

LinkedList - 2

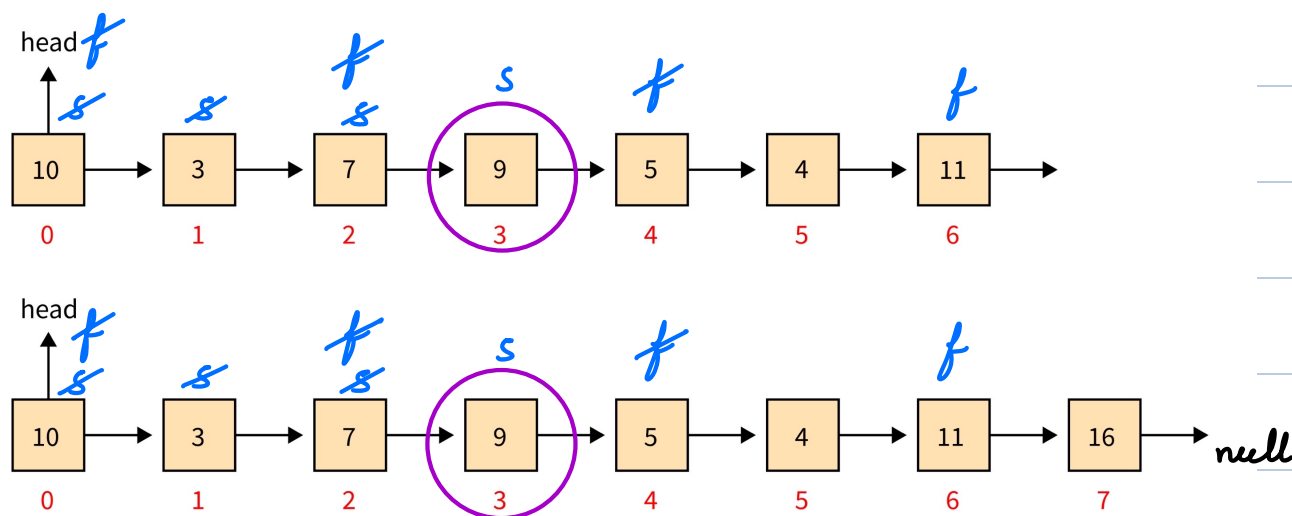
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Middle of a Linked-list



Sol 1 → 1) Find length of linked list (N). → $O(N)$

2) Travel half length ($N/2$). → $O(N/2)$

$TC = O(N)$ $SC = O(1)$

Sachin (200 Km/h)

Sol 2 →



if (Head == null) return null

s = f = Head

while (f.next != null && f.next.next != null) {

 s = s.next

 f = f.next.next

} return s

$TC = O(N/2) = O(N)$ $SC = O(1)$

Head = null



```
if (H1.data <= H2.data) {
```

```
    Head = H1
```

```
    H1 = H1.next
```

```
} else {
```

```
    Head = H2
```

```
    H2 = H2.next
```

```
}
```

```
cur = Head
```

```
while (H1 != null && H2 != null) {
```

```
    if (H1.data <= H2.data) {
```

```
        cur.next = H1
```

```
        H1 = H1.next
```

```
    } else {
```

```
        cur.next = H2
```

```
        H2 = H2.next
```

```
    } cur = cur.next
```

```
}
```

```
if (H1 == null) cur.next = H2
```

```
if (H2 == null) cur.next = H1
```

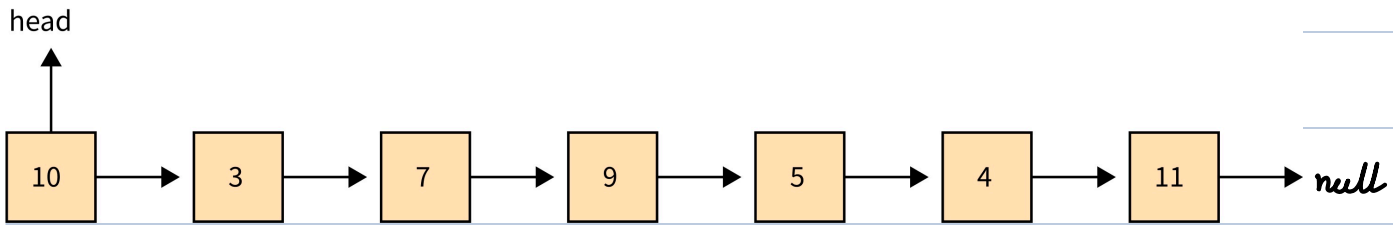
```
return Head
```

TC = $O(N+M)$

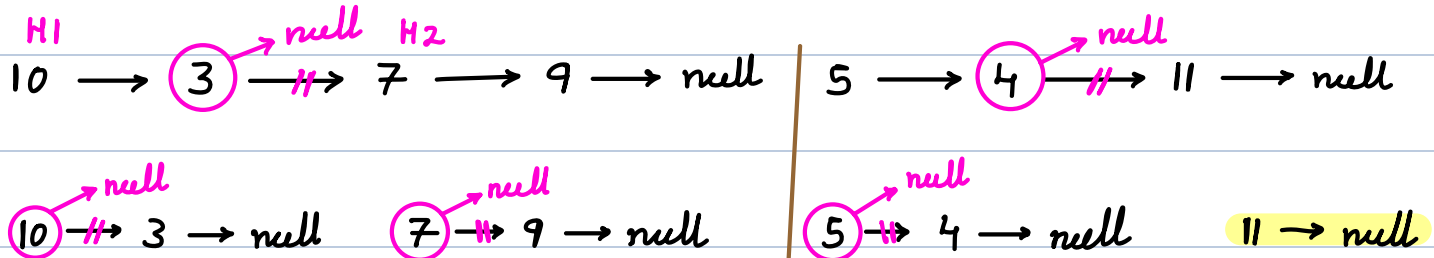
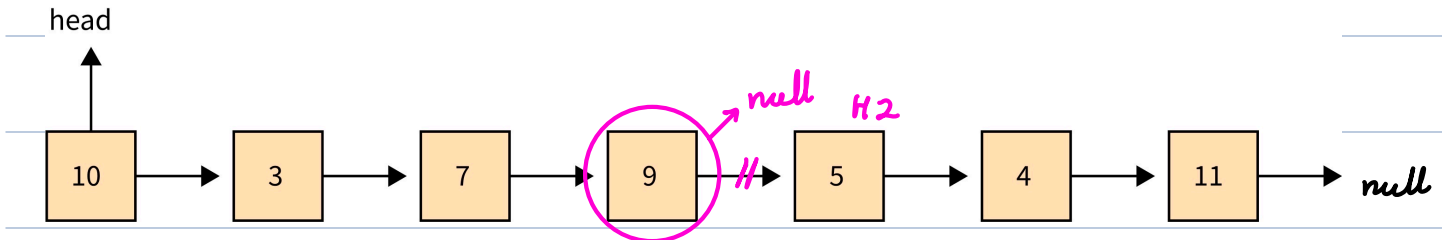
SC = $O(1)$



Merge Sort a Linked-list



Head 3 → 4 → 5 → 7 → 9 → 10 → 11 → null



10 → null 3 → null 7 → null 9 → null 5 → null 4 → null 11 → null

3 → 10 → null 7 → 9 → null 4 → 5 → null

3 → 7 → 9 → 10 → null 4 → 5 → 11 → null

3 → 4 → 5 → 7 → 9 → 10 → 11 → null



Idea

1. Find the middle node
2. Make recursive calls to sort 1st half and 2nd half
3. Finally, merge two sorted linked-list



```
Node sort (Head) {
```

```
    if (Head == null || Head.next == null)
```

```
        return Head
```

```
    mid = findMiddle (Head) → TC = O(N)
```

```
    H2 = mid.next
```

```
    mid.next = null
```

```
    H1 = sort (Head)
```

```
    H2 = sort (H2)
```

```
    return mergeSortedList (H1, H2) → TC = O(N)
```

```
}
```

TC = $O(N \log(N))$

SC = $O(\log(N))$

Scenario

You are using **Google Maps** to help you find your way around a new place. But, you get lost and end up walking in a circle. **Google Maps** has a way to keep track of where you've been with the help of special **sensors**.

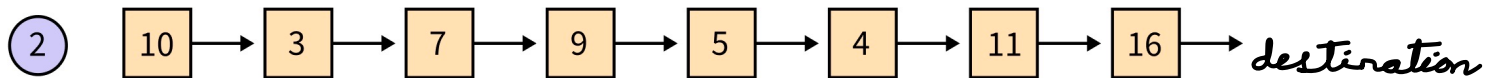
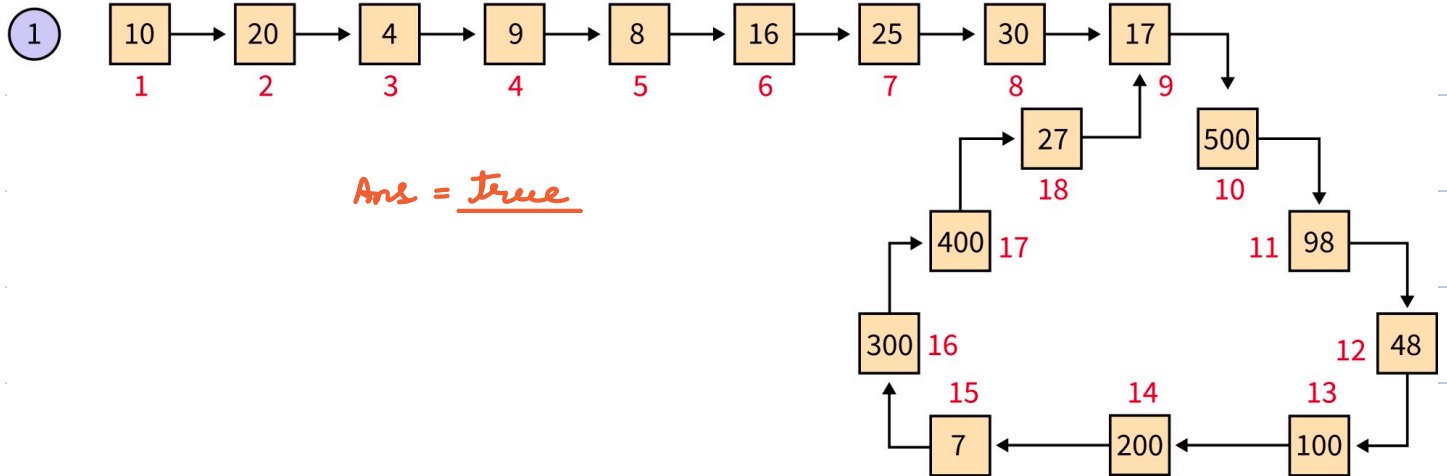
These sensors notice that you're **walking in a loop**, and now, **Google** wants to create a new feature to help you figure out exactly where you started going in circles.

Problem

You have a **linked list** that shows each **step** of your **journey**, like a chain of events. Some of these steps have accidentally led you back to a place you've already been, making you **walk in a loop**. The goal is to find out the exact point where you first started walking in this loop.



Check if there is a loop

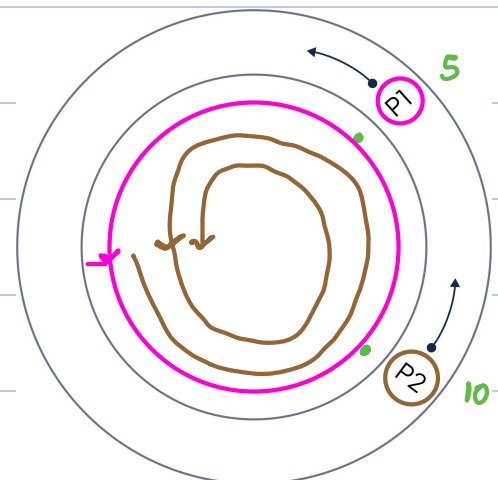


Sol 1 → Use hashset to check already visited node. ✓

SC = O(1)

O(1)

If two people are running with different speeds on a circular track, they will 100% meet at some point.



$s = f = \text{Head}$

while (f != null && f.next != null) {

`s = s.next`

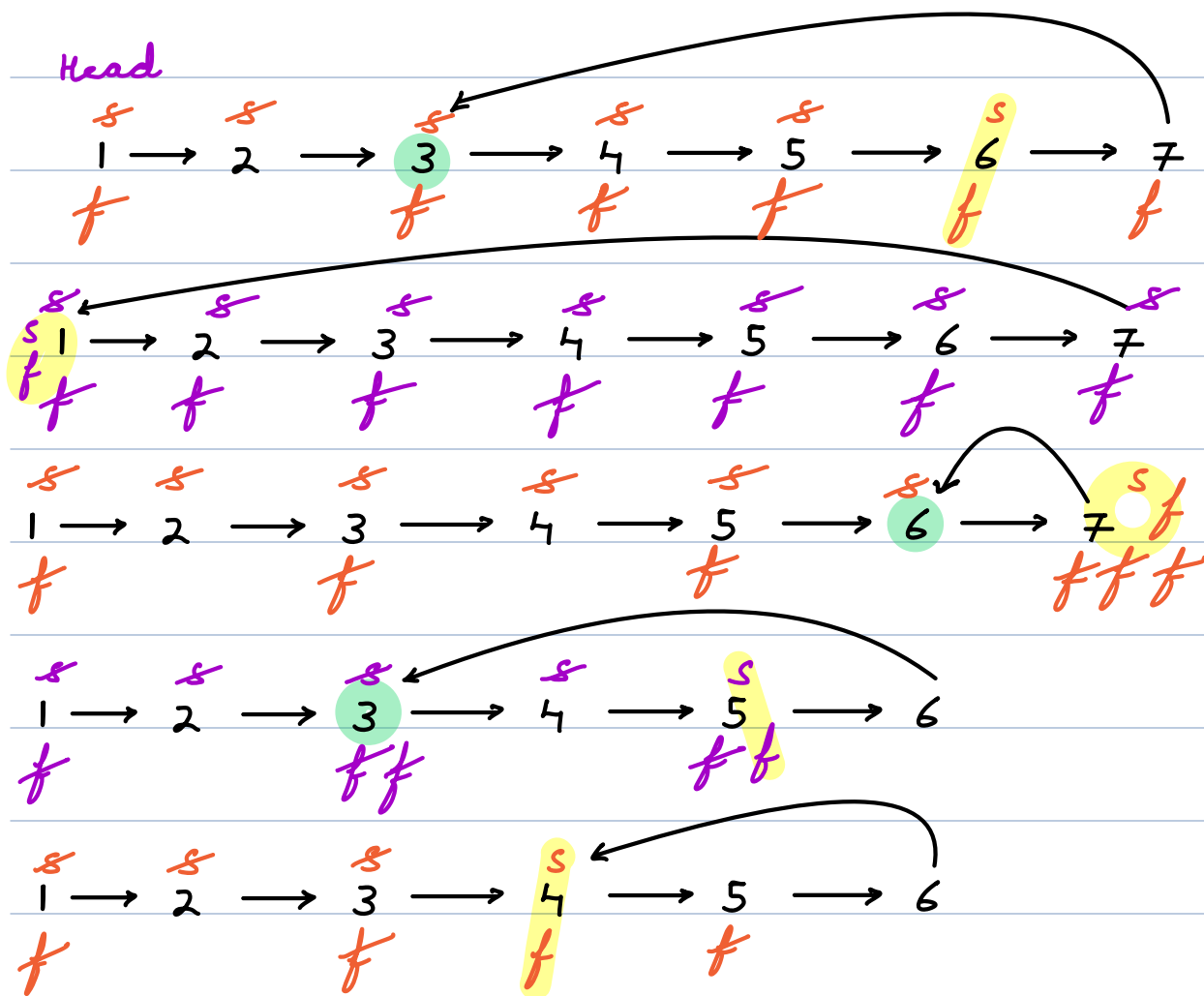
$f = f.next.next$

if (s == f) return true

3

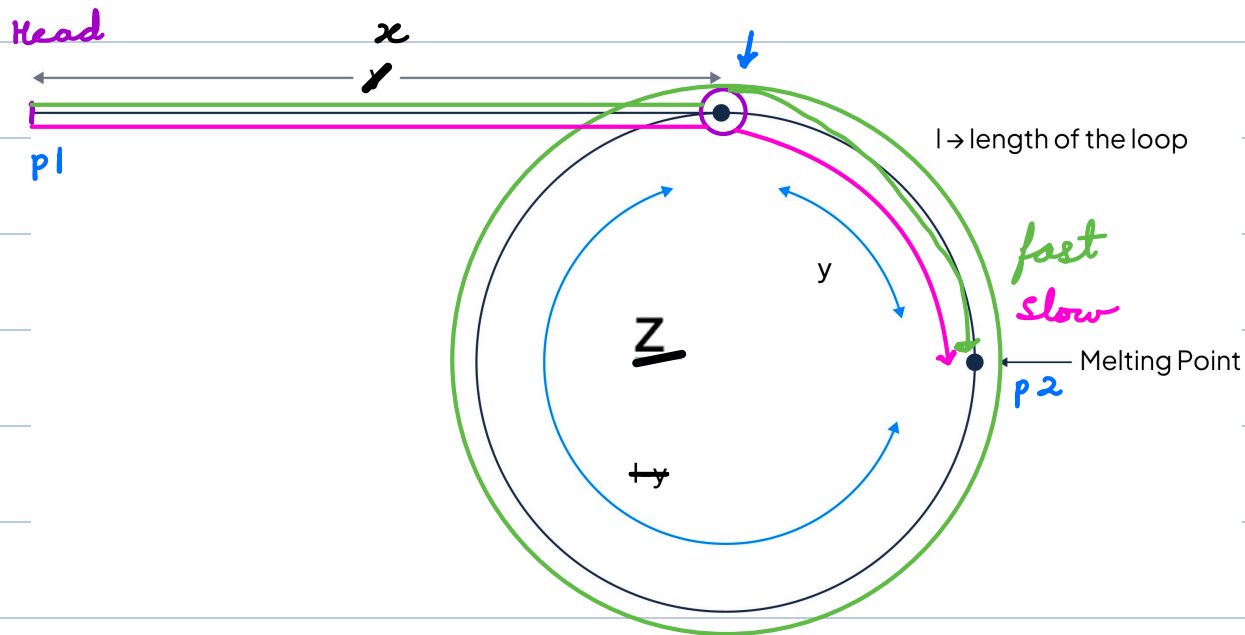
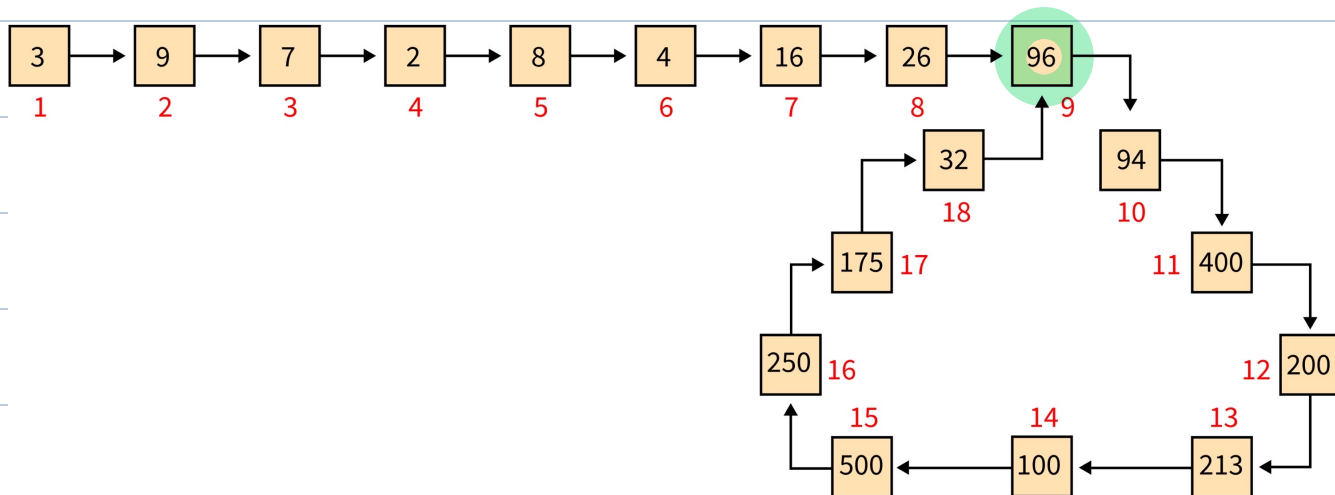
return false

$TC = \underline{O(N)}$ $SC = \underline{O(1)}$





★ Find the start point of the loop



Distance

$$\text{slow} = x + y$$

$$\text{fast} = x + y + z + y$$

Fast is all double speed \Rightarrow

$$x + y + z + y = 2 * (x + y)$$

$$\cancel{x + y} + z + \cancel{y} = \cancel{x + y} + x + y$$

$$\Rightarrow \boxed{z = x}$$



X

```
if (Head == null) return false
s = f = Head
while (f != null && f.next != null) {
    s = s.next
    f = f.next.next
    if (s == f) break
}
```

```
p1 = Head
p2 = s
while (p1 != p2) {
    p1 = p1.next
    p2 = p2.next
}
```

```
return p1
```

$TC = O(N)$ $SC = O(1)$
