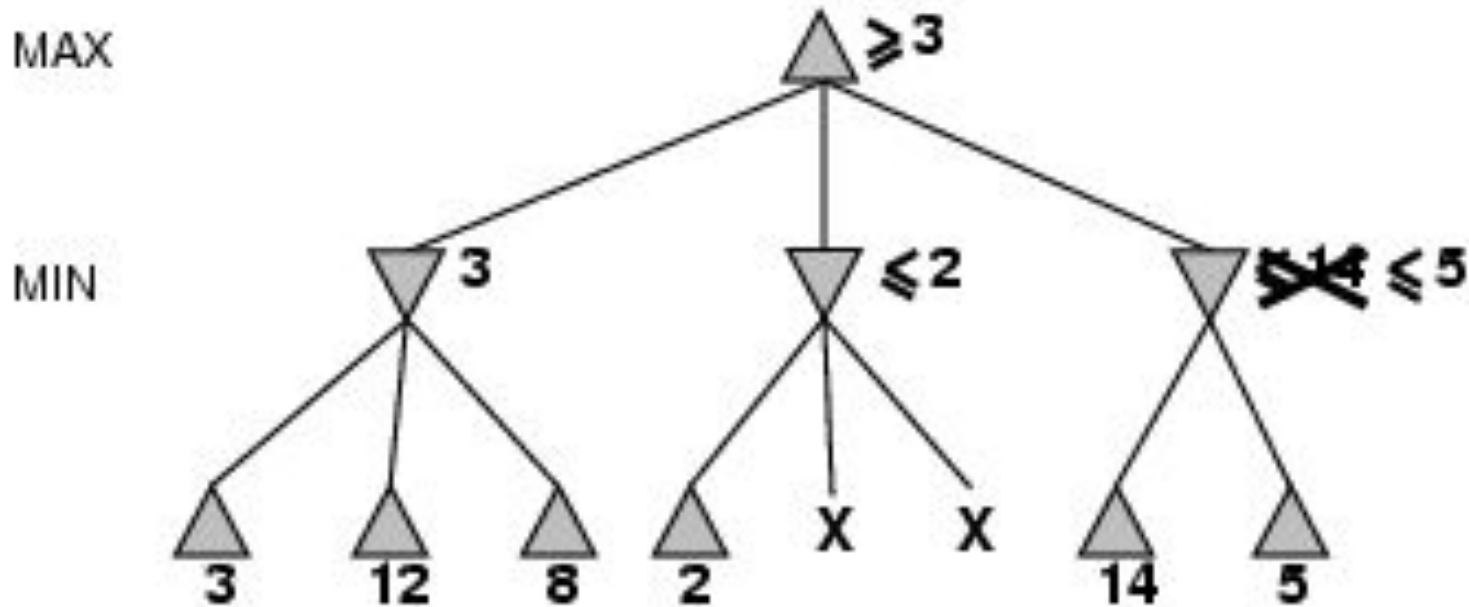


# $\alpha$ - $\beta$ pruning example

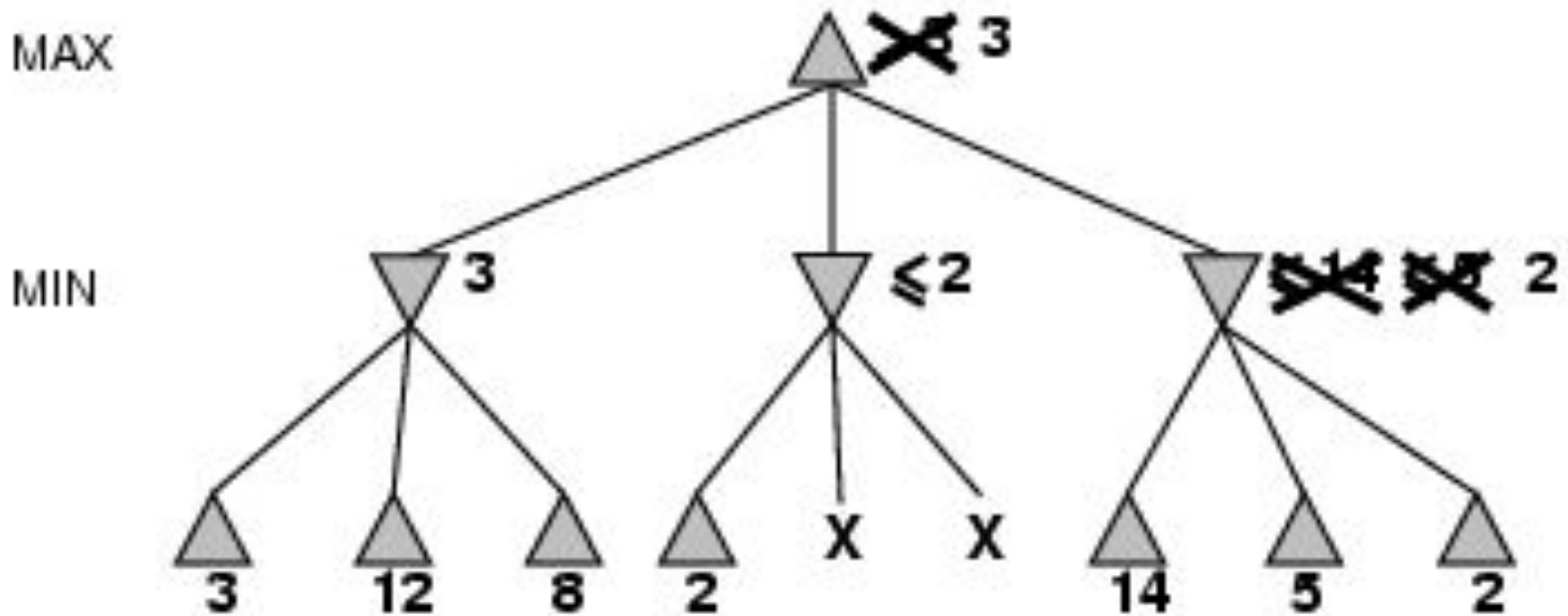




# $\alpha$ - $\beta$ pruning example



# $\alpha$ - $\beta$ pruning example

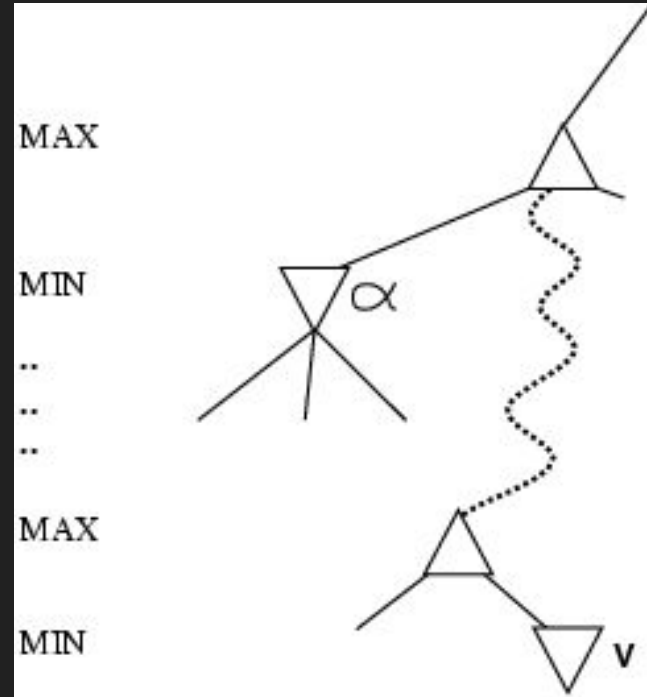


# Properties of $\alpha$ - $\beta$

- Pruning **does not** affect final result
- Good move ordering improves effectiveness of pruning
- With "perfect ordering," time complexity =  $O(b^{m/2})$ 
  - **doubles** depth of search
- A simple example of the value of reasoning about which computations are relevant (a form of **metareasoning**)

# Why is it called $\alpha$ - $\beta$ ?

- $\alpha$  is the value of the best (i.e., highest-value) choice found so far at any choice point along the path for *max*
- If  $v$  is worse than  $\alpha$ , *max* will avoid it
  - prune that branch
- Define  $\beta$  similarly for *min*



# The $\alpha$ - $\beta$ algorithm

**function** ALPHA-BETA-SEARCH(*state*) *returns an action*

**inputs:** *state*, current state in game

$v \leftarrow \text{MAX-VALUE}(\text{state}, -\infty, +\infty)$

**return** the *action* in SUCCESSORS(*state*) with value  $v$

---

**function** MAX-VALUE(*state*,  $\alpha$ ,  $\beta$ ) *returns a utility value*

**inputs:** *state*, current state in game

$\alpha$ , the value of the best alternative for MAX along the path to *state*

$\beta$ , the value of the best alternative for MIN along the path to *state*

**if** TERMINAL-TEST(*state*) **then return** UTILITY(*state*)

$v \leftarrow -\infty$

**for**  $a, s$  in SUCCESSORS(*state*) **do**

$v \leftarrow \text{MAX}(v, \text{MIN-VALUE}(s, \alpha, \beta))$

**if**  $v \geq \beta$  **then return**  $v$

$\alpha \leftarrow \text{MAX}(\alpha, v)$

**return**  $v$

# The $\alpha$ - $\beta$ algorithm

```
function MIN-VALUE(state,  $\alpha$ ,  $\beta$ ) returns a utility value  
  inputs: state, current state in game  
            $\alpha$ , the value of the best alternative for MAX along the path to state  
            $\beta$ , the value of the best alternative for MIN along the path to state  
  
  if TERMINAL-TEST(state) then return UTILITY(state)  
   $v \leftarrow +\infty$   
  for  $a, s$  in SUCCESSORS(state) do  
     $v \leftarrow \text{MIN}(v, \text{MAX-VALUE}(s, \alpha, \beta))$   
    if  $v \leq \alpha$  then return  $v$   
     $\beta \leftarrow \text{MIN}(\beta, v)$   
  return  $v$ 
```

# Resource limits

Suppose we have 100 secs, explore  $10^4$   
nodes/sec  
□  $10^6$  nodes per move

Standard approach:

- **cutoff test:**  
e.g., depth limit (perhaps add **quiescence search**)
- **evaluation function**  
= estimated desirability of position

# Evaluation functions

- For chess, typically **linear** weighted sum of features

$$Eval(s) = w_1 f_1(s) + w_2 f_2(s) + \dots + w_n f_n(s)$$

- e.g.,  $w_1 = 9$  with  
 $f_1(s) = (\text{number of white queens}) - (\text{number of black queens}), \text{ etc.}$



# Evaluation functions

- First, the evaluation function should order the *terminal states in the same way as the true utility function*;  
Second, the computation must not take too long!
- Third, for nonterminal states, the evaluation function should be strongly correlated with the actual chances of winning.

# Cutting off search

*MinimaxCutoff* is identical to *MinimaxValue* except

1. *Terminal?* is replaced by *Cutoff?*
2. *Utility* is replaced by *Eval*

TERMINAL-TEST--> **if CUTOFF-TEST(stated, depth) then return EVAL(state)**

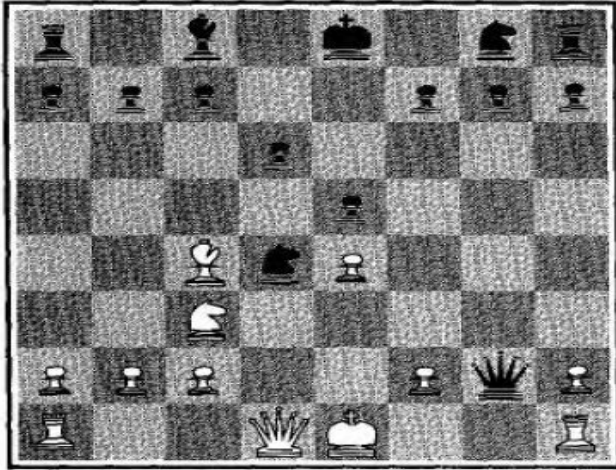
Does it work in practice?

$$b^m = 10^6, b=35 \quad \square \quad m=4$$

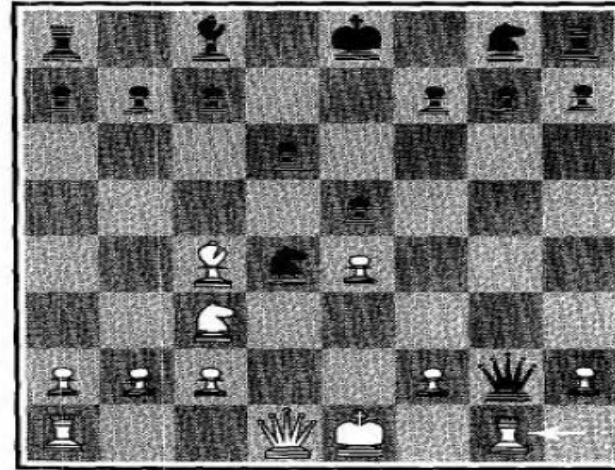
4-ply lookahead is a hopeless chess player!

- 4-ply  $\approx$  human novice
- 8-ply  $\approx$  typical PC, human master
- 12-ply  $\approx$  Deep Blue, Kasparov

# Cutting off search



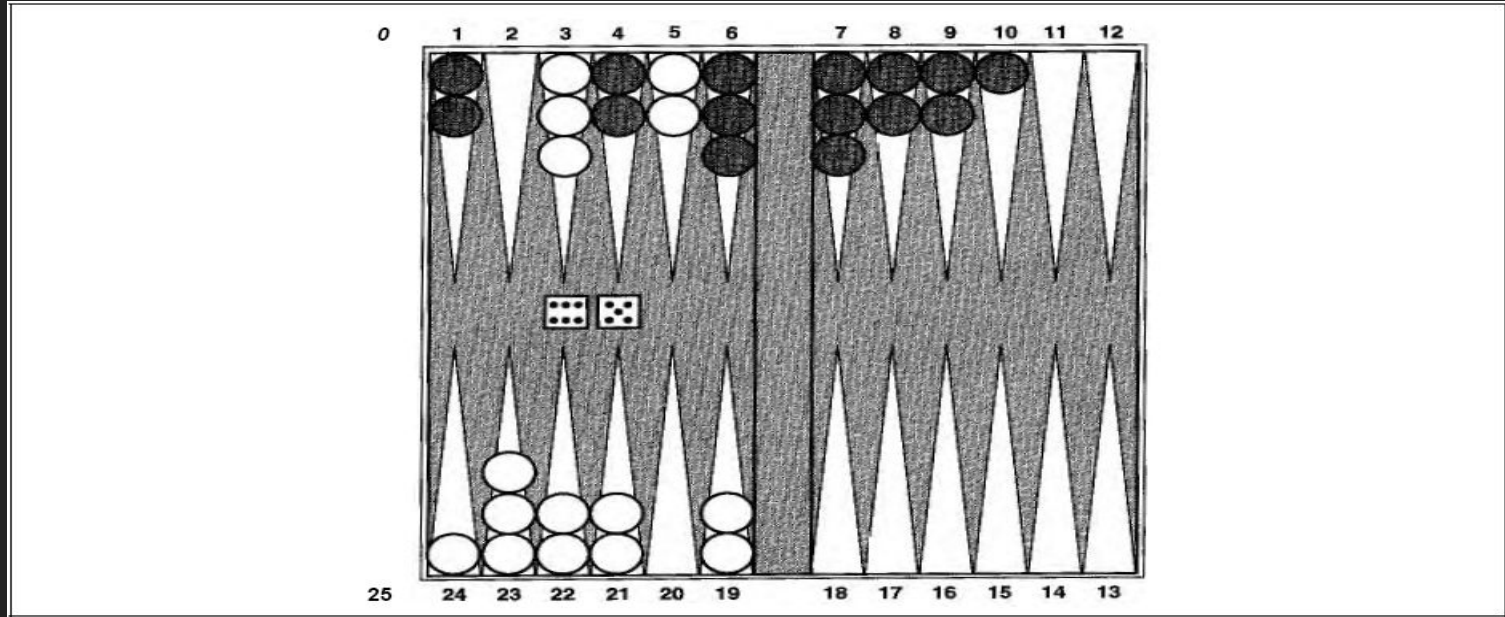
(a) White to move



(b) White to move

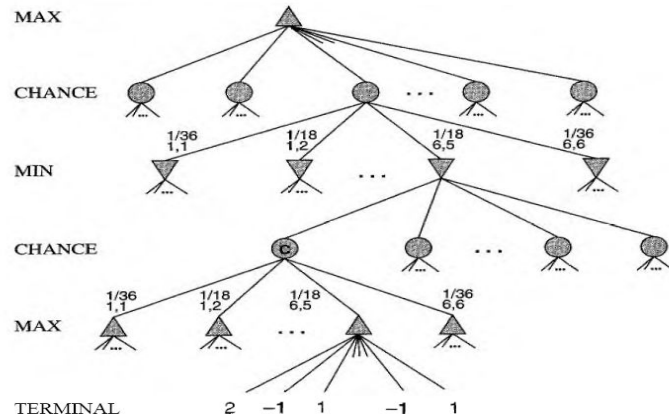
**Figure 6.8** Two slightly different chess positions. In (a), black has an advantage of a knight and two pawns and will win the game. In (b), black will lose after white captures the queen.

# Game Include an Element of Chance

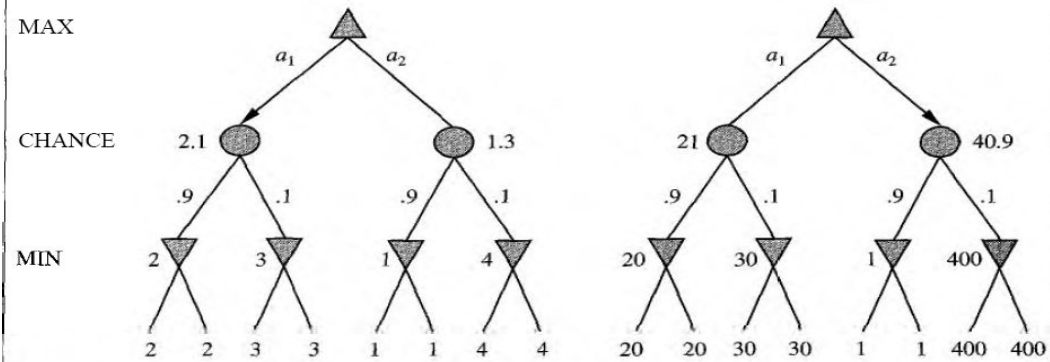


Backgammon

# Game Include an Element of Chance



**Figure 6.11** Schematic game tree for a backgammon position.



**Figure 6.12** An order-preserving transformation on leaf values changes the best move.

EXPECTIMINIMAX( $n$ ) =

$$\begin{cases} \text{UTILITY}(n) & \text{if } n \text{ is a terminal state} \\ \max_{s \in \text{Successors}(n)} \text{EXPECTIMINIMAX}(s) & \text{if } n \text{ is a MAX node} \\ \min_{s \in \text{Successors}(n)} \text{EXPECTIMINIMAX}(s) & \text{if } n \text{ is a MIN node} \\ \sum_{s \in \text{Successors}(n)} P(s) \cdot \text{EXPECTIMINIMAX}(s) & \text{if } n \text{ is a chance node} \end{cases}$$

# Summary

- ▣ Games are fun to work on!  
They illustrate several important points about AI
  - perfection is unattainable ▣ must approximate
- ▣ MiniMax and Alpha beta pruning