

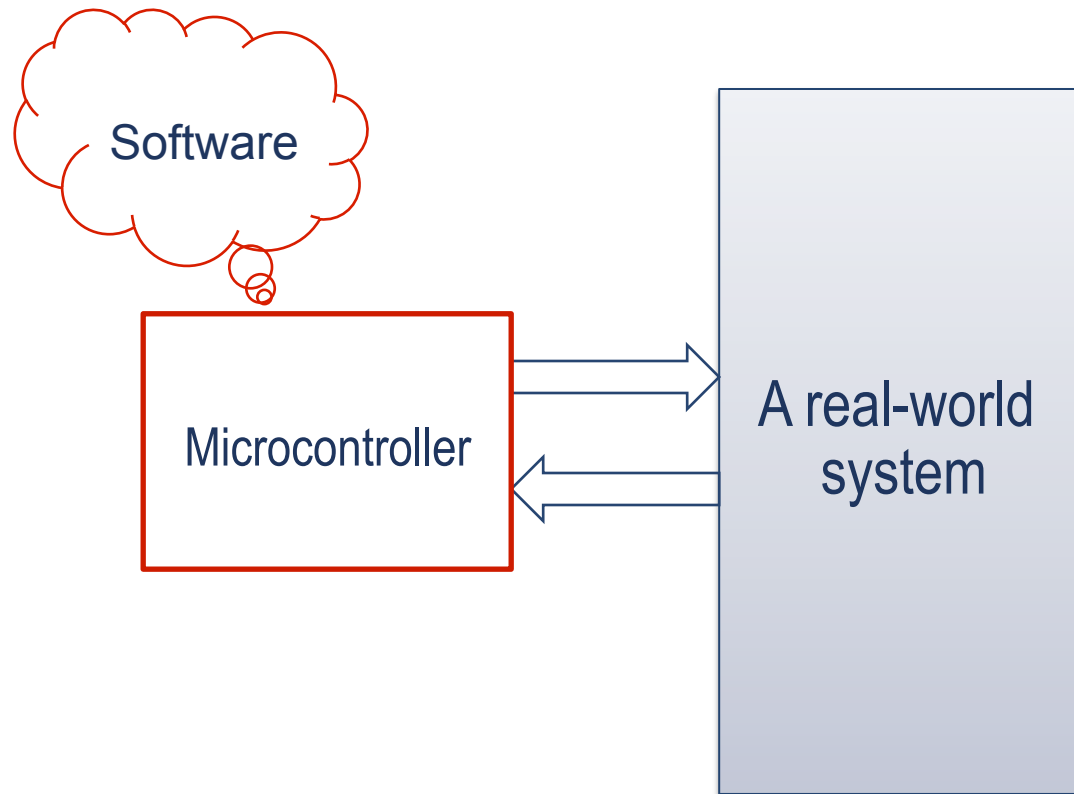
ECE 2534

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Overview of  
**PIC32, ~~Cerebot~~ Digilent, MPLAB,**  
and other things

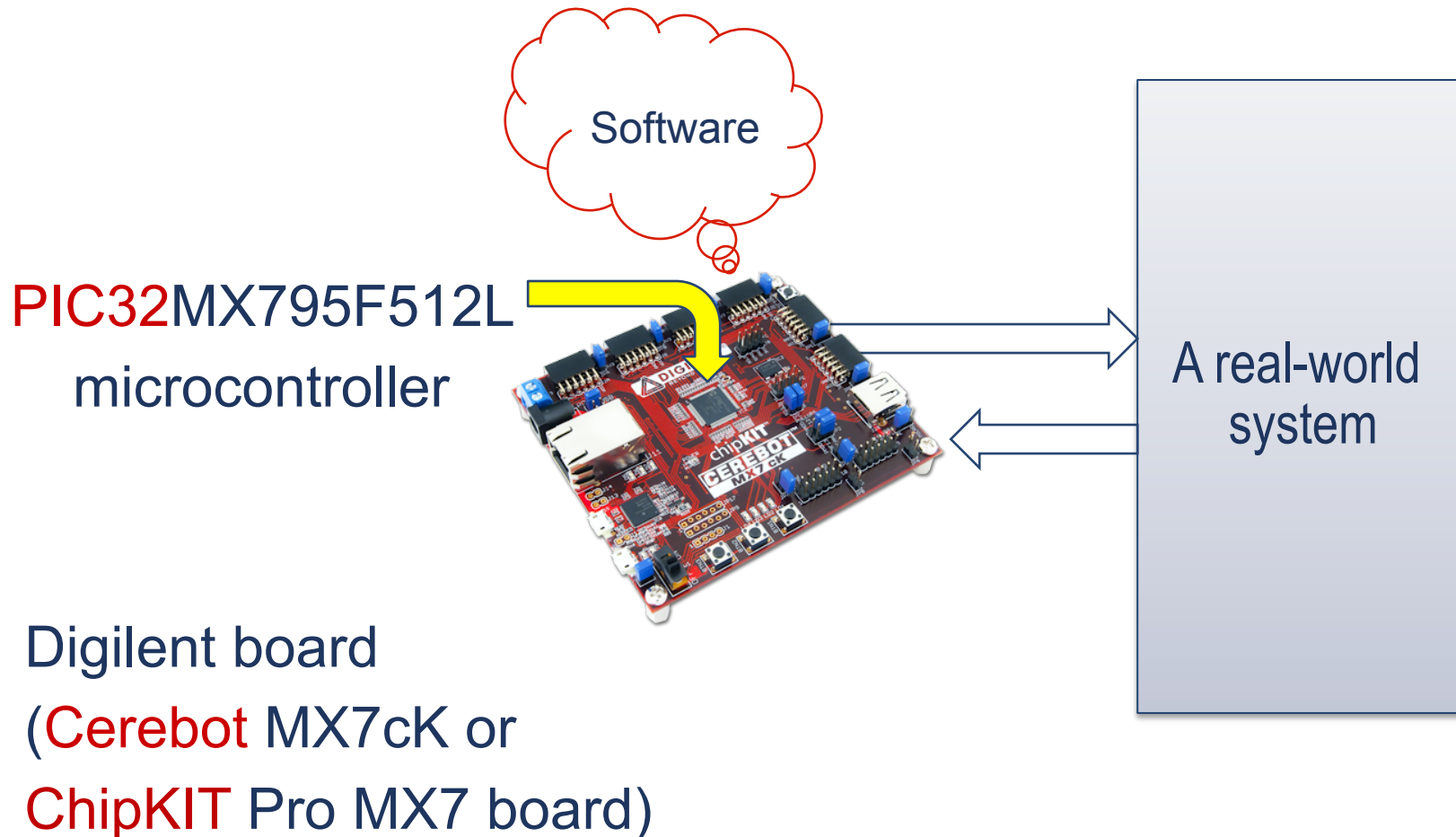
# The BIG PICTURE

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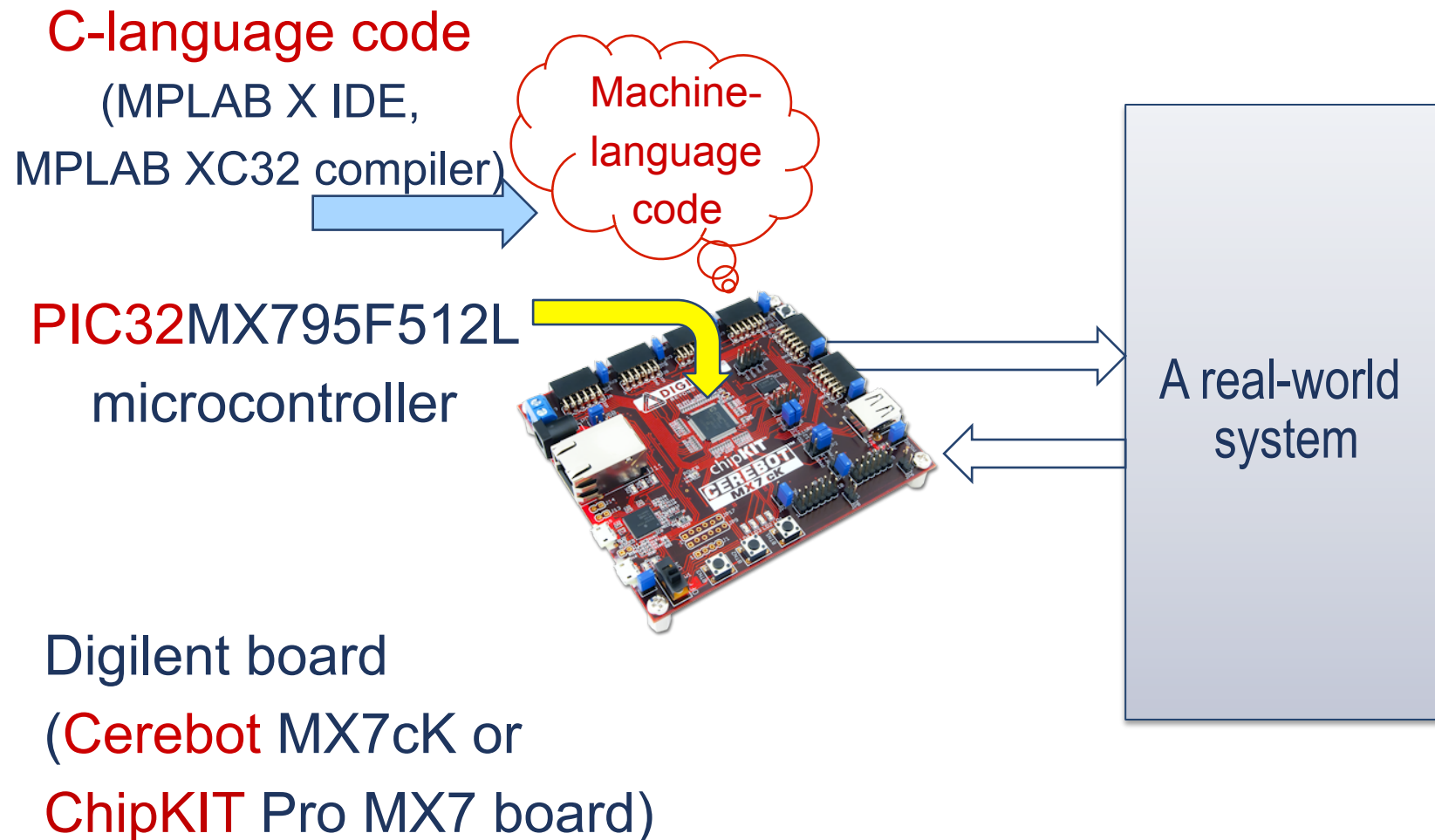
# The BIG PICTURE

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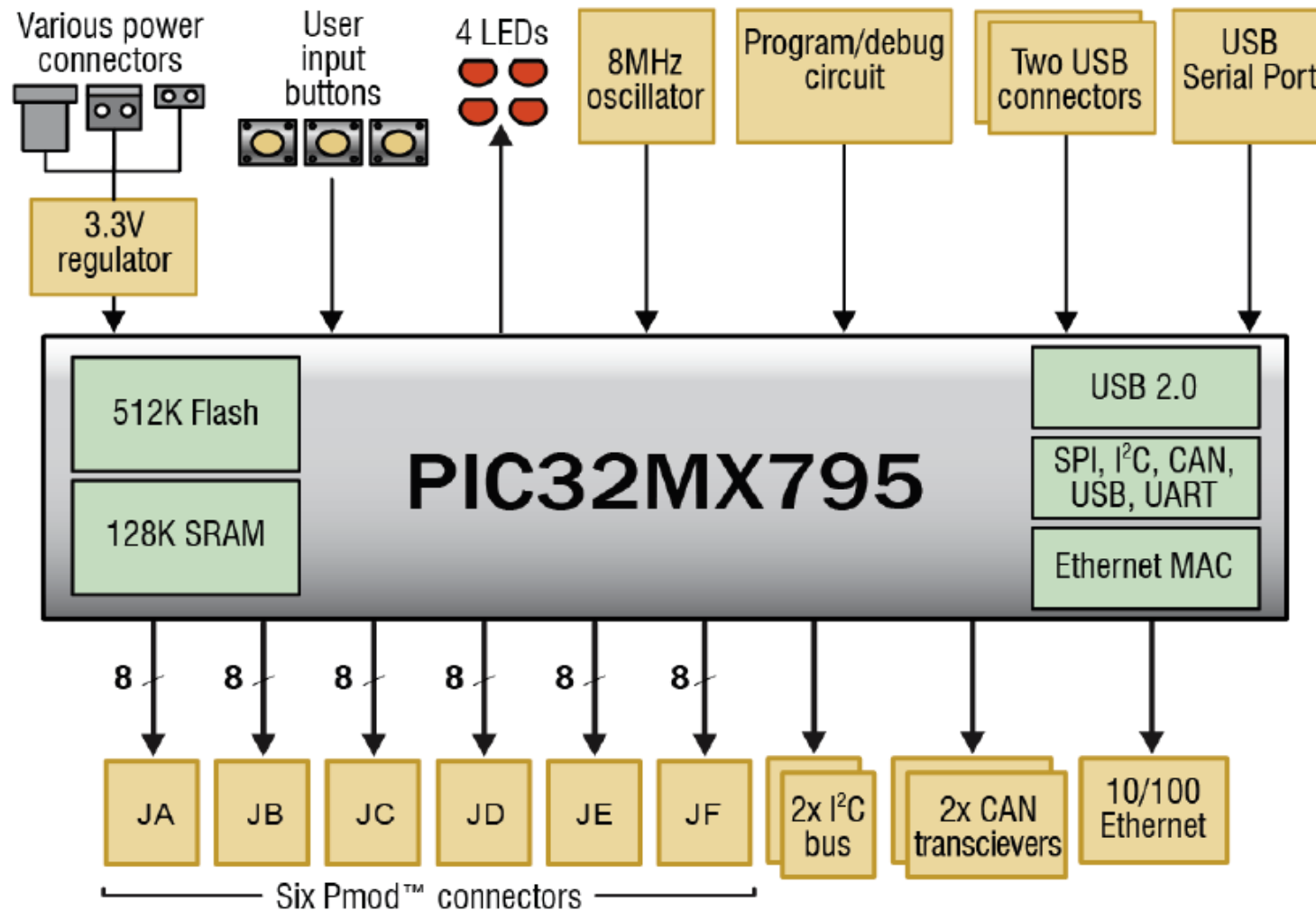


# The BIG PICTURE

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# Digilent board (high-level view)



(PIC32 datasheet, section 1)

**Note 1:** Some features are not available on all device variants.

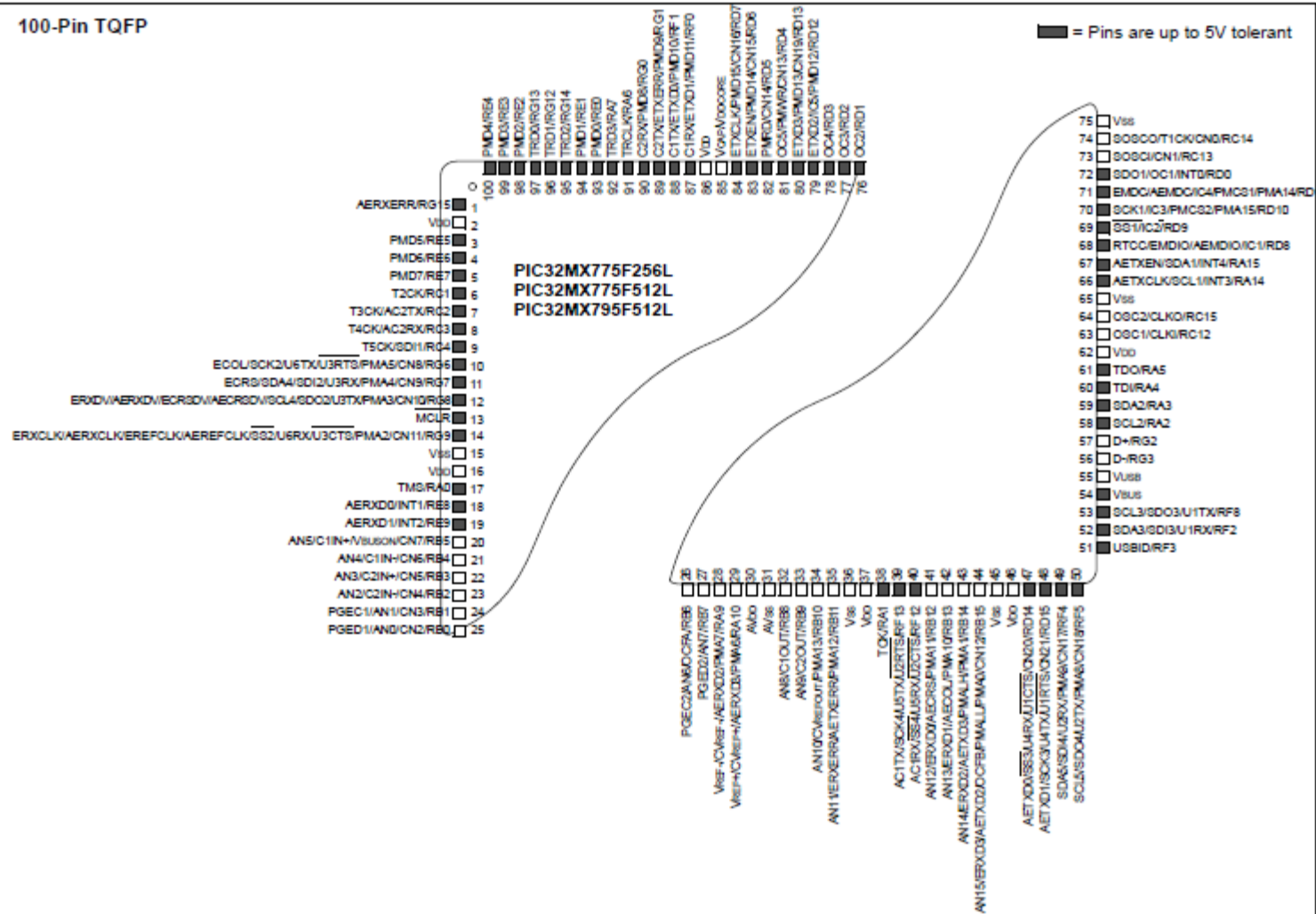
**Note 2:** BOR functionality is provided when the on-board voltage regulator is enabled.

# PIC32 package

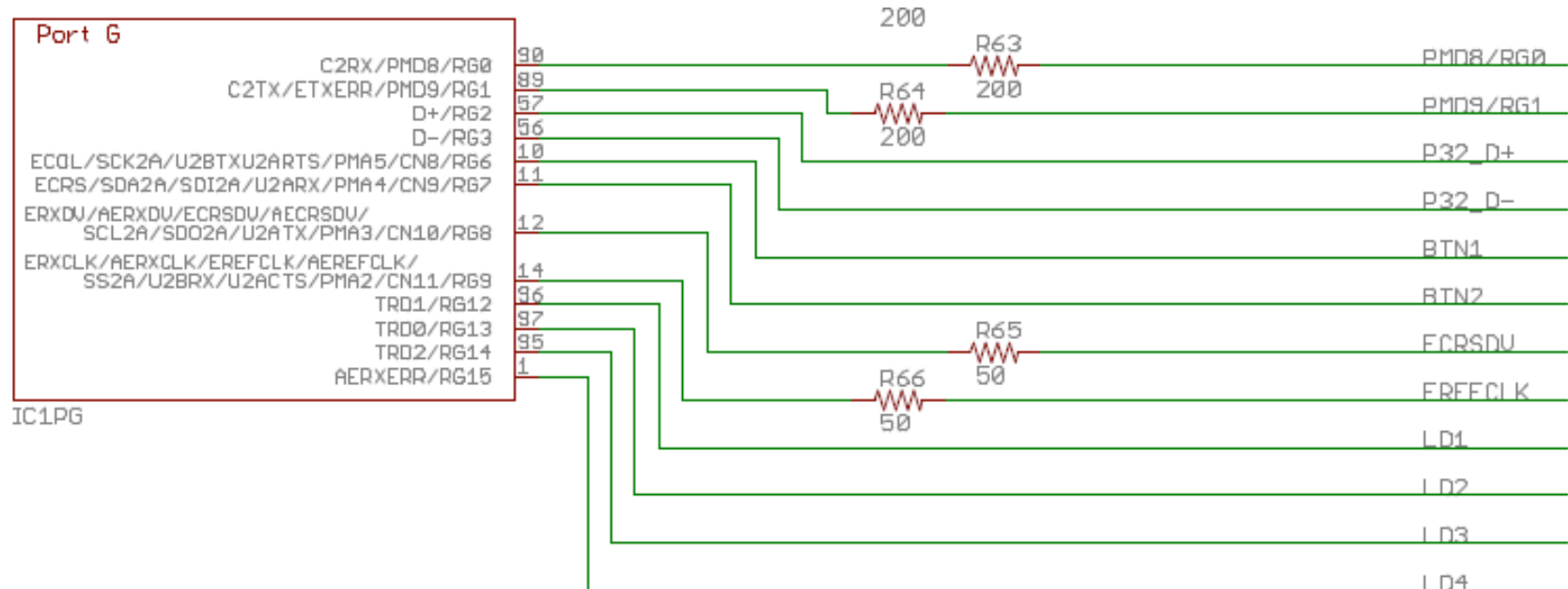
(PIC32 datasheet)

## Pin Diagrams (Continued)

### 100-Pin TQFP



# From Digilent schematics



Cerebot 32MX7

Copyright 2010, Digilent Inc.

Engineer: NEA

SHEET: PIC32 Microcontroller

Author: GA

TITLE: Cerebot 32MX7

Rev: C

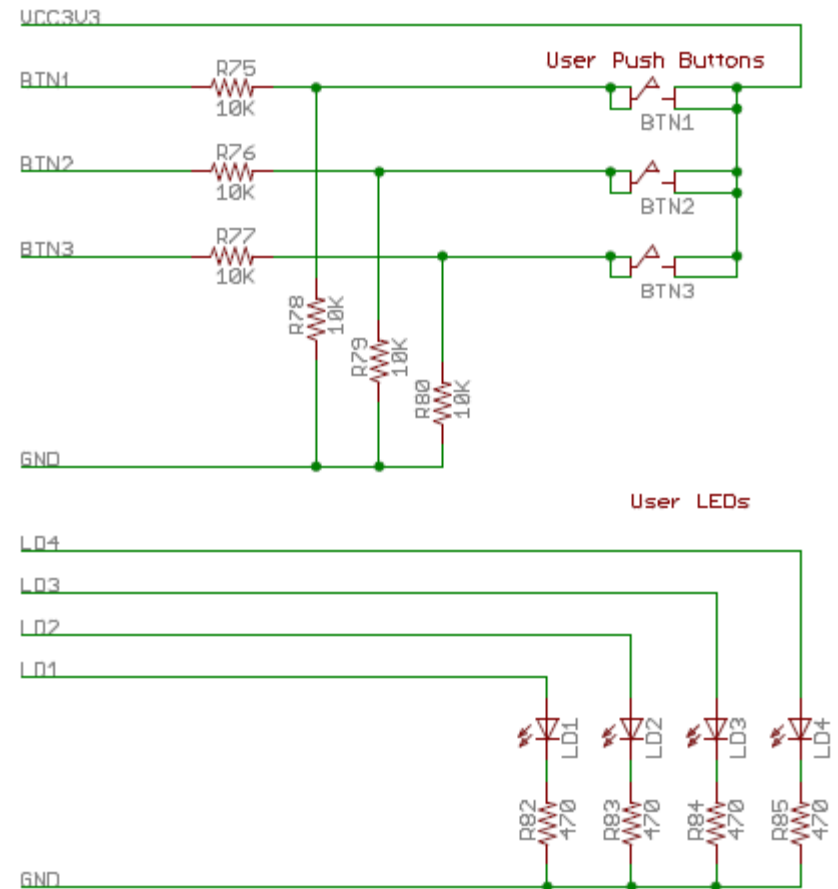
Doc#: 500-186

Date: 10/20/2010

Sheet: 5/9



# From Digilent schematics



Cerebot 32MX7

Copyright 2010, Digilent Inc.

Engineer: NEA

SHEET: Misc. I/O

Author: GA

TITLE: Cerebot 32MX7

Rev: C

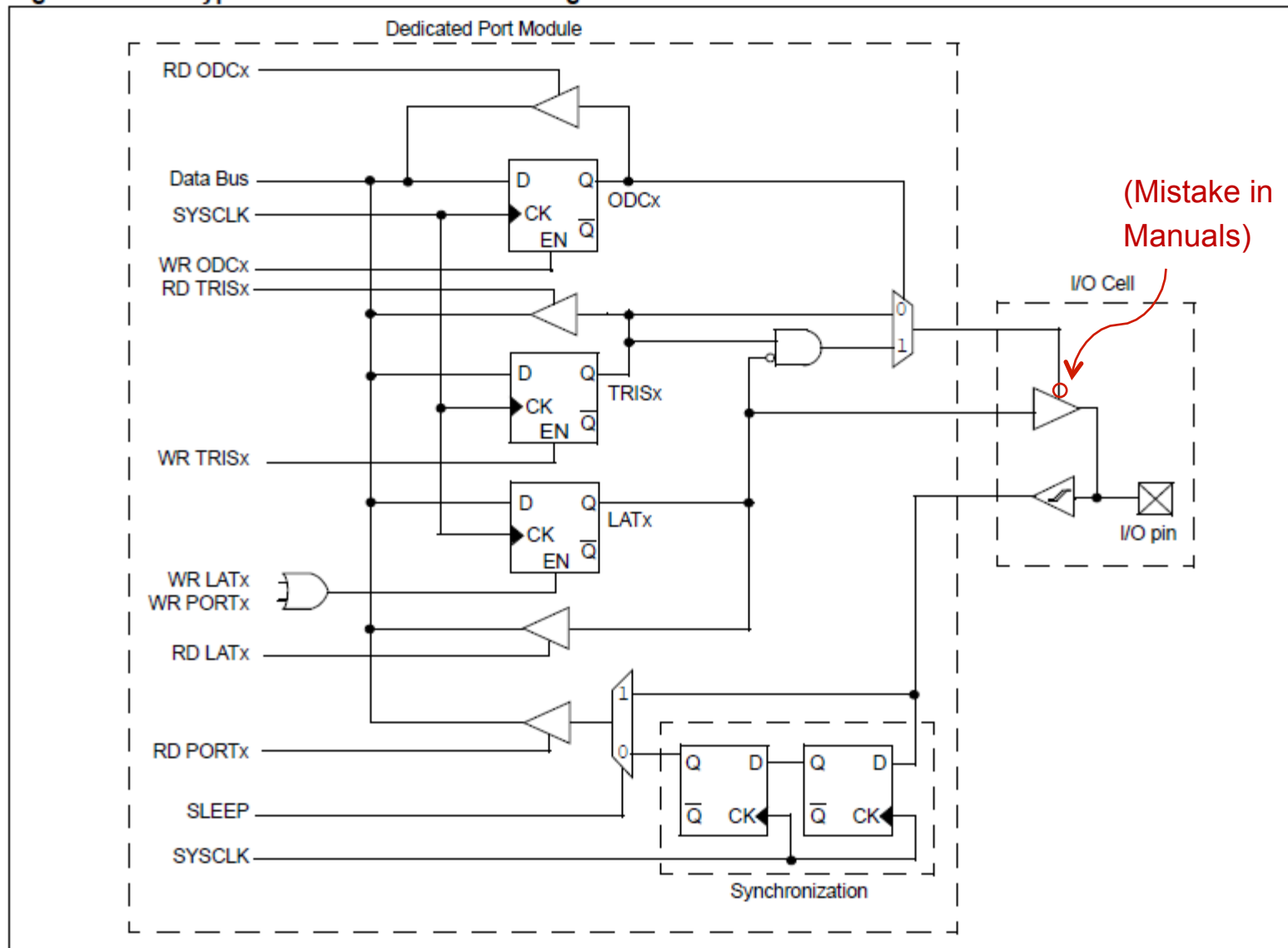
Doc#: 500-186

Date: 10/20/2010

Sheet: 6/9

# One bit on a PIC32 I/O Port

Figure 12-1: Typical Port Structure Block Diagram



# Summary

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## ❑ Need to think at several levels . . .

- Entire system

The microcontroller is (ultimately) a component in a larger system

- Microcontroller board

- The microcontroller has to sit somewhere, with power supply and electrical connections

- The microcontroller has I/O ports that interface to external devices

- Microcontroller

- The microcontroller has on-chip peripherals, such as timers, that need to be controlled through software

- The microcontroller has a (rather complex) CPU that will try to fetch instructions and execute them

- Instructions and data sit in memory (on-chip, possibly off-chip)

- Circuits & electronics

- None of this works without good electrical design, proper signal conditioning, etc.