

△ Ideas in proof of Jordan normal form,

$$T: V \rightarrow V \quad \underline{T} \text{ is nilpotent. Goal } \underline{g} \sim \begin{pmatrix} J_{0, m_1} & & \\ & \ddots & \\ & & J_{0, m_r} \end{pmatrix}$$

$$V^{(j)} = \ker(T^j) = \{ \vec{v} \mid g^j \vec{v} = 0 \}$$

$$V = V^{(n)} \supset V^{(n-1)} \supset V^{(n-2)} \supset \dots \supset V^{(1)} = V^{(0)} = \{0\}$$

$$d_j = \dim V^{(j)}$$

$$U^{(j)} = V^{(j)} / V^{(j-1)}$$

$$c_j = \dim U^{(j)} = \dim V^{(j)} - \dim V^{(j-1)} = d_j - d_{j-1}$$

△ Idea 1: $\{ \overleftarrow{T^{j-1}v}, \overleftarrow{T^{j-2}v}, \dots, \overleftarrow{Tv}, v \}$ provide good basis

T acts on them like Jordan blocks

Idea 2: Lemma Basis: $W \subset V$ invariant subspace, $U = V/W$

Given basis $\{\bar{e}_i\}$ for U , $\{f_j\}$ for W , pick for any \bar{e}_i $e_i = \bar{e}_i + W$

Then $\{e_i, f_j\}$ is basis for V

If you can give basis for quotient spaces (subspace) give basis for V

Generalise:

$$\begin{array}{ccc} V^{(n)} \supset V^{(n-1)} \supset \dots \supset V^{(1)} \supset V^{(0)} \\ \underbrace{\qquad\qquad\qquad} & \underbrace{\qquad\qquad\qquad} & \underbrace{\qquad\qquad\qquad} \\ U^{(n)} \supset U^{(n-1)} \supset \dots \supset U^{(1)} = V^{(1)} / V^{(0)} \rightarrow \text{subspace} \\ \underbrace{\qquad\qquad\qquad} & \underbrace{\qquad\qquad\qquad} & \underbrace{\qquad\qquad\qquad} \\ \text{quotient spaces} & & \end{array}$$

Lemma Basis: If given basis for each $U^{(j)} \Rightarrow$ get basis for V

$$\text{Check: } \sum \dim U^{(j)} = \dim V$$

$$\text{pf: } \sum c_j = \sum_{j=1}^n (d_j - d_{j-1}) = \underbrace{(d_1 - d_0)}_0 + \underbrace{(d_2 - d_1)}_{\Delta} + \dots + \underbrace{(d_n - d_{n-1})}_{\Delta} = d_n = n$$

$$\begin{aligned} \text{pf: } \sum c_j &= \sum_{j=1}^n (d_j - d_{j-1}) = (d_1 - d_0) + (d_2 - d_1) + \dots + (d_n - d_{n-1}) \\ &= n - 0 = n = \dim V \end{aligned}$$

Idea 3: Lemma 3: Given a set of L.I. vectors $v_1, \dots, v_c \in V^{(j)}$
 but not in $V^{(j-1)}$ s.t. $\{\bar{v}_1, \dots, \bar{v}_c\}$ is L.I.,
 then $\{T^{m-1}v_1, T^{m-2}v_1, \dots, v_1, T^{m-1}v_2, \dots, Tv_2, v_2, \dots\}$
 $= \{T^j v_k\}_{k=1, \dots, c}^{j=0, \dots, m-1}$ is L.I.

Lemma 3', T induces maps $\bar{T}: U^{(i)} \rightarrow U^{(i-1)}$
 Furthermore, \bar{T} is injective: $\begin{cases} \text{sends L.I. vectors to L.I. vectors} \\ \ker \bar{T} = \{0\} \end{cases}$

Sketch of proof: $T: V^{(i)} \rightarrow V^{(i-1)}$

$$\bar{T}: \begin{matrix} U^{(i)} \\ v = v + V^{(i-1)} \end{matrix} \mapsto \begin{matrix} Tv + T(V^{(i-1)}) \\ \uparrow \\ U^{(i-1)} \end{matrix} = \begin{matrix} Tv + \\ \uparrow \\ V^{(i-1)} \end{matrix}$$

The proof for \bar{T} sending L.I. vectors to L.I. vectors
 is similar to our proof for Lemma 3.

Corollary for Lemma 3': $\dim U^{(i)} \leq \dim U^{(i-1)}$ $C_n \leq C_{n-1} \leq \dots \leq C_1$

pf: $\bar{T}: U^{(i)} \rightarrow U^{(i-1)}$

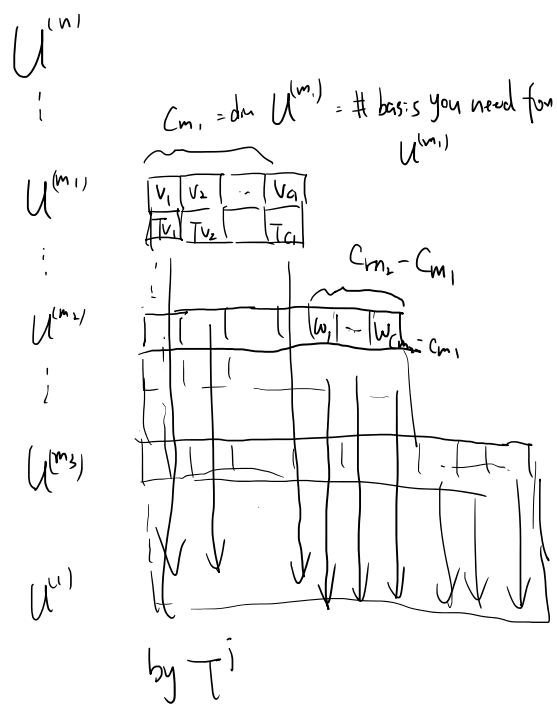
$$\dim U^{(i-1)} \geq \dim \text{Im}(\bar{T}) = \dim U^{(i)} - \underbrace{\dim(\ker(\bar{T}))}_{\substack{\text{injective} \\ = \dim U^{(i)}}} \quad \#$$

idea: basis for $U^{(i)}$ give L.I. vectors for $U^{(i-1)}, U^{(i-2)}, \dots, U^{(1)}$

by applying \overline{T} repeatedly

△ Combine ideas together

Diagram



m_1 is first jump in

$$0 \leq C_n \leq C_{n+1} \quad \dots \quad \dots \leq C_1$$

$$0 = C_{m+1} < C_m$$

m_1 is next jump

$$C_{m_1} = C_{m_{21}} < C_{m_2}$$

pick $v_1 \dots v_{C_{m_1}}$ for $U^{(m_1)}$

Pick additional $w_1, \dots, w_{C_{m_2} - C_{m_1}}$ for $U^{(m)}$

Finitley many Steps

Δ General guide for Jordan form $\left\{ \begin{array}{l} \text{given } g, \text{ find Jordan} \\ \text{find } h, \text{ s.t. } h^{-1}gh \text{ is Jordan} \end{array} \right.$

Step 1: Find char poly $P_g(x)$, all eigenvalues χ_i with multiplicities n_i

Step 2: focus on one eigenvalue λ_i, n_i

$$g_{\lambda_i}^j := (g - \lambda_i I)^j \quad j \leq n_i \quad (g - \lambda_i I \text{ is nilpotent on } V_{\lambda_i})$$

Compute $d_{\lambda,i,j} = \dim \ker (g - \lambda, I)^j$ $\left\{ \begin{array}{l} d_{\lambda,i,j} = n - \text{rank}(g - \lambda, I)^j \\ \text{Find } \{ \vec{v} \mid g_{\lambda,i}^j \vec{v} = 0 \} \end{array} \right.$

Check: $d_{x,n} \geq d_{x,n-1} \geq \dots \geq d_{x,1}$

Check: $d_{\lambda, n} \geq d_{\lambda, n-1} \geq \dots \geq d_{\lambda, 1}$

Step 3: Compute $C_{\lambda, j} = d_{\lambda, j} - d_{\lambda, j-1}$ get $C_{\lambda, n} \leq \dots \leq C_{\lambda, 1}$
 record all jumps in $C_{\lambda, n}, \dots, C_{\lambda, 1}$

For example first jump \downarrow previous ones $0 < C_{\lambda, m_1}$
 record where it jumps m_1 Size of Jordan blocks
 & size of jump C_{λ, m_1} number of Jordan block J_{λ, m_1}
of blocks of same size

2nd jump record \downarrow previous ones $< C_{\lambda, m_2}$
 where it jumps m_2
 size of jump $C_{\lambda, m_2} - C_{\lambda, m_1}$ (C_{m2} - C_{m1}) number of J_{λ, m_2}

Repeat Step 2-3 for each λ_i get Jordan form for g

Step 4: Find vectors $\underline{v_1 \dots v_{C_{m_1}}}, \underline{w_1 \dots w_{C_{m_2} - C_{m_1}}}$ apply g_{λ_i} repeatedly to them

$$\begin{matrix} v_1 \\ g_{\lambda_i} v_1 \\ g_{\lambda_i}^2 v_1 \\ \vdots \\ g_{\lambda_i}^{m_1-1} v_1 \end{matrix}$$

$$\begin{matrix} w_1 \\ \vdots \\ w_{C_{m_2} - C_{m_1}} \end{matrix}$$

$\underline{v_1 \dots v_{C_{m_1}}} \in V^{(m_1)}$, but
 not in $V^{(m_1-1)}$
 as they should give basis in $V^{(m_1)}$
 $g_{\lambda_i}^{m_1} v_i = 0$

Repeat Step 2 - 4 for all λ_i

Step 5: Form matrix h by putting $\{g_{\lambda_i}^j v_k \text{ or } w_k\}$ as column vectors
 h is square matrix $\{g_{\lambda_i}^{j-1} v_k, \dots, g_{\lambda_i} v_k, v_k\}$

$v_{x_1}, \dots, v_{x_k}, v_k$
are put together

(Step 6 optional if you have plenty of time: check $h^{-1}g$ is Jordan)

Example 1:
$$g = \begin{pmatrix} 2 & 1 & 1 \\ -1 & 0 & -1 \\ 0 & 0 & 1 \end{pmatrix}$$

Solution: Step 1
$$p_\lambda(g) = \begin{vmatrix} \lambda-2 & -1 & -1 \\ 1 & \lambda & 1 \\ 0 & 0 & \lambda-1 \end{vmatrix} = (\lambda-1) \begin{vmatrix} \lambda-2 & -1 \\ 1 & \lambda \end{vmatrix} = (\lambda-1)^3$$

Single eigenvalue $\lambda=1$ multiplicity 3

Step 2:
$$g_\lambda = g - \lambda I = \begin{pmatrix} 1 & 1 & 1 \\ -1 & -1 & -1 \\ 0 & 0 & 0 \end{pmatrix} \quad \text{rk} = 1. \quad V^{(1)} = \left\{ \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} \mid \underline{v_1 + v_2 + v_3 = 0} \right\}$$

$$g_\lambda^2 = 0 \quad \underline{V^{(2)} = V} \quad \underline{g_\lambda^3 = 0} \quad \underline{V^{(3)} = V}$$

$$d_3 = \dim \ker(g_\lambda^3) = 3 \quad d_2 = 3 \quad d_1 = 2$$

Step 3:
$$c_3 = 0 < \underline{c_2 = 1} < c_1 = d_1 - d_0 = 2.$$

2 jumps

First jump happens at $\bar{j}=2$ \Rightarrow 1 Jordan block
jump size 1 $J_{1,2}$

2nd jump at $\bar{j}=1$ \Rightarrow 1 Jordan block
size 1 $J_{1,1}$

$$\Rightarrow g \sim \begin{pmatrix} \boxed{J_{1,2}} & & \\ & J_{1,1} & \\ & & \end{pmatrix} = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Step 4: 1st jump find $v \in V^{(2)}$ but $v \notin V^{(1)}$

(need $\bar{v} \in V^{(2)}/V^{(1)}$ is basis, but it's 1-dim)

just pick $v = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$ Indeed $\in V^{(2)}$ not in $V^{(1)}$

$$g_{\lambda} v = \begin{pmatrix} 1 & 1 & -1 \\ -1 & 1 & -1 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix} \in V^{(1)}$$

$$(g_{\lambda}^2 v = 0)$$

for 2nd jump we need find $w \in \underline{V^{(1)}}$ l.e. from $\underline{v}, g_{\lambda} v$

just pick

$$w = \begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}$$

(other choices $\begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} \dots \begin{pmatrix} 2 \\ -1 \\ -1 \end{pmatrix} \dots$
 $v_1 + v_2 + v_3 = 0$)

Step 5 Putting together:

$$h = (\underline{g_{\lambda} v}, v, w) = \begin{pmatrix} 1 & 1 & 0 \\ -1 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix}$$

Example 2: $g = \begin{pmatrix} 2 & 0 & 0 & 0 \\ 1 & 2 & 0 & 0 \\ 0 & 1 & 2 & 0 \\ 1 & 0 & 1 & 2 \end{pmatrix}$

Step 1. $\lambda = 2$ $n = 4$.

Step 2: $g_{\lambda} = g - \lambda I = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \end{pmatrix}$

$$g_{\lambda}^2 = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix}$$

$$g_{\lambda}^3 = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix}$$

$$g_{\lambda}^4 = 0$$

$$\underline{V^{(4)} = V} \quad \underline{d_4 = 4} \quad \underline{V^{(3)} = \left\{ \begin{pmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{pmatrix} \mid \begin{pmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{pmatrix} = 0 \right\}} = \left\{ \begin{pmatrix} 0 \\ v_2 \\ v_3 \\ v_4 \end{pmatrix} \right\} \quad \underline{d_3 = 3}$$

$$V^{(2)} = \left\{ \vec{v} \mid \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{pmatrix} = 0 \right\} = \left\{ \begin{pmatrix} 0 \\ 0 \\ v_3 \\ v_4 \end{pmatrix} \right\} \quad \underline{d_2 = 2}$$

$$\underline{V^{(1)} = \left\{ \vec{v} \mid \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{pmatrix} = 0 \right\} = \left\{ \begin{pmatrix} 0 \\ 0 \\ 0 \\ v_4 \end{pmatrix} \right\}} \quad \underline{d_1 = 1}$$

Step 3: $\angle C_4 = C_3 = C_2 = C_1 = 1$

$$\sim \lambda: 0 < C_4 = C_3 = C_2 = C_1 = 1$$

only 1 jump at $j=4 \Rightarrow 1$ Jordan block

$$J_{2,4}$$

$$g \sim (J_{2,4}) = \begin{pmatrix} 2 & 1 & & \\ & 2 & 1 & \\ & & 2 & 1 \\ & & & 2 \end{pmatrix}$$

Step 4: Just need to find $v \in V^{(4)}$ not in $V^{(3)}$

$$\text{just pick } v = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

$$g_\lambda v = \begin{pmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 1 \end{pmatrix}$$

$$g_\lambda^2 v = \begin{pmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \\ 0 \end{pmatrix}$$

$$g_\lambda^3 v = \begin{pmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

$$g_\lambda \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix} = 0$$

Step 5: $h = (g_\lambda^3 v, g_\lambda^2 v, g_\lambda v, v) = \begin{pmatrix} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 1 & 0 \end{pmatrix}$

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$$V^{(1)} = \{ g_\lambda \cdot \vec{v} = 0 \} = \left\{ \begin{pmatrix} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & & 1 \end{pmatrix} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{pmatrix} = 0 \right\}$$

$$\Rightarrow \begin{pmatrix} 0 \\ v_1 \\ v_2 \\ v_1 + v_3 \end{pmatrix} = 0$$

$$\Rightarrow \underline{v_1 = 0} \quad v_2 = 0 \quad v_1 + v_3 = 0 \Rightarrow v_3 = 0$$

$$V^{(1)} = \left\{ \begin{pmatrix} 0 \\ 0 \\ 0 \\ v_4 \end{pmatrix} \right\}$$