

Part 2

**ECE 2534** 



## Outline

- Motivation
- Basic idea
- ADC on the PIC32
- Digital-to-analog conversion methods
- Analog-to-digital conversion methods



#### **REMINDER:**

#### Need to interface with the real (analog) world



## Analog to digital:

$$D = \left(\frac{V_{In} - V_{RefLow}}{V_{RefHigh} - V_{RefLow}}\right) \times 2^{n}$$

## Digital to analog:

$$V_{Out} = \left(\frac{D}{2^n}\right) \left(V_{RefHigh} - V_{RefLow}\right) + V_{RefLow}$$



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## Digital-to-Analog Conversion

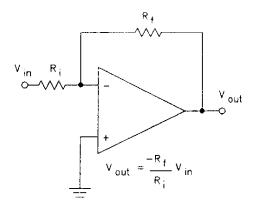
- Goal
  - □ Convert a digital value to an analog voltage
  - □ Usually an unsigned binary number, 8 to 16 bits
  - □ Common output range: a few volts, such as 0 to Vcc or −12 V to +12 V
- Normally use a linear mapping
- Common concerns
  - Resolution
  - □ Accuracy
  - Conversion speed



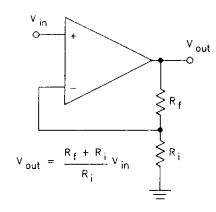
#### Three methods for D/A conversion

- Binary weighted ladder
- R-2R ladder
- Pulse-width modulation

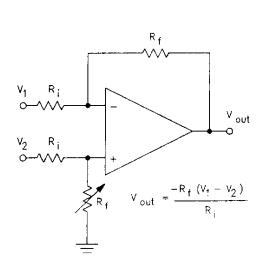
# First. . . some op-amp circuits



(a) Inverting Amplifier



(b) Noninverting Amplifier



 $V_{out} = -R_f \left( \frac{V_1}{R_1} + \frac{V_2}{R_2} + \frac{V_3}{R_3} \right)$ 

V out

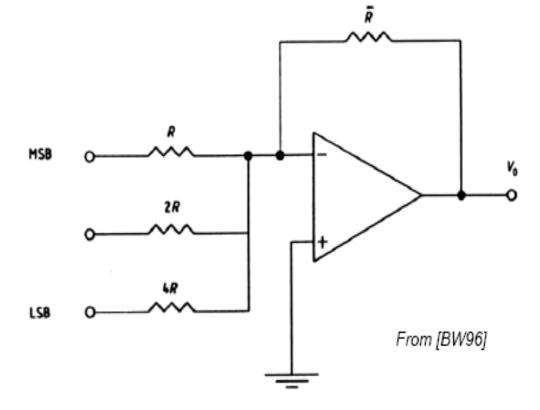
(c) Differential Amplifier

(d) Summing Amplifier



## Binary weighted ladder

- Based on the Summing Amplifier
- One bit per input
- Each input resistor is 2X the previous value
- $ightharpoonup V_{RefHigh}$  if input bit is 1, otherwise ground
- 3-bit example:





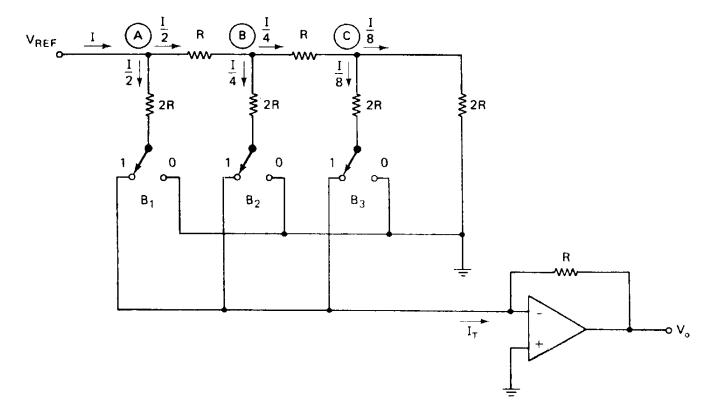
## Binary weighted ladder

- Fast conversion, but . ..
- Not practical for large n because many different high-accuracy resistors are needed
- The lowest-value resistor R affects the MSB and must have the highest accuracy
- "usually limited to 8-bit resolution or less"



#### R-2R ladder

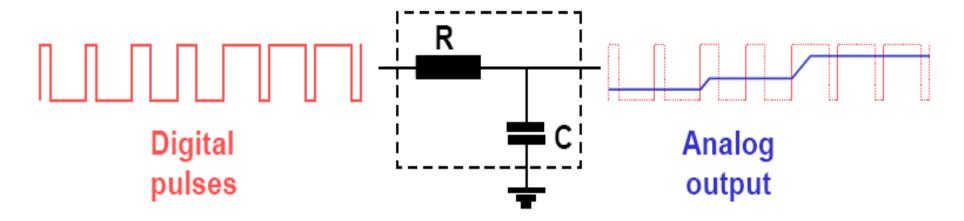
- Uses 2*n* resistors, with only two resistance values
- Somewhat slower than the previous case, because the RC effects increase for each additional R-2R stage
- 3-bit example:





## PWM technique

- Simplest type of DAC
- Digital system generates a PWM waveform, selecting pulse widths based on the binary values being converted to analog form
- The waveform is input to a low-pass analog filter





## PWM technique

- Often used for electric motor speed control
- Now becoming common in high-fidelity audio

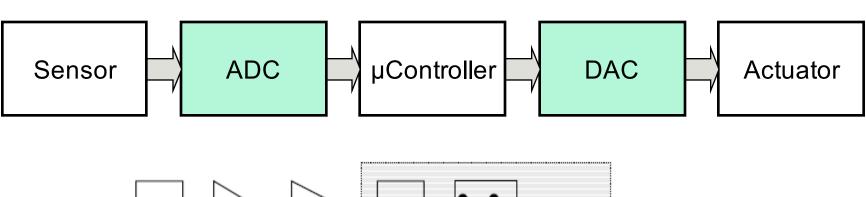


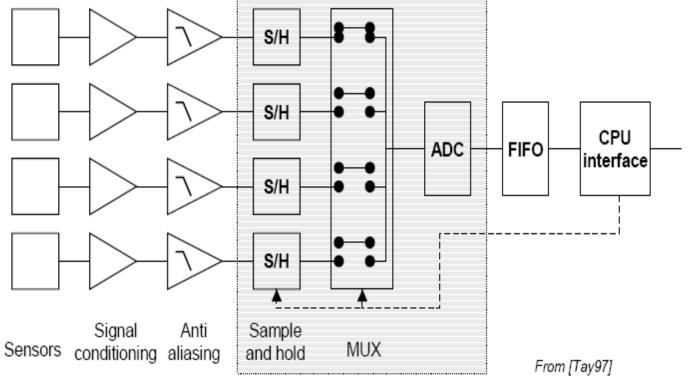
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# 

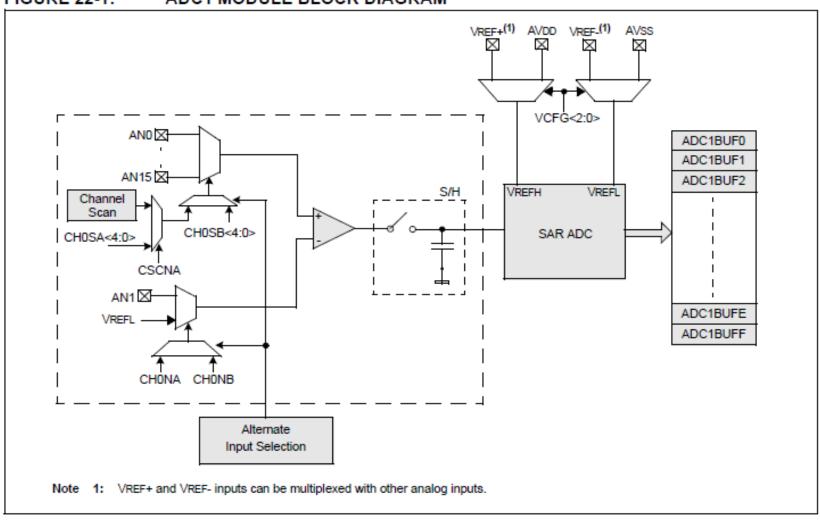
## System overview, again





# Comparision with PIC32

FIGURE 22-1: ADC1 MODULE BLOCK DIAGRAM





#### Signal conditioning

- □ Many sensors provide noisy, weak signals (e.g., a few mV or uV)
- □ Often need to amplify, filter, linearize

#### Antialiasing

 For time-varying signals, often use LPF to make sure the Nyquist criterion is satisfied



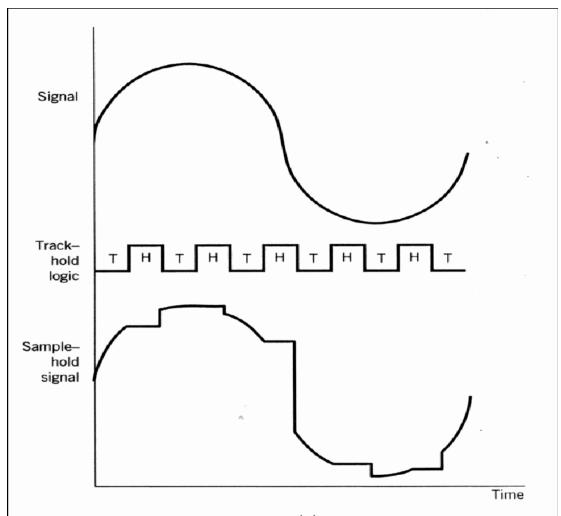
## Sample and hold circuits

# Two basic operating modes

- □ Sample mode: The S/H output follows the input ("Acquisition time")
- ☐ Hold mode: Try to hold the output constant ("Conversion time")

#### Goal:

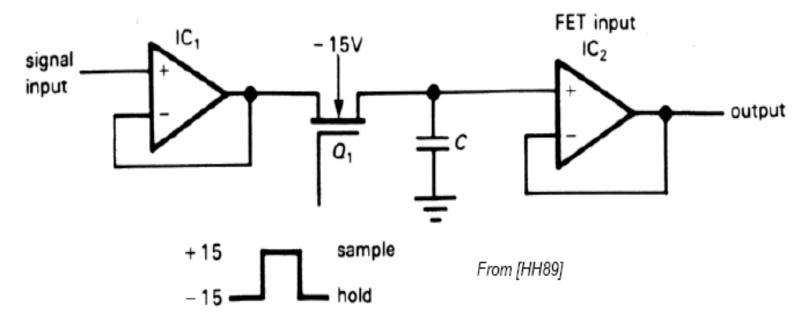
□ Provide a steady voltage level to the ADC during conversion





## Example S/H circuit components

- FET-based switch
- Capacitor to hold voltage steady
- Voltage followers as buffers

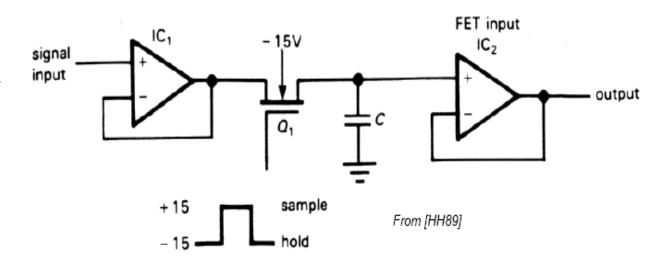




## Main S/H circuit components

#### Components

- □ FET-based switch
- Capacitor to hold voltage steady
- Voltage followers as buffers



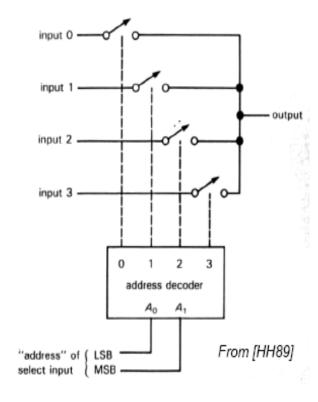
#### Operation

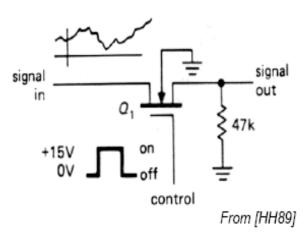
- □ IC1 provides low Zout version of input signal
- □ FET passes the signal during 'sample' and disconnects during 'hold'
- C preserves the value during 'hold'
- IC2 is a high Zin op-amp to minimize capacitor discharge during 'hold'



# Multiplexers

- MUX: a device that outputs one signal that is selected from several input signals
- FET-based analog switches
  - □ N-channel enhancement-mode MOS-FET
  - □ When gate is grounded or negative, the FET is nonconducting
  - $\hfill\Box$  Drain-source resistance in the order of 10,000  $M\Omega$
  - □ Bringing the gate to +15V puts the drainsource channel into conduction
  - $\square$  Drain-source resistance in the order of 100 $\Omega$







# Given a stable analog voltage, how to perform A/D conversion?

- Goal
  - □ Convert an analog voltage level to a digital value
  - ☐ Usually 8 to 16 bits
  - □ Common input range: a few volts, such as 0 to VDD or −12 V to +12 V
- Normally use a linear mapping
- Common concerns
  - □ Resolution
  - □ Accuracy
  - Conversion speed



## **Analog-to-Digital Conversion**

Typical conversion

$$D = \left(\frac{V_{In} - V_{RefLow}}{V_{RefHigh} - V_{RefLow}}\right) \times 2^{n}$$

- $\Box$   $V_{ln}$  = analog input voltage
- $\square$  D = binary output value
- $\square$  *n* = number of bits
- $\Box V_{RefHigh}$  = upper reference voltage
- $\Box V_{RefLow}$  = lower reference voltage



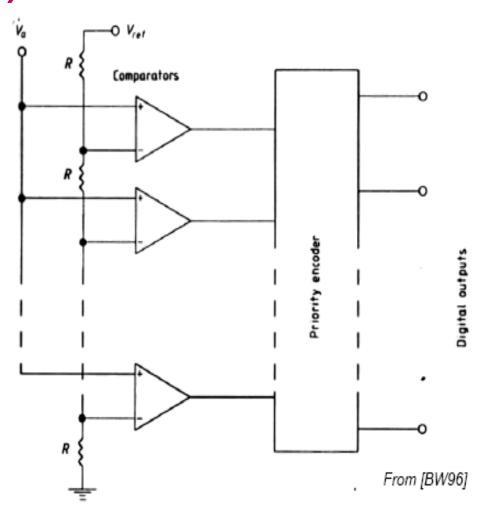
#### Methods for A/D conversion

- Flash converter
- Counting converter
- Successive approximation



## Flash (parallel) conversion

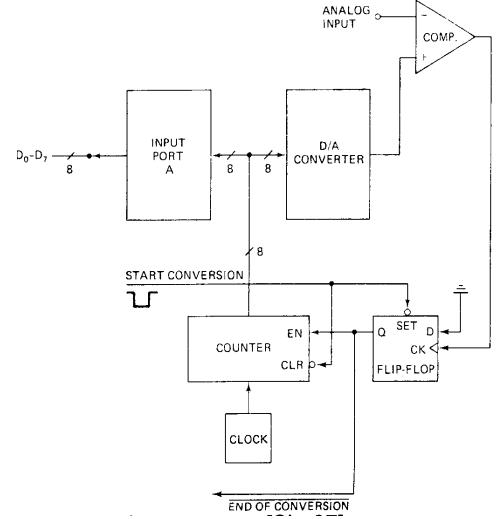
- Use 2<sup>n</sup>comparators
- Priority encoder
- Fast & expensive





## Counting conversion

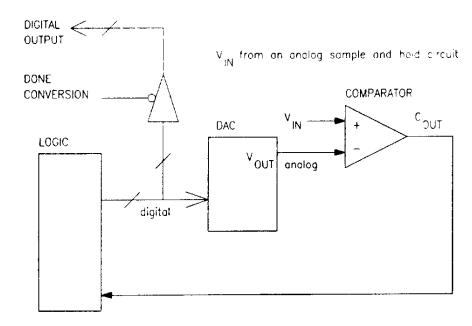
- Use a DAC
- Count up until DAC output matches the input voltage
- Slow



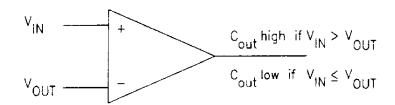


## Successive approximation

- Use a DAC
- Do a smarter search for the best digital value



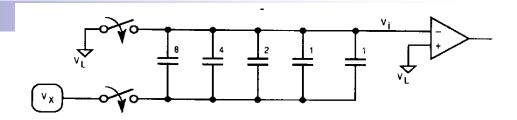
(a) Block Diagram of Successive-Approximation System



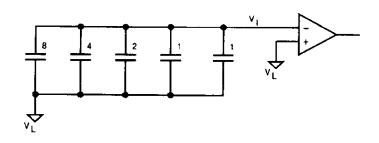
(b) Operation of Comparator



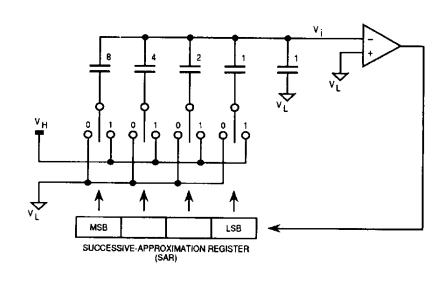
- A form of successive approximation
- First try MSB, then next bit, then next, . . .



(a) Sample Mode



(b) Hold Mode



(c) Approximation Mode



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  - Pulse-width modulation
- Analog-to-digital conversion methods
  - □ Flash converter
  - □ Counting converter
  - □ Successive approximation