

△ Review inner product on  $\mathbb{R}^3$

$$\vec{x} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \quad \vec{y} = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} \quad (\vec{x}, \vec{y}) = \vec{x} \cdot \vec{y} = \underline{x_1 y_1 + x_2 y_2 + x_3 y_3}$$

it can be used to describe when  $\vec{x} \perp \vec{y} \Leftrightarrow (\vec{x}, \vec{y}) = 0$

it can give length / distance

$$\|\vec{x}\| = (\vec{x}, \vec{x})^{\frac{1}{2}}$$

properties for  $(,)$

- △ symmetric:  $(\vec{x}, \vec{y}) = (\vec{y}, \vec{x})$
- △ linear in both variables:  $(a_1 \vec{x}_1 + a_2 \vec{x}_2, \vec{y}) = a_1 (\vec{x}_1, \vec{y}) + a_2 (\vec{x}_2, \vec{y})$   
Similar in  $\vec{y}$  position

△ (optional) positive definite:  $(\vec{x}, \vec{x}) \geq 0$

with  $(\vec{x}, \vec{x}) = 0$  iff  $\vec{x} = 0$

$$(\vec{x} + \vec{z}) \cdot \vec{y} = \vec{x} \cdot \vec{y} + \vec{z} \cdot \vec{y}$$

linear in  $\vec{x}$   $(\vec{x} + \vec{z}, \vec{y}) = \left( \begin{pmatrix} x_1 + z_1 \\ x_2 + z_2 \end{pmatrix}, \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} \right)$

$$\begin{aligned} \mathbb{R}^2, (\vec{x}, \vec{y}) &= x_1 y_1 + x_2 y_2 = (x_1 + z_1) \cdot y_1 + (x_2 + z_2) y_2 \\ \vec{x}, \vec{y}, \vec{z} &= \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}, \dots, \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} = \underbrace{x_1 y_1 + z_1 y_1}_{(\vec{x}, \vec{y})} + \underbrace{x_2 y_2 + z_2 y_2}_{(\vec{z}, \vec{y})} \\ &= (\vec{x}, \vec{y}) + (\vec{z}, \vec{y}) \end{aligned}$$

△ Review: transpose of a matrix,  $\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}^T = \begin{pmatrix} 1 & 3 \\ 2 & 4 \end{pmatrix}$

~~$$(x_1 \dots x_n)^T = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$$~~

$$\begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}^T = (x_1 \dots x_n)$$

~~$$\begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix}$$~~

$$g = (g_{ij})_{ij}$$

$$g^T = (g_{ji})_{ji}$$

← i-row j-col element of  $g^T$  is  $\underline{g_{ji}}$

Let:  $(AB)^T = B^T \cdot A^T$

$$\begin{aligned} \left( (1, 2) \begin{pmatrix} 3 \\ 4 \end{pmatrix} \right)^T &= \begin{pmatrix} 3 \\ 4 \end{pmatrix}^T \cdot (1, 2)^T \\ &= \begin{pmatrix} 3 & 4 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 2 \end{pmatrix} \\ &= 1 \cdot 3 + 2 \cdot 4 = 11 \end{aligned}$$

Given  $V/\alpha$

Given  $V/\mathbb{C}$   
 $\Delta$  Definition: A Complex inner product / Hermitian form is a map

$$\langle \cdot, \cdot \rangle : V \times V \rightarrow \mathbb{C}$$

$$v_1, v_2 \mapsto \langle v_1, v_2 \rangle$$

Strong Chap 9

Satisfying following properties

$$\textcircled{1} \text{ Conjugate symmetric : } \langle v_1, v_2 \rangle = \overline{\langle v_2, v_1 \rangle}$$

$$\textcircled{2} \text{ Sesquilinear : linear in 2nd component } \langle v_1, a_1 x_1 + a_2 x_2 \rangle = a_1 \langle v_1, x_1 \rangle + a_2 \langle v_1, x_2 \rangle$$

$$a_i, a_j \in \mathbb{C}$$

Conjugate linear  
in 1st component

$$\langle a_1 v_1 + a_2 v_2, x \rangle = \overline{a_1} \langle v_1, x \rangle + \overline{a_2} \langle v_2, x \rangle$$

$$\textcircled{3} \text{ (optional) positive definite Hermitian form, } \langle v, v \rangle \geq 0 \text{ is a real number}$$

$$\langle v, v \rangle = 0 \text{ iff } v = 0$$

Example:  $V = \mathbb{C}$   $\|z\| = (\bar{z} \cdot z)^{\frac{1}{2}}$   $\langle z_1, z_2 \rangle = \bar{z}_1 \cdot z_2$

Standard Hermitian form:  $V = \mathbb{C}^n$

$$\vec{x} = (x_1, \dots, x_n)^T \quad \vec{y} = (y_1, \dots, y_n)^T$$

$$\langle \vec{x}, \vec{y} \rangle = \sum_i \bar{x}_i \cdot y_i$$

$$\text{Check: } \langle \vec{y}, \vec{x} \rangle = \sum_i \bar{y}_i \cdot x_i = \overline{\left( \sum_i \bar{x}_i y_i \right)} = \overline{\langle \vec{x}, \vec{y} \rangle}$$

$$\langle \vec{x}, a \vec{y} \rangle = \sum_i \bar{x}_i \cdot (a y_i) = a \left( \sum_i \bar{x}_i y_i \right)$$

$$\langle a \vec{x}, \vec{y} \rangle = \sum_i \overline{(a x_i)} \cdot y_i = \overline{a} \left( \sum_i \bar{x}_i y_i \right)$$

$$\text{Check } \langle \vec{x}, \vec{x} \rangle = \sum_i \underbrace{\bar{x}_i \cdot x_i}_{\geq 0} \geq 0 \text{ with } = 0 \text{ iff } x_i = 0 \forall i$$

$\Delta$  Fix a basis  $B_v = \{e_1, \dots, e_n\}$ , then Hermitian form can be described

in terms of matrix  $H = (\langle e_i, e_j \rangle)_{ij}$

As  $B_v$  is basis  $v = \sum_i a_i e_i$   $\vec{w} = \sum_j b_j e_j$

$$\langle v, w \rangle \stackrel{\text{sesquilinearity}}{=} \sum_{i,j} \bar{a}_i b_j \langle e_i, e_j \rangle = \begin{pmatrix} \bar{a}_1 & \dots & \bar{a}_n \end{pmatrix} H \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix}$$

$$\text{RHS} = \begin{pmatrix} \bar{a}_1 & \dots & \bar{a}_n \end{pmatrix} H \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix} = \sum_i \left( \sum_j \bar{a}_j \langle e_j, e_i \rangle \right) b_i$$

$$\text{RHS} = \underbrace{\left( \overline{(a_1 \dots a_n)} H \right)}_{j\text{-column of it} = \sum \bar{a}_i \langle e_i, e_j \rangle} \cdot \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix} = \sum_i \left( \sum_j \bar{a}_i \langle e_i, e_j \rangle \right) b_j$$

$$\Delta \text{ Lemma: } v = (e_1 \dots e_n) \begin{pmatrix} a_1 \\ \vdots \\ a_n \end{pmatrix} \quad w = (e_1 \dots e_n) \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix}$$

$$H = (\langle e_i, e_j \rangle)_{ij} \quad \text{then } \langle v, w \rangle = \overline{(a_1 \dots a_n)} H \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix}$$

$$\Delta \text{ Definition: given } g, \quad g^* = \overline{(g^T)} \quad \left( \begin{pmatrix} a_1 \\ \vdots \\ a_n \end{pmatrix} \right)^*$$

$$\text{Lemma: } H^* = H$$

$$\text{pf: by def, } \underline{(H^*)_{ij}} = \underline{(\overline{H^T})_{ij}} = \overline{(H^T)_{ji}} = \overline{(H)_{ji}}$$

$$= \langle e_j, e_i \rangle = \langle e_i, e_j \rangle = \underline{(H)_{ij}} \Rightarrow H^* = H \quad \#$$

$\Delta$  Def alternatively: Hermitian matrix is any  $H$  st.  $H^* = H$

Hermitian form  $\xleftrightarrow{\text{basis}}$  Hermitian matrix

$$\Delta \text{ Def: } v_1 \perp v_2 \text{ iff } \langle v_1, v_2 \rangle = 0 \text{ iff } \langle v_2, v_1 \rangle = 0$$

$$\text{Def: ONB} = \boxed{\text{Orthonormal basis}} \text{ for } \langle, \rangle \text{ is } \{e_1, \dots, e_n\} \text{ s.t.}$$

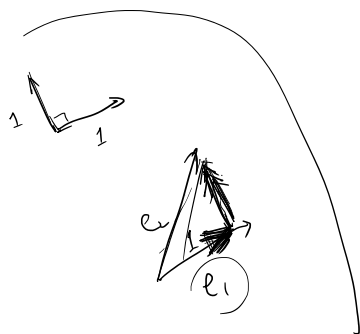
$$\langle e_i, e_i \rangle = 1 \quad \langle e_i, e_j \rangle = 0 \text{ if } i \neq j$$

$$\langle e_i, e_j \rangle = \delta_{ij} = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{otherwise (} i \neq j \text{)} \end{cases}$$

$\Delta$  Lem: ONB always exists of positive definite Hermitian forms.

Pf: Gram-Schmidt algorithm:

Given any basis  $\{e_1, \dots, e_n\} \rightarrow \text{ONB}$



Step 1:  $e_1^0 = \frac{e_1}{\langle e_1, e_1 \rangle^{\frac{1}{2}}}$   $\langle e_1^0, e_1^0 \rangle = \frac{1}{\langle e_1, e_1 \rangle} \langle e_1, e_1 \rangle = 1$

Step 2:  $e_2' = e_2 - \overline{\langle e_2, e_1^0 \rangle} e_1^0$

Claim:  $e_2' \perp e_1^0$  indeed  $\langle e_2', e_1^0 \rangle$

$= \langle e_2, e_1^0 \rangle - \langle e_2, e_1^0 \rangle \underbrace{\langle e_1^0, e_1^0 \rangle}_{=1} = 0$

$e_2^0 = \frac{e_2'}{\langle e_2', e_2' \rangle^{\frac{1}{2}}}$

Step 3:  $e_3' = e_3 - \overline{\langle e_3, e_1^0 \rangle} e_1^0 - \overline{\langle e_3, e_2^0 \rangle} e_2^0$

$e_3^0 = \frac{e_3'}{\langle e_3', e_3' \rangle^{\frac{1}{2}}}$

Finish in finite steps #

$\Delta$  Change basis:  $(e_1, \dots, e_n) \quad \langle, \rangle \rightarrow H = (\langle e_i, e_j \rangle)_{ij}$

new basis  $(\underline{f_1, \dots, f_n}) = (\underline{e_1, \dots, e_n}) h \rightarrow H' = (\langle f_i, f_j \rangle)_{ij}$

Lem:  $H' = h^* \cdot H \cdot h$   $f_i = \sum_k \underline{e_k h_{ki}}$   $f_j = \sum_l e_l h_{lj}$

Pf (Sketch):  $(H')_{ij} = (\underline{h^* H h})_{ij}$

LHS:  $\langle f_i, f_j \rangle = \sum_k \sum_l \overline{h_{ki}} h_{lj} \langle e_k, e_l \rangle$   
= RHS

$\Delta$  Fix the standard Hermitian form  $\langle, \rangle$

Def: a unitary matrix  $g$ , is such that  $g^* \cdot g = I$

Lemma:  $g$  is a unitary matrix iff  $\langle v, w \rangle = \langle gv, gw \rangle$   
for any  $v, w \in V$

Pf: For the standard  $\langle, \rangle$  and standard basis  $(e_1, \dots, e_n)$

on ONB

$H$  associated to then if  $(\langle e_i, e_j \rangle)_{i,j} = (S_{ij}) = I$

Previous lemma  $\Rightarrow \langle v, w \rangle = H \cdot \vec{w} = \vec{v}^* \cdot \vec{w}$

$$\langle g v, g w \rangle = (g \vec{v})^* \cdot (g \vec{w}) = \vec{v}^* \cdot g^* \cdot g \cdot \vec{w}$$

$$(g \vec{v})^* = \overline{(g \vec{v})^T} = \vec{v}^T \cdot g^T$$

$$\langle g v, g w \rangle = \langle v, w \rangle \quad \text{iff} \quad \vec{v}^* g^* g \vec{w} = \vec{v}^* \cdot \vec{w} \quad \forall v, w$$

$$\text{iff} \quad g^* g = I$$

$\Delta$  Example  $g = \begin{pmatrix} e^{i\theta_1} & \\ & e^{i\theta_2} \end{pmatrix}$  is unitary as  $g^* = \begin{pmatrix} e^{-i\theta_1} & \\ & e^{-i\theta_2} \end{pmatrix}$

$$= \begin{pmatrix} \cos \theta_1 + i \sin \theta_1 & \\ & \cos \theta_2 + i \sin \theta_2 \end{pmatrix}^* \rightarrow \begin{pmatrix} \cos \theta_1 - i \sin \theta_1 & \\ & \cos \theta_2 - i \sin \theta_2 \end{pmatrix}$$

$\Delta$  Corollary:  $\{e_1, \dots, e_n\}$  is ONB for  $\langle \cdot, \cdot \rangle$ , and  $g$  is unitary  
then  $\{g e_1, \dots, g e_n\}$  is still ONB

$\Delta$  Thm. Fix standard  $\langle \cdot, \cdot \rangle$ , given an Hermitian matrix  $H$

①.  $\exists$  Unitary  $h$ , s.t.  $h^* H h$  is diagonal

with diagonal entries being real numbers  $\left( \begin{pmatrix} a_1 \\ \vdots \\ a_n \end{pmatrix} \right)^* = \begin{pmatrix} a_1 & \dots & a_n \end{pmatrix}$

rephrasing ②  $\exists$  another ONB  $\{f_1, \dots, f_n\}$  s.t.

$f_i$  are eigenvectors for  $H$

$\overline{a_i} = a_i \Rightarrow \text{real \#}$   
"x+iy"

Δ Definition: For any subspace  $W \subset V$ ,  $V$  with  $\langle, \rangle$   
define  $W^\perp = \{v \in V \mid \langle v, w \rangle = 0 \ \forall w \in W\}$