Computational Geometry

(csci3250)

Laura Toma

Bowdoin College

Finding collinear points

We'll start with a warmup problem:

Problem: Given a set of n points in 2D, determine if there exist three points that are collinear.

Come up with different solutions to this problem (and analyze/compare them).

Finding collinear points

Brute force:

- for all distinct triplets of points p_i, p_j, p_k
 - · check if they are collinear

- Correct?
 - yes because it checks all triplets
- · Worst-case running time:
 - n chose 3 = $\Theta(n^3)$ triplets
 - · checking if three points are collinear can be done in constant time

$$==> O(n^3)$$
 algorithm

• Space: O(1)

Via sorting

- \bullet initialize array L = empty
- for all distinct pairs of points p_i, p_j
 - compute their line equation (slope, intercept) and add it to an array L
- sort array L by (slope, intercept)
- ullet traverse L and if you find any 3 consecutive identical (s,i) \to collinear

- Correct?
 - if points a, b, c are collinear ==> (slope, intercept) of (a,b) (b,c) and (a,c) are the same
- Worst-case running time:
 - $\Theta(n^2) + sort(n^2) = \Theta(n^2 \lg n)$
- · Space:
 - $\Theta(n^2)$ for L

With a binary search tree

- initialize BBST = empty
- for all distinct pairs of points p_i, p_j
 - compute their line equation (s, i)
 - insert (s,i) in BBST; if when inserting you find that (s,i) is already in the tree, you
 got three collinear points and return true
- (if you ever get here) return false
- Correct?
 - if points a, b, c are collinear ==> (slope, intercept) of (a,b) (b,c) and (a,c) are the same
- · Worst-case running time:
 - using a balanced tree (like red-black tree, or AVL-tree, or...)
 - $\Theta(n^2)$ inserts => $\Theta(n^2 \lg n)$
- · Space:
 - $\Theta(n^2)$ for BBST

With hashing

A hash table supports find(x), insert(x), delete(x)

- initialize HashTable = empty
- for all distinct pairs of points p_i, p_j
 - compute their line equation (s, i)
 - insert (s,i) in HashTable; if when inserting you find that (s,i) is already in the HT,
 you got three collinear points and return true
- (if you ever get here) return false

- Correct?
 - if points a, b, c are collinear ==> (slope, intercept) of (a,b) (b,c) and (a,c) are the same
- Worst-case running time:
 - $\Theta(n^2)$ searches & inserts => $\Theta(n^2)$ If we assume O(1) for find(x).
- · Space:
 - $\Theta(n^2)$ for hash table

Hashing

List<T>[] t;
int n;

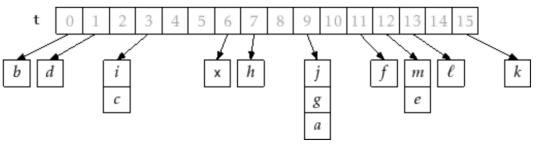


Figure 5.1: An example of a ChainedHashTable with n = 14 and

t.length = 16. In this example hash(x) = 6

Does find(x) run in O(1)?

- · Run time depends on how many other elements have same hash
- O(1) on the average assuming a good hash function (spreads the keys uniformly) and m = O(n). Worst-case is still O(n).
- O(1) expected worst-case can be achieved with universal hashing (by choosing the hash function uniformly at random from a set of universal hash functions, i.e. which guarantee no collision with high probability)

Families of universal hash functions are known for integers

can be extended to primitive types (char, float, string)

Summary: does find(x) run in O(1) ?

theory: O(1) expected, could be O(n) worst case

O(1) approximately true for many real world situations

With hashing

Algorithm 4

- initialize HashTable = empty
- for all distinct pairs of points p_i, p_j
 - compute their line equation (s, i)
 - insert (s,i) in HashTable; if when inserting you find that (s,i) is already in the HT,
 you got three collinear points and return true
- (if you ever get here) return false

• In conclusion, this runs in $\Theta(n^2)$ on the average, assuming a good hash function

A different way to sort

- for every point p_i
 - set array L = empty
 - for every point p_j (with $p_j! = p_i$)
 - * compute slope of p_j wrt to p_i and add it to array L
 - sort L
 - traverse L and if you find two consecutive points that have same slope, they are collinear with p_i so return true
- (if you get here) return false
- Correct?
 - if points a, b, c are collinear ==> slope of b and c wrt a are equal
- · Worst-case running time:
 - $n \times sort(n) = \Theta(n^2 \lg n)$
- Space:
 - $\Theta(n)$ for L

Summary

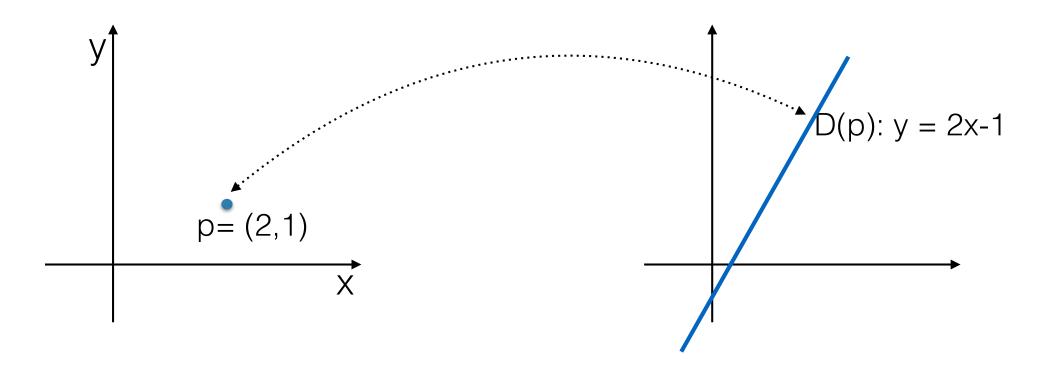
· Problem: Given a set of n points in the plane, determine if any are collinear.

Algorithms

- brute force: $O(n^3)$
- via sorting: $O(n^2 \lg n)$ with $O(n^2)$ space
- with BBST: same as above
- hashing: $O(n^2)$ with $O(n^2)$ space assuming good hash function
- smart sort: $O(n^2 \lg n)$ with O(n) space

Can we do better?

Duality transforms of points and lines in \mathbb{R}^2



Definition: The duality transform is defined as:

$$p = (a, b)$$
 $\cdots \rightarrow D(p) : y = ax - b$
 $l : y = ax - b$ $\cdots \rightarrow D(l) : p = (a, b)$

Write the duals for the following points

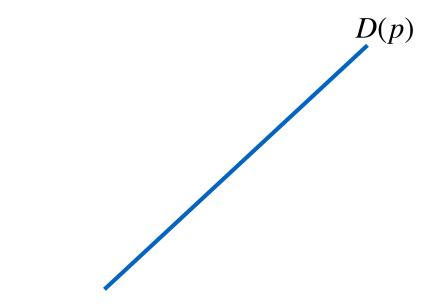
$$p = (1,1)$$
 $p = (3,5)$
 $p = (-4,2)$
 $p = (0,1)$

Write the duals for the following lines:

$$y = 3x - 4$$
$$y = x - 1$$
$$y = 2x + 1$$
$$y = x$$

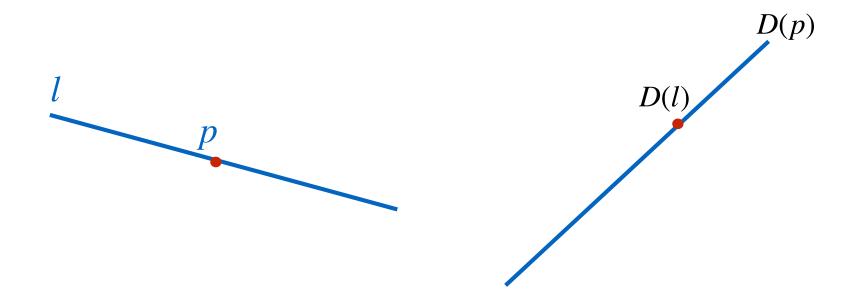
Lemma 1:

•
$$D(D(p)) = p$$
 and $D(D(l)) = l$



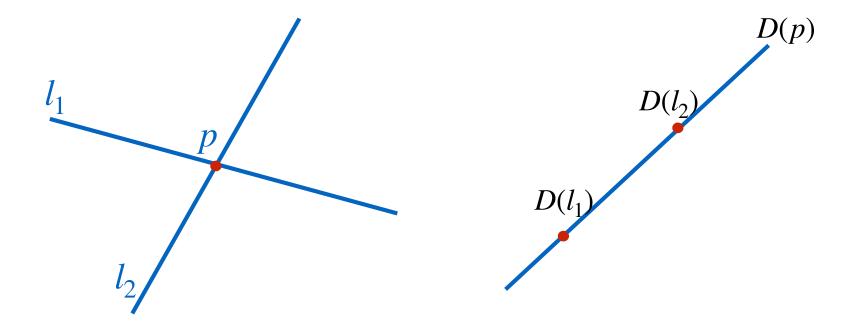
Lemma 2 [Incidence preserving]:

• If p lies on a line l, than D(l) lies on D(p)



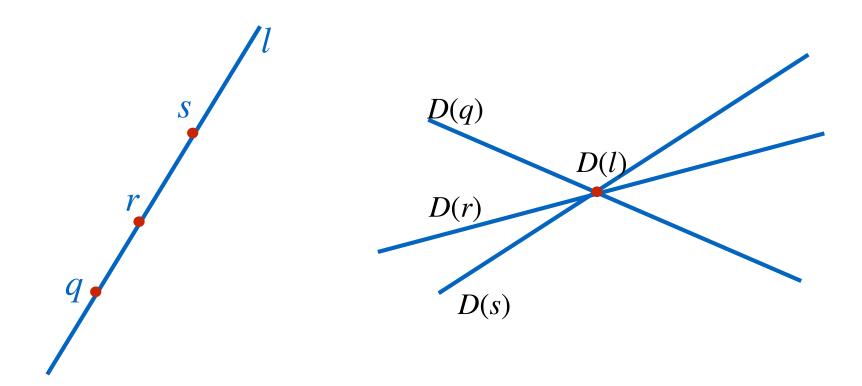
Lemma 3:

• l_1 and l_2 interect in point $p\iff D(p)$ passes through $D(l_1)$ and $D(l_2)$

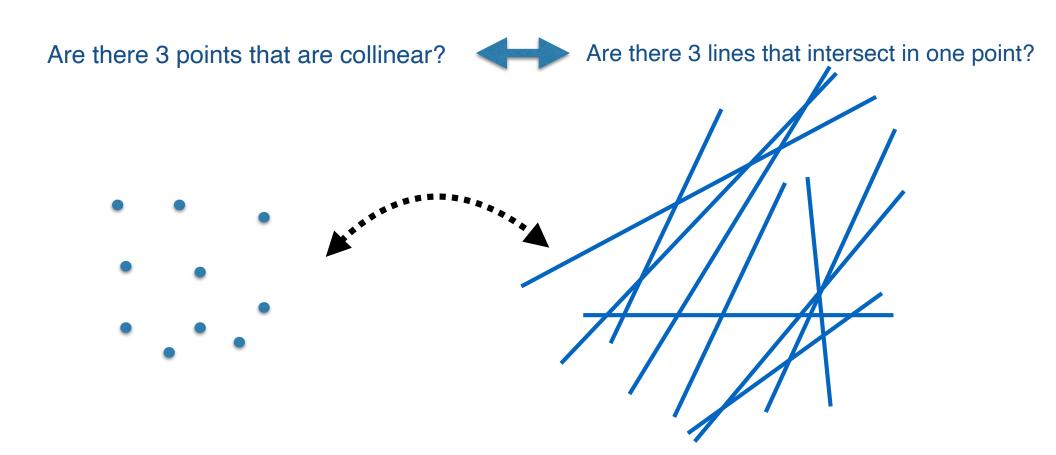


Lemma 4:

q, r, s collinear <=> D(q), D(r), D(s) intersect in a common point



And now back to our problem



It is known how to compute the intersections of n lines in $O(n \lg n) + k = O(n^2)$, where $k = O(n^2)$ is the nb. of intersections

Summary

Problem: Given a set of n points in the plane, determine if any are collinear.

Algorithms

• brute force: $O(n^3)$

• via sorting: $O(n^2 \lg n)$ with $O(n^2)$ space

· with BBST: same

• hashing: $O(n^2)$ with $O(n^2)$ space assuming good hash function

• smart sort: $O(n^2 \lg n)$ with O(n) space

• And fastest solution: compute line intersections in the dual in $O(n^2)$