Pnl Manual

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Contents

1 Introduction

1.1 What is Pnl

Pnl is a scientific library written in C and distributed under the Gnu Lesser General Public Licence (LGPL). This manual is divided into four parts.

- Mathematical functions: complex numbers, special functions, standard financial functions for the Black & Scholes model.

- Linear algebra : vectors, matrices (dense and sparse), hypermatrices, tridiagonal matrices, band matrices and the corresponding routines to manipulate them and solve linear systems.

- Probabilistic functions: random number generators and cumulative distribution functions.

- Deterministic toolbox : FFT, Laplace inversion, numerical integration, zero searching, multivariate polynomial regression, ...

1.2 A few helpful conventions

- All header file names are prefixed by `pnl_` and are surrounded by the preprocessor conditionals

  ```
  #ifndef _PNL_MATRIX_H
  #define _PNL_MATRIX_H

  ...

  #endif /* _PNL_MATRIX_H
  ```

  All the header files are protected by an `extern "C"` declaration for possible use with a C++ compiler. The header files must be include using

  ```
  #include "pnl/pnl_xxx.h"
  ```

- All function names are prefixed by `pnl_` except those implementing complex number arithmetic which are named following the *C99* complex library but using a capitalised first letter `C`.
  For example, the addition of two complex numbers is performed by the function `Cadd`.

- Function containing `_create` in their names always return a pointer to an object created by one or several calls to dynamic allocation. Once these objects are not used, they must be freed by calling the same function but ending in `_free`. A function `pnl_foo_create_yyy` returns a `PnlFoo *` object (note the "∗") and a function `pnl_foo_bar_create_yyy` returns a `PnlFooBar *` object (note the "∗"). These objects must be freed by calling respectively `pnl_foo_free` or `pnl_foo_bar_free`.

- Functions ending in `_clone` take two arguments `src` and `dest` and modify `dest` to make it identical to `src`, ie. they have the same size and data. Note that no new object is allocated, `dest` must exist before calling this function.

- Functions ending in `_copy` create a new object identical (ie. with the same size and content) as its argument but independent (ie. modifying one of them does not alter the other). Calling `A = pnl_xxx_copy(B)` is equivalent to first calling `A = pnl_xxx_new()` function and then `pnl_xxx_clone(A, B)`.

- Every object must implement a `pnl_xxx_new` function which returns a pointer to an empty object with all its elements properly set to 0. This means that the objects returned by the `pnl_xxx_new` functions can be used as output arguments for functions ending in `_inplace` for instance. They are suitable for being resized.

- Functions containing `_wrap_` in their names always return an object, not a pointer to an object, and do not make any use of dynamic allocation. The returned object must not be freed. For instance, a function `pnl_foo_wrap_xxx` returns an object `PnlFoo` and a function `pnl_foo_bar_wrap_xxx` returns an object `PnlFooBar`

  ```
  PnlVectComplex *v1;
  PnlVectComplex v2;
  v1 = pnl_vect_complex_create_from_scalar (5, Complex(0., 1.));
  v2 = pnl_vect_complex_wrap_subvect (v1, 1, 2);

  ...

  pnl_vect_complex_free (&v1);
  ```

  The vector `v1` is of size 5 and contains the pure imaginary number i. The vector `v2` only provides a view to `v1(1:1+2)`, which means that modifying `v2` will also modify `v1` and vice-versa because `v1` shares part of its data with `v2`. Note that only `v1` must be freed and **not** `v2`.

- Functions ending in `_init` do not create any object but only perform some internal initialisation.

- Hypermatrices, matrices and vectors are stored using a flat block of memory obtained by concatenating the matrix rows and C-style pointer-to-pointer arrays. Matrices are stored in row-major order, which means that the column index moves continuously. Note that this convention is not *Blas & Lapack* compliant since Fortran expects 2-dimensional arrays to be stored in a column-major order.

- Type names always begin with `Pnl`, they do not contain underscores but instead we use capital letters to separate units in type names.
  Examples : `PnlMat`, `PnlMatComplex`.

- Object and function names are intimately linked : an object `PnlFoo` is manipulated by functions starting in `pnl_foo`, an object `PnlFooBar` is manipulated by functions starting in `pnl_foo_bar`. In table 1, we summarise the types and their corresponding prefixes.

- All macro names begin with `PNL_` and are capitalised.

- Differences between **copy** and **clone** methods. The `copy` methods take a single argument and return a pointer to an object of the same type which is an independent copy of its argument. Example:

  ```
  PnlVect *v1, *v2;
  ```

Pnl types	Pnl prefix
PnlVect	pnl_vect
PnlVectComplex	pnl_vect_complex
PnlVectInt	pnl_vect_int
PnlMat	pnl_mat
PnlMatComplex	pnl_mat_complex
PnlMatInt	pnl_mat_int
PnlSpMat	pnl_sp_mat
PnlSpMatComplex	pnl_sp_mat_complex
PnlSpMatInt	pnl_sp_mat_int
PnlHmat	pnl_hmat
PnlHmatComplex	pnl_hmat_complex
PnlHmatInt	pnl_hmat_int
PnlTridiagMat	pnl_tridiag_mat
PnlBandMat	pnl_band_mat
PnlList	pnl_list
PnlBasis	pnl_basis
PnlCgSolver	pnl_cg_solver
PnlBicgSolver	pnl_bicg_solver
PnlGmresSolver	pnl_gmres_solver

Figure 1: Pnl types

```
v1 = pnl_vect_create_from_scalar (5, 2.5);
v2 = pnl_vect_copy (v1);
```

`v1` and `v2` are two vectors of size 5 with all their elements equal to 2.5. Note that `v2` **must not** have been created by a call to `pnl_vect_create_xxx` because otherwise it will cause a memory leak. `v1` and `v2` are independent in the sense that a modification to one of them does not affect the other.

The `clone` methods take two arguments and fill the first one with the second one. Example:

```
PnlVect *v1, *v2;
v1 = pnl_vect_create_from_scalar (5, 2.5);
v2 = pnl_vect_new ();
pnl_vect_clone (v2, v1);
```

v1 and v2 are two vectors of size 5 with all their elements equal to 2.5. Note that v2 **must** have been created by a call to pnl_vect_new because otherwise the function pnl_vect_clone will crash. v1 and v2 are independent in the sense that a modification to one of them does not modify the other.

- All objects are measured using integers int and not size_t. Hence, iterations over vectors, matrices, ... should use an index of type int.
- In fonctions ending in inplace, the output parameter must be different from any of the input parameters.

1.3 Using Pnl

In this section, we assume that the library is installed in the directory $HOME/pnl-xxx.
Once installed, the library can be found in the $HOME/pnl-xxx/lib directory and the header files in the $HOME/pnl-xxx/include directory.

1.3.1 Compiling and Linking

The header files of the library are installed in a root pnl directory and should always be included with this pnl/ prefix. So, for instance to use random number generators you should include

```
#include <pnl/pnl_random.h>
```

Compiling and linking by hand. If gcc or llvm is used, you should pass the following options

- -I$HOME/pnl-xxx/include for compiling
- -L$HOME/pnl-xxx/lib -lpnl for linking

This does not work straight away on all OS especially if the library is not installed in a standard directory namely /usr/ or /usr/local/ for which you need a privileged writing access. On some systems, you may need to add to the linker flags the dependencies of the library, which can become very tedious. Therefore, we provide a second automatic mechanism which takes care of the dependencies on its own.

Compiling and linking using an automatic Makefile. This mechanism only works under Unix (it has been tested under various Linux distributions and Mac OS X).
First, you need to create a new directory wherever you want, put in all your code and create a Makefile as below
To define your target just add the executable name, say my-exec, to the BINS list and create an entry my_exec_SRC carrying the list of source files needed to create your executable. Note that if dashes '-' may appear in an executable name, the name of the associated variable holding the list of source files is obtained by replacing dashes with underscores '_' and adding the _SRC suffix.
Assume you want to create two binaries : my-exec based on mixed C and C++ code (file1.c and file2.cpp) and mybinary based on poo1.cxx and poo2.cpp. You can use the following Makefile.

```
## Flags passed to the linker
LDFLAGS=

## Flags passed to the compiler
CFLAGS=

## list of executables to create
BINS=my-exec mybinary

my_exec_SRC=file1.c file2.cpp
# optional flags for compiling and linking
my_exec_CFLAGS=
my_exec_CXXFLAGS=
my_exec_LDFLAGS=

mybinary_SRC=poo1.cxx poo2.cpp
# optional flags for compiling and linking
mybinary_CFLAGS=
mybinary_CXXFLAGS=
mybinary_LDFLAGS=


## This line must be the last one
include full_path_to_pnl_build/CMakeuser.incl
```

Let us comment a little the different variables

- `CFLAGS`: global flags used for creating objects based on C code
- `CXXFLAGS`: global flags used for creating objects based on C++ code
- `LDFLAGS`: gobal linker flags.
- `binaryname_CFLAGS`: flags used when creating the objects based on C code and required by `binaryname`
- `binaryname_CXXFLAGS`: flags used when creating the objects based on C++ code and required by `binaryname`
- `binaryname_LDFLAGS`: flags used when linking objects for creating `binaryname`

An example of such a Makefile can be found in `pnl-xxx/perso`.
Warning: if a file appears in the source list of several binairies, the flags used to compile this file are determined by the ones of the first binary involving this file. In the following example `main.cpp` will always be compiled with the flag `-O3` even for generating `bin2`

```
BINS=bin1 bin2

bin1_SRC=main.cpp poo1.c
my_exec_CXXFLAGS=-O3
```

```
bin2_SRC=main.cpp poo2.c
mybinary_CXXFLAGS=-g -O0

## This line must be the last one
include full_path_to_pnl_build/CMakeuser.incl
```

Compiling and linking using CMake. If you already use CMake for your new project, just add the following to your toplevel `CMakeLists.txt`

```
find_package(Pnl REQUIRED)
set(LIBS ${LIBS} ${PNL_LIBRARIES})
include_directories(${PNL_INCLUDE_DIRS})
# Deactivate PNL debugging stuff on Release builds
if(${CMAKE_BUILD_TYPE} STREQUAL "Release")
    add_definitions(-DPNL_RANGE_CHECK_OFF)
endif()
```

Then, call cmake with the following extra flag

```
-DCMAKE_PREFIX_PATH=path/to/build-dir
```

or add the variable `CMAKE_BUILD_TYPE` to the GUI.

Just in case, we give an example of a complete although elementary `CMakeLists.txt`

```
cmake_minimum_required(VERSION 2.8)
# Declare a project
project(my-project CXX)

# Release or Debug
if (NOT CMAKE_BUILD_TYPE)
    message(STATUS "Setting build type to 'Debug' as none was specified.")
    set(CMAKE_BUILD_TYPE Debug CACHE STRING "Choose the type of build." FORCE)
endif ()


# Detect PNL
find_package(Pnl REQUIRED)
set(LIBS ${LIBS} ${PNL_LIBRARIES})
include_directories(${PNL_INCLUDE_DIRS})
if(${CMAKE_BUILD_TYPE} STREQUAL "Release")
    add_definitions(-DPNL_RANGE_CHECK_OFF)
endif()

# Adding an executable.
add_executable(exec-name list_of_source_files)
target_link_libraries(exec-name ${LIBS})
```

1.3.2 Inline Functions and getters

If it is supported by your compiler, getter and setter functions are declared as inline functions. This is automatically detected when running CMake. By default, setter and getter functions check that the required access is valid, basically it boils down to checking whether the index of the access is within an acceptable range. These extra tests can become very expensive when getter and setter function are intensively called.
Thus, it is possible to alter this default behaviour by defining the macro `PNL_RANGE_CHECK_OFF`. This macro is automatically defined when the library is compiled in Release mode, ie. with `-DCMAKE_BUILD_TYPE=Release` passed to CMake.

2 Objects

2.1 The top-level object

The PnlObject structure is used to simulate some inheritance between the ojbects of Pnl. It must be the first element of all the objects existing in Pnl so that casting any object to a PnlObject is legal

```
typedef unsigned int PnlType;

typedef void (DestroyFunc) (void **);
typedef PnlObject* (CopyFunc) (PnlObject *);
typedef PnlObject* (NewFunc) (PnlObject *);
typedef void (CloneFunc) (PnlObject *dest, const PnlObject *src);
struct _PnlObject
{
  PnlType type; /*!< a unique integer id */
  const char *label; /*!< a string identifier (for the moment not useful) */
  PnlType parent_type; /*!< the identifier of the parent object is any,
                          otherwise parent_type=id */
  int nref; /*!< number of references on the object */
  DestroyFunc *destroy; /*!< frees an object */
  NewFunc     *constructor; /*!< New function */
  CopyFunc    *copy; /*!< Copy function */
  CloneFunc   *clone; /*!< Clone function */
};
```

Here is the list of all the types actually defined
We provide several macros for manipulating PnlObejcts.

- **PNL_OBJECT** (o)
  Description Cast any object into a PnlObject
- **PNL_VECT_OBJECT** (o)
  Description Cast any object into a PnlVectObject
- **PNL_MAT_OBJECT** (o)
  Description Cast any object into a PnlMatObject

PnlType	Description
PNL_TYPE_VECTOR	general vectors
PNL_TYPE_VECTOR_DOUBLE	real vectors
PNL_TYPE_VECTOR_INT	integer vectors
PNL_TYPE_VECTOR_COMPLEX	complex vectors
PNL_TYPE_MATRIX	general matrices
PNL_TYPE_MATRIX_DOUBLE	real matrices
PNL_TYPE_MATRIX_INT	integer matrices
PNL_TYPE_MATRIX_COMPLEX	complex matrices
PNL_TYPE_TRIDIAG_MATRIX	general tridiagonal matrices
PNL_TYPE_TRIDIAG_MATRIX_DOUBLE	real tridiagonal matrices
PNL_TYPE_BAND_MATRIX	general band matrices
PNL_TYPE_BAND_MATRIX_DOUBLE	real band matrices
PNL_TYPE_SP_MATRIX	sparse general matrices
PNL_TYPE_SP_MATRIX_DOUBLE	sparse real matrices
PNL_TYPE_SP_MATRIX_INT	sparse integer matrices
PNL_TYPE_SP_MATRIX_COMPLEX	sparse complex matrices
PNL_TYPE_HMATRIX	general hyper matrices
PNL_TYPE_HMATRIX_DOUBLE	real hyper matrices
PNL_TYPE_HMATRIX_INT	integer hyper matrices
PNL_TYPE_HMATRIX_COMPLEX	complex hyper matrices
PNL_TYPE_BASIS	bases
PNL_TYPE_RNG	random number generators
PNL_TYPE_LIST	doubly linked list
PNL_TYPE_ARRAY	array

Table 1: PnlTypes

- **PNL_SP_MAT_OBJECT** (o)
  Description Cast any object into a PnlSpMatObject
- **PNL_HMAT_OBJECT** (o)
  Description Cast any object into a PnlHmatObject
- **PNL_BAND_MAT_OBJECT** (o)
  Description Cast any object into a PnlBandMatObject
- **PNL_TRIDIAGMAT_OBJECT** (o)
  Description Cast any object into a PnlTridiagMatObject
- **PNL_BASIS_OBJECT** (o)
  Description Cast any object into a PnlBasis
- **PNL_RNG_OBJECT** (o)
  Description Cast any object into a PnlRng
- **PNL_LIST_OBJECT** (o)
  Description Cast any object into a PnlList
- **PNL_LIST_ARRAY** (o)
  Description Cast any object into a PnlArray
- **PNL_GET_TYPENAME** (o)
  Description Return the name of the type of any object inheriting from PnlObject
- **PNL_GET_TYPE** (o)
  Description Return the type of any object inheriting from PnlObject
- **PNL_GET_PARENT_TYPE** (o)
  Description Return the parent type of any object inheriting from PnlObject
- PnlObject ∗ **pnl_object_create** (PnlType t)
  Description Create an empty PnlObject of type `t` which can any of the registered types, see Table 1.

2.2 List object

This section describes functions for creating an manipulating lists. Lists are internally stored as doubly linked lists.
The structures and functions related to lists are declared in `pnl/pnl_list.h`.

```
typedef struct _PnlCell PnlCell;
struct _PnlCell
{
  struct _PnlCell *prev;  /*!< previous cell or 0 */
  struct _PnlCell *next;  /*!< next cell or 0 */
  PnlObject *self;       /*!< stored object */
};
```

```
typedef struct _PnlList PnlList;
struct _PnlList
{
  /**
   * Must be the first element in order for the object mechanism to work
   * properly. This allows any PnlList pointer to be cast to a PnlObject
   */
  PnlObject object;
  PnlCell *first; /*!< first element of the list */
  PnlCell *last; /*!< last element of the list */
  PnlCell *curcell; /*!< last accessed element,
                       if never accessed is NULL */
  int icurcell; /*!< index of the last accessed element,
                   if never accessed is NULLINT */
  int len; /*!< length of the list */
};
```

Important note: Lists only store addresses of objects. So when an object is inserted into a list, only its address is stored into the list. This implies that you **must not** free any objects inserted into a list. The deallocation is automatically handled by the function pnl_list_free.

- PnlList ∗ **pnl_list_new** ()
  Description Create an empty list
- PnlCell ∗ **pnl_cell_new** ()
  Description Create an cell list
- PnlList ∗ **pnl_list_copy** (const PnlList ∗A)
  Description Create a copy of a PnlList . Each element of the list `A` is copied by calling the its copy member.
- void **pnl_list_clone** (PnlList ∗dest, const PnlList ∗src)
  Description Copy the content of `src` into the already existing list `dest`. The list `dest` is automatically resized. This is a hard copy, the contents of both lists are independent after cloning.
- void **pnl_list_free** (PnlList ∗∗L)
  Description Free a list
- void **pnl_cell_free** (PnlCell ∗∗c)
  Description Free a list
- PnlObject ∗ **pnl_list_get** (PnlList ∗L, int i)
  Description This function returns the content of the `i`–th cell of the list `L`. This function is optimized for linearly accessing all the elements, so it can be used inside a for loop for instance.
- void **pnl_list_insert_first** (PnlList ∗L, PnlObject ∗o)
  Description Insert the object `o` on top of the list `L`. Note that `o` is not copied in `L`, so do **not** free `o` yourself, it will be done automatically when calling pnl_list_free

- void **pnl_list_insert_last** (PnlList ∗L, PnlObject ∗o)
  Description Insert the object `o` at the bottom of the list `L`. Note that `o` is not copied in `L`, so do **not** free `o` yourself, it will be done automatically when calling pnl_list_free

- void **pnl_list_remove_last** (PnlList ∗L)
  Description Remove the last element of the list `L` and frees it.

- void **pnl_list_remove_first** (PnlList ∗L)
  Description Remove the first element of the list `L` and frees it.

- void **pnl_list_remove_i** (PnlList ∗L, int i)
  Description Remove the `i-th` element of the list `L` and frees it.

- void **pnl_list_concat** (PnlList ∗L1, PnlList ∗L2)
  Description Concatenate the two lists `L1` and `L2`. The resulting list is store in `L1` on exit. Do **not** free `L2` since concatenation does not actually copy objects but only manipulates addresses.

- void **pnl_list_resize** (PnlList ∗L, int n)
  Description Change the length of `L` to become `n`. If the length of `L` id increased, the extra elements are set to NULL.

- void **pnl_list_print** (const PnlList ∗L)
  Description Only prints the types of each element. When the PnlObject object has a print member, we will use it.

2.3 Array object

This section describes functions for creating and manipulating arrays of PnlObjects.
The structures and functions related to arrays are declared in `pnl/pnl_array.h`.

```
typedef struct _PnlArray PnlArray;
struct _PnlArray
{
  /**
   * Must be the first element in order for the object mechanism to work
   * properly. This allows any PnlArray pointer to be cast to a PnlObject
   */
  PnlObject object;
  int size;
  PnlObject **array;
  int mem_size;
};
```

Important note: Arrays only store addresses of objects. So when an object is inserted into an array, only its address is stored into the array. This implies that you **must not** free any objects inserted into a array. The deallocation is automatically handled by the function pnl_array_free.

- PnlArray * **pnl_array_new** ()
  Description Create an empty array

- PnlArray * **pnl_array_create** (int n)
  Description Create an array of length `n`.

- PnlArray * **pnl_array_copy** (const PnlArray *A)
  Description Create a copy of a PnlArray . Each element of the array `A` is copied by calling the `A[i].object.copy`.

- void **pnl_array_clone** (PnlArray *dest, const PnlArray *src)
  Description Copy the content of `src` into the already existing array `dest`. The array `dest` is automatically resized. This is a hard copy, the contents of both arrays are independent after cloning.

- void **pnl_array_free** (PnlArray **)
  Description Free an array and all the objects hold by the array.

- int **pnl_array_resize** (PnlArray *T, int size)
  Description Resize `T` to be `size` long. As much as possible of the original data is kept.

- PnlObject * **pnl_array_get** (PnlArray *T, int i)
  Description This function returns the content of the `i`–th cell of the array `T`. No copy is made.

- PnlObject * **pnl_array_set** (PnlArray *T, int i, PnlObject *O)
  Description `T[i] = O`. No copy is made, so the object `O` must not be freed manually.

- void **pnl_array_print** (PnlArray *)
  Description Not yet implemented because it would require that the structure PnlObject has a field copy.

3 Mathematical framework

3.1 General tools

The macros and functions of this paragraph are defined in `pnl/pnl_mathtools.h`.

3.1.1 Constants

A few mathematical constants are provided by the library. Most of them are actually already defined in `math.h`, `values.h` or `limits.h` and a few others have been added.

M_E	e^1
M_LOG2E	$\log_2 e$
M_LOG10E	$\log_{10} e$
M_LN2	$\log_e 2$
M_LN10	$\log_e 10$
M_PI	π
M_2PI	2π
M_PI_2	$\pi/2$
M_PI_4	$\pi/4$
M_1_PI	$1/\pi$
M_2_PI	$2/\pi$
M_2_SQRTPI	$2/\sqrt{\pi}$
M_SQRT2PI	$sqrt 2\pi$
M_SQRT2	$\sqrt{2}$
M_EULER	$\gamma = \lim_{n\to\infty} \left(\sum_{k=1}^{n} \frac{1}{k} - \ln(n)\right)$
M_SQRT1_2	$1/\sqrt{2}$
M_1_SQRT2PI	$1/\sqrt{2\pi}$
M_SQRT2_PI	$\sqrt{2/\pi}$
INT_MAX	2147483647
MAX_INT	INT_MAX
DBL_MAX	$1.79769313486231470e+308$
DOUBLE_MAX	DBL_MAX
DBL_EPSILON	$2.2204460492503131e-16$
PNL_NEGINF	$-\infty$
PNL_POSINF	$+\infty$
PNL_INF	$+\infty$
NAN	Not a Number

3.1.2 A few macros

- **PNL_IS_ODD** (int n)
  Description Return 1 if `n` is odd and 0 otherwise.
- **PNL_IS_EVEN** (int n)
  Description Return 1 if `n` is even and 0 otherwise.
- **PNL_ALTERNATE** (int n)
  Description Return $(-1)^{\mathtt{n}}$.
- **MIN** (x,y)
  Description Return the minimum of `x` and `y`.
- **MAX** (x,y)
  Description Return the maximum of `x` and `y`.
- **ABS** (x)
  Description Return the absolute value of `x`.
- **PNL_SIGN** (x)
  Description Return the sign of `x` (-1 if x $<$ 0, 0 otheriwse).

- **SQR** (x)
  Description Return x^2.

- **CUB** (x)
  Description Return x^3.

3.1.3 Functions

- double **pnl_nan** ()
  Description Return `NaN`

- double **pnl_posinf** ()
  Description Return `+ infinity`

- double **pnl_neginf** ()
  Description Return `- infinity`

- int **pnl_isnan** (double x)
  Description Return `+1` if `x=NaN`

- int **pnl_isinf** (double x)
  Description Return `+1` if `x=+Inf`, `-1` if `x=-Inf` and `0` otherwise.

- int **pnl_isfinite** (double x)
  Description Return `1` if `x!=+-Inf`

- int **pnl_itrunc** (double s)
  Description This function is similar to the `trunc` function (provided by the C library) but the result is typed as an integer instead of a double. Digits may be lost if `s` exceeds `MAX_INT`.

- long int **pnl_ltrunc** (double s)
  Description This function is similar to the `trunc` function (provided by the C library) but the result is typed as a long integer instead of a double.

- double **pnl_trunc** (double s)
  Description Return the nearest integer not greater than the absolute value of `s`. This function is part of C99 as `trunc`.

- double **pnl_round** (double s)
  Description Return the integral value nearest to x rounding half-way cases away from zero, regardless of the current rounding direction. This function is part of C99 as `round`.

- int **pnl_iround** (double s)
  Description This function is similar to the `round` function (provided by the C library) but the result is typed as an integer instead of a double. Digits may be lost if `s` exceeds `MAX_INT`.

- long int **pnl_lround** (double s)
  Description This function is similar to the `round` function (provided by the C library) but the result is typed as a long integer instead of a double.

- double **pnl_fact** (double x)
  Description See pnl_sf_fact

- double **pnl_lgamma** (double x)
  Description See pnl_sf_log_gamma

- double **pnl_tgamma** (double x)
  Description See pnl_sf_gamma

- double **pnl_acosh** (double x)
  Description Compute `acosh(x)`.

- double **pnl_asinh** (double x)
  Description Compute `asinh(x)`.

- double **pnl_atanh** (double x)
  Description Compute `atanh(x)`.

- double **pnl_log1p** (double x)
  Description Compute `log(1+x)` accurately for small values of `x`

- double **pnl_expm1** (double x)
  Description Compute `exp(x)-1` accurately for small values of `x`

- double **pnl_cosm1** (double x)
  Description Compute `cos(x)-1` accurately for small values of `x`

- double **pnl_pow_i** (double x, int n)
  Description Compute `x^n` for an integer `n`.

3.2 Complex numbers

3.2.1 Overview

The complex type and related functions are defined in the header `pnl/pnl_complex.h`.

The first native implementation of complex numbers in the C language appeared in C99, which is unfortunately not available on all platforms. For this reason, we provide here an implementation of complex numbers.

```
typedef struct {
    double r; /*!< real part */
    double i; /*!< imaginary part */
} dcomplex;
```

3.2.2 Constants

CZERO	0 as a complex number
CONE	1 as a complex number
CI	I the unit complex number

3.2.3 Functions

- double, double **CMPLX** (dcomplex z)
  Description `z.r, z.i`

- dcomplex **Complex** (double x, double y)
  Description `x + i y`

- dcomplex **Complex_polar** (double r, double theta)
  Description `r exp(i theta)`

- double **Creal** (dcomplex z)
  Description $\mathrm{R}(z)$

- double **Cimag** (dcomplex z)
  Description $\mathrm{Im}(z)$

- dcomplex **Cadd** (dcomplex z, dcomplex b)
  Description `z+b`

- dcomplex **CRadd** (dcomplex z, double b)
  Description `z+b`

- dcomplex **RCadd** (double b, dcomplex z)
  Description `b+z`

- dcomplex **Csub** (dcomplex z, dcomplex b)
  Description `z-b`

- dcomplex **CRsub** (dcomplex z, double b)
  Description `z-b`

- dcomplex **RCsub** (double b, dcomplex z)
  Description `b-z`

- dcomplex **Cminus** (dcomplex z)
  Description `-z`

- dcomplex **Cmul** (dcomplex z, dcomplex b)
  Description `z*b`

- dcomplex **RCmul** (double x, dcomplex z)
  Description `x*z`

- dcomplex **CRmul** (dcomplex z, double x)
  Description `z * x`

- dcomplex **CRdiv** (dcomplex z, double x)
  Description `z/x`

- dcomplex **RCdiv** (double x, dcomplex z)
  Description `x/z`

- dcomplex **Conj** (dcomplex z)
  Description $\overline{z}$

- dcomplex **Cinv** (dcomplex z)
  Description `1/z`

- dcomplex **Cdiv** (dcomplex z, dcomplex w)
  Description `z/w`

- double **Csqr_norm** (dcomplex z)
  Description $\mathrm{Re}(z)^2 + \mathrm{im}(z)^2$

- double **Cabs** (dcomplex z)
  Description `|z|`

- dcomplex **Csqrt** (dcomplex z)
  Description `sqrt(z)` , square root (with positive real part)

- dcomplex **Clog** (dcomplex z)
  Description `log(z)`

- dcomplex **Cexp** (dcomplex z)
  Description `exp(z)`

- dcomplex **CIexp** (double t)
  Description `exp( it )`

- dcomplex **Cpow** (dcomplex z, dcomplex w)
  Description z^w, power function

- dcomplex **Cpow_real** (dcomplex z, double x)
  Description z^x, power function

- dcomplex **Ccos** (dcomplex z)
  Description `cos(g)`

- dcomplex **Csin** (dcomplex z)
  Description `sin(g)`

- dcomplex **Ctan** (dcomplex z)
  Description `tan(z)`

- dcomplex **Ccotan** (dcomplex z)
  Description `cotan(z)`

- dcomplex **Ccosh** (dcomplex z)
  Description `cosh(g)`

- dcomplex **Csinh** (dcomplex z)
  Description `sinh(g)`

- dcomplex **Ctanh** (dcomplex z)
  Description $\tanh(z) = \frac{1-\mathrm{e}^{-2z}}{1+\mathrm{e}^{-2z}}$

- dcomplex **Ccotanh** (dcomplex z)
  Description $\text{cotanh}(z) = \frac{1+e^{-2z}}{1-e^{-2z}}$
- double **Carg** (dcomplex z)
  Description `arg(z)`
- dcomplex **Ctgamma** (dcomplex z)
  Description `Gamma(z)`, the Gamma function
- dcomplex **Clgamma** (dcomplex z)
  Description `log(Gamma (z))`, the logarithm of the Gamma function
- void **Cprintf** (dcomplex z)
  Description Print a complex number on the standard output

Most algebraic operations on complex numbers are implemented using the following naming for the functions

- All these function names begin in `C_op_`,
- The small letters `a, b` denote two complex numbers whereas `d` is a real number,
- The letter `i` denotes the multiplication by the pure imagniary number $\imath$,
- The letter `c` indicates that the next coming number is conjugated.
- The letters `p, m` denote the two standard operations *plus* and *minus* respectively.

For example C_op_idamcb is $\imath d\left(a - \bar{b}\right)$. So functions are :

- dcomplex **C_op_apib** (dcomplex a, dcomplex b)
  Description $a + \imath b$.
- dcomplex **C_op_apcb** (dcomplex a, dcomplex b)
  Description $a + \bar{b}$.
- dcomplex **C_op_amcb** (dcomplex a, dcomplex b)
  Description $a - \bar{b}$.
- dcomplex **C_op_amib** (dcomplex a, dcomplex b)
  Description `a - i b`
- dcomplex **C_op_dapb** (double d, dcomplex a, dcomplex b)
  Description $d(a + b)$.
- dcomplex **C_op_damb** (double d, dcomplex a, dcomplex b)
  Description $d(a - b)$.
- dcomplex **C_op_dapib** (double d, dcomplex a, dcomplex b)
  Description $d(a + \imath b)$.
- dcomplex **C_op_damib** (double d, dcomplex a, dcomplex b)
  Description $d(a - \imath b)$.

- dcomplex **C_op_dapcb** (double d, dcomplex a, dcomplex b)
  Description $d\left(a+\bar{b}\right)$.

- dcomplex **C_op_damcb** (double d, dcomplex a, dcomplex b)
  Description $d\left(a-\bar{b}\right)$.

- dcomplex **C_op_idapb** (double d, dcomplex a, dcomplex b)
  Description $\imath d\left(a+b\right)$.

- dcomplex **C_op_idamb** (double d, dcomplex a, dcomplex b)
  Description $\imath d\left(a-b\right)$.

- dcomplex **C_op_idapcb** (double d, dcomplex a, dcomplex b)
  Description $\imath d\left(a+\bar{b}\right)$.

- dcomplex **C_op_idamcb** (double d, dcomplex a, dcomplex b)
  Description $\imath d\left(a-\bar{b}\right)$.

4 Linear Algebra

4.1 Vectors

4.1.1 Overview

The structures and functions related to vectors are declared in `pnl/pnl_vector.h`. Vectors are declared for several basic types : double, int, and dcomplex. In the following declarations, `BASE` must be replaced by one the previous types and the corresponding vector structures are respectively named PnlVect, PnlVectInt, PnlVectComplex

```
typedef struct _PnlVect {
  /**
   * Must be the first element in order for the object mechanism to work
   * properly. This allows any PnlVect pointer to be cast to a PnlObject
   */
  PnlObject object;
  int size; /*!< size of the vector */
  int mem_size; /*!< size of the memory block allocated for array */
  double *array; /*!< pointer to store the data */
  int owner; /*!< 1 if the object owns its array member, 0 otherwise */
} PnlVect;

typedef struct _PnlVectInt {
  /**
   * Must be the first element in order for the object mechanism to work
   * properly. This allows any PnlVectInt pointer to be cast to a PnlObject
   */
  PnlObject object;
  int size; /*!< size of the vector */
```

```
  int mem_size; /*!< size of the memory block allocated for array */
  int *array; /*!< pointer to store the data */
  int owner; /*!< 1 if the object owns its array member, 0 otherwise */
} PnlVectInt;

typedef struct _PnlVectComplex {
  /**
   * Must be the first element in order for the object mechanism to work
   * properly. This allows any PnlVectComplex pointer to be cast
   * to a PnlObject
   */
  PnlObject object;
  int size; /*!< size of the vector */
  int mem_size; /*!< size of the memory block allocated for array */
  dcomplex *array; /*!< pointer to store the data */
  int owner; /*!< 1 if the object owns its array member, 0 otherwise */
} PnlVectComplex;
```

`size` is the size of the vector, `array` is a pointer containing the data and `owner` is an integer to know if the vector owns its `array` pointer (`owner=1`) or shares it with another structure (`owner=0`). `mem_size` is the number of elements the vector can hold at most.

4.1.2 Functions

General functions These functions exist for all types of vector no matter what the basic type is. The following conventions are used to name functions operating on vectors. Here is the table of prefixes used for the different basic types.

type	prefix	BASE
double	pnl_vect	double
int	pnl_vect_int	int
dcomplex	pnl_vect_complex	dcomplex

In this paragraph, we present the functions operating on PnlVect which exist for all types. To deduce the prototypes of these functions for other basic types, one must replace `pnl_vect` and `double` according the above table.

Constructors and destructors There are no special functions to access the size of a vector, instead the field `size` should be accessed directly.

- PnlVect $*$ **pnl_vect_new** ()
  Description Create a new PnlVect of size 0.

- PnlVect $*$ **pnl_vect_create** (int size)
  Description Create a new PnlVect pointer.

- PnlVect $*$ **pnl_vect_create_from_zero** (int size)
  Description Create a new PnlVect pointer and sets it to zero.

- PnlVect * **pnl_vect_create_from_scalar** (int size, double x)
  Description Create a new PnlVect pointer and sets all elements t `x`.

- PnlVect * **pnl_vect_create_from_ptr** (int size, const double *x)
  Description Create a new PnlVect pointer and copies `x` to `array`.

- PnlVect * **pnl_vect_create_from_mat** (const PnlMat *M)
  Description Create a new PnlVect pointer of size `M->mn` and copy the content of `M` row wise.

- PnlVect * **pnl_vect_create_from_list** (int size, ...)
  Description Create a new PnlVect pointer of length `size` filled with the extra arguments passed to the function. The number of extra arguments passed must be equal to `size` and they must be of the type BASE. Example: To create a vector {1., 2.}, you should enter pnl_vect_create_from_list(2, 1.0, 2.0) and NOT pnl_vect_create_from_list(2, 1.0, 2) or pnl_vect_create_from_list(2, 1, 2.0). Be aware that this cannot be checked inside the function.

- PnlVect * **pnl_vect_create_from_file** (const char *file)
  Description Read a vector from a file and creates the corresponding PnlVect . The data might be stored as a single blank separated line or as a one column file with one element per line.

- PnlVect * **pnl_vect_copy** (const PnlVect *v)
  Description This is a copying constructor. It creates a copy of a PnlVect .

- void **pnl_vect_clone** (PnlVect *clone, const PnlVect *v)
  Description Clone a PnlVect . `clone` must be an already existing PnlVect . It is resized to match the size of `v` and the data are copied. Future modifications to `v` will not affect `clone`.

- PnlVect * **pnl_vect_create_subvect_with_ind** (const PnlVect *V, const PnlVectInt *ind)
  Description Create a new vector containing `V(ind(:))`.

- void **pnl_vect_extract_subvect_with_ind** (PnlVect *V_sub, const PnlVect *V, const PnlVectInt *ind)
  Description On exit, `V_sub = V(ind(:))`.

- PnlVect * **pnl_vect_create_subvect** (const PnlVect *V, int i, int len)
  Description Create a new vector containing `V(i:i+len-1)`. The elements are copied.

- void **pnl_vect_extract_subvect** (PnlVect *V_sub, const PnlVect *V, int i, int len)
  Description On exit, `V_sub = V(i:i+len-1)`. The elements are copied.

- void **pnl_vect_free** (PnlVect **v)
  Description Free a PnlVect pointer and set the data pointer to NULL

- PnlVect **pnl_vect_wrap_array** (const double *x, int size)
  Description Create a PnlVect containing the data `x`. No copy is made. It is just a container.

- PnlVect **pnl_vect_wrap_subvect** (const PnlVect *x, int i, int s)
  Description Create a PnlVect containing `x(i:i+s-1)`. No copy is made. It is just a container. The returned PnlVect has `size=s` and `owner=0`.

- PnlVect **pnl_vect_wrap_subvect_with_last** (const PnlVect *x, int i, int j)
  Description Create a PnlVect containing `x(i:j)`. No copy is made. It is just a container.

- PnlVect **pnl_vect_wrap_mat** (const PnlMat *M)
  Description Return a PnlVect (not a pointer) whose array is the row wise array of `M`. The new vector shares its data with the matrix `M`, which means that any modification to one of them will affect the other.

Resizing vectors

- int **pnl_vect_resize** (PnlVect *v, int size)
  Description Resize a PnlVect . It copies as much of the old data to fit in the resized object.

- int **pnl_vect_resize_from_ptr** (PnlVect *v, int size, double *t)
  Description Resize a PnlVect and uses `t` to fill the vector. `t` must be of size `size`.

Accessing elements If it is supported by the compiler, the following functions are declared inline. To speed up these functions, you can define the macro `PNL_RANGE_CHECK_OFF`, see Section 1.3.2 for an explanation.
Accessing elements of a vector is faster using the following macros

- **GET** (PnlVect *v, int i)
  Description Return `v[i]` for reading, eg. `x=GET(v,i)`

- **GET_INT** (PnlVectInt *v, int i)
  Description Same as GET but for an integer vector.

- **GET_COMPLEX** (PnlVectComplex *v, int i)
  Description Same as GET but for a complex vector.

- **LET** (PnlVect *v, int i)
  Description Return `v[i]` as a lvalue for writing, eg. `LET(v,i)=x`

- **LET_INT** (PnlVectInt *v, int i)
  Description Same as LET but for an integer vector.

- **LET_COMPLEX** (PnlVectComplex *v, int i)
  Description Same as LET but for a complex vector.

- void **pnl_vect_set** (PnlVect *v, int i, double x)
  Description Set v[i]=x

- double **pnl_vect_get** (const PnlVect *v, int i)
  Description Return the value of v[i].

- void **pnl_vect_lget** (PnlVect *v, int i)
  Description Return the address of v[i].

- void **pnl_vect_set_all** (PnlVect *v, double x)
  Description Set all elements to x.

- void **pnl_vect_set_zero** (PnlVect *v)
  Description Set all elements to zero.

Printing vector

- void **pnl_vect_print** (const PnlVect *V)
  Description Print a PnlVect as a column vector

- void **pnl_vect_fprint** (FILE *fic, const PnlVect *V)
  Description Print a PnlVect in file `fic` as a column vector.

- void **pnl_vect_print_asrow** (const PnlVect *V)
  Description Print a PnlVect as a row vector

- void **pnl_vect_fprint_asrow** (FILE *fic, const PnlVect *V)
  Description Print a PnlVect in file `fic` as a row vector.

- void **pnl_vect_print_nsp** (const PnlVect *V)
  Description Print a vector to the standard output in a format compatible with Nsp.

- void **pnl_vect_fprint_nsp** (FILE *fic, const PnlVect *V)
  Description Print a vector to a file in a format compatible with Nsp.

Applying external operation to vectors

- void **pnl_vect_minus** (PnlVect *lhs)
  Description In-place unary minus

- void **pnl_vect_plus_scalar** (PnlVect *lhs, double x)
  Description In-place vector scalar addition

- void **pnl_vect_minus_scalar** (PnlVect *lhs, double x)
  Description In-place vector scalar substraction

- void **pnl_vect_mult_scalar** (PnlVect *lhs, double x)
  Description In-place vector scalar multiplication

- void **pnl_vect_div_scalar** (PnlVect *lhs, double x)
  Description In-place vector scalar division

Element wise operations

- void **pnl_vect_plus_vect** (PnlVect *lhs, const PnlVect *rhs)
  Description In-place vector vector addition

- void **pnl_vect_minus_vect** (PnlVect *lhs, const PnlVect *rhs)
  Description In-place vector vector substraction

- void **pnl_vect_inv_term** (PnlVect *lhs)
  Description In-place term by term vector inversion

- void **pnl_vect_div_vect_term** (PnlVect *lhs, const PnlVect *rhs)
  Description In-place term by term vector division

- void **pnl_vect_mult_vect_term** (PnlVect *lhs, const PnlVect *rhs)
  Description In-place vector vector term by term multiplication

- void **pnl_vect_map** (PnlVect *lhs, const PnlVect *rhs, double(*f)(double))
  Description `lhs = f(rhs)`

- void **pnl_vect_map_inplace** (PnlVect *lhs, double(*f)(double))
  Description `lhs = f(lhs)`

- void **pnl_vect_map_vect** (PnlVect *lhs, const PnlVect *rhs1, const PnlVect *rhs2, double(*f)(double, double))
  Description `lhs = f(rhs1, rhs2)`

- void **pnl_vect_map_vect_inplace** (PnlVect *lhs, PnlVect *rhs, double(*f)(double,double))
  Description `lhs = f(lhs,rhs)`

- void **pnl_vect_axpby** (double a, const PnlVect *x, double b, PnlVect *y)
  Description Compute `y : = a x + b y`. When `b==0`, the content of `y` is not used on input and instead `y` is resized to match `x`.

- double **pnl_vect_sum** (const PnlVect *lhs)
  Description Return the sum of all the elements of a vector

- void **pnl_vect_cumsum** (PnlVect *lhs)
  Description Compute the cumulative sum of all the elements of a vector. The original vector is modified

- double **pnl_vect_prod** (const PnlVect *V)
  Description Return the product of all the elements of a vector

- void **pnl_vect_cumprod** (PnlVect *lhs)
  Description Compute the cumulative product of all the elements of a vector. The original vector is modified

Scalar products and norms

- double **pnl_vect_norm_two** (const PnlVect *V)
  Description Return the two norm of a vector

- double **pnl_vect_norm_one** (const PnlVect *V)
  Description Return the one norm of a vector

- double **pnl_vect_norm_infty** (const PnlVect *V)
  Description Return the infinity norm of a vector

- double **pnl_vect_scalar_prod** (const PnlVect *rhs1, const PnlVect *rhs2)
  Description Compute the scalar product between 2 vectors

- int **pnl_vect_cross** (PnlVect *lhs, const PnlVect *x, const PnlVect *y)
  Description Compute the cross product of `x` and `y` and store the result in `lhs`. The vectors `x` and `y` must be of size 3 and FAIL is returned otherwise.

- double **pnl_vect_dist** (const PnlVect *x, const PnlVect *y)
  Description Compute the distance between `x` and `y`, ie $\sqrt{\sum_i |x_i - y_i|^2}$.

Test functions

- int **pnl_vect_eq** (const PnlVect *V1, const PnlVect *V2)
  Description Test if two vectors are equal. Returns `TRUE` or `FALSE`.

- int **pnl_vect_eq_all** (const PnlVect *v, double x)
  Description Test if all the components of `v` are equal to `x`. Returns `TRUE` or `FALSE`.

Ordering functions The following functions are not defined for PnlVectComplex because there is no total ordering on Complex numbers

- double **pnl_vect_max** (const PnlVect *V)
  Description Return the maximum of a a vector

- double **pnl_vect_min** (const PnlVect *V)
  Description Return the minimum of a vector

- void **pnl_vect_minmax** (double *m, double *M, const PnlVect *)
  Description Compute the minimum and maximum of a vector which are returned in `m` and `M` respectively.

- void **pnl_vect_min_index** (double *m, int *im, const PnlVect *)
  Description Compute the minimum of a vector and its index stored in sets `m` and `im` respectively.

- void **pnl_vect_max_index** (double *M, int *iM, const PnlVect *)
  Description Compute the maximum of a vector and its index stored in sets `m` and `im` respectively.

- void **pnl_vect_minmax_index** (double ∗m, double ∗M, int ∗im, int ∗iM, const PnlVect ∗)
  Description Compute the minimum and maximum of a vector and the corresponding indices stored respectively in `m`, `M`, `im` and `iM`.

- void **pnl_vect_qsort** (PnlVect ∗, char order)
  Description Sort a vector using a quick sort algorithm according to `order` (`'i'` for increasing or `'d'` for decreasing).

- void **pnl_vect_qsort_index** (PnlVect ∗, PnlVectInt *index, char order)
  Description Sort a vector using a quick sort algorithm according to `order` (`'i'` for increasing or `'d'` for decreasing). On output, `index` contains the permutation used to sort the vector.

- int **pnl_vect_find** (PnlVectInt ∗ind, char ∗type, int(∗f)(double ∗t), . . .)
  Description `f` is a function taking a C array as argument and returning an integer. `type` is a string composed by the letters 'r' and 'v' and is used to describe the types of the arguments appearing after `f`. This function aims at simulating Scilab's `find` function. Here are a few examples (capital letters are used for vectors and small letters for real values)

  – `ind = find ( a < X )`

  ```
  int isless ( double *t ) { return t[0] < t[1]; }
  pnl_vect_find ( ind, "rv", isless, a, X );
  ```

  – `ind = find (X <= Y)`

  ```
  int isless ( double *t ) { return t[0] <= t[1]; }
  pnl_vect_find ( ind, "vv", isless, X, Y );
  ```

  – `ind = find ((a < X) && (X <= Y))`

  ```
  int cmp ( double *t )
  {
    return (t[0] <= t[1]) && (t[1] <= t[2]);
  }
  pnl_vect_find ( ind, "rvv", cmp, a, X, Y );
  ```

  `ind` contains on exit the indices `i` for which the function `f` returned `1`. This function returns `OK` or `FAIL` when something went wrong (size mismatch between matrices, invalid string type).

Misc

- void **pnl_vect_swap_elements** (PnlVect ∗v, int i, int j)
  Description Exchange `v[i]` and `v[j]`.

- void **pnl_vect_reverse** (PnlVect *v)
  Description Perform a mirror operation on v. On output `v[i] = v[n-1-i]` for `i=0,...,n-1` where `n` is the length of the vector.

Complex vector functions

- void **pnl_vect_complex_mult_double** (PnlVectComplex *lhs, double x)
  Description In-place multiplication by a double.

- PnlVectComplex* **pnl_vect_complex_create_from_array** (int size, const double *re, const double *im)
  Description Create a PnlVectComplex given the arrays of the real parts `re` and imaginary parts `im`.

- void **pnl_vect_complex_split_in_array** (const PnlVectComplex *v, double *re, double *im)
  Description Split a complex vector into two C arrays : the real parts of the elements of `v` are stored into `re` and the imaginary parts into `im`.

- void **pnl_vect_complex_split_in_vect** (const PnlVectComplex *v, PnlVect *re, PnlVect *im)
  Description Split a complex vector into two PnlVect 's : the real parts of the elements of `v` are stored into `re` and the imaginary parts into `im`.

There exist functions to directly access the real or imaginary parts of an element of a complex vector. These functions also have inlined versions that are used if the variable `HAVE_INLINE` was declared at compilation time.

- double **pnl_vect_complex_get_real** (const PnlVectComplex *v, int i)
  Description Return the real part of `v[i]`.

- double **pnl_vect_complex_get_imag** (const PnlVectComplex *v, int i)
  Description Return the imaginary part of `v[i]`.

- double* **pnl_vect_complex_lget_real** (const PnlVectComplex *v, int i)
  Description Return the real part of `v[i]` as a lvalue.

- double* **pnl_vect_complex_lget_imag** (const PnlVectComplex *v, int i)
  Description Return the imaginary part of `v[i]` as a lvalue.

- void **pnl_vect_complex_set_real** (const PnlVectComplex *v, int i, double re)
  Description Set the real part of `v[i]` to `re`.

- void **pnl_vect_complex_set_imag** (const PnlVectComplex *v, int i, double im)
  Description Set the imaginary part of `v[i]` to `im`.

Equivalently to these functions, there exist macros. When the compiler is able to handle inline code, there is no gain in using macros instead of inlined functions at least in principle.

- **GET_REAL** (v, i)
  Description Return the real part of `v[i]`.

- **GET_IMAG** (v, i)
  Description Return the imaginary part of `v[i]`.

- **LET_REAL** (v, i)
  Description Return the real part of `v[i]` as a lvalue.

- **LET_IMAG** (v, i)
  Description Return the imaginary part of `v[i]` as a lvalue.

4.2 Compact Vectors

4.2.1 Short description

```
typedef struct PnlVectCompact {
  /**
   * Must be the first element in order for the object mechanism to work
   * properly. This allows any PnlVectCompact pointer to be cast to a PnlObject
   */
  PnlObject object;
  int size; /* size of the vector */
  double val; /* single value */
  double *array; /* Pointer to double values */
  char convert; /* 'a', 'd' : array, double */
} PnlVectCompact;
```

4.2.2 Functions

- PnlVectCompact ∗ **pnl_vect_compact_new** ()
  Description Create a PnlVectCompact of size 0.

- PnlVectCompact ∗ **pnl_vect_compact_create** (int n, double x)
  Description Create a PnlVectCompact filled in with `x`

- PnlVectCompact ∗ **pnl_vect_compact_create_from_ptr** (int n, double *x)
  Description Create a PnlVectCompact filled in with the content of `x`. Note that `x` must have at least `n` elements.

- int **pnl_vect_compact_resize** (PnlVectCompact ∗v, int size, double x)
  Description Resize a PnlVectCompact .

- PnlVectCompact ∗ **pnl_vect_compact_copy** (const PnlVectCompact ∗v)
  Description Copy a PnlVectCompact

- void **pnl_vect_compact_free** (PnlVectCompact ∗∗v)
  Description Free a PnlVectCompact

- PnlVect ∗ **pnl_vect_compact_to_pnl_vect** (const PnlVectCompact ∗C)
  Description Convert a PnlVectCompact pointer to a PnlVect pointer.

- double **pnl_vect_compact_get** (const PnlVectCompact ∗C, int i)
  Description Access function

- void **pnl_vect_compact_set_all** (PnlVectCompact *C, double x)
  Description Set all elements of `C` to `x`. `C` is converted to a compact storage.

- void **pnl_vect_compact_set_ptr** (PnlVectCompact *C, double *ptr)
  Description Copy the array `ptr` into `C`. We assume that the sizes match. `C` is converted to a non compact storage.

4.3 Matrices

4.3.1 Overview

The structures and functions related to matrices are declared in `pnl/pnl_matrix.h`.

```
typedef struct _PnlMat{
  /**
   * Must be the first element in order for the object mechanism to work
   * properly. This allows any PnlMat pointer to be cast to a PnlObject
   */
  PnlObject object;
  int m; /*!< nb rows */
  int n; /*!< nb columns */
  int mn; /*!< product m*n */
  int mem_size; /*!< size of the memory block allocated for array */
  double *array; /*!< pointer to store the data row-wise */
  int owner; /*!< 1 if the object owns its array member, 0 otherwise */
} PnlMat;

typedef struct _PnlMatInt{
  /**
   * Must be the first element in order for the object mechanism to work
   * properly. This allows any PnlMatInt pointer to be cast to a PnlObject
   */
  PnlObject object;
  int m; /*!< nb rows */
  int n; /*!< nb columns */
  int mn; /*!< product m*n */
  int mem_size; /*!< size of the memory block allocated for array */
  int *array; /*!< pointer to store the data row-wise */
  int owner; /*!< 1 if the object owns its array member, 0 otherwise */
} PnlMatInt;

typedef struct _PnlMatComplex{
  /**
   * Must be the first element in order for the object mechanism to work
   * properly. This allows any PnlMatComplex pointer to be cast
   * to a PnlObject
   */
  PnlObject object;
```

```
  int m; /*!< nb rows */
  int n; /*!< nb columns */
  int mn; /*!< product m*n */
  int mem_size; /*!< size of the memory block allocated for array */
  dcomplex *array; /*!< pointer to store the data row-wise */
  int owner; /*!< 1 if the object owns its array member, 0 otherwise */
} PnlMatComplex;
```

`m` is the number of rows, `n` is the number of columns. `array` is a pointer containing the data of the matrix stored line wise, The element `(i, j)` of the matrix is `array[i*m+j]`. `owner` is an integer to know if the matrix owns its `array` pointer (`owner=1`) or shares it with another structure (`owner=0`). `mem_size` is the number of elements the matrix can hold at most.
The following operations are implemented on matrices and vectors. `alpha` and `beta` are numbers, `A` and `B` are matrices and `x` and `y` are vectors.

pnl_mat_axpy	`B := alpha * A + B`
pnl_mat_scalar_prod	`x' A y`
pnl_mat_dgemm	`C := alpha * op (A) * op (B) + beta * C`
pnl_mat_mult_vect_transpose_inplace	`y = A' * x`
pnl_mat_mult_vect_inplace	`y = A * x`
pnl_mat_lAxpby	`y := lambda * A * x + beta * y`
pnl_mat_dgemv	`y := alpha * op (A) * x + beta * y`
pnl_mat_dger	`A := alpha x * y' + A`

4.3.2 Generic Functions

These functions exist for all types of matrices no matter what the basic type is. The following conventions are used to name functions operating on matrices. Here is the table of prefixes used for the different basic types.

type	prefix	BASE
double	pnl_mat	double
int	pnl_mat_int	int
dcomplex	pnl_mat_complex	dcomplex

In this paragraph we present the functions operating on PnlMat which exist for all types. To deduce the prototypes of these functions for other basic types, one must replace `pnl_mat` and `double` according the above table.

Constructors and destructors There are no special functions to access the sizes of a matrix, instead the fields `m`, `n` and `mn` give direct access to the number of rows, columns and the size of the matrix.

- PnlMat ∗ **pnl_mat_new** ()
  Description Create a PnlMat of size 0
- PnlMat ∗ **pnl_mat_create** (int m, int n)
  Description Create a PnlMat with `m` rows and `n` columns.

- PnlMat ∗ **pnl_mat_create_from_scalar** (int m, int n, double x)
Description Create a PnlMat with `m` rows and `n` columns and sets all the elements to `x`.

- PnlMat ∗ **pnl_mat_create_from_zero** (int m, int n)
Description Create a PnlMat with `m` rows and `n` columns and sets all elements to 0.

- PnlMat ∗ **pnl_mat_create_from_ptr** (int m, int n, const double ∗x)
Description Create a PnlMat with `m` rows and `n` columns and copies the array `x` to the new vector. Be sure that `x` is long enough to fill all the vector because it cannot be checked inside the function.

- PnlMat ∗ **pnl_mat_create_from_list** (int m, int n, ...)
Description Create a new PnlMat pointer of size `m x n` filled with the extra arguments passed to the function. The number of extra arguments passed must be equal to `m x n`, be aware that this cannot be checked inside the function.

- PnlMat ∗ **pnl_mat_copy** (const PnlMat ∗M)
Description Create a new PnlMat which is a copy of `M`.

- PnlMat ∗ **pnl_mat_create_diag_from_ptr** (const double ∗x, int d)
Description Create a new squared PnlMat by specifying its size and diagonal terms as an array.

- PnlMat ∗ **pnl_mat_create_diag** (const PnlVect ∗V)
Description Create a new squared PnlMat by specifying its diagonal terms in a PnlVect .

- PnlMat ∗ **pnl_mat_create_from_file** (const char ∗file)
Description Read a matrix from a file and creates the corresponding PnlMat . The following conventions are used for the storage in a file:
  - one row of the matrix corresponds to one line of the file
  - the elements of a row should be separated by blanks (spaces or tabs) and nothing else (no comma or semi-colon separators are detected).

- void **pnl_mat_free** (PnlMat ∗∗M)
Description Free a PnlMat and sets `*M` to `NULL`

- PnlMat **pnl_mat_wrap_array** (const double ∗x, int m, int n)
Description Create a PnlMat of size `m x n` which contains `x`. No copy is made. It is just a container.

- PnlMat **pnl_mat_wrap_vect** (const PnlVect ∗V)
Description Return a PnlMat (not a pointer) whose array is the array of `V`. The new matrix shares its data with the vector `V`, which means that any modification to one of them will affect the other.

- void **pnl_mat_clone** (PnlMat ∗clone, const PnlMat ∗M)
Description Clone `M` into `clone`. No no new PnlMat is created.

- int **pnl_mat_resize** (PnlMat ∗M, int m, int n)
Description Resize a PnlMat . The new matrix is of size `m x n`. The old data are lost.

- PnlVect * **pnl_vect_create_submat** (const PnlMat *M, const PnlVectInt *indi, const PnlVectInt *indj)
  Description Create a new vector containing the values `M(indi(:), indj(:))`. `indi` and `indj` must be of the same size.

- void **pnl_vect_extract_submat** (PnlVect *V_sub, const PnlMat *M, const PnlVectInt *indi, const PnlVectInt *indj)
  Description On exit, `V_sub = M(indi(:), indj(:))`. `indi` and `indj` must be of the same size.

- void **pnl_mat_extract_subblock** (PnlMat *M_sub, const PnlMat *M, int i, int len_i, int j, int len_j)
  Description `M_sub = M(i:i+len_i-1, j:j+len_j-1)`. `len_i` (resp. `len_j`) is the number of rows (resp. columns) to be extracted.

- void **pnl_mat_set_subblock** (PnlMat *M, const PnlMat *block, int i, int j)
  Description If `block` is a matrix of size `m_block x n_block`, the dimensions of `M` must satisfy that `M->m >= i + m_block` and `M->n >= j + n_block`. On output `M(i:i+m_block-1, j:j+n_block-1) = block`.

Accessing elements. If it is supported by the compiler, the following functions are declared inline. To speed up these functions, you can define the macro `PNL_RANGE_CHECK_OFF`, see Section 1.3.2 for an explanation.
Accessing elements of a matrix is faster using the following macros

- **MGET** (PnlMat *M, int i, int j)
  Description Return `M[i,j]` for reading, eg. `x=MGET(M,i,j)`

- **MGET_INT** (PnlMatInt *M, int i, int j)
  Description Same as MGET but for an integer matrix.

- **MGET_COMPLEX** (PnlMatComplex *M, int i, int j)
  Description Same as MGET but for a complex matrix.

- **MLET** (PnlMat *M, int i, int j)
  Description Return `M[i,j]` as a lvalue for writing, eg. `MLET(M,i,j)=x`

- **MLET_INT** (PnlMatInt *M, int i, int j)
  Description Same as MLET but for an integer matrix.

- **MLET_COMPLEX** (PnlMatComplex *M, int i, int j)
  Description Same as MLET but for a complex matrix.

- void **pnl_mat_set** (PnlMat *M, int i, int j, double x)
  Description Set the value of M[i, j]=x

- double **pnl_mat_get** (const PnlMat *M, int i, int j)
  Description Get the value of M[i, j]

- double * **pnl_mat_lget** (PnlMat *M, int i, int j)
  Description Return the address of M[i, j] for use as a lvalue.

- void **pnl_mat_set_all** (PnlMat *M, double x)
Description Set all elements of `M` to `x`.

- void **pnl_mat_set_zero** (PnlMat *M)
Description Set all elements of `M` to `0`.

- void **pnl_mat_set_id** (PnlMat *M)
Description Set the matrix `M` to the identity matrix. `M` must be a square matrix.

- void **pnl_mat_set_diag** (PnlMat *M, double x, int d)
Description Set the `d`$^{\text{th}}$ diagonal terms of the matrix `M` to the value `x`. `M` must be a square matrix.

- void **pnl_mat_set_from_ptr** (PnlMat *M, const double *x)
Description Set `M` row–wise with the values given by `x`. The array `x` must be at least M->mn long.

- void **pnl_mat_get_row** (PnlVect *V, const PnlMat *M, int i)
Description Extract and copies the `i`-th row of `M` into `V`.

- void **pnl_mat_get_col** (PnlVect *V, const PnlMat *M, int j)
Description Extract and copies the `j`-th column of `M` into `V`.

- PnlVect **pnl_vect_wrap_mat_row** (const PnlMat *M, int i)
Description Return a PnlVect (not a pointer) whose array is the `i`-th row of `M`. The new vector shares its data with the matrix `M`, which means that any modification to one of them will affect the other.

- PnlMat **pnl_mat_wrap_mat_rows** (const PnlMat *M, int i_start, int i_end)
Description Return a PnlMat (not a pointer) holding rows from `i_start` to `i_end` (included) of `M`. The new matrix shares its data with the matrix `M`, which means that any modification to one of them will affect the other.

- void **pnl_mat_swap_rows** (PnlMat *M, int i, int j)
Description Swap two rows of a matrix.

- void **pnl_mat_set_col** (PnlMat *M, const PnlVect *V, int j)
Description Replace the `i`-th column of a matrix M by a vector V

- void **pnl_mat_set_row** (PnlMat *M, const PnlVect *V, int i)
Description Replace the `i`-th row of a matrix M by a vector V

- void **pnl_mat_add_row** (PnlMat *M, int i, const PnlVect *r)
Description Add a row in matrix `M` before position `i` and fill it with the content of `r`. If `r == NULL`, row `i` is left uninitialized. The index `i` may vary between `0` — add a row at the top of the matrix — and `M->m` — add a row after all rows.

- void **pnl_mat_del_row** (PnlMat *M, int i)
Description Delete the row with index `i` (between `0` and `M->m-1`) of the matrix `M`.

Printing Matrices

- void **pnl_mat_print** (const PnlMat *M)
  Description Print a matrix to the standard output.

- void **pnl_mat_fprint** (FILE *fic, const PnlMat *M)
  Description Print a matrix to a file.

- void **pnl_mat_print_nsp** (const PnlMat *M)
  Description Print a matrix to the standard output in a format compatible with Nsp.

- void **pnl_mat_fprint_nsp** (FILE *fic, const PnlMat *M)
  Description Print a matrix to a file in a format compatible with Nsp. The saved matrix can be reloaded by the function pnl_mat_create_from_file.

Applying external operations

- void **pnl_mat_plus_scalar** (PnlMat *lhs, double x)
  Description In-place matrix scalar addition

- void **pnl_mat_minus_scalar** (PnlMat *lhs, double x)
  Description In-place matrix scalar substraction

- void **pnl_mat_mult_scalar** (PnlMat *lhs, double x)
  Description In-place matrix scalar multiplication

- void **pnl_mat_div_scalar** (PnlMat *lhs, double x)
  Description In-place matrix scalar division

Element wise operations

- void **pnl_mat_mult_mat_term** (PnlMat *lhs, const PnlMat *rhs)
  Description In-place matrix matrix term by term product

- void **pnl_mat_div_mat_term** (PnlMat *lhs, const PnlMat *rhs)
  Description In-place matrix matrix term by term division

- void **pnl_mat_map_inplace** (PnlMat *lhs, double(*f)(double))
  Description `lhs = f(lhs)`.

- void **pnl_mat_map** (PnlMat *lhs, const PnlMat *rhs, double(*f)(double))
  Description `lhs = f(rhs)`.

- void **pnl_mat_map_mat_inplace** (PnlMat *lhs, const PnlMat *rhs, double(*f)(double, double))
  Description `lhs = f(lhs, rhs)`.

- void **pnl_mat_map_mat** (PnlMat *lhs, const PnlMat *rhs1, const PnlMat *rhs2, double(*f)(double, double))
  Description `lhs = f(rhs1, rhs2)`.

- double **pnl_mat_sum** (const PnlMat *lhs)
  Description Sum matrix component-wise

- void **pnl_mat_sum_vect** (PnlVect *y, const PnlMat *A, char c)
  Description Sum matrix column or row wise. Argument `c` can be either 'r' (to get a row vector) or 'c' (to get a column vector). When `c='r'`, $y(j) = \sum_i A_{ij}$ and when `c='rc`, $y(i) = \sum_j A_{ij}$.

- void **pnl_mat_cumsum** (PnlMat *A, char c)
  Description Cumulative sum over the rows or columns. Argument `c` can be either 'r' to sum over the rows or 'c' to sum over the columns. When `c='r'`, $A_{ij} = \sum_{1 \le k \le i} A_{kj}$ and when `c='rc`, $A_{ij} = \sum_{1 \le k \le j} A_{ik}$.

- double **pnl_mat_prod** (const PnlMat *lhs)
  Description Product matrix component-wise

- void **pnl_mat_prod_vect** (PnlVect *y, const PnlMat *A, char c)
  Description Prod matrix column or row wise. Argument `c` can be either 'r' (to get a row vector) or 'c' (to get a column vector). When `c='r'`, $y(j) = \prod_i A_{ij}$ and when `c='rc`, $y(i) = \prod_j A_{ij}$.

- void **pnl_mat_cumprod** (PnlMat *A, char c)
  Description Cumulative prod over the rows or columns. Argument `c` can be either 'r' to prod over the rows or 'c' to prod over the columns. When `c='r'`, $A_{ij} = \prod_{1 \le k \le i} A_{kj}$ and when `c='rc`, $A_{ij} = \prod_{1 \le k \le j} A_{ik}$.

Test functions

- int **pnl_mat_eq** (const PnlMat *M1, const PnlMat *M2)
  Description Test if two matrices are equal. Returns `TRUE` or `FALSE`.

- int **pnl_mat_eq_all** (const PnlMat *M, double x)
  Description Test if all the components of `M` are equal to `x`. Returns `TRUE` or `FALSE`.

Ordering operations

- void **pnl_mat_max** (PnlVect *M, const PnlMat *A, char d)
  Description On exit, $\texttt{M}(i) = \max_j(\texttt{A}(i,j))$ when `d='c'` and $\texttt{M}(i) = \max_j(\texttt{A}(j,i))$ when `d='r'` and $\texttt{M}(0) = \max_{i,j} = \texttt{A}(i,j)$ when `d='*'`.

- void **pnl_mat_min** (PnlVect *m,const PnlMat *A, char d)
  Description On exit, $\texttt{m}(i) = \min_j(\texttt{A}(i,j))$ when `d='c'` and $\texttt{m}(i) = \min_j(\texttt{A}(j,i))$ when `d='r'` and $\texttt{M}(0) = \min_{i,j} = \texttt{A}(i,j)$ when `d='*'`.

- void **pnl_mat_minmax** (PnlVect *m, PnlVect *M, const PnlMat *A, char d)
  Description On exit, $\texttt{m}(i) = \min_j(\texttt{A}(i,j))$ and $\texttt{M}(i) = \max_j(\texttt{A}(i,j))$ when `d='c'` and $\texttt{m}(i) = \min_j(\texttt{A}(j,i))$ and $\texttt{M}(i) = \min_j(\texttt{A}(j,i))$ when `d='r'` and $\texttt{M}(0) = \max_{i,j} = \texttt{A}(i,j)$ and $\texttt{m}(0) = \min_{i,j} = \texttt{A}(i,j)$ when `d='*'`.

- void **pnl_mat_min_index** (PnlVect *m, PnlVectInt *im, const PnlMat *A, char d)
  Description Idem as pnl_mat_min and `index` contains the indices of the minima. If `index==NULL`, the indices are not computed.

- void **pnl_mat_max_index** (PnlVect *M, PnlVectInt *iM, const PnlMat *A, char d)
  Description Idem as pnl_mat_max and `index` contains the indices of the maxima. If `index==NULL`, the indices are not computed.

- void **pnl_mat_minmax_index** (PnlVect *m, PnlVect *M, PnlVectInt *im, PnlVectInt *iM, const PnlMat *A, char d)
  Description Idem as pnl_mat_minmax and `im` contains the indices of the minima and `iM` contains the indices of the minima. If `im==NULL` (resp. `iM==NULL`, the indices of the minima (resp. maxima) are not computed.

- void **pnl_mat_qsort** (PnlMat *, char dir, char order)
  Description Sort a matrix using a quick sort algorithm according to `order` (`'i'` for increasing or `'d'` for decreasing). The parameter `dir` determines whether the matrix is sorted by rows or columns. If `dir='c'`, each row is sorted independently of the others whereas if `dir='r'`, each column is sorted independently of the others.

- void **pnl_mat_qsort_index** (PnlMat *, PnlMatInt *index, char dir, char order)
  Description Sort a matrix using a quick sort algorithm according to `order` (`'i'` for increasing or `'d'` for decreasing). The parameter `dir` determines whether the matrix is sorted by rows or columns. If `dir='c'`, each row is sorted independently of the others whereas if `dir='r'`, each column is sorted independently of the others. In addition to the function pnl_mat_qsort, the permutation index is computed and stored into `index`.

- int **pnl_mat_find** (PnlVectInt *indi, PnlVectInt indj, char *type, int(*f)(double *t), ...)
  Description `f` is a function taking a C array as argument and returning an integer. `type` is a string composed by the letters 'r' and 'm' and is used to describe the types of the arguments appearing after `f` : 'r' for real numbers and 'm' for matrices. This function aims at simulating Scilab's `find` function. Here are a few examples (capital letters are used for matrices and small letters for real values)

  – `[indi, indj] = find ( a < X )`

    ```
    int isless ( double *t ) { return t[0] < t[1]; }
    pnl_mat_find ( indi, indj, "rm", isless, a, X );
    ```

  – `ind = find (X <= Y)`

    ```
    int isless ( double *t ) { return t[0] <= t[1]; }
    pnl_mat_find ( ind, "mm", isless, X, Y );
    ```

  – `[indi, indj] = find ((a < X) && (X <= Y))`

```
int cmp ( double *t )
{
  return (t[0] <= t[1]) && (t[1] <= t[2]);
}
pnl_mat_find ( indi, indj, "rmm", cmp, a, X, Y );
```

`(indi, indj)` contains on exit the indices `(i,j)` for which the function `f` returned `1`. Note that if `indj == NULL` on entry, a linear indexing is used for matrices, which means that matrices are seen as large vectors built up be stacking rows. This function returns `OK` or `FAIL` if something went wrong (size mismatch between matrices, invalid string type).

Standard matrix operations

- void **pnl_mat_plus_mat** (PnlMat *lhs, const PnlMat *rhs)
  Description In-place matrix matrix addition

- void **pnl_mat_minus_mat** (PnlMat *lhs, const PnlMat *rhs)
  Description In-place matrix matrix substraction

- void **pnl_mat_sq_transpose** (PnlMat *M)
  Description On exit, `M` is transposed

- PnlMat * **pnl_mat_transpose** (const PnlMat *M)
  Description Create a new matrix which is the transposition of `M`

- void **pnl_mat_tr** (PnlMat *tM, const PnlMat *M)
  Description On exit, `tM = M'`

- double **pnl_mat_trace** (const PnlMat *M)
  Description Return the trace of a square matrix.

- void **pnl_mat_axpy** (double alpha, const PnlMat *A, PnlMat *B)
  Description Compute `B := alpha * A + B`

- void **pnl_mat_dger** (double alpha, const PnlVect *x, const PnlVect *y, PnlMat *A)
  Description Compute `A := alpha x * y' + A`

- PnlVect * **pnl_mat_mult_vect** (const PnlMat *A, const PnlVect *x)
  Description Matrix vector multiplication `A * x`

- void **pnl_mat_mult_vect_inplace** (PnlVect *y, const PnlMat *A, const PnlVect *x)
  Description In place matrix vector multiplication `y = A * x`. You cannot use the same vector for `x` and `y`.

- PnlVect * **pnl_mat_mult_vect_transpose** (const PnlMat *A, const PnlVect *x)
  Description Matrix vector multiplication `A' * x`

- void **pnl_mat_mult_vect_transpose_inplace** (PnlVect *y, const PnlMat *A, const PnlVect *x)
  Description In place matrix vector multiplication `y = A' * x`. You cannot use the same vector for `x` and `y`. The vectors `x` and `y` must be different.

- int **pnl_mat_cross** (PnlMat *lhs, const PnlMat *A, const PnlMat *B)
  Description Compute the cross products of the vectors given in matrices `A` and `B` which must have either 3 rows or 3 columns. A row wise computation is first tried, then a column wise approach is tested. `FAIL` is returned in case no dimension equals 3.

- void **pnl_mat_lAxpby** (double lambda, const PnlMat *A, const PnlVect *x, double b, PnlVect *y)
  Description Compute `y := lambda A x + b y`. When `b=0`, the content of `y` is not used on input and instead `y` is resized to match `A*x`. The vectors `x` and `y` must be different.

- void **pnl_mat_dgemv** (char trans, double lambda, const PnlMat *A, const PnlVect *x, double mu, PnlVect *b)
  Description Compute `b := lambda op(A) x + mu b`, where `op (X) = X` or `op (X) = X'`. If `trans='N'` or `trans='n'`, `op (A) = A`, whereas if `trans='T'` or `trans='t'`, `op (A) = A'`.When `mu==0`, the content of `b` is not used and instead `b` is resized to match `op(A)*x`. The vectors `x` and `b` must be different.

- void **pnl_mat_dgemm** (char transA, char transB, double alpha, const PnlMat *A, const PnlMat *B, double beta, PnlMat *C)
  Description Compute `C := alpha * op(A) * op (B) + beta * C`. When beta=0, the content of `C` is unused and instead `C` is resized to store `alpha A *B`. If `transA='N'` or `transA='n'`, `op (A) = A`, whereas if `transA='T'` or `transA='t'`, `op (A) = A'`. The same holds for `transB`. The matrix `C` must be different from `A` and `B`.

- PnlMat * **pnl_mat_mult_mat** (const PnlMat *rhs1, const PnlMat *rhs2)
  Description Matrix multiplication `rhs1 * rhs2`

- void **pnl_mat_mult_mat_inplace** (PnlMat *lhs, const PnlMat *rhs1, const PnlMat *rhs2)
  Description In-place matrix multiplication `lhs = rhs1 * rhs2`. The matrix `lhs` must be different from `rhs1` and `rhs2`.

- double **pnl_mat_scalar_prod** (const PnlMat *A, const PnlVect *x, const PnlVect *y)
  Description Compute `x' * A * y`

- void **pnl_mat_exp** (PnlMat *B, const PnlMat *A)
  Description Compute the matrix exponential `B = exp(A)`.

- void **pnl_mat_log** (PnlMat *B, const PnlMat *A)
  Description Compute the matrix logarithm `B = log(A)`. For the moment, this function only works if `A` is diagonalizable.

- void **pnl_mat_eigen** (PnlVect *v, PnlMat *P, const PnlMat *A, int with_eigenvector)

Description Compute the eigenvalues (stored in `v`) and optionally the eigenvectors stored column wise in `P` when `with_eigenvector==TRUE`. If `A` is symmetric or Hermitian in the complex case, `P` is orthonormal. When `with_eigenvector=FALSE`, `P` can be `NULL`.

Linear systems and matrix decompositions The following functions are designed to solve linear system of the from `A x = b` where `A` is a matrix and `b` is a vector except in the functions pnl_mat_syslin_mat, pnl_mat_lu_syslin_mat and pnl_mat_chol_syslin_-mat which expect the right hand side member to be a matrix too. Whenever the vector `b` is not needed once the system is solved, you should consider using "inplace" functions.
All the functions described in this paragraph return `OK` if the computations have been carried out successfully and `FAIL` otherwise.

- int **pnl_mat_chol** (PnlMat ∗M)
  Description Compute the Cholesky decomposition of `M`. `M` must be symmetric, the positivity is tested in the algorithm. `M = L * L'`. On exit, the lower part of `M` contains the Cholesky decomposition L and the upper part is set to zero.

- int **pnl_mat_pchol** (PnlMat ∗M, double tol, int ∗rank, PnlVectInt ∗p)
  Description Compute the Cholesky decomposition of `M` with complete pivoting. `P' * A * P = L * L'`. `M` must be symmetric positive semi-definite. On exit, the lower part of `M` contains the Cholesky decomposition `L` and the upper part is set to zero. The permutation matrix is stored in an integer vector `p` : the only non zero elements of `P` are `P(p(k),k) = 1`

- int **pnl_mat_lu** (PnlMat ∗A, PnlPermutation ∗p)
  Description Compute a P A = LU factorization. `P` must be an already allocated PnlPermutation . On exit the decomposition is stored in `A`, the lower part of `A` contains L while the upper part (including the diagonal terms) contains U. Remember that the diagonal elements of `L` are all 1. Row `i` of `A` was interchanged with row `p(i)`.

- int **pnl_mat_upper_syslin** (PnlVect ∗x, const PnlMat ∗U, const PnlVect ∗b)
  Description Solve an upper triangular linear system `U x = b`

- int **pnl_mat_lower_syslin** (PnlVect ∗x, const PnlMat ∗L, const PnlVect ∗b)
  Description Solve a lower triangular linear system `L x = b`

- int **pnl_mat_chol_syslin** (PnlVect ∗x, const PnlMat ∗chol, const PnlVect ∗b)
  Description Solve a symmetric definite positive linear system A x = b, in which `chol` is assumed to be the Cholesky decomposition of A computed by pnl_mat_chol

- int **pnl_mat_chol_syslin_inplace** (const PnlMat ∗chol, PnlVect ∗b)
  Description Solve a symmetric definite positive linear system A x = b, in which `chol` is assumed to be the Cholesky decomposition of A computed by pnl_mat_chol. The solution of the system is stored in `b` on exit.

- int **pnl_mat_lu_syslin** (PnlVect ∗x, const PnlMat ∗LU, const PnlPermutation ∗p, const PnlVect ∗b)
  Description Solve a linear system A x = b using a LU decomposition. `LU` and `P` are assumed to be the PA = LU decomposition as computed by pnl_mat_lu. In particular,

the structure of the matrix `LU` is the following : the lower part of `A` contains L while the upper part (including the diagonal terms) contains U. Remember that the diagonal elements of `L` are all 1.

- int **pnl_mat_lu_syslin_inplace** (const PnlMat *LU, const PnlPermutation *p, PnlVect *b)
  Description Solve a linear system A x = b using a LU decomposition. `LU` and `P` are assumed to be the PA = LU decomposition as computed by pnl_mat_lu. In particular, the structure of the matrix `LU` is the following : the lower part of `A` contains L while the upper part (including the diagonal terms) contains U. Remember that the diagonal elements of `L` are all 1. The solution of the system is stored in `b` on exit.

- int **pnl_mat_syslin** (PnlVect *x, const PnlMat *A, const PnlVect *b)
  Description Solve a linear system A x = b using a LU factorization which is computed inside this function.

- int **pnl_mat_syslin_inplace** (PnlMat *A, PnlVect *b)
  Description Solve a linear system A x = b using a LU factorization which is computed inside this function. The solution of the system is stored in `b` and `A` is overwritten by its LU decomposition.

- int **pnl_mat_syslin_mat** (PnlMat *A, PnlMat *B)
  Description Solve a linear system A X = B using a LU factorization which is computed inside this function. `A` and `B` are matrices. `A` must be square. The solution of the system is stored in `B` on exit. On exit, `A` contains the LU decomposition of the input matrix which is lost.

- int **pnl_mat_chol_syslin_mat** (const PnlMat *A, PnlMat *B)
  Description Solve a linear system A X = B using a Cholesky factorization of the symmetric positive defnite matrix `A`. `A` contains the Cholesky decomposition as computed by pnl_mat_chol. `B` is matrix with the same number of rows as `A`. The solution of the system is stored in `B` on exit.

- int **pnl_mat_lu_syslin_mat** (const PnlMat *A, const PnlPermutation *p, PnlMat *B)
  Description Solve a linear system A X = B using a `P A = L U` factorization. `A` contains the `L U` factors and `p` the associated permutation. `A` and `p` must have been computed by pnl_mat_lu. `B` is matrix with the same number of rows as `A`. The solution of the system is stored in `B` on exit.

The following functions are designed to invert matrices. The authors provide these functions although they cannot find good reasons to use them. Note that to solve a linear system, one must used the `syslin` functions and not invert the system matrix because it is much longer.

- int **pnl_mat_upper_inverse** (PnlMat *A, const PnlMat *B)
  Description Inversion of an upper triangular matrix

- int **pnl_mat_lower_inverse** (PnlMat *A, const PnlMat *B)
  Description Inversion of a lower triangular matrix

- int **pnl_mat_inverse** (PnlMat *inverse, const PnlMat *A)
  Description Compute the inverse of a matrix A and stores the result into `inverse`. A LU factorisation of the matrix `A` is computed inside this function.

- int **pnl_mat_inverse_with_chol** (PnlMat *inverse, const PnlMat *A)
  Description Compute the inverse of a symmetric positive definite matrix A and stores the result into `inverse`. The Cholesky factorisation of the matrix `A` is computed inside this function.

4.3.3 Functions specific to base type `double`

Linear systems and matrix decompositions The following functions are designed to solve linear system of the from `A x = b` where `A` is a matrix and `b` is a vector except in the functions pnl_mat_syslin_mat, pnl_mat_lu_syslin_mat and pnl_mat_chol_syslin_-mat which expect the right hand side member to be a matrix too. Whenever the vector `b` is not needed once the system is solved, you should consider using "inplace" functions.
All the functions described in this paragraph return `OK` if the computations have been carried out successfully and `FAIL` otherwise.

- int **pnl_mat_qr** (PnlMat *Q, PnlMat *R, PnlPermutation *p, const PnlMat *A)
  Description Compute a `A P = QR` decomposition. If on entry `P=NULL`, then the decomposition is computed without pivoting, i.e `A = QR`. When $P \neq NULL$, `P` must be an already allocated PnlPermutation . `Q` is an orthogonal matrix, i.e $\texttt{Q}^{-1} = \texttt{Q}^T$ and `R` is an upper triangular matrix. The use of pivoting improves the numerical stability when `A` is almost rank deficient, i.e when the smallest eigenvalue of `A` is very close to 0.

- int **pnl_mat_qr_syslin** (PnlVect *x, const PnlMat *Q, const PnlMat *R, const PnlVectInt *p, const PnlVect *b)
  Description Solve a linear system `A x = b` where `A` is given by its QR decomposition with column pivoting as computed by the function pnl_mat_qr.

- int **pnl_mat_ls** (const PnlMat *A, PnlVect *b)
  Description Solve a linear system A x = b in the least square sense, i.e. $\texttt{x} = \arg\min_U \|A* u-b\|^2$. The solution is stored into `b` on exit. It internally uses a `AP = QR` decomposition.

- int **pnl_mat_ls_mat** (const PnlMat *A, PnlMat *B)
  Description Solve a linear system A X = B with `A` and `B` two matrices in the least square sense, i.e. $\texttt{X} = \arg\min_U \|A*U-B\|^2$. The solution is stored into `B` on exit. It internally uses a `AP = QR` decomposition. Same function as pnl_mat_ls but handles several r.h.s.

4.3.4 Functions specific to base type `dcomplex`

- PnlMatComplex * **pnl_mat_complex_create_from_mat** (const PnlMat *R)
  Description Create a complex matrix using a real one. The complex parts of the entries of the returned matrix are all set to zero.

4.3.5 Permutations

```
typedef PnlVectInt PnlPermutation;
```

The `PnlPermutation` type is actually nothing else than a vector of integers, i.e. a `PnlVectInt`. It is used to store the partial pivoting with row interchanges transformation needed in the LU decomposition. We use the *Blas* convention for storing permutations. Consider a `PnlPermutation p` generated by a LU decomposition of a matrix `A` : to compute the decomposition, row `i` of `A` was interchanged with row `p(i)`.

- PnlPermutation ∗ **pnl_permutation_new** ()
  Description Create an empty PnlPermutation .

- PnlPermutation ∗ **pnl_permutation_create** (int n)
  Description Create a PnlPermutation of size `n`.

- void **pnl_permutation_free** (PnlPermutation ∗∗p)
  Description Free a PnlPermutation .

- void **pnl_permutation_inverse** (PnlPermutation ∗inv, const PnlPermutation ∗p)
  Description Compute in `inv` the inverse of the permutation `p`.

- void **pnl_vect_permute** (PnlVect ∗px, const PnlVect ∗x, const PnlPermutation ∗p)
  Description Apply a PnlPermutation to a PnlVect .

- void **pnl_vect_permute_inplace** (PnlVect ∗x, const PnlPermutation ∗p)
  Description Apply a PnlPermutation to a PnlVect in-place.

- void **pnl_vect_permute_inverse** (PnlVect ∗px, const PnlVect ∗x, const PnlPermutation ∗p)
  Description Apply the inverse of PnlPermutation to a PnlVect .

- void **pnl_vect_permute_inverse_inplace** (PnlVect ∗x, const PnlPermutation ∗p)
  Description Apply the inverse of a PnlPermutation to a PnlVect in-place.

- void **pnl_mat_col_permute** (PnlMat ∗pX, const PnlMat ∗X, const PnlPermutation ∗p)
  Description Apply a PnlPermutation to the columns of a matrix. `pX` contains the result of the permutation applied to `X`.

- void **pnl_mat_row_permute** (PnlMat ∗pX, const PnlMat ∗X, const PnlPermutation ∗p)
  Description Apply a PnlPermutation to the rows of a matrix. `pX` contains the result of the permutation applied to `X`.

- void **pnl_permutation_fprint** (FILE ∗fic, const PnlPermutation ∗p)
  Description Print a permutation to a file.

- void **pnl_permutation_print** (const PnlPermutation ∗p)
  Description Print a permutation to the standard output.

4.4 Tridiagonal Matrices

4.4.1 Overview

The structures and functions related to tridiagonal matrices are declared in `pnl/pnl_tridiag_matrix.h`.
We only store the three main diagonals as three vectors.

```
typedef struct PnlTridiagMat{
  /**
   * Must be the first element in order for the object mechanism to work
   * properly. This allows any PnlTridiagMat pointer to be cast to a PnlObject
   */
  PnlObject object;
  int size; /*!< number of rows, the matrix must be square */
  double *D; /*!< diagonal elements */
  double *DU; /*!< upper diagonal elements */
  double *DL; /*!< lower diagonal elements */
} PnlTridiagMat;
```

`size` is the size of the matrix, `D` is an array of size `size` containing the diagonal terms. `DU`, `DL` are two arrays of size `size-1` containing respectively the upper diagonal ($M_{i,i+1}$) and the lower diagonal ($M_{i-1,i}$).

```
typedef struct PnlTridiagMatLU{
  /**
   * Must be the first element in order for the object mechanism to work
   * properly. This allows any PnlTridiagMatLU pointer to be cast to a PnlObject
   */
  PnlObject object;
  int size; /*!< number of rows, the matrix must be square */
  double *D; /*!< diagonal elements */
  double *DU; /*!< upper diagonal elements */
  double *DU2; /*!< second upper diagonal elements */
  double *DL; /*!< lower diagonal elements */
  int *ipiv; /*!< Permutation: row i has been interchanged with row ipiv(i) */
};
```

This type is used to store the LU decomposition of a tridiagonal matrix.

4.4.2 Functions

Constructors and destructors

- PnlTridiagMat $*$ **pnl_tridiag_mat_new** ()
  Description Create a PnlTridiagMat with size 0

- PnlTridiagMat $*$ **pnl_tridiag_mat_create** (int size)
  Description Create a PnlTridiagMat with size `size`

- PnlTridiagMat * **pnl_tridiag_mat_create_from_scalar** (int size, double x)
  Description Create a PnlTridiagMat with the 3 diagonals filled with `x`
- PnlTridiagMat * **pnl_tridiag_mat_create_from_two_scalar** (int size, double x, double y)
  Description Create a PnlTridiagMat with the diagonal filled with `x` and the upper and lower diagonals filled with `y`
- PnlTridiagMat * **pnl_tridiag_mat_create_from_ptr** (int size, const double *lower_D, const double *D, const double *upper_D)
  Description Create a PnlTridiagMat
- PnlTridiagMat * **pnl_tridiag_mat_create_from_mat** (const PnlMat *mat)
  Description Create a tridiagonal matrix from a full matrix (all the elements but the 3 diagonal ones are ignored).
- PnlMat * **pnl_tridiag_mat_to_mat** (const PnlTridiagMat *T)
  Description Create a full matrix from a tridiagonal one.
- PnlTridiagMat * **pnl_tridiag_mat_copy** (const PnlTridiagMat *T)
  Description Copy a tridiagonal matrix.
- void **pnl_tridiag_mat_clone** (PnlTridiagMat *clone, const PnlTridiagMat *T)
  Description Copy the content of `T` into `clone`
- void **pnl_tridiag_mat_free** (PnlTridiagMat **v)
  Description Free a PnlTridiagMat
- int **pnl_tridiag_mat_resize** (PnlTridiagMat *v, int size)
  Description Resize a PnlTridiagMat .

Accessing elements. If it is supported by the compiler, the following functions are declared inline. To speed up these functions, you can use the macro constant `PNL_RANGE_CHECK_OFF`, see Section 1.3.2 for an explanation.

- void **pnl_tridiag_mat_set** (PnlTridiagMat *self, int d, int up, double x)
  Description Set `self[d, d+up] = x`, `up` can be $\{-1, 0, 1\}$.
- double **pnl_tridiag_mat_get** (const PnlTridiagMat *self, int d, int up)
  Description Get `self[d, d+up]`, `up` can be $\{-1, 0, 1\}$.
- double * **pnl_tridiag_mat_lget** (PnlTridiagMat *self, int d, int up)
  Description Return the address `self[d, d+up] = x`, `up` can be $\{-1, 0, 1\}$.

Printing Matrix

- void **pnl_tridiag_mat_fprint** (FILE *fic, const PnlTridiagMat *M)
  Description Print a tri-diagonal matrix to a file.
- void **pnl_tridiag_mat_print** (const PnlTridiagMat *M)
  Description Print a tridiagonal matrix to the standard output.

Algebra operations

- void **pnl_tridiag_mat_plus_tridiag_mat** (PnlTridiagMat *lhs, const PnlTridiagMat *rhs)
  Description In-place matrix matrix addition

- void **pnl_tridiag_mat_minus_tridiag_mat** (PnlTridiagMat *lhs, const PnlTridiagMat *rhs)
  Description In-place matrix matrix substraction

- void **pnl_tridiag_mat_plus_scalar** (PnlTridiagMat *lhs, double x)
  Description In-place matrix scalar addition

- void **pnl_tridiag_mat_minus_scalar** (PnlTridiagMat *lhs, double x)
  Description In-place matrix scalar substraction

- void **pnl_tridiag_mat_mult_scalar** (PnlTridiagMat *lhs, double x)
  Description In-place matrix scalar multiplication

- void **pnl_tridiag_mat_div_scalar** (PnlTridiagMat *lhs, double x)
  Description In-place matrix scalar division

Element-wise operations

- void **pnl_tridiag_mat_mult_tridiag_mat_term** (PnlTridiagMat *lhs, const PnlTridiagMat *rhs)
  Description In-place matrix matrix term by term product

- void **pnl_tridiag_mat_div_tridiag_mat_term** (PnlTridiagMat *lhs, const PnlTridiagMat *rhs)
  Description In-place matrix matrix term by term division

- void **pnl_tridiag_mat_map_inplace** (PnlTridiagMat *lhs, double(*f)(double))
  Description `lhs = f(lhs)`.

- void **pnl_tridiag_mat_map_tridiag_mat_inplace** (PnlTridiagMat *lhs, const PnlTridiagMat *rhs, double(*f)(double, double))
  Description `lhs = f(lhs, rhs)`.

Standard matrix operations & Linear systems

- void **pnl_tridiag_mat_mult_vect_inplace** (PnlVect *lhs, const PnlTridiagMat *mat, const PnlVect *rhs)
  Description In place matrix multiplication. The vector `lhs` must be different from `rhs`.

- PnlVect * **pnl_tridiag_mat_mult_vect** (const PnlTridiagMat *mat, const PnlVect *vec)
  Description Matrix multiplication

- void **pnl_tridiag_mat_lAxpby** (double lambda, const PnlTridiagMat ∗A, const PnlVect ∗x, double mu, PnlVect ∗b)
  Description Compute `b := lambda A x + mu b`. When `mu==0`, the content of `b` is not used on input and instead `b` is resized to match `A*x`. Note that the vectors `x` and `b` must be different.

- double **pnl_tridiag_mat_scalar_prod** (const PnlVect ∗x,const PnlTridiagMat ∗A, const PnlVect ∗y)
  Description Compute `x' * A * y`

- void **pnl_tridiag_mat_syslin_inplace** (PnlTridiagMat ∗M, PnlVect ∗b)
  Description Solve the linear system M x = b. The solution is written into `b` on exit. On exit, `M` is modified and becomes unusable.

- void **pnl_tridiag_mat_syslin** (PnlVect ∗x, PnlTridiagMat ∗M, const PnlVect ∗b)
  Description Solve the linear system M x = b. On exit, `M` is modified and becomes unusable.

- PnlTridiagMatLU ∗ **pnl_tridiag_mat_lu_new** ()
  Description Create an empty PnlTridiagMatLU

- PnlTridiagMatLU ∗ **pnl_tridiag_mat_lu_create** (int size)
  Description Create a PnlTridiagMatLU with size `size`

- PnlTridiagMatLU ∗ **pnl_tridiag_mat_lu_copy** (const PnlTridiagMatLU ∗mat)
  Description Create a new PnlTridiagMatLU which is a copy of `mat`.

- void **pnl_tridiag_mat_lu_clone** (PnlTridiagMatLU ∗clone, const PnlTridiagMatLU ∗mat)
  Description Clone a PnlTridiagMatLU . `clone` must already exist, no memory is allocated for the envelope.

- void **pnl_tridiag_mat_lu_free** (PnlTridiagMatLU ∗∗m)
  Description Free a PnlTridiagMatLU

- int **pnl_tridiag_mat_lu_resize** (PnlTridiagMatLU ∗v, int size)
  Description Resize a PnlTridiagMatLU

- int **pnl_tridiag_mat_lu_compute** (PnlTridiagMatLU ∗LU, const PnlTridiagMat ∗A)
  Description Compute the LU factorisation of a tridiagonal matrix `A`. `LU` must have already been created using pnl_tridiag_mat_lu_new. On exit, `LU` contains the decomposition which is suitable for use in pnl_tridiag_mat_lu_syslin.

- int **pnl_tridiag_mat_lu_syslin_inplace** (PnlTridiagMatLU ∗LU, PnlVect ∗b)
  Description Solve a linear system `A x = b` where the matrix `LU` is given the LU decomposition of A previously computed by pnl_tridiag_mat_lu_compute. On exit, `b` is overwritten by the solution `x`.

- int **pnl_tridiag_mat_lu_syslin** (PnlVect ∗x, PnlTridiagMatLU ∗LU, const PnlVect ∗b)

Description Solve a linear system `A x = b` where the matrix `LU` is given the LU decomposition of A previously computed by pnl_tridiag_mat_lu_compute.

4.5 Band Matrices

4.5.1 Overview

```
typedef struct
{
  /**
   * Must be the first element in order for the object mechanism to work
   * properly. This allows any PnlBandMat pointer to be cast to a PnlObject
   */
  PnlObject object;
  int m; /*!< nb rows */
  int n; /*!< nb columns */
  int nu; /*!< nb of upperdiagonals */
  int nl; /*!< nb of lowerdiagonals */
  int m_band; /*!< nb rows of the band storage */
  int n_band; /*!< nb columns of the band storage */
  double *array;  /*!< a block to store the bands */
} PnlBandMat;
```

The structures and functions related to band matrices are declared in `pnl/pnl_band_matrix.h`.

4.5.2 Functions

Constructors and destructors

- PnlBandMat * **pnl_band_mat_new** ()
  Description Create a band matrix of size 0.

- PnlBandMat * **pnl_band_mat_create** (int m, int n, int nl, int nu)
  Description Create a band matrix of size `m x n` with `nl` lower diagonals and `nu` upper diagonals.

- PnlBandMat * **pnl_band_mat_create_from_mat** (const PnlMat *BM, int nl, int nu)
  Description Extract a band matrix from a PnlMat .

- void **pnl_band_mat_free** (PnlBandMat **)
  Description Free a band matrix.

- void **pnl_band_mat_clone** (PnlBandMat *clone, const PnlBandMat *M)
  Description Copy the band matrix `M` into `clone`. No new PnlBandMat is created.

- PnlBandMat * **pnl_band_mat_copy** (PnlBandMat *BM)
  Description Create a new band matrix which is a copy of `BM`. Each band matrix owns its data array.

- PnlMat * **pnl_band_mat_to_mat** (PnlBandMat *BM)
  Description Create a full matrix from a band matrix.

- int **pnl_band_mat_resize** (PnlBandMat *BM, int m, int n, int nl, int nu)
  Description Resize `BM` to store a `m x n` band matrix with `nu` upper diagonals and `nl` lower diagonals.

Accessing elements. If it is supported by the compiler, the following functions are declared inline. To speed up these functions, you can use the macro constant `PNL_RANGE_CHECK_OFF`, see Section 1.3.2 for an explanation.

- void **pnl_band_mat_set** (PnlBandMat *M, int i, int j, double x)
  Description $M_{i,j} = x$.

- void **pnl_band_mat_get** (PnlBandMat *M, int i, int j)
  Description Return $M_{i,j}$.

- void **pnl_band_mat_lget** (PnlBandMat *M, int i, int j)
  Description Return the address $\&(M_{i,j})$.

- void **pnl_band_mat_set_all** (PnlBandMat *M, double x)
  Description Set all the elements of `M` to `x`.

- void **pnl_band_mat_print_as_full** (PnlBandMat *M)
  Description Print a band matrix in a full format.

Element wise operations

- void **pnl_band_mat_plus_scalar** (PnlBandMat *lhs, double x)
  Description In-place addition, `lhs += x`

- void **pnl_band_mat_minus_scalar** (PnlBandMat *lhs, double x)
  Description In-place substraction `lhs -= x`

- void **pnl_band_mat_div_scalar** (PnlBandMat *lhs, double x)
  Description `lhs = lhs ./ x`

- void **pnl_band_mat_mult_scalar** (PnlBandMat *lhs, double x)
  Description `lhs = lhs * x`

- void **pnl_band_mat_plus_band_mat** (PnlBandMat *lhs, const PnlBandMat *rhs)
  Description In-place addition, `lhs += rhs`

- void **pnl_band_mat_minus_band_mat** (PnlBandMat *lhs, const PnlBandMat *rhs)
  Description In-place substraction `lhs -= rhs`

- void **pnl_band_mat_inv_term** (PnlBandMat *lhs)
  Description In-place term by term inversion `lhs = 1 ./ rhs`

- void **pnl_band_mat_div_band_mat_term** (PnlBandMat *lhs, const PnlBandMat *rhs)
  Description In-place term by term division `lhs = lhs ./ rhs`

- void **pnl_band_mat_mult_band_mat_term** (PnlBandMat *lhs, const PnlBandMat *rhs)
  Description In-place term by term multiplication `lhs = lhs .* rhs`

- void **pnl_band_mat_map** (PnlBandMat *lhs, const PnlBandMat *rhs, double(*f)(double))
  Description `lhs = f(rhs)`

- void **pnl_band_mat_map_inplace** (PnlBandMat *lhs, double(*f)(double))
  Description `lhs = f(lhs)`

- void **pnl_band_mat_map_band_mat_inplace** (PnlBandMat *lhs, const PnlBandMat *rhs, double(*f)(double,double))
  Description `lhs = f(lhs,rhs)`

Standard matrix operations & Linear system

- void **pnl_band_mat_lAxpby** (double lambda, const PnlBandMat *A, const PnlVect *x, double mu, PnlVect *b)
  Description Compute `b := lambda A x + mu b`. When `mu==0`, the content of `b` is not used on input and instead `b` is resized to match the size of `A*x`.

- void **pnl_band_mat_mult_vect_inplace** (PnlVect *y, const PnlBandMat *BM, const PnlVect *x)
  Description `y = BM * x`

- void **pnl_band_mat_syslin_inplace** (PnlBandMat *M, PnlVect *b)
  Description Solve the linear system `M x = b` with `M` a PnlBandMat . **Note** that M is modified on output and becomes unusable. On exit, the solution `x` is stored in `b`.

- void **pnl_band_mat_syslin** (PnlVect *x,PnlBandMat *M, PnlVect *b)
  Description Solve the linear system `M x = b` with `M` a PnlBandMat . **Note** that M is modified on output and becomes unusable.

- void **pnl_band_mat_lu** (PnlBandMat *BM, PnlVectInt *p)
  Description Compute the LU decomposition with partial pivoting with row interchanges. On exit, `BM` is enlarged to store the LU decomposition. On exit, `p` stores the permutation applied to the rows. Note that the Lapack format is used to store `p`, this format differs from the one used by PnlPermutation .

- void **pnl_band_mat_lu_syslin_inplace** (const PnlBandMat *M, PnlVectInt *p, PnlVect *b)
  Description Solve the band linear system `M x = b` where `M` is the LU decomposition computed by pnl_band_mat_lu and `p` the associated permutation. On exit, the solution `x` is stored in `b`.

- void **pnl_band_mat_lu_syslin** (PnlVect *x, const PnlBandMat *M, PnlVectInt *p, const PnlVect *b)
  Description Solve the band linear system `M x = b` where `M` is the LU decomposition computed by pnl_band_mat_lu and `p` the associated permutation.

4.6 Sparse Matrices

4.6.1 Short description

The structures and functions related to matrices are declared in `pnl/pnl_sp_matrix.h`.

```
typedef struct _PnlSpMat
{
  /**
   * Must be the first element in order for the object mechanism to work
   * properly. This allows a PnlSpMat pointer to be cast to a PnlObject
   */
  PnlObject object;
  int m; /*!< number of rows */
  int n; /*!< number of columns */
  int nz; /*!< number of non-zero elements */
  int *J; /*!< column indices, vector of size nzmax */
  int *I; /*!< row offset integer vector,
            array[I[i]] is the first element of row i.
            Vector of size (m+1) */
  double *array; /*!< pointer to store the data of size nzmax*/
  int nzmax; /*!< size of the memory block allocated for array */
} PnlSpMat;

typedef struct _PnlSpMatInt
{
  /**
   * Must be the first element in order for the object mechanism to work
   * properly. This allows a PnlSpMat pointer to be cast to a PnlObject
   */
  PnlObject object;
  int m; /*!< number of rows */
  int n; /*!< number of columns */
  int nz; /*!< number of non-zero elements */
  int *J; /*!< column indices, vector of size nzmax */
  int *I; /*!< row offset integer vector,
            array[I[i]] is the first element of row i.
            Vector of size (m+1) */
  int *array; /*!< pointer to store the data of size nzmax */
  int nzmax; /*!< size of the memory block allocated for array */
} PnlSpMatInt;

typedef struct _PnlSpMatComplex
```

```
{
  /**
   * Must be the first element in order for the object mechanism to work
   * properly. This allows a PnlSpMat pointer to be cast to a PnlObject
   */
  PnlObject object;
  int m; /*!< number of rows */
  int n; /*!< number of columns */
  int nz; /*!< number of non-zero elements */
  int *J; /*!< column indices, vector of size nzmax */
  int *I; /*!< row offset integer vector,
            array[I[i]] is the first element of row i.
            Vector of size (m+1) */
  dcomplex *array; /*!< pointer to store the data of size nzmax */
  int nzmax; /*!< size of the memory block allocated for array */
} PnlSpMatComplex;
```

The non zero elements of row `i` are stored in `array` between the indices `I[i]` and `I[i+1]-1`. The array `J` contains the column indices of every element of `array`.

Sparse matrices are defined using the internal template approach and can be used for integer, float or complex base data according to the following table

base type	prefix	type
double	pnl_sp_mat	PnlSpMat
int	pnl_sp_mat_int	PnlSpMatInt
dcomplex	pnl_sp_mat_complex	PnlSpMatComplex

4.6.2 Functions

Constructors and destructors

- PnlSpMat * **pnl_sp_mat_new** ()
  Description Create an empty sparse matrix.

- PnlSpMat * **pnl_sp_mat_create** (int m, int n, int nzmax)
  Description Create a sparse matrix with size `m x n` designed to hold at most `nzmax` non zero elements.

- void **pnl_sp_mat_clone** (PnlSpMat *dest, const PnlSpMat *src)
  Description Clone `src` into `dest`, which is automatically resized. On output, `dest` and `src` are equal but independent.

- PnlSpMat * **pnl_sp_mat_copy** (PnlSpMat *src)
  Description Create an independent copy of `src`.

- void **pnl_sp_mat_free** (PnlSpMat **)
  Description Delete a sparse matrix.

- int **pnl_sp_mat_resize** (PnlSpMat *M, int m, int n, int nzmax)
  Description Resize an existing PnlSpMat to become a `m x n` sparse matrices holding at most `nzmax`. Note that no old data are kept except if `M->m` is left unchanged and we only call this function to increase `M->nzmax`. Return `OK` or `FAIL`.

- PnlMat * **pnl_mat_create_from_sp_mat** (const PnlSpMat *M)
  Description Create a dense PnlMat from a spare one.

- PnlSpMat * **pnl_sp_mat_create_from_mat** (const PnlMat *M)
  Description Create a sparse matrix from a dense one.

- int **pnl_sp_mat_eq** (const PnlSpMat *Sp1, const PnlSpMat *Sp2)
  Description Test if two sparse matrices are equal, ie. if they have the same size (m, n, nz) and hold the same values. Return `TRUE` or `FALSE`.

Accessing elements

- void **pnl_sp_mat_set** (PnlSpMat *M, int i, int j, double x)
  Description Set `M[i,j] = x`. This function increases `M->nzmax` if necessary.

- double **pnl_sp_mat_get** (const PnlSpMat *M, int i, int j)
  Description Return `M[i,j]`. If `M` has no entry with such an index, zero is returned.

Applying external operations

- void **pnl_sp_mat_plus_scalar** (PnlSpMat *M, double x)
  Description Add `x` to all non zero entries of `M`. To apply the operation to all entries including the zero ones, first convert `M` to a dense matrix and use pnl_mat_plus_scalar.

- void **pnl_sp_mat_minus_scalar** (PnlSpMat *M, double x)
  Description Substract `x` to all non zero entries of `M`. To apply the operation to all entries including the zero ones, first convert `M` to a dense matrix and use pnl_mat_minus_scalar.

- void **pnl_sp_mat_mult_scalar** (PnlSpMat *M, double x)
  Description In-place matrix scalar multiplication

- void **pnl_sp_mat_div_scalar** (PnlSpMat *M, double x)
  Description In-place matrix scalar division

Standard matrix operations

- void **pnl_sp_mat_fprint** (FILE *fic, const PnlSpMat *M)
  Description Print a sparse matrix to a file descriptor using the format `(row, col) -> val`.

- void **pnl_sp_mat_print** (const PnlSpMat *M)
  Description Same as pnl_sp_mat_fprint but print to standard output.

- void **pnl_sp_mat_mult_vect** (()PnlVect *y, const PnlSpMat *A, const PnlVect *x)
  Description `y = A x`.

- void **pnl_sp_mat_lAxpby** (double lambda, const PnlSpMat *A, const PnlVect *x, double b, PnlVect *y)
  Description Compute `y := lambda A x + b y`. When `b=0`, the content of `y` is not used on input and instead `y` is resized to match `A*x`. The vectors `x` and `y` must be different.

4.7 Hyper Matrices

4.7.1 Short description

The Hyper matrix types and related functions are defined in the header `pnl/pnl_matrix.h`.

```
typedef struct PnlHmat{
  /**
   * Must be the first element in order for the object mechanism to work
   * properly. This allows any PnlHmat pointer to be cast to a PnlObject
   */
  PnlObject object;
  int ndim; /*!< nb dimensions */
  int *dims; /*!< pointer to store the values of the ndim dimensions */
  int mn; /*!< product dim_1 *...*dim_ndim */
  int *pdims; /*!< array of size ndim, s.t. pdims[i] = dims[ndim-1] x ... dims[i+1]
                 with pdims[ndim - 1] = 1 */
  double *array; /*!< pointer to store */
} PnlHmat;

typedef struct PnlHmatInt{
  /**
   * Must be the first element in order for the object mechanism to work
   * properly. This allows any PnlHmatInt pointer to be cast to a PnlObject
   */
  PnlObject object;
  int ndim; /*!< nb dimensions */
  int *dims; /*!< pointer to store the value of the ndim dimensions */
  int mn; /*!< product dim_1 *...*dim_ndim */
  int *pdims; /*!< array of size ndim, s.t. pdims[i] = dims[ndim-1] x ... dims[i+1]
                 with pdims[ndim - 1] = 1 */
  int *array; /*!< pointer to store */
} PnlHmatInt;

typedef struct PnlHmatComplex{
  /**
   * Must be the first element in order for the object mechanism to work
   * properly. This allows any PnlHmatComplex pointer to be cast to a PnlObject
   */
  PnlObject object;
```

```
  int ndim; /*!< nb dimensions */
  int *dims; /*!< pointer to store the value of the ndim dimensions */
  int mn; /*!< product dim_1 *...*dim_ndim */
  int *pdims; /*!< array of size ndim, s.t. pdims[i] = dims[ndim-1] x ... dims[i+1]
               with pdims[ndim - 1] = 1 */
  dcomplex *array; /*!< pointer to store */
} PnlHmatComplex;
```

`ndim` is the number of dimensions, `dim` is an array to store the size of each dimension and `nm` contains the product of the sizes of each dimension. `array` is an array of size `mn` containing the data. The integer array `pdims` is used to create the one–to–one map between the natural indexing and the linear indexing used in `array`.

4.7.2 Functions

These functions exist for all types of hypermatrices no matter what the basic type is. The following conventions are used to name functions operating on hypermatrices. Here is the table of prefixes used for the different basic types.

base type	prefix	type
double	pnl_hmat	PnlHmat
int	pnl_hmat_int	PnlHmatInt
dcomplex	pnl_hmat_complex	PnlHmatComplex

In this paragraph, we present the functions operating on PnlHmat which exist for all types. To deduce the prototypes of these functions for other basic types, one must replace `pnl_hmat` and `double` according the above table.

Constructors and destructors

- PnlHmat ∗ **pnl_hmat_new** ()
  Description Create an empty PnlHmat .
- PnlHmat ∗ **pnl_hmat_create** (int ndim, const int ∗dims)
  Description Create a PnlHmat with `ndim` dimensions and the size of each dimension is given by the entries of the integer array `dims`
- PnlHmat ∗ **pnl_hmat_create_from_scalar** (int ndim, const int ∗dims, double x)
  Description Create a PnlHmat with `ndim` dimensions given by $\prod_i$ `dims`[i] filled with `x`.
- PnlHmat ∗ **pnl_hmat_create_from_ptr** (int ndim, const int ∗dims, const double ∗x)
- void **pnl_hmat_free** (PnlHmat ∗∗H)
  Description Free a PnlHmat
- PnlHmat ∗ **pnl_hmat_copy** (const PnlHmat ∗H)
  Description Copy a PnlHmat .
- void **pnl_hmat_clone** (PnlHmat ∗clone, const PnlHmat ∗H)
  Description Clone a PnlHmat .

- int **pnl_hmat_resize** (PnlHmat *H, int ndim, const int *dims)
  Description Resize a PnlHmat .

Accessing elements

- void **pnl_hmat_set** (PnlHmat *self, int *tab, double x)
  Description Set the element of index `tab` to `x`.

- double **pnl_hmat_get** (const PnlHmat *self, int *tab)
  Description Return the value of the element of index `tab`

- double* **pnl_hmat_lget** (PnlHmat *self, int *tab)
  Description Return the address of self[tab] for use as a lvalue.

- PnlMat **pnl_mat_wrap_hmat** (PnlHmat *H, int *t)
  Description Return a true PnlMat not a pointer holding the data `H(t,:,:)`. Note that `t` must be of size `ndim-2` and that it cannot be checked within the function. The returned matrix shares its data with `H`, it is only a view not a true copy.

- PnlVect **pnl_vect_wrap_hmat** (PnlHmat *H, int *t)
  Description Return a true PnlVect not a pointer holding the data `H(t,:)`. Note that `t` must be of size `ndim-1` and that it cannot be checked within the function. The returned vector shares its data with `H`, it is only a view not a true copy.

Printing hypermatrices

- void **pnl_hmat_print** (const PnlHmat *H)
  Description Print an hypermatrix.

Term by term operations

- void **pnl_hmat_plus_hmat** (PnlHmat *lhs, const PnlHmat *rhs)
  Description Compute `lhs += rhs`.

- void **pnl_hmat_mult_scalar** (PnlHmat *lhs, double x)
  Description Compute `lhs *= x` where x is a real number.

4.8 Iterative Solvers

4.8.1 Overview

The structures and functions related to solvers are declared in `pnl/pnl_linalgsolver.h`.

```
typedef struct _PnlIterationBase PnlIterationBase;
typedef struct _PnlCgSolver PnlCgSolver;
typedef struct _PnlBicgSolver PnlBicgSolver;
typedef struct _PnlGmresSolver PnlGmresSolver;

struct _PnlIterationBase
{
```

```
  /**
   * Must be the first element in order for the object mechanism to work
   * properly. This allows any PnlVectXXX pointer to be cast to a PnlObject
   */
  PnlObject object;
  int iteration;
  int max_iter;
  double normb;
  double tol_;
  double resid;
  int error;
  /* char *  err_msg; */
};

/* When you repeatedly use iterative solvers, do not malloc each time */
struct _PnlCgSolver
{
  /**
   * Must be the first element in order for the object mechanism to work
   * properly. This allows any PnlCgSolver  pointer to be cast to a PnlObject
   */
  PnlObject object;
  PnlVect * r;
  PnlVect * z;
  PnlVect * p;
  PnlVect * q;
  double rho;
  double oldrho;
  double beta;
  double alpha;
  PnlIterationBase * iter;
} ;

struct _PnlBicgSolver
{
  /**
   * Must be the first element in order for the object mechanism to work
   * properly. This allows any PnlBicgSolver pointer to be cast to a PnlObject
   */
  PnlObject object;
  double rho_1, rho_2, alpha, beta, omega;
  PnlVect * p;
  PnlVect * phat;
  PnlVect * s;
  PnlVect * shat;
  PnlVect * t;
  PnlVect * v;
```

```
  PnlVect * r;
  PnlVect *  rtilde;
  PnlIterationBase * iter;
} ;

struct _PnlGmresSolver
{
  /**
   * Must be the first element in order for the object mechanism to work
   * properly. This allows any PnlGmresSolver pointer to be cast to a PnlObject
   */
  PnlObject object;
  int restart;
  double beta;
  PnlVect * s;
  PnlVect * cs;
  PnlVect * sn;
  PnlVect * w;
  PnlVect * r;
  PnlMat * H;
  PnlVect * v[MAX_RESTART];
  PnlIterationBase *iter;
  PnlIterationBase *iter_inner;
} ;
```

A Left preconditioner solves the problem :

$$PMx = Pb,$$

and whereas right preconditioner solves

$$MPy = b, \qquad Py = x.$$

More information is given in *Saad, Yousef (2003). Iterative methods for sparse linear systems (2nd ed. ed.). SIAM. ISBN 0898715342. OCLC 51266114.* The reader will find in this book some discussion about right or/and left preconditioner and a description of the following algorithms.
These algorithms, we implemented with a left preconditioner. Right preconditioner can be easily computed changing matrix vector multiplication operator from $M\ x$ to $M\ P_R\ x$ and solving $P_R y = x$ at the end of algorithm.

4.8.2 Functions

Three methods are implemented : Conjugate Gradient, BICGstab and GMRES with restart. For each of them a structure is created to store temporary vectors used in the algorithm. In some cases, we have to apply iterative methods more than once : for example to solve at each time step a discrete form of an elliptic problem come from parabolic problem. In the cases, do not call the constructor and destructor at each time, but instead use the initialization and solve procedures.
Formally we have,

```
Create iterative method
For each time step
  Initialisation of iterative method
  Solve linear system link to elliptic problem
end for
free iterative method
```

In these functions, we don't use any particular matrix structure. We give the matrix vector multiplication as a parameter of the solver.

Conjugate Gradient method Only available for symmetric and positive matrices.

- PnlCgSolver ∗ **pnl_cg_solver_new** ()
  Description Create an empty PnlCgSolver
- PnlCgSolver ∗ **pnl_cg_solver_create** (int Size, int max-iter, double tolerance)
  Description Create a new PnlCgSolver pointer.
- void **pnl_cg_solver_initialisation** (PnlCgSolver ∗Solver, const PnlVect ∗b)
  Description Initialisation of the solver at the beginning of iterative method.
- void **pnl_cg_solver_free** (PnlCgSolver ∗∗Solver)
  Description Destructor of iterative solver
- int **pnl_cg_solver_solve** (void(∗matrix vector-product)(const void ∗, const PnlVect ∗, const double, const double, PnlVect ∗), const void ∗Matrix-Data, void(∗matrix vector-product-PC)(const void ∗, const PnlVect ∗, const double, const double, PnlVect ∗), const void ∗PC-Data, PnlVect ∗x, const PnlVect ∗b, PnlCgSolver ∗Solver)
  Description Solve the linear system matrix vector-product is the matrix vector multiplication function matrix vector-product-PC is the preconditionner function Matrix-Data & PC-Data is data to compute matrix vector multiplication.

BICG stab

- PnlBicgSolver ∗ **pnl_bicg_solver_new** ()
  Description Create an empty PnlBicgSolver.
- PnlBicgSolver ∗ **pnl_bicg_solver_create** (int Size, int max-iter, double tolerance)
  Description Create a new PnlBicgSolver pointer.
- void **pnl_bicg_solver_initialisation** (PnlBicgSolver ∗Solver, const PnlVect ∗b)
  Description Initialisation of the solver at the beginning of iterative method.
- void **pnl_bicg_solver_free** (PnlBicgSolver ∗∗Solver)
  Description Destructor of iterative solver
- int **pnl_bicg_solver_solve** (void(∗matrix vector-product)(const void ∗, const PnlVect ∗, const double, const double, PnlVect ∗), const void ∗Matrix-Data, void(∗matrix vector-product-PC)(const void ∗, const PnlVect ∗, const double, const double, PnlVect ∗), const void ∗PC-Data, PnlVect ∗x, const PnlVect ∗b, PnlBicgSolver ∗Solver)

Description Solve the linear system matrix vector-product is the matrix vector multiplication function matrix vector-product-PC is the preconditioner function Matrix-Data & PC-Data is data to compute matrix vector multiplication.

GMRES with restart See *Saad, Yousef (2003)* for a discussion about the restart parameter. For GMRES we need to store at the p-th iteration p vectors of the same size of the right and side. It could be very expensive in term of memory allocation. So GMRES with restart algorithm stop if $p = restart$ and restarts the algorithm with the previously computed solution as initial guess.
Note that if restart equals m, we have a classical GMRES algorithm.

- PnlGmresSolver ∗ **pnl_gmres_solver_new** ()
  Description Create an empty PnlGmresSolver

- PnlGmresSolver ∗ **pnl_gmres_solver_create** (int Size, int max-iter, int restart, double tolerance)
  Description Create a new PnlGmresSolver pointer.

- void **pnl_gmres_solver_initialisation** (PnlGmresSolver ∗Solver, const PnlVect ∗b)
  Description Initialisation of the solver at the beginning of iterative method.

- void **pnl_gmres_solver_free** (PnlGmresSolver ∗∗Solver)
  Description Destructor of iterative solver

- int **pnl_gmres_solver_solve** (void(∗matrix vector-product)(const void ∗, const PnlVect ∗, const double, const double, PnlVect ∗), const void ∗Matrix-Data, void(∗matrix vector-product-PC)(const void ∗, const PnlVect ∗, const double, const double, PnlVect ∗), const void ∗PC-Data, PnlVect ∗x, const PnlVect ∗b, PnlGmresSolver ∗Solver)
  Description Solve the linear system matrix vector-product is the matrix vector multiplication function matrix vector-product-PC is the preconditionner function Matrix-Data & PC-Data is data to compute matrix vector multiplication.

In the next paragraph, we write all the solvers for PnlMat . This will be done as follows: construct an application matrix vector.

```
static void pnl_mat_mult_vect_applied(const void *mat, const PnlVect *vec,
                                       const double a , const double b,
                                       PnlVect *lhs)
{pnl_mat_lAxpby(a, (PnlMat*)mat, vec, b, lhs);}
```

and give it as the parameter of the iterative method

```
int pnl_mat_cg_solver_solve(const PnlMat * Matrix, const PnlMat * PC,
                            PnlVect * x, const PnlVect *b, PnlCgSolver * Solver)
{ return pnl_cg_solver_solve(pnl_mat_mult_vect_applied,
                             Matrix, pnl_mat_mult_vect_applied,
                             PC, x, b, Solver);}
```

In practice, we cannot define all iterative methods for all structures. With this implementation, the user can easily :

- implement right precondioner,
- implement method with sparse matrix and diagonal preconditioner, or special combination of this form ...

Iterative algorithms for PnlMat

- int **pnl_mat_cg_solver_solve** (const PnlMat *M, const PnlMat *PC, PnlVect *x, const PnlVect *b, PnlCgSolver *Solver)
  Description Solve the linear system `M x = b` with preconditionner PC.
- int **pnl_mat_bicg_solver_solve** (const PnlMat *M, const PnlMat *PC, PnlVect *x, const PnlVect *b, PnlBicgSolver *Solver)
  Description Solve the linear system `M x = b` with preconditionner PC.
- int **pnl_mat_gmres_solver_solve** (const PnlMat *M, const PnlMat *PC, PnlVect *x, PnlVect *b, PnlGmresSolver *Solver)
  Description Solve the linear system `M x = b` with preconditionner PC.

5 Cumulative distribution Functions

The functions related to this chapter are declared in `pnl/pnl_cdf.h`.
For various distribution functions, we provide functions named `pnl_cdf_xxx` where `xxx` is the abbreviation of the distribution name. All these functions are based on the same prototype

$$p = 1 - q; \quad p = \int^{x} density(u)du$$

- `which` If `which=1`, it computes `p` and `q`. If `which=2`, it computes `x`. For higher values of `which` it computes one the parameters characterizing the distribution using all the others, `p, q, x`.
- `p` the probability $\int^x density(u)du$
- `q` $= 1 - p$
- `x` the upper bound of the integral
- `status` an integer which indicates on exit the success of the computation. (0) if calculation completed correctly. (-I) if the input parameter number I was out of range. (1) if the answer appears to be lower than the lowest search bound. (2) if the answer appears to be higher than the greatest search bound. (3) if $p + q \neq 1$.
- `bound` is undefined if STATUS is 0. Bound exceeded by parameter number I if STATUS is negative. Lower search bound if STATUS is 1. Upper search bound if STATUS is 2.

- void **pnl_cdf_bet** (int *which, double *p, double *q, double *x, double *y, double *a, double *b, int *status, double *bound)
  Description Cumulative Distribution Function BETA distribution.

- void **pnl_cdf_bin** (int ∗which, double ∗p, double ∗q, double ∗x, double ∗xn, double ∗pr, double ∗ompr, int ∗status, double ∗bound)
Description Cumulative Distribution Function BINa distribution.

- void **pnl_cdf_chi** (int ∗which, double ∗p, double ∗q, double ∗x, double ∗df, int ∗status, double ∗bound)
Description Cumulative Distribution Function CHI-Square distribution.

- void **pnl_cdf_chn** (int ∗which, double ∗p, double ∗q, double ∗x, double ∗df, double ∗pnonc, int ∗status, double ∗bound)
Description Cumulative Distribution Function Non-central Chi-Square distribution.

- void **pnl_cdf_f** (int ∗which, double ∗p, double ∗q, double ∗x, double ∗dfn, double ∗dfd, int ∗status, double ∗bound)
Description Cumulative Distribution Function F distribution.

- void **pnl_cdf_fnc** (int ∗which, double ∗p, double ∗q, double ∗x, double ∗dfn, double ∗dfd, double ∗pnonc, int ∗status, double ∗bound)
Description Cumulative Distribution Function Non-central F distribution.

- void **pnl_cdf_gam** (int ∗which, double ∗p, double ∗q, double ∗x, double ∗shape, double ∗rate, int ∗status, double ∗bound)
Description Cumulative Distribution Function GAMma distribution. Note that the parameter `rate` is `1/scale`. The density writes $f(x) = 1/(s^a\Gamma(a))x^{a-1}e^{-x/s}$ with `scale=s` and `shape=1/rate=a`.

- void **pnl_cdf_nbn** (int ∗which, double ∗p, double ∗q, double ∗x, double ∗xn, double ∗pr, double ∗ompr, int ∗status, double ∗bound)
Description Cumulative Distribution Function Negative BiNomial distribution.

- void **pnl_cdf_nor** (int ∗which, double ∗p, double ∗q, double ∗x, double ∗mean, double ∗sd, int ∗status, double ∗bound)
Description Cumulative Distribution Function NORmal distribution.

- void **pnl_cdf_poi** (int ∗which, double ∗p, double ∗q, double ∗x, double ∗xlam, int ∗status, double ∗bound)
Description Cumulative Distribution Function POIsson distribution.

- void **pnl_cdf_t** (int ∗which, double ∗p, double ∗q, double ∗x, double ∗df, int ∗status, double ∗bound)
Description Cumulative Distribution Function T distribution.

- double **pnl_cdfchi2n** (double x, double df, double ncparam)
Description Compute the cumulative density function at `x` of the non central χ^2 distribution with `df` degrees of freedom and non centrality parameter `ncparam`.

- void **pnl_cdfbchi2n** (double x, double df, double ncparam, double beta, double ∗P)
Description Store in `P` the cumulative density function at `x` of the random variable `beta *X` where `X` is non central χ^2 random variable with `df` degrees of freedom and non centrality parameter `ncparam`.

- double **pnl_normal_density** (double x)
  Description Normal density function.

- double **pnl_cdfnor** (double x)
  Description Cumulative normal distribution function.

- double **pnl_cdf2nor** (double a, double b, double r)
  Description Cumulative bivariate normal distribution function, returns $\frac{1}{2\pi\sqrt{1-r^2}} \int_{-\infty}^{a} \int_{-\infty}^{b} e^{-\frac{x^2-2rxy+y^2}{2(1-r^2)}} dxdy$.

- double **pnl_inv_cdfnor** (double x)
  Description Inverse of the cumulative normal distribution function.

6 Random Number Generators

The functionalities described in this chapter are declared in `pnl/pnl_random.h`.
Random number generators should be called through the new *rng* interface based on the PnlRng object. This interface uses reentrant functions and is suitable for multi-threaded applications.
The older *rand* interface is kept for compatibility purposes only and should not be used in new code.

Random generator	index	Type	Info
KNUTH	PNL_RNG_KNUTH	pseudo	
MRGK3	PNL_RNG_MRGK3	pseudo	
MRGK5	PNL_RNG_MRGK5	pseudo	
SHUFL	PNL_RNG_SHUFL	pseudo	
L'ECUYER	PNL_RNG_L_ECUYER	pseudo	
TAUSWORTHE	PNL_RNG_TAUSWORTHE	pseudo	
MERSENNE	PNL_RNG_MERSENNE	pseudo	
SQRT	PNL_RNG_SQRT	quasi	
HALTON	PNL_RNG_HALTON	quasi	
FAURE	PNL_RNG_FAURE	quasi	
SOBOL_I4	PNL_RNG_SOBOL_I4	quasi	uses 32 bit intergers
SOBOL_I8	PNL_RNG_SOBOL2_I8	quasi	uses 64 bit intergers
NIEDERREITER	PNL_RNG_NIEDERREITER	quasi	

Table 2: Indices of the random generators

6.1 The rng interface

It is possible to create several random number generators each with its own state variable so that they can evolve independently in a shared memory environment. These generators are suitable for use in multi-threaded programs.

```
typedef struct _PnlRng PnlRng;
struct _PnlRng
```

```
{
  PnlObject object;
  int type; /*!< generator type *
  void (*Compute)(PnlRng *g, double *sample); /*!< the function to compute the
                                                   next number in the sequence */
  int rand_or_quasi; /*!< can be PNL_MC or PNL_QMC */
  int dimension; /*!< dimension of the space in which we draw the samples */
  int counter; /*!< counter = number of samples already drawn */
  int has_gauss; /*!< Is a gaussian deviate available? */
  double gauss; /*!< If has_gauss==1, gauss a gaussian sample */
  int size_state; /*!< size in bytes of the state variable */
  void *state; /*!< state of the random generator */
};
```

- void **pnl_rng_free** (PnlRng ∗∗)
  Description Free a PnlRng .
- PnlRng ∗ **pnl_rng_create** (int type)
  Description Create a PnlRng corresponding to `type` which can be any of the values `PNL_RNG_XXX` listed in Table 2 which correspond to **pseudo** random number generators. Once a generator has been created, you **must** call pnl_rng_sseed before using it.
- void **pnl_rng_sseed** (PnlRng ∗rng, unsigned long int s)
  Description Set the seed of the genrator `rng` using `s`. If `s=0`, then a default seed (depending on the generator) is used.
- int **pnl_rng_sdim** (PnlRng ∗rng, int dim)
  Description Set the dimension of the state space for a QMC generator and initializes it accordingly. Returns OK if the generator has been initialized properly and FAIL otherwise.
- PnlRng ∗ **pnl_rng_copy** (const PnlRng ∗rng)
  Description Create a copy of `rng`.
- void **pnl_rng_clone** (PnlRng ∗dest, const PnlRng ∗src)
  Description Copy the content of `src` into the already existing basis `dest`. On exit, `src` and `dest` are identical but independent.
- PnlRng ∗ **pnl_rng_dcmt_create_id** (int id, ulong seed)
  Description Create a generator with type `PNL_RNG_DCMT` and identifier `id`. Two generators with different `id`s are independent. Note that the returned generator must be initialized with pnl_rng_sseed before usage. The identifier `id` can for instance correspond to the thread number or the processor rank in parallel computing.
- PnlRng ∗∗ **pnl_rng_dcmt_create_array_id** (int start_id, int max_id, ulong seed, int ∗count)
  Description Create an array of generators with types `PNL_RNG_DCMT` and identifiers linearly varying between `start_id` and `max_id`. The number of generators created is `max_id - start_id + 1`. All the generators are independent. Note that each generator of the returned array must be initialized with pnl_rng_sseed before usage.

- PnlRng ** **pnl_rng_dcmt_create_array** (int n, ulong seed, int *count)
  Description Create an array of `n` independent DCMT. `seed` is the seed used to initialize the Mersenne Twister generator internally used to find new DCMT. On exit, `count` contains the number of generators actually created. Before using the generators, you must initialize each of them by calling the function pnl_rng_sseed `count` times.

Some auxiliary functions internally used (to be used with caution)

- PnlRng * **pnl_rng_new** ()
  Description Create an empty PnlRng .

- void **pnl_rng_init** (PnlRng *rng, int type)
  Description Initialize an empty PnlRng as returned by pnl_rng_new to become a generator of type `type` which can be any of the values `PNL_RNG_XXX` listed in Table 2 which correspond to **pseudo** random number generators. Calling pnl_rng_create is equivalent to calling first pnl_rng_new and then pnl_rng_init.

- PnlRng * **pnl_rng_get_from_id** (int id)
  Description Return the global generator described by its macro name. The variable `id` can be any of the values `PNL_RNG_XXX` listed in Table 2.

The following functions return one sample from the specified distribution.

- int **pnl_rng_bernoulli** (double p, PnlRng *rng)
  Description Generate a sample from the Bernouilli law on $\{0, 1\}$ with parameter `p`.

- long **pnl_rng_poisson** (double lambda, PnlRng *rng)
  Description Generate a sample from the Poisson law with parameter `lambda`.

- double **pnl_rng_exp** (double lambda, PnlRng *rng)
  Description Generate a sample from the Exponential law with parameter `lambda`.

- double **pnl_rng_dblexp** (double lambda_p, double lambda_m, double p, PnlRng *rng)
  Description Generate a sample from the asymmetric exponential distribution with density
  $$p\lambda_p \, \mathrm{e}^{-\lambda_p y} \, 1_{\{y>0\}} + (1-p)\lambda_m \, \mathrm{e}^{-\lambda_m |y|} \, 1_{\{y<0\}}$$
  where $\lambda_p > 0, \lambda_m > 0$ and $p \in [0, 1]$.

- double **pnl_rng_uni** (PnlRng *rng)
  Description Generate a sample from the Uniform law on $]0, 1]$.

- double **pnl_rng_uni_ab** (double a, double b, PnlRng *rng)
  Description Generate a sample from the Uniform law on $[a, b]$.

- double **pnl_rng_normal** (PnlRng *rng)
  Description Generate a sample from the standard normal distribution.

- double **pnl_rng_lognormal** (double m, double sigma2, PnlRng *rng)
  Description Generate a sample from the log-normal distribution. The underlying normal distribution has mean `m` and variance `sigma2`.

- double **pnl_rng_invgauss** (double mu, double lambda, PnlRng *rng)
  Description Generate a sample from the inverse Gaussian distribution with mean `mu` and shape parameter `lambda`.

- long **pnl_rng_poisson1** (double lambda, double t,PnlRng *rng)
  Description Generate a sample from a Poisson process with intensity `lambda` at time `t`.

- double **pnl_rng_gamma** (double a, double b, PnlRng *rng)
  Description Generate a sample from the $\Gamma(a, b)$ distribution.

- double **pnl_rng_chi2** (double df, PnlRng *rng)
  Description Generate a sample from the centered $\chi^2(df)$ distribution.

- double **pnl_rng_ncchi2** (double df, double xnonc, PnlRng *rng)
  Description Generate a sample from the non central χ^2 distribution with `df` degrees of freedom and non central parameter `xnonc`.

- double **pnl_rng_bessel** (double v, double a,PnlRng *rng)
  Description Generate a sample from the Bessel distribution with parameters `v > -1` and `a > 0`.

- double **pnl_rng_gauss** (int d, int create_or_retrieve, int index, PnlRng *rng)
  Description The second argument can be either `CREATE` (to actually draw the sample) or `RETRIEVE` (to retrieve that element of index `index`). With `CREATE`, it draws `d` random normal variables and stores them for future usage. They can be withdrawn using `RETRIEVE` with the index of the number to be retrieved.

The following functions take an already existing PnlVect *as first argument and fill each entry of the vector with a sample from the specified distribution. All the entries are independent. The difference between $n-$samples from a distribution in dimension 1, and one sample from the same distribution in dimension n only matters when using a **quasi** random number generator.

- void **pnl_vect_rng_bernoulli** (PnlVect *V, int samples, double a, double b, double p, PnlRng *rng)
  Description Simulate an i.i.d. sample from the Bernoulli distribution with values in `a,b` and parameter `p`. The result is stored in `V`.

- void **pnl_vect_rng_bernoulli_d** (PnlVect *V, int dimension, const PnlVect *a, const PnlVect *b, const PnlVect *p, PnlRng *rng)
  Description Simulate a random vector according to the Bernoulli distribution with values in `{a,b}` and parameter `p`. The result is stored in `V`, ie. `V(i)` follows a Bernoulli distribution on `{a(i), b(i)}` with parameter `p(i)`.

- void **pnl_vect_rng_poisson** (PnlVect *V, int samples, double lambda, PnlRng *rng)
  Description Simulate an i.i.d. sample from the Poisson distribution with parameter `lambda`. The result is stored in `V`. Note that, we are using double based vectors and not integer based vectors.

- void **pnl_vect_rng_poisson_d** (PnlVect *V, int dimension, const PnlVect *lambda, PnlRng *rng)

Description Simulate a random vector according to the Poisson distribution with **vector** parameter `lambda`. The result is stored in `V`, ie. `V(i)` follows a Poisson distribution with parameter `lambda(i)`. Note that, we are using double based vectors and not integer based vectors.

- void **pnl_vect_rng_uni** (PnlVect *G, int samples, double a, double b, PnlRng *rng)
  Description `G` is a vector of independent and identically distributed samples from the uniform distribution on $[a, b]$.

- void **pnl_vect_rng_normal** (PnlVect *G, int samples, PnlRng *rng)
  Description `G` is a vector of independent and identically distributed samples from the standard normal distribution.

- void **pnl_vect_rng_uni_d** (PnlVect *G, int d, double a, double b, PnlRng *rng)
  Description `G` is a sample from the uniform distribution on $[a, b]^{\mathrm{d}}$.

- void **pnl_vect_rng_normal_d** (PnlVect *G, int d, PnlRng *rng)
  Description `G` is a sample from the `d`-dimensional standard normal distribution.

The following functions take an already existing PnlMat *as first argument and fill each entry of the matrix with a sample from the specified distribution. All the entries are independent. On return, the matrix `M` is of size `samples x dimension`. The rows of `M` are independent and identically distributed. Each row is a sample from the given law in dimension `dimension`.

- void **pnl_mat_rng_uni** (PnlMat *M, int samples, int d, const PnlVect *a, const PnlVect *b, PnlRng *rng)
  Description `M` contains `samples` samples from the uniform distribution on $\prod_{i=1}^{d}[a_i, b_i]$.

- void **pnl_mat_rng_uni2** (PnlMat *M, int samples, int d, double a, double b, PnlRng *rng)
  Description `M` contains `samples` samples from the uniform distribution on $[a, b]^{\mathrm{d}}$.

- void **pnl_mat_rng_normal** (PnlMat *M, int samples, int d, PnlRng *rng)
  Description `M` contains `samples` samples from the `d`-dimensional standard normal distribution.

- void **pnl_mat_rng_bernoulli** (PnlMat *M, int samples, int dimension, const PnlVect *a, const PnlVect *b, const PnlVect *p, PnlRng *rng)
  Description Compute a random matrix with independent rows, each of them having a vector Bernoulli distribution, ie. `M(i, j)` follows a Bernoulli distribution on `{a(j), b(j)}` with parameter `p(j)`.

- void **pnl_mat_rng_poisson** (PnlMat *M, int samples, int dimension, const PnlVect *lambda, PnlRng *rng)
  Description Compute a random matrix with independent rows, each of them having a vector Poisson distribution, ie. `M(i, j)` follows a Poisson distribution with parameter `p(j)`.

Some examples

```
#include <stdlib.h>
#include "pnl/pnl_random.h"

int main ()
{
  int i, M;
  PnlRng *rng = pnl_rng_create(PNL_RNG_MERSENNE);
  PnlVect *v = pnl_vect_new();
  M = 10000;

  /* rng must be initialized. When sseed=0, a default
     value depending on the generator is used */
     pnl_rng_sseed(rng, 0);

  for (i=0 ; i<M ; i++)
  {
    /* Simulates a normal random vector in R^{10} */
    pnl_vect_rng_normal(v, 10, rng);
    /* Do something with v */
  }

  pnl_vect_free(&v);
  pnl_rng_free(&rng); /* Frees the generator */
  exit(0);
}
```

```
#include <stdlib.h>
#include <time.h>
#include "pnl/pnl_random.h"

int main ()
{
  int i, M;
  double E;
  PnlRng *rng = pnl_rng_create(PNL_RNG_MERSENNE);
  M = 10000;

  /* rng must be initialized. */
  pnl_rng_sseed(rng, time (NULL));

  for (i=0 ; i<M ; i++)
  {
    /* Simulates an exponential random variable */
    E = pnl_rng_exp(1, rng);
    /* Do something with E */
  }
```

```
  pnl_rng_free(&rng); /* Frees the generator */
  exit(0);
}
```

6.2 The *rand* interface (deprecated)

Note: *For backward compatibility with older versions of the PNL, we still provide the old* rand *interface to random number generation although we strongly encourage users to use the new* rng *interface (see section 6.1).*
Every generator is identified by an integer valued macro. One must **NOT** refer to a generator using directly the value of the macro `PNL_RNG_XXX` because there is no warranty that the order used to store the generators will remain the same in future releases. Instead, one should call generators directly using their macro names.
The initial seeds of all the generators are fixed by the function pnl_rand_init but you can change it by calling pnl_rand_sseed.
Before starting to use random number generators, you **must** initialize them by calling

- int **pnl_rand_init** (int type_generator, int simulation_dim, long samples)
  Description It resets the sample counter to 0 and checks that the generator described by `type_generator` can actually generate `samples` in dimension `simulation_dim` and fixes the seed.

- int **pnl_rand_or_quasi** (int type_generator)
  Description Return the type the generator of index `type_generator`, `PNL_MC` or `PNL_-QMC`

- void **pnl_rand_sseed** ((int type_generator, unsigned long int seed))
  Description It sets the seed of the generator `type_generator` with `seed`.

- const char $*$ **pnl_rand_name** (int type_generator)
  Description Return the name of the generator of index `type_generator`

Once a generator is chosen, there are several functions available in the library to draw samples according to a given law.
The following functions return one sample from a specified law.

- int **pnl_rand_bernoulli** (double p, int type_generator)
  Description Generate a sample from the Bernouilli law on $\{0, 1\}$ with parameter `p`.

- long **pnl_rand_poisson** (double lambda, int type_generator)
  Description Generate a sample from the Poisson law with parameter `lambda`.

- double **pnl_rand_exp** (double lambda, int type_generator)
  Description Generate a sample from the Exponential law with parameter `lambda`.

- double **pnl_rand_uni** (int type_generator)
  Description Generate a sample from the Uniform law on $[0, 1]$.

- double **pnl_rand_uni_ab** (double a, double b, int type_generator)
  Description Generate a sample from the Uniform law on $[a, b]$.

- double **pnl_rand_normal** (int type_generator)
  Description Generate a sample from the standard normal distribution.
- long **pnl_rand_poisson1** (double lambda, double t, int type_generator)
  Description Generate a sample from a Poisson process with intensity `lambda` at time `t`.
- double **pnl_rand_gamma** (double a, double b, int type_generator)
  Description Generate a sample from the $\Gamma(a, b)$ distribution.
- double **pnl_rand_chi2** (double n, int type_generator)
  Description Generate a sample from the centered $\chi^2(n)$ distribution.
- double **pnl_rand_bessel** (double v, double a, int generator)
  Description Generate a sample from the Bessel distribution with parameters `v > -1` and `a > 0`.

The following functions take an already existing PnlVect $*$ as its first argument and fill each entry of the vector with a sample from the specified law. All the entries are independent. The difference between $n-$samples from a distribution in dimension 1, and one sample from the same distribution in dimension n only matters when using a **Quasi** random number generator.

- void **pnl_vect_rand_uni** (PnlVect $*$G, int samples, double a, double b, int type_-generator)
  Description `G` is a vector of independent and identically distributed samples from the uniform distribution on $[a, b]$.
- void **pnl_vect_rand_normal** (PnlVect $*$G, int samples, int generator)
  Description `G` is a vector of independent and identically distributed samples from the standard normal distribution.
- void **pnl_vect_rand_uni_d** (PnlVect $*$G, int d, double a, double b, int type_-generator)
  Description `G` is a sample from the uniform distribution on $[a, b]^{\mathrm{d}}$.
- void **pnl_vect_rand_normal_d** (PnlVect $*$G, int d, int generator)
  Description `G` is a sample from the `d`-dimensional standard normal distribution.

The following functions take an already existing PnlMat $*$ as first argument and fill each entry of the vector with a sample from the specified law. All the entries are in-dependant. On return, the matrix `M` is of size `samples x dimension`. The rows of `M` are independently and identically distributed. Each row is a sample from the given law in dimension `dimension`.

- void **pnl_mat_rand_uni** (PnlMat $*$M, int samples, int d, const PnlVect $*$a, const PnlVect $*$b, int type_generator)
  Description `M` contains `samples` samples from the uniform distribution on $\prod_{i=1}^{d}[a_i, b_i]$.
- void **pnl_mat_rand_uni2** (PnlMat $*$M, int samples, int d, double a, double b, int type_generator)
  Description `M` contains `samples` samples from the uniform distribution on $[a, b]^{\mathrm{d}}$.
- void **pnl_mat_rand_normal** (PnlMat $*$M, int samples, int d, int type_generator)
  Description `M` contains `samples` samples from the `d`-dimensional standard normal distribution.

Because of the use of **Quasi** random number generators, you may need to draw a set of samples at once because they represent one sample from a multi-dimensional distribution. The following function enables to draw one sample from the `dimension`-dimensional standard normal distribution and store it so that you can access the elements individually afterwards.

- double **pnl_rand_gauss** (int d, int create_or_retrieve, int index, int type_generator)
  Description The second argument can be either `CREATE` (to actually draw the sample) or `RETRIEVE` (to retrieve that element of index `index`). With `CREATE`, it draws `d` random normal variables and stores them for future usage. They can be withdrawn using `RETRIEVE` with the index of the number to be retrieved.

7 Function bases and regression

7.1 Overview

To use these functionalities, you should include `pnl/pnl_basis.h`.

```
struct PnlBasis_t {
  PnlObject     object;
  /** The basis type */
  int           id;
  /** The string to label the basis */
  const char   *label;
  /** The number of variates */
  int           nb_variates;
  /** The total number of elements in the basis */
  int           nb_func;
  /** The tensor matrix */
  PnlMatInt    *T;
  /** The sparse Tensor matrix */
  PnlSpMatInt  *SpT;
  /** The number of functions in the tensor #T */
  int           len_T;
  /** The i-th element of the one dimensional basis. */
  double      (*f)(double    x, int i);
  /** The first derivative of i-th element of the one dimensional basis */
  double      (*Df)(double   x, int i);
  /** The second derivative of the i-th element of the one dimensional basis */
  double      (*D2f)(double  x, int i);
  /** TRUE if the basis is reduced */
  int           isreduced;
  /** The center of the domain */
  double       *center;
  /** The inverse of the scaling factor to map the domain to [-1, 1]^nb_variates */
  double       *scale;
  /** An array of additional functions */
  PnlRnFuncR   *func_list;
```

```
  /** The number of functions in #func_list */
  int          len_func_list;
};
```

A PnlBasis is a family of multivariate functions with real values. Tow different kinds of functions can be stored in these families: tensor functions — originally, this was the only possibility, and standard multivariate function typed as PnlRnFuncR.

Tensor functions. Tensors functions are built as a tensor product of one dimensional elements. Hence, we only need a tensor matrix `T` to describe a multi-dimensional basis in terms of the one dimensional one. These tensors functions can be easily evaluated and differentiated twice, see pnl_basis_eval, pnl_basis_eval_vect, pnl_basis_eval_D, pnl_basis_eval_D_vect, pnl_basis_eval_D2, pnl_basis_eval_D2_vect, pnl_basis_eval_derivs, pnl_basis_eval_derivs_vect.
The two tensors `T` and `SpT` do actually store the same information — `T(i,j)` is the degree w.r.t the `j`-th variable in the `i`-th function. Originally, we were only using the dense representation `T`, which is far more convenient to use when building the basis but it slows down the evaluation of the basis by a great deal. To overcome this lack of efficiency, a sparse storage has been added.

PNL_BASIS_CANONICAL	for the Canonical polynomials
PNL_BASIS_HERMITE	for the Hermite polynomials
PNL_BASIS_TCHEBYCHEV	for the Tchebychev polynomials

Table 3: Names of the bases. See also function pnl_basis_type_register to register more basis types.

The Hermite polynomials are defined by

$$H_n(x) = (-1)^n \mathrm{e}^{\frac{x^2}{2}} \frac{d^n}{dx^n} \mathrm{e}^{-\frac{x^2}{2}} .$$

If G is a real valued standard normal random variable, $\mathbb{E}[H_n(G)H_m(G)] = n! 1_{\{n=m\}}$.

Standard multivariate functions. These functions are supposed to be PnlRnFuncR.
To make this toolbox more complete, it is now possible to add some extra functions, which are not tensor product. They are stored using an independent mechanism in `func_list`. These additional functions are only taken into account by the methods pnl_basis_i, pnl_basis_i_vect, pnl_basis_eval and pnl_basis_eval_vect. Note in particular that it is not possible to differentiate these functions. To add an extra function to an existing PnlBasis, call the function pnl_basis_add_function.

7.2 Functions

- int **pnl_basis_type_register** (const char *name, double (*f)(double, int), double (*Df)(double, int), double (*D2f)(double, int))
  Description Register a new basis type and return the index to be passed to pnl_basis_create . The variable `name` is a unique string identifier of the family. The variables `f`,

Df, D2f are the one dimensional basis functions, its first and second order derivatives. Each of these functions must return a double and take two arguments : the first one is the point at which evaluating the basis functions, the second one is the index of function. Here is a toy example to show how the canonical basis is registered (this family is actually already available with the id PNL_BASIS_CANONICAL, so the following example may look a little fake)

```
double f(double x, int n) { return pnl_pow_i(x, n); }
double Df(double x, int n) { return n * pnl_pow_i(x, n-1); }
double f(double x, int n) { return n * (n-1) * pnl_pow_i(x, n-2); }

int id = pnl_basis_register ("Canonic", f, Df, D2f);
/*
 * B is the Canonical basis of polynomials with degree less or equal than 2 in
 * dimension 5.
 */
PnlBasis *B = pnl_basis_create_from_degree (id, 2, 5);
```

- PnlBasis * **pnl_basis_new** ()
  Description Create an empty PnlBasis .

- void **pnl_basis_print** (const PnlBasis *B)
  Description Print the characteristics of a basis.

- PnlBasis * **pnl_basis_create** (int index, int nb_func, int nb_variates)
  Description Create a PnlBasis for the family defined by index (see Table 3 and pnl_basis_type_register) with nb_variates variates. The basis will contain nb_func.

- PnlBasis * **pnl_basis_create_from_degree** (int index, int degree, int nb_variates)
  Description Create a PnlBasis for the family defined by index (see Table 3 and pnl_basis_type_register) with total degree less or equal than degree and nb_variates variates. The total degree is the sum of the partial degrees.
  For instance, calling pnl_basis_create_from_degree (index, 2, 4) is equivalent to

calling `pnl_basis_create_from_tensor (index, T)` where `T` is given by

$$\begin{pmatrix} 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 2 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 2 \end{pmatrix}$$

- PnlBasis * **pnl_basis_create_from_prod_degree** (int index, int degree, int nb_variates)
  Description Create a PnlBasis for the family defined by `index` (see Table 3 and pnl_basis_type_register) with total degree less or equal than `degree` and `nb_variates` variates. The total degree is the product of `MAX(1, d_i)` where the `d_i` are the partial degrees.

- PnlBasis * **pnl_basis_create_from_tensor** (int index, PnlMatInt *T)
  Description Create a PnlBasis for the polynomial family defined by `index` (see Table 3) using the basis described by the tensor matrix `T`. The number of lines of `T` is the number of functions of the basis whereas the numbers of columns of `T` is the number of variates of the functions. Note that `T` is not copied inside this function but only its address is stored, so **never** free `T`. It will be freed when calling pnl_basis_free on the returned object. i
  Here is an example of a tensor matrix. Assume you are working with three variate functions, the basis `{ 1, x, y, z, x^2, xy, yz, z^3}` is decomposed in the one dimensional canonical basis using the following tensor matrix

$$\begin{pmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 2 & 0 & 0 \\ 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 3 \end{pmatrix}$$

- void **pnl_basis_add_function** (PnlBasis *b, PnlRnFuncR *f)
  Description Add the function `f` to the already existing basis `b`.

- void **pnl_basis_clone** (PnlBasis *dest, const PnlBasis *src)
Description Clone `src` into `dest`. The basis `dest` must already exist before calling this function. On exit, `dest` and `src` are identical and independent.

- PnlBasis * **pnl_basis_copy** (const PnlBasis *B)
Description Create a copy of `B`.

- void **pnl_basis_set_from_tensor** (PnlBasis *b, int index, const PnlMatInt *T)
Description Set an alredy existing basis `b` to a polynomial family defined by `index` (see Table 3) using the basis described by the tensor matrix `T`. The number of lines of `T` is the number of functions of the basis whereas the numbers of columns of `T` is the number of variates of the functions.
Same function as pnl_basis_create_from_tensor except that it operates on an already existing basis.

- PnlBasis * **pnl_basis_create_from_hyperbolic_degree** (int index, double degree, double q, int n)
Description Create a sparse basis of polynomial with `n` variates. We give the example of the Canonical basis. A canonical polynomial with `n` variates writes $X_1^{\alpha_1} X_2^{\alpha_2} \dots X_n^{\alpha_n}$. To be a member of the basis, it must satisfy $(\sum_{i=1}^{n} {\alpha_i}^q)^{1/q} \le degree$. This kind of basis based on an hyperbolic set of indices gives priority to polynomials associated to low order interaction.

- void **pnl_basis_free** (PnlBasis **basis)
Description Free a PnlBasis created by pnl_basis_create. Beware that `basis` is the address of a PnlBasis *.

- void **pnl_basis_del_elt** (PnlBasis *B, const PnlVectInt *d)
Description Remove the function defined by the tensor product `d` from an existing basis `B`.

- void **pnl_basis_del_elt_i** (PnlBasis *B, int i)
Description Remove the `i-th` element of basis `B`.

- void **pnl_basis_add_elt** (PnlBasis *B, const PnlVectInt *d)
Description Add the function defined by the tensor `d` to the Basis `B`.

Functional regression based on a least square approach often leads to ill conditioned linear systems. One way of improving the stability of the system is to use centered and renormalised polynomials so that the original domain of interest $\mathcal{D}$ (a subset of $\mathbb{R}^d$) is mapped to $[-1,1]^d$. If the domain $\mathcal{D}$ is rectangular and writes $[a,b]$ where $a, b \in \mathbb{R}^d$, the mapping is done by

$$x \in \mathcal{D} \longmapsto \left(\frac{x_i - (b_i + a_i)/2}{(b_i - a_i)/2} \right)_{i=1,\cdots,d} \tag{1}$$

- void **pnl_basis_set_domain** (PnlBasis *B, const PnlVect *a, const PnlVect *b)
Description This function declares `B` as a centered and normalised basis as defined by Equation 1. Calling this function is equivalent to calling pnl_basis_set_reduced with `center=(b+a)/2` and `scale=(b-a)/2`.

- void **pnl_basis_set_reduced** (PnlBasis *B, const PnlVect *center, const PnlVect *scale)
Description This function declares `B` as a centered and normalised basis using the mapping

$$x \in \mathcal{D} \longmapsto \left(\frac{x_i - \texttt{center}_i}{\texttt{scale}_i} \right)_{i=1,\cdots,d}$$

- int **pnl_basis_fit_ls** (PnlBasis *P, PnlVect *coef, PnlMat *x, PnlVect *y)
Description Compute the coefficients `coef` defined by

$$\texttt{coef} = \arg\min_{\alpha} \sum_{i=1}^{n} \left(\sum_{j=0}^{\texttt{N}} \alpha_j P_j(x_i) - y_i \right)^2$$

where `N` is the number of functions to regress upon and n is the number of points at which the values of the original function are known. P_j is the $j-th$ basis function. Each row of the matrix `x` defines the coordinates of one point x_i. The function to be approximated is defined by the vector `y` of the values of the function at the points `x`.

- double **pnl_basis_ik_vect** (const PnlBasis *b, const PnlVect *x, int i, int k)
Description An element of a basis writes $\prod_{l=0}^{\texttt{nb}_\texttt{v}\texttt{ariates}} \phi_l(x_l)$ where the ϕ's are one dimensional polynomials. This functions computes the therm ϕ_k of the `i-th` basis function at the point `x`.

- double **pnl_basis_i_vect** (const PnlBasis *b, const PnlVect *x, int i)
Description If `b` is composed of $f_0, \dots, f_{\texttt{nb\_func}-1}$, then this function returns $f_i(x)$.

- double **pnl_basis_i_D_vect** (const PnlBasis *b, const PnlVect *x, int i, int j)
Description If `b` is composed of $f_0, \dots, f_{\texttt{nb\_func}-1}$, then this function returns $\partial_{x_\texttt{j}} f_i(x)$.

- double **pnl_basis_i_D2_vect** (const PnlBasis *b, const PnlVect *x, int i, int j1, int j2)
Description If `b` is composed of $f_0, \dots, f_{\texttt{nb\_func}-1}$, then this function returns $\partial^2_{x_{\texttt{j1}}, x_{\texttt{j2}}} f_i(x)$.

- void **pnl_basis_eval_derivs_vect** (const PnlBasis *b, const PnlVect *coef, const PnlVect *x, double *fx, PnlVect *Dfx, PnlMat *D2fx)
Description Compute the function, the gradient and the Hessian matrix of $\sum_{k=0}^{n} \texttt{coef}_k P_k(\cdot)$ at the point `x`. On output, `fx` contains the value of the function, `Dfx` its gradient and `D2fx` its Hessian matrix. This function is optimized and performs much better than calling pnl_basis_eval, pnl_basis_eval_D and pnl_basis_eval_D2 sequentially.

- double **pnl_basis_eval_vect** (const PnlBasis *basis, const PnlVect *coef, const PnlVect *x)
Description Compute the linear combination of `P_k(x)` defined by `coef`. Given the coefficients computed by the function pnl_basis_fit_ls, this function returns $\sum_{k=0}^{n} \texttt{coef}_k P_k(\texttt{x})$.

- double **pnl_basis_eval_D_vect** (const PnlBasis *basis, const PnlVect *coef, const PnlVect *x, int i)

Description Compute the derivative with respect to `x_i` of the linear combination of `P_k(x)` defined by `coef`. Given the coefficients computed by the function pnl_basis_-fit_ls, this function returns $\partial_{x_i} \sum_{k=0}^{n} \texttt{coef}_k P_k(\texttt{x})$ The index `i` may vary between `0` and `P->nb_variates - 1`.

- double **pnl_basis_eval_D2_vect** (const PnlBasis *basis, const PnlVect *coef, const PnlVect *x, int i, int j)
  Description Compute the derivative with respect to `x_i` of the linear combination of `P_k(x)` defined by `coef`. Given the coefficients computed by the function pnl_basis_-fit_ls, this function returns $\partial_{x_i} \partial_{x_j} \sum_{k=0}^{n} \texttt{coef}_k P_k(\texttt{x})$. The indices `i` and `j` may vary between `0` and `P->nb_variates - 1`.

The following functions are provided for compatibility purposes but are marked as deprecated. Use the functions with the `_vect` extension.

- double **pnl_basis_ik** (const PnlBasis *b, const double *x, int i, int k)
  Description Same as function pnl_basis_ik_vect but takes a C array as the point of evaluation.

- double **pnl_basis_i** (PnlBasis *b, double *x, int i)
  Description Same as function pnl_basis_i_vect but takes a C array as the point of evaluation.

- double **pnl_basis_i_D** (const PnlBasis *b, const double *x, int i, int j)
  Description Same as function pnl_basis_i_D_vect but takes a C array as the point of evaluation.

- double **pnl_basis_i_D2** (const PnlBasis *b, const double *x, int i, int j1, int j2)
  Description Same as function pnl_basis_i_D2_vect but takes a C array as the point of evaluation.

- double **pnl_basis_eval** (PnlBasis *P, PnlVect *coef, double *x)
  Description Same as function pnl_basis_eval_vect but takes a C array as the point of evaluation.

- double **pnl_basis_eval_D** (PnlBasis *P, PnlVect *coef, double *x, int i)
  Description Same as function pnl_basis_eval_D_vect but takes a C array as the point of evaluation.

- double **pnl_basis_eval_D2** (PnlBasis *P, PnlVect *coef, double *x, int i, int j)
  Description Same as function pnl_basis_eval_D2_vect but takes a C array as the point of evaluation.

- void **pnl_basis_eval_derivs** (PnlBasis *P, PnlVect *coef, double *x, double *fx, PnlVect *Dfx, PnlMat *D2fx)
  Description Same as function pnl_basis_eval_derivs_vect but takes a C array as the point of evaluation.

8 Numerical integration

8.1 Overview

To use these functionalities, you should include `pnl/pnl_integration.h`.
Numerical integration methods are designed to numerically evaluate the integral over a finite or non finite interval (resp. over a square) of real valued functions defined on $\mathbb{R}$ (resp. on $\mathbb{R}^2$).

```
typedef struct {
  double (*function) (double x, void *params);
  void *params;
} PnlFunc;

typedef struct {
  double (*function) (double x, double y, void *params);
  void *params;
} PnlFunc2D;
```

We provide the following two macros to evaluate a PnlFunc or PnlFunc2D at a given point

```
#define PNL_EVAL_FUNC(F, x) (*((F)->function))(x, (F)->params)
#define PNL_EVAL_FUNC2D(F, x, y) (*((F)->function))(x, y, (F)->params)
```

8.2 Functions

- double **pnl_integration** (PnlFunc *F, double x0, double x1, int n, char *meth)
  Description Evaluate $\int_{x_0}^{x_1} F$ using `n` discretization steps. The method used to discretize the integral is defined by `meth` which can be `"rect"` (rectangle rule), `"trap"` (trapezoidal rule), `"simpson"` (Simpson's rule).

- double **pnl_integration_2d** (PnlFunc2D *F, double x0, double x1, double y0, double y1, int nx, int ny, char *meth)
  Description Evaluate $\int_{[x_0,x_1]\times[y_0,y_1]} F$ using `nx` (resp. `ny`) discretization steps for `[x0, x1]` (resp. `[y0, y1]`). The method used to discretize the integral is defined by `meth` which can be `"rect"` (rectangle rule), `"trap"` (trapezoidal rule), `"simpson"` (Simpson's rule).

- int **pnl_integration_qng** (PnlFunc *F, double x0, double x1, double epsabs, double epsrel, double *result, double *abserr, int *neval)
  Description Evaluate $\int_{x_0}^{x_1} F$ with an absolute error less than `espabs` and a relative error less than `esprel`. The value of the integral is stored in `result`, while the variables `abserr` and `neval` respectively contain the absolute error and the number of function evaluations. This function returns `OK` if the required accuracy has been reached and `FAIL` otherwise. This function uses a non-adaptive Gauss Konrod procedure (qng routine from *QuadPack*).

- int **pnl_integration_GK** (PnlFunc *F, double x0, double x1, double epsabs, double epsrel, double *result, double *abserr, int *neval)

Description This function is a synonymous of pnl_integration_qng and is only available for backward compatibility. It is deprecated, please use pnl_integration_qng instead.

- int **pnl_integration_qng_2d** (PnlFunc2D *F, double x0, double x1, double y0, double y1, double epsabs, double epsrel, double *result, double *abserr, int *neval)
  Description Evaluate $\int_{[x_0,x_1]\times[y_0,y_1]} F$ with an absolute error less than `espabs` and a relative error less than `esprel`. The value of the integral is stored in `result`, while the variables `abserr` and `neval` respectively contain the absolute error and the number of function evaluations. This function returns `OK` if the required accuracy has been reached and `FAIL` otherwise.

- int **pnl_integration_GK2D** (PnlFunc *F, double x0, double x1, double epsabs, double epsrel, double *result, double *abserr, int *neval)
  Description This function is a synonymous of pnl_integration_qng_2d and is only available for backward compatibility. It is deprecated, please use pnl_integration_qng_2d instead.

- int **pnl_integration_qag** (PnlFunc *F, double x0, double x1, double epsabs, int limit, double epsrel, double *result, double *abserr, int *neval)
  Description Evaluate $\int_{x_0}^{x_1} F$ with an absolute error less than `espabs` and a relative error less than `esprel`. `x0` and `x1` can be non finite (i.e. `PNL_NEGINF` or `PNL_POSINF`). The value of the integral is stored in `result`, while the variables `abserr` and `neval` respectively contain the absolute error and the number of iterations. `limit` is the maximum number of subdivisions of the interval `(x0,x1)` used during the integration. If on input, `limit 0`, then 750 subdivisions are used. This function returns `OK` if the required accuracy has been reached and `FAIL` otherwise. This function uses some adaptive procedures (qags and qagi routines from *QuadPack*). This function is able to handle functions `F` with integrable singularities on the interval `[x0,x1]`.

- int **pnl_integration_qagp** (PnlFunc *F, double x0, double x1, const PnlVect *singularities, double epsabs, int limit, double epsrel, double *result, double *abserr, int *neval)
  Description Evaluate $\int_{x_0}^{x_1} F$ for a function `F` with known singularities listed in `singularities`. `singularities` must be a sorted vector which does not contain `x0` nor `x1`. `x0` and `x1` must be finite. The value of the integral is stored in `result`, while the variables `abserr` and `neval` respectively contain the absolute error and the number of iterations. `limit` is the maximum number of subdivisions of the interval `(x0,x1)` used during the integration. If on input, `limit = 0`, then 750 subdivisions are used. This function returns `OK` if the required accuracy has been reached and `FAIL` otherwise. This function uses some adaptive procedures (qagp routine from *QuadPack*). This function is able to handle functions `F` with integrable singularities on the interval `[x0,x1]`.

9 Fast Fourier Transform

9.1 Overview

The forward Fourier transform of a vector c is defined by

$$z_j = \sum_{k=1}^{N} c_k \, \mathrm{e}^{-i(j-1)(k-1)2\pi/N}, \quad j = 1, \cdots, N$$

The inverse Fourier transform enables to recover c from z and is defined by

$$c_k = \sum_{j=1}^{N} z_j \, \mathrm{e}^{i(j-1)(k-1)2\pi/N}, \quad j = 1, \cdots, N$$

The coefficients of the Fourier transform of a real function satisfy the following relation

$$z_k = \overline{z_{N-k}}, \tag{2}$$

where N is the number of discretization points.
A few remarks on the FFT of real functions and its inverse transform:

- We only need half of the coefficients.
- When a value is known to be real, its imaginary part is not stored. So the imaginary part of the zero-frequency component is never stored as it is known to be zero.
- For a sequence of even length the imaginary part of the frequency $n/2$ is not stored either, since the symmetry (2) implies that this is purely real too.

FFTPack storage The functions use the fftpack storage convention for half-complex sequences. In this convention, the half-complex transform of a real sequence is stored with frequencies in increasing order, starting from zero, with the real and imaginary parts of each frequency in neighboring locations.
The storage scheme is best shown by some examples. The table below shows the output for an odd-length sequence, $n = 5$. The two columns give the correspondence between the 5 values in the half-complex sequence (stored in a PnlVect V) and the values (PnlVectComplex C) that would be returned if the same real input sequence were passed to pnl_dft_complex as a complex sequence (with imaginary parts set to 0),

$$\begin{aligned} &C(0) = V(0) + \imath 0, \\ &C(1) = V(1) + \imath V(2), \\ &C(2) = V(3) + \imath V(4), \\ &C(3) = V(3) - \imath V(4) = \overline{C(2)}, \\ &C(4) = V(1) + \imath V(2) = \overline{C(1)} \end{aligned} \tag{3}$$

The elements of index greater than $N/2$ of the complex array, as $C(3)$ $C(4)$, are filled in using the symmetry condition.

The next table shows the output for an even-length sequence, $n = 6$. In the even case there are two values which are purely real,

$$\begin{array}{l} C(0) = V(0) + \imath 0, \\ C(1) = V(1) + \imath V(2), \\ C(2) = V(3) + \imath V(4), \\ C(3) = V(5) - \imath 0 = \overline{C(0)}, \\ C(4) = V(3) - \imath V(4) = \overline{C(2)}, \\ C(5) = V(1) + \imath V(2) = \overline{C(1)} \end{array} \tag{4}$$

9.2 Functions

To use the following functions, you should include `pnl/pnl_fft.h`.
The following functions comes from a C version of the Fortran FFTPack library available on `http://www.netlib.org/fftpack`.

- int **pnl_fft_inplace** (PnlVectComplex *data)
  Description Compute the FFT of `data` in place. The original content of `data` is lost.

- int **pnl_ifft_inplace** (PnlVectComplex *data)
  Description Compute the inverse FFT of `data` in place. The original content of `data` is lost.

- int **pnl_fft** (const PnlVectComplex *in, PnlVectComplex *out)
  Description Compute the FFT of `in` and stores it into `out`.

- int **pnl_ifft** (const PnlVectComplex *in, PnlVectComplex *out)
  Description Compute the inverse FFT of `in` and stores it into `out`.

- int **pnl_fft2** (double *re, double *im, int n)
  Description Compute the FFT of the vector of length `n` whose real (resp. imaginary) parts are given by the arrays `re` (resp. `im`). The real and imaginary parts of the FFT are respectively stored in `re` and `im` on output.

- int **pnl_ifft2** (double *re, double *im, int n)
  Description Compute the inverse FFT of the vector of length `n` whose real (resp. imaginary) parts are given by the arrays `re` (resp. `im`). The real and imaginary parts of the inverse FFT are respectively stored in `re` and `im` on output.

- int **pnl_real_fft** (const PnlVect *in, PnlVectComplex *out)
  Description Compute the FFT of the real valued sequence `in` and stores it into `out`.

- int **pnl_real_ifft** (const PnlVect *in, PnlVectComplex *out)
  Description Compute the inverse FFT of `in` and stores it into `out`.

- int **pnl_real_fft_inplace** (double *data, int n)
  Description Compute the FFT of the real valued vector `data` of length `n`. The result is stored in `data` using the FFTPack storage described above, see 9.1.

- int **pnl_real_ifft_inplace** (double ∗data, int n)
Description Compute the inverse FFT of the vector `data` of length `n`. `data` is supposed to be the FFT coefficients a real valued sequence stored using the FFTPack storage. On output, `data` contains the inverse FFT.

- int **pnl_real_fft2** (double ∗re, double ∗im, int n)
Description Compute the FFT of the real vector `re` of length `n`. `im` is only used on output to store the imaginary part the FFT. The real part is stored into `re`

- int **pnl_real_ifft2** (double ∗re, double ∗im, int n)
Description Compute the inverse FFT of the vector `re + i * im` of length `n`, which is supposed to be the FFT of a real valued sequence. On exit, `im` is unused.

- int **pnl_fft2d_inplace** (PnlMatComplex ∗data)
Description Compute the 2D FFT of `data`. This function applies a 1D FFT to each row of the matrix and then a 1D FFT to each column of the modified matrix.

- int **pnl_ifft2d_inplace** (PnlMatComplex ∗data)
Description Compute the inverse 2D FFT of `data`. This function is the inverse of the function pnl_fft2d_inplace.

- int **pnl_fft2d** (const PnlMatComplex ∗in, PnlMatComplex ∗out)
Description Compute the 2D FFT of `in` and stores it into `out`.

- int **pnl_ifft2d** (const PnlMatComplex ∗in, PnlMatComplex ∗out)
Description Compute the inverse 2D FFT of `in` and stores it into `out`.

- int **pnl_real_fft2d** (const PnlMat ∗in, PnlMatComplex ∗out)
Description Compute the 2D FFT of the real matrix `in` and stores it into `out`.

- int **pnl_real_ifft2d** (const PnlMatComplex ∗in, PnlMatComplex ∗out)
Description Compute the inverse 2D FFT of the complex matrix `in` which is known to be the forward 2D FFT a real matrix. The result id stored it into `out`. Note that this function modifies the input matrix `in`.

10 Inverse Laplace Transform

For a real valued function f such that $t \longmapsto f(t)\,\mathrm{e}^{-\sigma_c t}$ is integrable over $\mathbb{R}^+$, we can define its Laplace transform

$$\hat{f}(\lambda) = \int_0^\infty f(t)\,\mathrm{e}^{-\lambda t}\,dt \qquad \text{for } \lambda \in \mathbb{C} \text{ with } \mathrm{Re}(\lambda) \geq \sigma_c.$$

To use the following functions, you should include `pnl/pnl_laplace.h`.

```
typedef struct
{
  dcomplex (*F) (dcomplex x, void *params);
  void *params;
} PnlCmplxFunc;
```

- double **pnl_ilap_euler** (PnlCmplxFunc *fhat, double t, int N, int M)
Description Compute $f(\mathtt{t})$ where f is given by its Laplace transform `fhat` by numerically inverting the Laplace transform using Euler's summation. The values `N = M = 15` usually give a very good accuracy. For more details on the accuracy of the method.

- double **pnl_ilap_cdf_euler** (PnlCmplxFunc *fhat, double t, double h, int N, int M)
Description Compute the cumulative distribution function $F(\mathtt{t})$ where $F(x) = \int_0^x f(t)dt$ and f is a density function with values on the positive real linegiven by its Laplace transform `fhat`. The computation is carried out by numerical inversion of the Laplace transform using Euler's summation. The values `N = M = 15` usually give a very good accuracy. The parameter `h` is the discretization step, the algorithm is very sensitive to the choice of `h`.

- double **pnl_ilap_fft** (PnlVect *res, PnlCmplxFunc *fhat, double T, double eps)
Description Compute $f(t)$ for $t \in [h, \mathtt{T}]$ on a regular grid and stores the values in `res`, where $h = T/size(res)$. The function f is defined by its Laplace transform `fhat`, which is numerically inverted using a Fast Fourier Transform algorithm. The size of `res` is related to the choice of the relative precision `eps` required on the value of $f(t)$ for all $t \leq T$.

- double **pnl_ilap_gs** (PnlFunc *fhat, double t, int n)
Description Compute $f(\mathtt{t})$ where f is given by its Laplace transform `fhat` by numerically inverting the Laplace transform using a weighted combination of different Gaver Stehfest's algorithms. Note that this function does not need the complex valued Laplace transform but only the real valued one. `n` is the number of terms used in the weighted combination.

- double **pnl_ilap_gs_basic** (PnlFunc *fhat, double t, int n)
Description Compute $f(\mathtt{t})$ where f is given by its Laplace transform `fhat` by numerically inverting the Laplace transform using Gaver Stehfest's method. Note that this function does not need the complex valued Laplace transform but only the real valued one. `n` is the number of iterations of the algorithm. **Note :** This function is provided for test purposes only. The function pnl_ilap_gs gives far more accurate results.

11 Ordinary differential equations

11.1 Overview

To use these functionalities, you should include `pnl/pnl_integration.h`.
These functions are designed for numerically solving $n-$dimensional first order ordinary differential equation of the general form

$$\frac{dy_i}{dt}(t) = f_i(t, y_1(t), \cdots, y_n(t))$$

The system of equations is defined by the following structure

```
typedef struct
{
  void (*F) (int neqn, double t, const double *y, double *yp, void *params);
```

```
  int neqn;
  void *params;
} PnlODEFunc ;
```

- int **neqn**
  Description Number of equations

- void ∗ **params**
  Description An untyped structure used to pass extra arguments to the function `f` defining the system

- void **(∗ F)** (int neqn, double t, const double ∗y, double ∗yp, void ∗params)
  Description After calling the fuction, `yp` should be defined as follows `yp_i = f_i(neqn, t, y, params)`. `y` and `yp` should be both of size `neqn`

We provide the following macro to evaluate a PnlODEFunc at a given point

```
#define PNL_EVAL_ODEFUNC(Fstruct, t, y, yp) \
    (*((Fstruct)->F))((Fstruct)->neqn, t, y, yp, (Fstruct)->params)
```

11.2 Functions

- int **pnl_ode_rkf45** (PnlODEFunc ∗f, double ∗y, double t, double t_out, double relerr, double abserr, int ∗flag)
  Description This function computes the solution of the system defined by the PnlODEFunc `f` at the point `t_out`. On input, $(\mathtt{t}, \mathtt{y})$ should be the initial condition, `abserr,relerr` are the maximum absolute and relative errors for local error tests (at each step, `abs(local error)` should be less that `relerr * abs(y) + abserr`). Note that if `abserr = 0` or `relerr = 0` on input, an optimal value for these variables is computed inside the function The function returns an error `OK` or `FAIL`. In case of an `OK` code, the `y` contains the solution computed at `t_out`, in case of a `FAIL` code, `flag` should be examined to determine the reason of the error. Here are the different possible values for `flag`

  – `flag = 2` : integration reached `t_out`, it indicates successful return and is the normal mode for continuing integration.

  – `flag = 3` : integration was not completed because relative error tolerance was too small. relerr has been increased appropriately for continuing.

  – `flag = 4` : integration was not completed because more than 3000 derivative evaluations were needed. this is approximately 500 steps.

  – `flag = 5` : integration was not completed because solution vanished making a pure relative error test impossible. must use non-zero abserr to continue. using the one-step integration mode for one step is a good way to proceed.

  – `flag = 6` : integration was not completed because requested accuracy could not be achieved using smallest allowable stepsize. user must increase the error tolerance before continued integration can be attempted.

– `flag = 7` : it is likely that rkf45 is inefficient for solving this problem. too much output is restricting the natural stepsize choice. use the one-step integrator mode. see pnl_ode_rkf45_step.

– `flag = 8` : invalid input parameters this indicator occurs if any of the following is satisfied - neqn <= 0, t=tout, relerr or abserr <= 0.

- int **pnl_ode_rkf45_step** (PnlODEFunc ∗f, double ∗y, double ∗t, double t_out, double ∗relerr, double abserr, double ∗work, int ∗iwork, int ∗flag)
  Description Same as pnl_ode_rkf45 but it only computes one step of integration in the direction of `t_out`. `work` and `iwork` are working arrays of size `3 + 6 * neqn` and `5` respectively and should remain untouched between successive calls to the function. On output `t` holds the point at which integration stopped and `y` the value of the solution at that point.

12 Optimization

To use the functions described in this section, you should include `pnl/pnl_optim.h`.

12.1 Linear constrained optimization (linear programming)

12.1.1 Overview

Consider the minimization problem

$$\begin{aligned} \min_x \quad & C^T x \\ \text{s.t.} \quad & A_{\text{ineq}}\, x \le B_{\text{ineq}} \\ & A_{\text{eq}}\, x = B_{\text{eq}} \\ & x_{\min} \le x \le x_{\max} \end{aligned}$$

12.1.2 Functions

To solve such a linear problem, we provide a wrapper to the *LPSolve* library (`http://lpsolve.sourceforge.net`).

- int **pnl_optim_linprog** (const PnlVect ∗C, const PnlMat ∗A_ineq, const PnlVect ∗B_ineq, const PnlMat ∗A_eq, const PnlVect ∗B_eq, const PnlVect ∗x_min, const PnlVect ∗x_max, int debug, PnlVect ∗xopt, double ∗fobj_opt)
  Description This function has the following arguments:

  – `C` The coefficients of the linear objective function.

  – `A_ineq` The l.h.s matrix of the inequality constraints. Can be NULL.

  – `B_ineq` The r.h.s vector of the inequality constraints. The lengh of `B_ineq` must match the number of rows of `A_ineq`.

  – `A_eq` The l.h.s matrix of the equality constraints. Can be NULL.

  – `B_eq` The r.h.s vector of the equality constraints. The lengh of `B_eq` must match the number of rows of `A_ineq`.

- x_min The lower bound on x. If NULL, it means all the components of x must be non negative.
- x_max The upper bound on x. If NULL, it means +Infinity for all the components.
- debug TRUE or FALSE. If TRUE some debugging details are printed.
- xopt The argmin of the problem.
- fobj_opt The value of the obective funtion at the optimum xopt

The function returns OK or FAIL.

- int **pnl_optim_linprog_sp** (const PnlSpMat ∗C, const PnlSpMat ∗A_ineq, const PnlVect ∗B_ineq, const PnlSpMat ∗A_eq, const PnlVect ∗B_eq, const PnlVectInt ∗index_min, const PnlVect ∗x_min, const PnlVectInt ∗index_max, const PnlVect ∗x_max, int debug, PnlVect ∗xopt, double ∗fobj_opt)
  Description This function has the following arguments:

  - C The coefficients of the linear obejctive function, given as a sparse matrix with a single column.
  - A_ineq The l.h.s matrix of the inequality constraints. Can be NULL.
  - B_ineq The r.h.s vector of the inequality constraints. The lengh of B_ineq must match the number of rows of A_ineq.
  - A_eq The l.h.s matrix of the equality constraints. Can be NULL.
  - B_eq The r.h.s vector of the equality constraints. The lengh of B_eq must match the number of rows of A_ineq.
  - index_min The indices of the variables with a lower bound constraint. The corresponding lower bound is given in x_min
  - x_min The lower bound on x. If NULL, it means all the components of x must be non negative. Can be NULL. For non specified variables, the default lower bound is 0.
  - index_max The indices of the variables with an upper bound constraint. The corresponding lower bound is given in x_max. Can be NULL.
  - x_max The upper bound on x. If NULL, it means +Infinity for all the components. For non specified variables, the default upper bound is +Infinity..
  - debug TRUE or FALSE. If TRUE some debugging details are printed.
  - xopt The argmin of the problem.
  - fobj_opt The value of the obective funtion at the optimum xopt

  The function returns OK or FAIL.

12.2 Nonlinear constrained optimization

12.2.1 Overview

A standard Constrained Nonlinear Optimization problem can be written as:

$$(O) \begin{cases} \min \ f(x) \\ c^I(x) \geq 0 \\ c^E(x) = 0 \end{cases}$$

where the function $f : \mathbb{R}^n \to \mathbb{R}$ is the objective function, $c^I : \mathbb{R}^n \to \mathbb{R}^{m_I}$ are the inequality constraints and $c^E : \mathbb{R}^n \to \mathbb{R}^{m_E}$ are the equality constraints. These functions are supposed to be smooth.
In general, the inequality constraints are of the form $c^I(x) = (g(x),\ x - l,\ u - x)$. The vector l and u are the lower and upper bounds on the variables x and $g(x)$ and the non linear inequality constraints.
Under some conditions, if $x \in \mathbb{R}^n$ is a solution of problem (O), then there exist a vector $\lambda = (\lambda^I, \lambda^E) \in \mathbb{R}^{m_I} \times \mathbb{R}^{m_E}$, such that the well known Karush-Kuhn-Tucker (KKT) optimality conditions are satisfied:

$$(P) \begin{cases} \nabla \ell(x, \lambda^I, \lambda^E) = \nabla f(x) - \nabla c^I(x)\lambda^I - \nabla c^E(x)\lambda^E = 0 \\ c^E(x) = 0 \\ c^I(x) \geq 0 \\ \lambda^I \geq 0 \\ c_i^I(x)\lambda_i^I = 0,\ i = 1...m_I \end{cases}$$

l is known as the Lagrangian of the problem (O), λ^I and λ^E as the dual variables while x is the primal variable.

12.2.2 Functions

To solve an inequality constrained optimization problem, ie $m_E = 0$, we provide the following function.

- int **pnl_optim_intpoints_bfgs_solve** (PnlRnFuncR∗func, PnlRnFuncRm∗grad_func, PnlRnFuncRm∗nl_constraints, PnlVect ∗lower_bounds, PnlVect ∗upper_bounds, PnlVect ∗x_input, double tolerance, int iter_max, int print_inner_steps, PnlVect ∗output)
  Description This function has the following arguments:
  - `func` is the function to minimize f.
  - `grad` is the gradient of f. If this gradient is not available, then enter `grad`=NULL. In this case, finite difference will be used to estimate the gradient.
  - `nl_constraints` is the function $g(x)$, ie the non linear inequality constraints.
  - `lower_bounds` are the lower bounds on x. Can be NULL if there is no lower bound.
  - `upper_bounds` are the upper bounds on x. Can be NULL if there is no upper bound.
  - `x_input` is the initial point where the algorithm starts.
  - `tolerance` is the precision required in solving (P).
  - `iter_max` is the maximum number of iterations in the algorithm.
  - `print_algo_steps` is a flag to decide to print information.
  - `x_output` is the point where the algorithm stops.

The algorithm returns an *int*, its value depends on the output status of the algorithm. We have 4 cases:

- 0: Failure: Initial point is not strictly feasible.
- 1: Step is too small, we stop the algorithm.
- 2: Maximum number of iterations reached.
- 3: A solution has been found up to the required accuracy.

The last case is equivalent to the two inequalities:

$$||\nabla \ell(x, \lambda^I)||_\infty = ||\nabla f(x) - \nabla c^I(x)\lambda^I||_\infty < \texttt{tolerance}$$
$$||c^I(x)\lambda^I||_\infty < \texttt{tolerance}$$

where $c^I(x)$.∗ λ^I where '.∗' denotes the term by term multiplication.

The first inequality is known as the optimality condition, the second one as the complementarity condition.

Remarks Our implementation requires the initial point x_0 to be strictly feasible, ie: $c(x_0) > 0$. The algorithm tries to find a pair (x, λ) solving the Equations (P), but this does not guarantee that x is a global minimum of f on the set $\{c(x) \geq 0\}$.

13 Root finding

13.1 Overview

To provide a uniformed framework to root finding functions, we use several structures for storing different kind of functions. The pointer `params` is used to store the extra parameters. These new types come with dedicated macros starting in `PNL_EVAL` to evaluate the function and their Jacobian.

```
/*
 * f: R --> R
 * The function  pointer returns f(x)
 *
typedef struct {
  double (*F) (double x, void *params);
  void *params;
} PnlFunc ;
#define PNL_EVAL_FUNC(Fstruct, x) (*((Fstruct)->F))(x, (Fstruct)->params)


/*
 * f: R^2 --> R
 * The function pointer returns f(x)
 *
typedef struct {
```

```
  double (*F) (double x, double y, void *params);
  void *params;
} PnlFunc2D ;
#define PNL_EVAL_FUNC2D(Fstruct, x, y) (*((Fstruct)->F))(x, y, (Fstruct)->params)


/*
 * f: R --> R
 * The function pointer computes f(x) and Df(x) and stores them in fx
 * and dfx respectively
 *
typedef struct {
  void (*F) (double x, double *fx, double *dfx, void *params);
  void *params;
} PnlFuncDFunc ;
#define PNL_EVAL_FUNC_FDF(Fstruct, x, fx, dfx) (*((Fstruct)->F))(x, fx, dfx, (Fstruct)->pa


/*
 * f: R^n --> R
 * The function pointer returns f(x)
 *
typedef struct {
  double (*F) (const PnlVect *x, void *params);
  void *params;
} PnlRnFuncR ;
#define PNL_EVAL_RNFUNCR(Fstruct, x) (*((Fstruct)->F))(x, (Fstruct)->params)


/*
 * f: R^n --> R^m
 * The function pointer computes the vector f(x) and stores it in
 * fx (vector of size m)
 *
typedef struct {
  void (*F) (const PnlVect *x, PnlVect *fx, void *params);
  void *params;
} PnlRnFuncRm ;
#define PNL_EVAL_RNFUNCRM(Fstruct, x, fx) (*((Fstruct)->F))(x, fx, (Fstruct)->params)

/*
 * Synonymous of PnlRnFuncRm for f:R^n --> R^n
 *
typedef PnlRnFuncRm PnlRnFuncRn;
#define PNL_EVAL_RNFUNCRN  PNL_EVAL_RNFUNCRM
```

```
/*
 * f: R^n --> R^m
 * The function pointer computes the vector f(x) and stores it in fx
 * (vector of size m)
 * The Dfunction pointer computes the matrix Df(x) and stores it in dfx
 * (matrix of size m x n)
 *
typedef struct {
  void (*F) (const PnlVect *x, PnlVect *fx, void *params);
  void (*DF) (const PnlVect *x, PnlMat *dfx, void *params);
  void (*FDF) (const PnlVect *x, PnlVect *fx, PnlMat *dfx, void *params);
  void *params;
} PnlRnFuncRmDFunc ;
#define PNL_EVAL_RNFUNCRM_DF(Fstruct, x, dfx) \
    (*((Fstruct)->Dfunction))(x, dfx, (Fstruct)->params)
#define PNL_EVAL_RNFUNCRM_FDF(Fstruct, x, fx, dfx) \
    (*((Fstruct)->F))(x, fx, dfx, (Fstruct)->params)
#define PNL_EVAL_RNFUNCRM_F_DF(Fstruct, x, fx, dfx)     \
      if ( (Fstruct)->FDF != NULL )                     \
        {                                               \
          PNL_EVAL_RNFUNCRN_FDF (Fstruct, x, fx, dfx); \
        }                                               \
      else                                              \
        {                                               \
          PNL_EVAL_RNFUNCRN (Fstruct, x, fx);          \
          PNL_EVAL_RNFUNCRN_DF (Fstruct, x, dfx);      \
        }
/*
 * Synonymous of PnlRnFuncRmDFunc for f:R^n --> R^m
 *
typedef PnlRnFuncRmDFunc PnlRnFuncRnDFunc;
#define PNL_EVAL_RNFUNCRN_DF PNL_EVAL_RNFUNCRM_DF
#define PNL_EVAL_RNFUNCRN_FDF PNL_EVAL_RNFUNCRM_FDF
#define PNL_EVAL_RNFUNCRN_F_DF PNL_EVAL_RNFUNCRM_F_DF
```

13.2 Functions

To use the following functions, you should include `pnl/pnl_root.h`.

Real valued functions of a real argument

- double **pnl_root_brent** (PnlFunc *F, double x1, double x2, double *tol)
  Description Find the root of `F` between `x1` and `x2` with an accuracy of order `tol`. On exit `tol` is an upper bound of the error.
- int **pnl_root_newton_bisection** (PnlFuncDFunc *Func, double x_min, double x_max, double tol, int N_Max, double *res)
  Description Find the root of `F` between `x1` and `x2` with an accuracy of order `tol` and

a maximum of `N_max` iterations. On exit, the root is stored in `res`. Note that the function `Func` must also compute the first derivative of the function. This function relies on combining Newton's approach with a bisection technique.

- int **pnl_root_newton** (PnlFuncDFunc *Func, double x0, double x_eps, double fx_eps, int max_iter, double *res)
  Description Find the root of `f` starting from `x0` using Newton's method with descent direction given by the inverse of the derivative, ie. $d_k = f(x_k)/f'(x_k)$. Armijo's line search is used to make sure `|f|` decreases along the iterations. $\alpha_k = \max\{\gamma^j \; ; \; j \geq 0\}$ such that

$$|f(x_k + \alpha_k d_k)| \leq |f(x_k)|(1 - \omega\alpha_k).$$

  In this implementation, $\omega = 10^{-4}$ and $\gamma = 1/2$. The algorithm stops when one of the three following conditions is met:

  - the maximum number of iterations `max_iter` is reached;
  - the last improvement over `x` is smaller that `x * x_eps`;
  - at the current position `|f(x)| < fx_eps`

  On exit, the root is stored in `res`.

- int **pnl_root_bisection** (PnlFunc *Func, double xmin, double xmax, double epsrel, double espabs, int N_max, double *res)
  Description Find the root of `F` between `x1` and `x2` with the accuracy `|x2 - x1| < epsrel * x1 + epsabs` or with the maximum number of iterations `N_max`. On exit, `res = (x2 + x1) / 2`.

Vector valued functions with several arguments

- int **pnl_multiroot_newton** (PnlRnFuncRnDFunc *func, const PnlVect *x0, double x_eps, double fx_eps, int max_iter, int verbose, PnlVect *res)
  Description Find the root of `func` starting from `x0` using Newton's method with descent direction given by the inverse of the Jacobian matrix, ie. $d_k = (\nabla f(x_k))^{-1} f(x_k)$. Armijo's line search is used to make sure `|f|` decreases along the iterations. $\alpha_k = \max\{\gamma^j \; ; \; j \geq 0\}$ such that

$$|f(x_k + \alpha_k d_k)| \leq |f(x_k)|(1 - \omega\alpha_k).$$

  In this implementation, $\omega = 10^{-4}$ and $\gamma = 1/2$. The algorithm stops when one of the three following conditions is met:

  - the maximum number of iterations `max_iter` is reached;
  - the norm of the last improvement over `x` is smaller that `|x| * x_eps`;
  - at the current position `|f(x)| < fx_eps`

  On exit, the root is stored in `res`. Note that the function `F` must also compute the first derivative of the function. When defining `Func`, you must either define `Func->F` and `Func->DF` or `Func->FDF`.

We provide two wrappers for calling minpack routines.

- int **pnl_root_fsolve** (PnlRnFuncRnDFunc *f, PnlVect *x, PnlVect *fx, double xtol, int maxfev, int *nfev, PnlVect *scale, int error_msg)
  Description Compute the root of a function $f : \mathbb{R}^n \longmapsto \mathbb{R}^n$. Note that the number of components of `f` must be equal to the number of variates of `f`. This function returns `OK` or `FAIL` if something went wrong.
  Parameters

  – `f` is a pointer to a PnlRnFuncRnDFunc used to store the function whose root is to be found. `f` can also store the Jacobian of the function, if not it is computed using finite differences (see the file `examples/minpack_test.c` for a usage example). `f->FDF` can be NULL because it is not used in this function.

  – `x` contains on input the starting point of the search and an approximation of the root of `f` on output,

  – `xtol` is the precision required on `x`, if set to 0 a default value is used.

  – `maxfev` is the maximum number of evaluations of the function `f` before the algorithm returns, if set to 0, a coherent number is determined internally.

  – `nfev` contains on output the number of evaluations of `f` during the algorithm,

  – `scale` is a vector used to rescale `x` in a way that each coordinate of the solution is approximately of order 1 after rescaling. If on input `scale=NULL`, a scaling vector is computed internally by the algorithm.

  – `error_msg` is a boolean (`TRUE` or `FALSE`) to specify if an error message should be printed when the algorithm stops before having converged.

  – On output, `fx` contains `f(x)`.

- int **pnl_root_fsolve_lsq** (PnlRnFuncRmDFunc *f, PnlVect *x, int m, PnlVect *fx, double xtol, double ftol, double gtol, int maxfev, int *nfev, PnlVect *scale, int error_msg)
  Description Compute the root of $x \in \mathbb{R}^n \longmapsto \sum_{i=1}^{m} f_i(x)^2$, note that there is no reason why `m` should be equal to `n`.
  Parameters

  – `f` is a pointer to a PnlRnFuncRmDFunc used to store the function whose root is to be found. `f` can also store the Jacobian of the function, if not it is computed using finite differences (see the file `examples/minpack_test.c` for a usage example). `f->FDF` can be NULL because it is not used in this function.

  – `x` contains on input the starting point of the search and an approximation of the root of `f` on output,

  – `m` is the number of components of `f`,

  – `xtol` is the precision required on `x`, if set to 0 a default value is used.

  – `ftol` is the precision required on `f`, if set to 0 a default value is used.

  – `gtol` is the precision required on the Jacobian of `f`, if set to 0 a default value is used.

– `maxfev` is the maximum number of evaluations of the function `f` before the algorithm returns, if set to 0, a coherent number is determined internally.
– `nfev` contains on output the number of evaluations of `f` during the algorithm,
– `scale` is a vector used to rescale `x` in a way that each coordinate of the solution is approximately of order 1 after rescaling. If on input `scale=NULL`, a scaling vector is computed internally by the algorithm.
– `error_msg` is a boolean (`TRUE` or `FALSE`) to specify if an error message should be printed when the algorithm stops before having converged.
– On output, `fx` contains `f(x)`.

14 Special functions

The special function approximations are defined in the header `pnl/pnl_specfun.h`.

Most of these functions rely on the *Cephes* library which uses its own error mechanism which can be activated or deactivated using the two following functions

- void **pnl_deactivate_mtherr** ()
  Description Deactivate Cephes error mechanism

- void **pnl_activate_mtherr** ()
  Description Activate Cephes error mechanism

14.1 Real Bessel functions

- double **pnl_bessel_i** (double v, double x)
  Description Modified Bessel function of the first kind of order `v`.

- double **pnl_bessel_i_scaled** (double v, double x)
  Description Modified Bessel function of the first kind of order `v` divided by $e^{|x|}$.

- double **pnl_bessel_rati** (double v, double x)
  Description Ratio of modified Bessel functions of the first kind : $I_{v+1}(x)/I_v(x)$.

- double **pnl_bessel_j** (double v, double x)
  Description Bessel function of the first kind of order `v`.

- double **pnl_bessel_j_scaled** (double v, double x)
  Description Bessel function of the first kind of order `v`. Same function as pnl_bessel_j.

- double **pnl_bessel_y** (double v, double x)
  Description Modified Bessel function of the second kind of order `v`.

- double **pnl_bessel_y_scaled** (double v, double x)
  Description Modified Bessel function of the second kind of order `v`. Same function as pnl_bessel_y.

- double **pnl_bessel_k** (double v, double x)
  Description Bessel function of the third kind of order `v`.

- double **pnl_bessel_k_scaled** (double v, double x)
  Description Bessel function of the third kind of order `v` multiplied by e^x.

- dcomplex **pnl_bessel_h1** (double v, double x)
  Description Hankel function of the first kind of order `v`.

- dcomplex **pnl_bessel_h1_scaled** (double v, double x)
  Description Hankel function of the first kind of order `v` and divided by e^{Ix}.

- dcomplex **pnl_bessel_h2** (double v, double x)
  Description Hankel function of the second kind of order `v`.

- dcomplex **pnl_bessel_h2_scaled** (double v, double x)
  Description Hankel function of the second kind of order `v` and multiplied by e^{Ix}.

14.2 Complex Bessel functions

- dcomplex **pnl_complex_bessel_i** (double v, dcomplex z)
  Description Complex Modified Bessel function of the first kind of order `v`.

- dcomplex **pnl_complex_bessel_i_scaled** (double v, dcomplex z)
  Description Complex Modified Bessel function of the first kind of order `v` divided by $e^{|Creal(z)|}$.

- dcomplex **pnl_complex_bessel_rati** (double v, dcomplex x)
  Description Ratio of complex modified Bessel functions of the first kind : $I_{v+1}(x)/I_v(x)$.

- dcomplex **pnl_complex_bessel_j** (double v, dcomplex z)
  Description Complex Bessel function of the first kind of order `v`.

- dcomplex **pnl_complex_bessel_j_scaled** (double v, dcomplex z)
  Description Complex Bessel function of the first kind of order `v` divided by $e^{|Cimag(z)|}$.

- dcomplex **pnl_complex_bessel_y** (double v, dcomplex z)
  Description Complex Modified Bessel function of the second kind of order `v`.

- dcomplex **pnl_complex_bessel_y_scaled** (double v, dcomplex z)
  Description Complex Modified Bessel function of the second kind of order `v` divided by $e^{|Cimag(z)|}$.

- dcomplex **pnl_complex_bessel_k** (double v, dcomplex z)
  Description Complex Bessel function of the third kind of order `v`.

- dcomplex **pnl_complex_bessel_k_scaled** (double v, dcomplex z)
  Description Complex Bessel function of the third kind of order `v` multiplied by e^z.

- dcomplex **pnl_complex_bessel_h1** (double v, dcomplex z)
  Description Complex Hankel function of the first kind of order `v`.

- dcomplex **pnl_complex_bessel_h1_scaled** (double v, dcomplex z)
  Description Complex Hankel function of the first kind of order `v` and divided by e^{Iz}.

- dcomplex **pnl_complex_bessel_h2** (double v, dcomplex z)
  Description Complex Hankel function of the second kind of order `v`.

- dcomplex **pnl_complex_bessel_h2_scaled** (double v, dcomplex z)
  Description Complex Hankel function of the second kind of order `v` and multiplied by e^{Iz}.

14.3 Error functions

- double **pnl_sf_erf** (double x)
  Description Compute the error function $\frac{2}{\pi} \int_0^x \mathrm{e}^{-t^2} \, dt$.

- dcomplex **pnl_sf_complex_erf** (dcomplex z)
  Description Same as pnl_sf_erf for complex arguments.

- double **pnl_sf_erfc** (double x)
  Description Compute the complementary error function `1. - erf(x)`.

- dcomplex **pnl_sf_complex_erfc** (dcomplex x)
  Description Same as pnl_sf_erfc for complex arguments.

- double **pnl_sf_erfcx** (double x)
  Description Compute the scaled complementary error function of x, defined by $\mathrm{e}^{x^2} \operatorname{erfc}(x)$.

- dcomplex **pnl_sf_complex_erfcx** (dcomplex z)
  Description Same as pnl_sf_erfcx for complex arguments. Note that `erfcx(-i x) = w(x)`.

- dcomplex **pnl_sf_w** (dcomplex z)
  Description Compute $\mathrm{e}^{-z^2} \operatorname{erfc}(-i\,z)$.

- double **pnl_sf_w_im** (double x)
  Description Compute $2\,\mathrm{Dawson}(x)/\sqrt{\pi}$

- double **pnl_sf_erfi** (double x)
  Description Compute `-i erf(i z)`

- dcomplex **pnl_sf_complex_erfi** (dcomplex z)
  Description Same as pnl_sf_erfi for complex arguments.

- double **pnl_sf_dawson** (double x)
  Description Compute $\sqrt{\pi}/2 \; \mathrm{e}^{-x^2} \operatorname{erfi}(x)$.

- dcomplex **pnl_sf_complex_dawson** (dcomplex z)
  Description Same as pnl_sf_dawson for complex arguments.

- double **pnl_sf_log_erf** (double x)
  Description Compute log pnl_sf_erf(x)

- double **pnl_sf_log_erfc** (double x)
  Description Compute log pnl_sf_erfc(x)

14.4 Gamma functions

For $x > 0$, the Gamma Function is defined by

$$\Gamma(x) = \int_0^\infty \mathrm{e}^{-u}\, u^{x-1} du.$$

- double **pnl_sf_fact** (int n)
  Description Computes factorial of `n` $\Gamma(n+1)$.

- double **pnl_sf_gamma** (double x)
  Description Computes $\Gamma(x), x \geq 0$

- double **pnl_sf_log_gamma** (double x)
  Description Computes $\log(\Gamma(x)), x \geq 0$

- int **pnl_sf_log_gamma_sgn** (double x, double ∗y, int ∗sgn)
  Description Computes $y = \log(|\Gamma(x)|)$ for `x > 0` `sgn` contains the sign of $\Gamma(x)$ (-1 or +1).

- double **pnl_sf_choose** (int n, int k)
  Description Computes the binomial coefficient $\binom{n}{k} = \frac{n!}{k!(n-k)!}$ for $0 \leq k \leq n$ in double precision.

14.5 Digamma function

For $x > 0$, the digamma function ψ is defined as the logarithmic derivative of the Gamma function Γ

$$\psi(x) = \frac{d}{dx} \log \Gamma(x) = \frac{\Gamma'(x)}{\Gamma(x)}.$$

The function ψ admits the following integral representation

$$\psi(x) = \int_0^\infty \left(\frac{\mathrm{e}^{-u}}{u} - \frac{\mathrm{e}^{-xu}}{1 - \mathrm{e}^{-u}} \right).$$

- double **pnl_sf_psi** (double x)
  Description Return $\psi(x)$.

14.6 Incomplete Gamma functions

For $a \in \mathbb{R}$ and $x > 0$, the Incomplete Gamma Function is defined by

$$\Gamma(a, x) = \int_x^\infty \mathrm{e}^{-u}\, u^{a-1} du.$$

A relation similar to the one existing for the standard Gamma function holds

$$\Gamma(a, x) = \frac{-x^a \mathrm{e}^{-x} + \Gamma(a+1, x)}{a}.$$

$$\Gamma(a) = \int_0^\infty u^{a-1}\,\mathrm{e}^{-u}\,du$$
$$P(a,x) = \frac{\Gamma(a)-\Gamma(a,x)}{\Gamma(a)} = \frac{1}{\Gamma(a)}\int_0^x u^{a-1}\,\mathrm{e}^{-u}\,du$$
$$Q(a,x) = 1-P(a,x) = \frac{\Gamma(a,x)}{\Gamma(a)} = \frac{1}{\Gamma(a)}\int_x^\infty \mathrm{e}^{-u}\,u^{a-1}du.$$

- double **pnl_sf_gamma_inc** (double a, double x)
  Description Computes $\Gamma(a,x), \quad a \in \mathbb{R}, x \geq 0$
- void **pnl_sf_gamma_inc_P** (double a, double x)
  Description Computes $P(a,x), \quad a > 0, x \geq 0$
- void **pnl_sf_gamma_inc_Q** (double a, double x)
  Description Computes $Q(a,x), \quad a > 0, x \geq 0$

14.7 Exponential integrals

For $x > 0$ and $n \in \mathbb{N}$, the function E_n is defined by

$$E_n(x) = \int_1^\infty \mathrm{e}^{-xu}\,u^{-n}du$$

This function is linked to the Incomplete Gamma function by

$$E_n(x) = \int_x^\infty \mathrm{e}^{-xu}(xu)^{-n}x^{n-1}d(xu) = x^{n-1}\int_x^\infty \mathrm{e}^{-t}\,t^{-n}dt = x^{n-1}\Gamma(1-n,x),$$

from which we can deduce

$$nE_{n+1}(x) = \mathrm{e}^{-x} - xE_n(x).$$

For $n > 1$, the series expansion is given by

$$E_n(x) = x^{n-1}\Gamma(1-n) + \left[-\frac{1}{1-n} + \frac{x}{2-n} - \frac{x^2}{2(3-n)} + \frac{x^3}{6(4-n)} - \dots\right].$$

The asymptotic behaviour is given by

$$E_n(x) = \frac{\mathrm{e}^{-x}}{x}\left[1 - \frac{n}{x} + \frac{n(n+1)}{x^2} + \dots\right].$$

The special case $n = 1$ gives

$$E_1(x) = \int_x^\infty \frac{e^{-u}}{u}\,du, \quad |\mathrm{Arg}(x)| \geq \pi.$$

For any complex number x with positive real part, this can be written

$$E_1(x) = \int_1^\infty \frac{e^{-ux}}{u}\,du, \quad \Re(x) \geq 0.$$

By integrating the Taylor expansion of e^{-t}/t, and extracting the logarithmic singularity, we can derive the following series representation for $E_1(x)$,

$$E_1(x) = -\gamma - \ln x - \sum_{k=1}^\infty \frac{(-1)^k x^k}{k\;k!} \qquad |\mathrm{Arg}(x)| < \pi.$$

The function E_1 is linked to the exponential integral Ei

$$Ei(x) = \int_{-\infty}^{x} \frac{e^u}{u}\, du = -\int_{-x}^{\infty} \frac{e^{-u}}{u}\, du \quad \forall x \neq 0.$$

The above definition can be used for positive values of x, but the integral has to be understood in terms of its Cauchy principal value, due to the singularity of the integrand at zero.

$$Ei(-x) = -E_1(x), \quad \Re(x) \geq 0.$$

We deduce,

$$Ei(x) = \gamma + \ln x + \sum_{k=1}^{\infty} \frac{x^k}{k\, k!}, \quad x > 0.$$

For $x \in \mathbb{R}$

$$\Gamma(0, x) = \begin{cases} -Ei(-x) - \imath\pi & x < 0, \\ -Ei(-x) & x > 0. \end{cases}$$

- double **pnl_sf_expint_En** (int n, double x)
  Description Computes `E_n(x)` for $n \geq 0, x \geq 0$, or $x > 0$ when $n = 0$ or 1.

14.8 Hypergeometric functions

- double **pnl_sf_hyperg_2F1** (double a, double b, double c, double x)
  Description Compute the Gauss hypergeometric function `2F1(a,b,c,x)` for `|x| < 1` and for `x < -1` when `b,a,c,(b-a),(c-a),(c-b)` are not integers

- double **pnl_sf_hyperg_1F1** (double a, double b, double x)
  Description Compute the hypergeometric function `1F1(a,b,x)`

- double **pnl_sf_hyperg_2F0** (double a, double b, double x)
  Description Compute the hypergeometric function `2F0(a,b,x)` for `x<0` using the relation $2F0(a, b, x) = (-x)^{-a} U(a, 1 + a - b, -\frac{1}{x})$.

- double **pnl_sf_hyperg_0F1** (double c, double x)
  Description Compute the hypergeometric function `0F1(c,x)`

- double **pnl_sf_hyperg_U** (double a, double b, double x)
  Description Compute the confluent hypergeometric function `U(a,b,x)` with `x > 0`

15 Some bindings

15.1 MPI bindings

15.1.1 Overview

We provide some bindings for the MPI library to natively handle *PnlObjects*.
The functionnalities described in this chapter are declared in `pnl/pnl_mpi.h`.

15.1.2 Functions

All the following functions return an error code as an integer value. This returned value should be tested against `MPI_SUCCESS` to check that no error occurred.

- int **pnl_object_mpi_pack_size** (const PnlObject ∗Obj, MPI_Comm comm, int ∗size)
  Description Compute in `size` the amount of space needed to pack `Obj`.

- int **pnl_object_mpi_pack** (const PnlObject ∗Obj, void ∗buf, int bufsize, int ∗pos, MPI_Comm comm)
  Description Pack `Obj` into `buf` which must be at least of length `size`. `size` must be at least equal to the value returned by pnl_object_mpi_pack_size.

- int **pnl_object_mpi_unpack** (PnlObject ∗Obj, void ∗buf, int bufsize, int ∗pos, MPI_Comm comm)
  Description Unpack the content of `buf` starting at position `pos` (unless several objects have been packed contiguously, `*pos` should be equal to `0`). `buf` is a contigous memery area of length `bufsize` (note that the size is counted in bytes). `pos` is incremented and is on output the first location in the input buffer after the locations occupied by the message that was unpacked. `pos` is properly set for a future call to *MPI_Unpack* if any.

- int **pnl_object_mpi_send** (const PnlObject ∗Obj, int dest, int tag, MPI_Comm comm)
  Description Perform a standard-mode blocking send of `Obj`. The object is sent to the process with rank `dest`.

- int **pnl_object_mpi_ssend** (const PnlObject ∗Obj, int dest, int tag, MPI_Comm comm)
  Description Perform a standard-mode synchronous blocking send of `Obj`. The object is sent to the process with rank `dest`.

- int **pnl_object_mpi_recv** (PnlObject ∗Obj, int src, int tag, MPI_Comm comm, MPI_Status ∗status)
  Description Perform a standard-mode blocking receive of `Obj`. The object is sent to the process with rank `dest`. Note that `Obj` should be an already allocated object and that its type should match the true type of the object to be received. `src` is the rank of the process who sent the object.

- int **pnl_object_mpi_bcast** (PnlObject ∗Obj, int root, MPI_Comm comm)
  Description Broadcast the object `Obj` from the process with rank `root` to all other processes of the group `comm`.

- int **pnl_object_mpi_reduce** (PnlObject ∗Sendbuf, PnlObject ∗Recvbuf, MPI_Op op, int root, MPI_Comm comm)
  Description Perform the reduction described by `op` on the objects `Sendbuf` and stores the result into `Recvbuf`. Note that `Recvbuf` and `Sendbuf` must be of the same type. The argument `root` is the index of the root process and `comm` is a communicator. Not all reductions are implemented for all types. Here is the list of compatible reductions

MPI_SUM	PnlVect, PnlVectInt, PnlVectComplex, PnlMat, PnlMatInt, PnlMatComplex
MPI_PROD, MPI_MAX, MPI_MIN	PnlVect, PnlVectInt, PnlMat, PnlMatInt

For more expect users, we provide the following nonblocking functions.

- int **pnl_object_mpi_isend** (const PnlObject *Obj, int dest, int tag, MPI_Comm comm, MPI_Request *request)
  Description Start a standard-mode, nonblocking send of object `Obj` to the process with rank `dest`.

- int **pnl_object_mpi_irecv** (void **buf, int *size, int src, int tag, MPI_Comm comm, int *flag, MPI_Request *request)
  Description Start a standard-mode, nonblocking receive of object `Obj` from the process with rank `root`. On output `flag` equals to `TRUE` if the object can be received and `FALSE` otherwise (this is the same as for *MPI_Iprobe*).

15.2 The save/load interface

The interface is only accessible when the MPI bindings are compiled since it is based on the Packing/Unpacking facilities of MPI.
The functionnalities described in this chapter are declared in `pnl/pnl_mpi.h`.

- PnlRng ** **pnl_rng_create_from_file** (char *str, int n)
  Description Load `n` rng from the file of name `str` and returns an array of `n` PnlRng .

- int **pnl_rng_save_to_file** (PnlRng **rngtab, int n, char *str)
  Description Save `n` rng stored in `rngtab` into the file of name `str`.

- int **pnl_object_save** (PnlObject *O, FILE *stream)
  Description Save the object `O` into the stream `stream`. `stream` is typically created by calling fopen with `mode="wb"`. This function can be called several times to save several objects in the same stream.

- PnlObject* **pnl_object_load** (FILE *stream)
  Description Load an object from the stream `stream`. `stream` is typically created by calling fopen with `mode="rb"`. This function can be called several times to load several objects from the same stream. If `stream` was empty or it did not contain any PnlObjects, the function returns `NULL`.

- PnlList* **pnl_object_load_into_list** (FILE *stream)
  Description Load as many objects as possible from the stream `stream` and stores them into a PnlList . `stream` is typically created by calling fopen with `mode="rb"`. If `stream` was empty or it did not contain any PnlObjects, the function returns `NULL`.

16 Financial functions

The financial functions are defined in the header `pnl/pnl_finance.h`.

- int **pnl_cf_call_bs** (double s, double k, double T, double r, double divid, double sigma, double *ptprice, double *ptdelta)
  Description Compute the price and delta of a call option $(\texttt{s}-\texttt{k})_+$ in the Black-Scholes model with volatility `sigma`, instantaneous interest rate `r`, maturity `T` and dividend rate `divid`. The parameters `ptprice` and `ptdelta` are respectively set to the price and delta on output.

- int **pnl_cf_put_bs** (double s, double k, double T, double r, double divid, double sigma, double *ptprice, double *ptdelta)
  Description Compute the price and delta of a put option $(\texttt{k}-\texttt{s})_+$ in the Black-Scholes model with volatility `sigma`, instantaneous interest rate `r`, maturity `T` and dividend rate `divid`. The parameters `ptprice` and `ptdelta` are respectively set to the price and delta on output.

- double **pnl_bs_call** (double s, double k, double T, double r, double divid, double sigma)
  Description Compute the price of a call option with spot `s` and strike `k` in the Black-Scholes model with volatility `sigma`, instantaneous interest rate `r`, maturity `T` and dividend rate `divid`.

- double **pnl_bs_put** (double s, double k, double T, double r, double divid, double sigma)
  Description Compute the price a put option with spot `s` and strike `k` in the Black-Scholes model with volatility `sigma`, instantaneous interest rate `r`, maturity `T` and dividend rate `divid`.

- double **pnl_bs_call_put** (int iscall, double s, double k, double T, double r, double divid, double sigma)
  Description Compute the price of a put option if `iscall=0` or a call option if `iscall=1` with spot `s` and strike `k` in the Black-Scholes model with volatility `sigma`, instantaneous interest rate `r`, maturity `T` and dividend rate `divid`.

- double **pnl_bs_vega** (double s, double k, double T, double r, double divid, double sigma)
  Description Compute the vega of a put or call option with spot `s` and strike `k` in the Black-Scholes model with volatility `sigma`, instantaneous interest rate `r`, maturity `T` and dividend rate `divid`.

- double **pnl_bs_gamma** (double s, double k, double T, double r, double divid, double sigma)
  Description Compute the gamma of a put or call option with spot `s` and strike `k` in the Black-Scholes model with volatility `sigma`, instantaneous interest rate `r`, maturity `T` and dividend rate `divid`.

Practitioners do not speak in terms of option prices, but rather compare prices in terms of their implied Black & Scholes volatilities. So this parameter is very useful in practice. Here, we propose two functions to compute σ_{impl} : the first one is for one up-let, maturity, strike, option price. the second function is for a list of strikes and maturities, a matrix of prices (with strikes varying row-wise).

- double **pnl_bs_implicit_vol** (int is_call, double Price, double s, double K, double T, double r, double divid, int *error)
  Description Compute the implied volatility of a put option if `iscall=0` or a call option if `iscall=1` with spot `s` and strike `K` in the Black-Scholes model with instantaneous interest rate `r`, maturity `T` and dividend rate `divid`. On output `error` is `OK` if the computation of the implied volatility succeeded or `FAIL` if it failed.

- int **pnl_bs_matrix_implicit_vol** (const PnlMatInt *iscall, const PnlMat *Price, double s, double r, double divid, const PnlVect *K, const PnlVect *T, PnlMat *Vol)
  Description Compute the matrix of implied volatilities `Vol(i,j)` of a put option if `iscall(i,j)=0` or a call option if `iscall(i,j)=1` with spot `s` and strike `K(j)` in the Black-Scholes model with instantaneous interest rate `r`, maturity `T(j)` and dividend rate `divid`. This function returns the number of failures, when everything succeeded it returns 0.

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