## angleSkel.tree

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Fields	name name	⊞ id	<b>-</b>	offset	() channels			rotInd		r children	order order	posind	order	posino
1	'Hips'		0 [0,0,		1x6 cell		'zxy'	[5,6,4]	[1,2,3]	[2,7,12]	'xyz'	[1,2,3] [	'xyz'	[1,2]
2	'RightUpLeg'			3.1845,0,0]	1x3 cell		l 'zxy'	[8,9,7]	[]	3	'xyz'	[4,5,6]	'xyz'	[3,4]
3	'RightLeg'		_	61.9405,0]	1x3 cell		2 'zxy'	[11,12,10]		4	'xyz'	[7,8,9]	'xyz'	[5,6]
4	'RightFoot'		_	60.2236,0]	1x3 cell		3 'zxy'	[14,15,13]		5	'xyz'	[10,11,12]	'xyz'	[7,8]
5	'RightToeBase'		4 [0,0,	163.8842]	1x3 cell	-	1 'zxy'	[17,18,16]	[]	6	'xyz'	[13,14,15] (	'xyz'	[9,10]
6	'Site'		5 [0,0,	74.9994]	[]	5	5 []	[]	[]	[]	'xyz'	[16,17,18] [	'xyz'	[11,12]
7	'LeftUpLeg'		6 [138	.1848,0,0]	1x3 cell	]	l 'zxy'	[20,21,19]	[]	8	'xyz'	[19,20,21] {	'xyz'	[13,14]
8	'LeftLeg'		7 [0,-4	61.9402,0]	1x3 cell	7	7 'zxy'	[23,24,22]	[]	9	'xyz'	[22,23,24] 9	'xyz'	[15,16]
9	'LeftFoot'		8 [0,-4	60.2238,0]	1x3 cell	8	3 'zxy'	[26,27,25]	[]	10	'xyz'	[25,26,27]	'xyz'	[17,18]
10	'LeftToeBase'		9 [0,0,	163.8842]	1x3 cell	9	'zxy'	[29,30,28]	[]	11	'xyz'	[28,29,30]	'xyz'	[19,20]
11	'Site'		10 [0,0,	74.9993]	[]	10	[]	[]	[]	[]	'xyz'	[31,32,33] [	'xyz'	[21,22]
12	'Spine'		11[0,0.	1000,0]	1x3 cell	]	l 'zxy'	[32,33,31]	[]	13	'xyz'	[34,35,36]	'xyz'	[23,24]
13	'Spine1'		12 [0,25	4.2822,0]	1x3 cell	12	2 'zxy'	[35,36,34]	[]	[14,17,25]	'xyz'	[37,38,39] [	'xyz'	[25,26]
14	'Neck'		13 [0,24	19.9474,0]	1x3 cell	13	3 'zxy'	[38,39,37]	[]	15	'xyz'	[40,41,42]	'xyz'	[27,28]
15	'Head'		14 [0,1]	1.0848,0]	1x3 cell	14	1 'zxy'	[41,42,40]	[]	16	'xyz'	[43,44,45]	'xyz'	[29,30]
16	'Site'		15 [0,1]	[4.9990,0]	[]	15	5 []	[]	[]	[]	'xyz'	[46,47,48] [	'xyz'	[31,32]
17	'LeftShoulder'		16 [0,24	19.9474,0]	1x3 cell	13	3 'zxy'	[44,45,43]	[]	18	'xyz'	[49,50,51]	'xyz'	[33,34]
18	'LeftArm'		17 [0,16	6.3306,0]	1x3 cell	17	7 'zxy'	[47,48,46]	[]	19	'xyz'	[52,53,54]	'xyz'	[35,34]
19	'LeftForeArm'		18 [0,28	33.1723,0]	1x3 cell	18	3 'zxy'	[50,51,49]	[]	20	'xyz'	[55,56,57] 2	'xyz'	[37,38]
20	'LeftHand'		19 [0,24	18.3113,0]	1x3 cell	19	'zxy'	[53,54,52]	[]	[21,23]	'xyz'	[58,59,60] [	'xyz'	[39,40]
21	'LeftHandThumb'		20 [0,0,	0]	1x3 cell	20	'zxy'	[56,57,55]	[]	22	'xyz'	[61,62,63]	'xyz'	[41,42]
22	'Site'		21 [0,0,	99.9997]	[]	21	1[]	[]	[]	[]	'xyz'	[64,65,66] [	'xyz'	[43,44]
23	'L_Wrist_End'		22 [0,99	9.9970,0]	1x3 cell	20	'zxy'	[59,60,58]	[]	24	'xyz'	[67,68,69]	'xyz'	
24	'Site'		23 [0,0,	0]	[]	23	3[]	[]	[]	[]	'xyz'	[70,71,72] [	'xyz'	[45,46]
25	'RightShoulder'		24 [0,24	19.9474,0]	1x3 cell	13	3 'zxy'	[62,63,61]	[]	26	'xyz'	[73,74,75]	-	[47,48]
26	'RightArm'		25 [0,16	6.3307,0]	1x3 cell	25	'zxy'	[65,66,64]	[]	27	'xyz'	[76,77,78]	'xyz'	[49,50]
27	'RightForeArm'		26 [0,28	33.1712,0]	1x3 cell	26	5 'zxy'	[68,69,67]	[]	28	'xyz'	[79,80,81]	'xyz'	[51,52]
28	'RightHand'		27 [0,24	18.3149,0]	1x3 cell	27	7 'zxy'	[71,72,70]		[29,31]	'xyz'	[82,83,84] [	'xyz'	[53,54]
29	'RightHandThumb'		28 [0,0,		1x3 cell		3 'zxy'	[74,75,73]		30	'xyz'	[85,86,87]	'xyz'	[55,56]
30	'Site'			100.0004]	[]	-	9[]		[]	[]	'xyz'	[88,89,90]	'xyz'	[57,58]
31	'R Wrist End'		_	37.4996,0]	1x3 cell		3 'zxy'	[77,78,76]		32	'xyz'	[91,92,93]	'xyz'	[59,60]
32	'Site'		31 [0,0,		[]		1[]	[]	[]	[]	'xyz'	[94,95,96]	'xyz'	[61,62]
	•		[-,0,								XyZ	[94,93,90]	'xyz'	[63,64]

3D Positions

2D Positions