9. Threads

- Applications
- Principles
- Programmer Interface
- Threads and Signals
- Example
- Threads and Mutual Exclusion

Lightweight Shared Memory Concurrency

Motivations

- Finer-grain concurrency than processes
  - Reduce cost of process creation and context switch
  - $\approx$ lightweight processes
- Implement shared-memory parallel applications
  - Take advantage of cache-coherent parallel processing hardware

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Multi-Threaded Applications

Thread-Level Concurrency

- Many algorithms can be expressed more naturally with independent computation flows
- Reactive and interactive systems: safety critical controller, graphical user interface, web server, etc.
- Client-server applications, increase modularity of large applications without communication overhead
- Distributed component engineering (CORBA, DCOM), remote method invocation, etc.

Multi-Threaded Applications

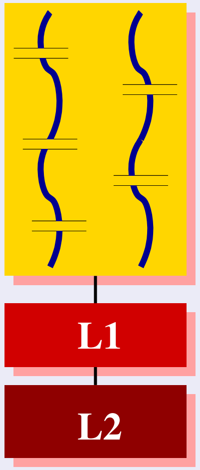
Thread-Level Parallelism

- Tolerate latency (I/O or memory), e.g., creating more logical threads than hardware threads
- Scalable usage of hardware resources, beyond instruction-level and vector parallelism
- Originate in server (database, web server, etc.) and computational (numerical simulation, signal processing, etc.) applications
- Now ubiquitous on multicore systems: Moore's law translates into performance improvements through thread-level parallelism only

Cache-Coherent Shared-Memory Architectures

Simultaneous Multi-Threaded (SMT)

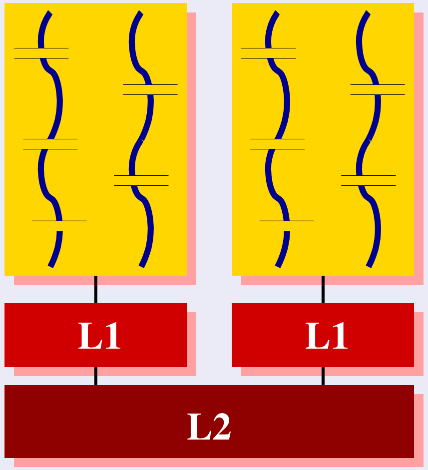
- A.k.a. hyper-threaded (Intel)



Cache-Coherent Shared-Memory Architectures

Chip Multi-Processor (CMP)

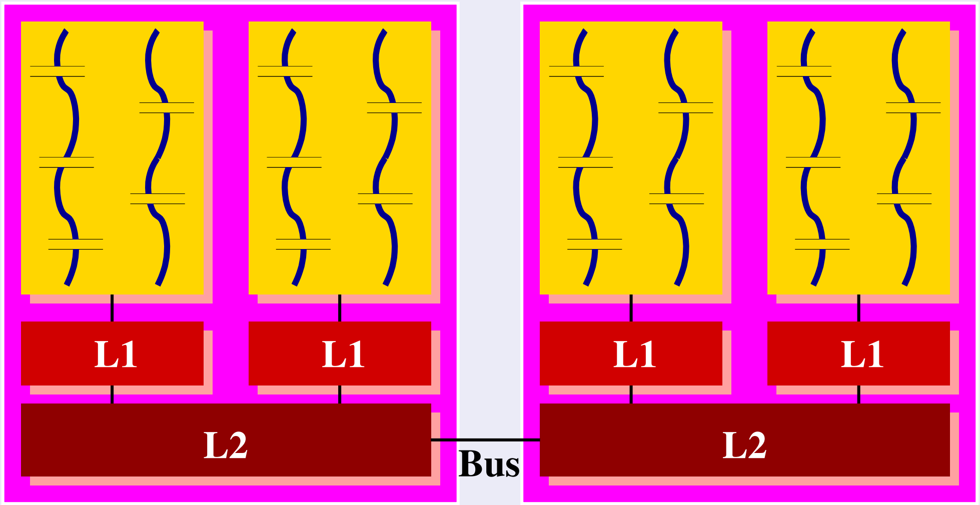
- A.k.a. multicore (Intel)



Cache-Coherent Shared-Memory Architectures

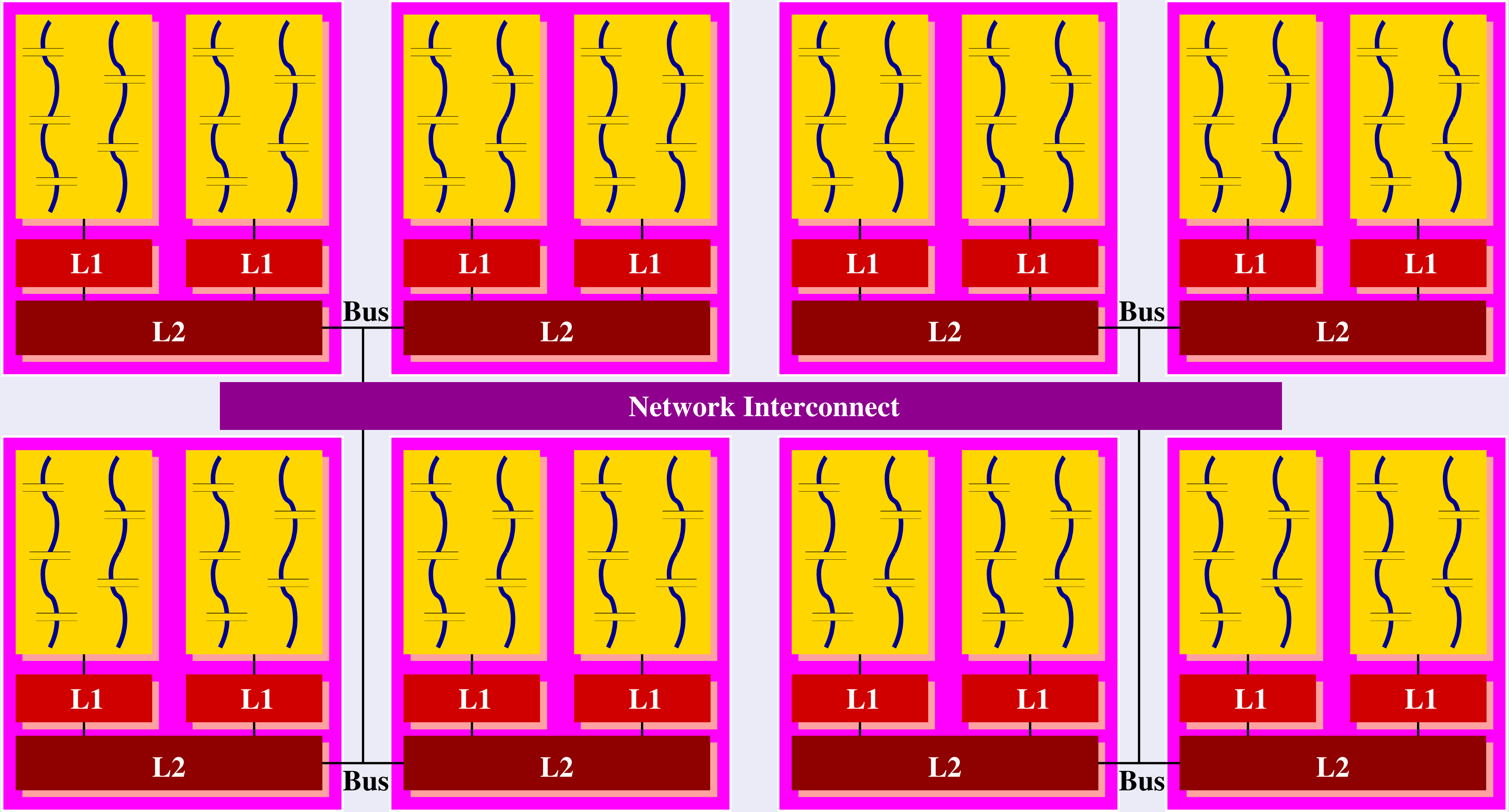
Symmetric Multi-Processor (SMP)

- Multiple chips interconnected with a bus



Cache-Coherent Shared-Memory Architectures

Non-Uniform Memory Architecture (NUMA)



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Principles

Thread-Level Concurrency and Parallelism

- A single process may contain multiple *control threads*, a.k.a. *logical threads*, or simply, *threads*
  - Share a *single memory space*
    - Code, static data, heap
  - Distinct, *separate stack*
- Impact on operating system
  - Schedule control threads and processes
  - Map control threads to hardware threads
  - Programmer interface compatibility with single-threaded processes
- `$ man 7 pthreads`

Threads vs. Processes

Shared Attributes

- PID, PPID, PGID, SID, UID, GID
- Current and root directories, controlling terminal, open file descriptors, record locks, file creation mask (`umask`)
- Timers, signal settings, priority (`nice`), resource limits and usage

Threads vs. Processes

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Distinct Attributes

- Thread identifier: `pthread_t` data type
- Signal mask (`pthread_sigmask()`)
- `errno` variable
- Scheduling policy and real-time priority
- CPU affinity (NUMA machines)
- Capabilities (Linux only, `$ man 7 capabilities`)

Threads vs. Processes

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To use POSIX threads, compile with `-pthread`

Thread-Local Storage

Thread-Specific Data (TSD)

- *Private memory* area associated with each thread
- Some global variables need to be private
  - Example: `errno`
  - More examples: OpenMP programming language extensions
  - General compilation method: *privatization*
- Implementation: `pthread_key_create()`

Finalization Functions

- Privatization of non-temporary data may require
  - *Copy-in*: broadcast shared value into multiple private variables
  - *Copy-out*: select a private value to update a shared variable upon termination
- Memory management (destructors) for dynamically allocated TSD

9. Threads

System Call: pthread_create()

Create a New Thread

```
#include <pthread.h>

int pthread_create(pthread_t *thread, pthread_attr_t *attr,
                   void *(*start_routine)(void *), void *arg);
```

Semantics

- The new thread calls `start_routine(arg)`
- The `attr` argument corresponds to thread attributes, e.g., it can be *detached* or *joinable*, see `pthread_attr_init()` and `pthread_detach()`
  - If `NULL`, default attributes are used (it is *joinable* (i.e., not *detached*) and has default (i.e., non *real-time*) scheduling policy
- Return **0** on success, or a non-null error condition; stores identifier of the new thread in the location pointed to by the `thread` argument
- Note: `errno` is *not* set

System Call: pthread_exit()

Terminate the Calling Thread

```
#include <pthread.h>

void pthread_exit(void *retval);
```

Semantics

- Terminates execution
  - After calling cleanup handlers; set with pthread_cleanup_push()
  - Then calling finalization functions for thread-specific data, see pthread_key_create()
- The retval argument (an arbitrary pointer) is the return value for the thread; it can be consulted with pthread_join()
- Called implicitely if the thread routine returns
- pthread_exit() never returns

System Call: `pthread_join()`

Wait For Termination of Another Thread

```
#include <pthread.h>

int pthread_join(pthread_t thread, void **thread_return);
```

Semantics

- Suspend execution of the calling thread until `thread` *terminates* or is *canceled*, see `pthread_cancel()`
- If `thread_return` is not null
  - Its value is the pointer returned upon termination of `thread`
  - Or `PTHREAD_CANCELED` if `thread` was canceled
- `thread` must not be *detached*, see `pthread_detach()`
- Thread resources are *not* freed upon termination, only when calling `pthread_join()` of `pthread_detach()`; watch out for memory leaks!
- Return **0** on success, or a non-null error condition
- Note: `errno` is *not* set

9. Threads

Threads and Signals

Sending a Signal to A Particular Thread

→ `pthread_kill()`
Behaves like `kill()`, but *signal actions and handlers are global to the process*

Blocking a Signal in A Particular Thread

→ `pthread_sigmask()`
Behaves like `sigprocmask()`

Suspending A Particular Thread Waiting for Signal Delivery

→ `sigwait()`
Behaves like `sugsuspend()`, suspending thread execution (thread-local) and blocking a set of signals (global to the process).

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Example: Typical Thread Creation/Joining

```
#include <pthread.h>
#include <stdio.h>
#include <stdlib.h>
#include <unistd.h>
#include <string.h>
#include <errno.h>
#include <sys/times.h>

#define NTHREADS 5

void *thread_fun(void *num) {
  int i = *(int *)num;

  printf("Thread %d\n", i);          // Or pthread_self()

  // ...
  // More thread-specific code
  // ...

  pthread_exit(NULL);          // Or simply return NULL
}
```

Example: Typical Thread Creation/Joining

```
pthread_t threads[NTHREADS];

int main(int argc, char *argv[]) {
  pthread_attr_t attr;
  int i, error;
  for (i = 0; i < NTHREADS; i++) {
    pthread_attr_init(&attr);
    int *ii = malloc(sizeof(int)); *ii = i;
    error = pthread_create(&threads[i], &attr, thread_fun, ii);
    if (error != 0) {
      fprintf(stderr, "Error in pthread_create: %s \n", strerror(error));
      exit(1);
    }
  }
  for (i=0; i < NTHREADS; i++) {
    error = pthread_join(threads[i], NULL);
    if (error != 0) {
      fprintf(stderr, "Error in pthread_join: %s \n", strerror(error));
      exit(1);
    }
  }
}
```

9. Threads

System Call: `pthread_mutex_init()`

Initialisation of a mutex

```
#include <pthread.h>
int pthread_mutex_init(pthread_mutex_t *mutex,
                       pthread_mutexattr_t *attr);
```

Semantics

- Perform `mutex` initialization
- The `mutex` variable has to be shared among the threads willing to use the same lock; initialization has to occur exactly one time
  - For re-using an already initialized mutex see `pthread_mutex_destroy`
- The `attr` argument is the mutex type attribute: it can be *fast*, *recursive* or *error checking*; see `pthread_mutexattr_init()`
  - If `NULL`, *fast* is assumed by default
- Return **0** on success, or a non-null error condition
- Initialization can also be performed statically with default attributes by using: `pthread_mutex_t mutex = PTHREAD_MUTEX_INITIALIZER;`

System Call: pthread_mutex_*un*lock()

Acquiring/Releasing a lock

```
#include <pthread.h>
int pthread_mutex_lock(pthread_mutex_t *mutex);
int pthread_mutex_unlock(pthread_mutex_t *mutex);
```

Semantics of pthread_mutex_lock

- Block the execution of the current thread until the lock referenced by mutex becomes available
  - Attemtping to re-lock a mutex after acquiring the lock leads to different behaviour depending on mutex attributes (see previous slide)
- Return **0** on success, or a non-null error condition

Semantics of pthread_mutex_unlock

- Release the lock (if acquired by the current thread)
- The lock is passed to a blocked thread (if any) depending on schedule
- Return **0** on success, or a non-null error condition

System Call: pthread_mutex_*try/timed*lock()

Acquiring a lock without blocking

```
#include <pthread.h>
int pthread_mutex_trylock(pthread_mutex_t * mutex);
int pthread_mutex_timedlock(pthread_mutex_t * mutex,
                            struct timespec * abs_timeout);
```

Semantics of pthread_mutex_trylock

- Try to acquire the lock and return immediately in case of failure
- Return **0** on success, or a non-null error condition

Semantics of pthread_mutex_timedlock

- Block the execution of the current thread until the lock becomes available or until abs_timeout elapses
- Return **0** on success, or a non-null error condition

Read/Write Locks

Principles

- Allow concurrent read and guarantee excluse write
- Similar API to regular mutexes
  - `pthread_rwlock_init()` – Initialize a Read/Write Lock
  - `pthread_rwlock_rdlock()` – Get a Shared Read Lock
  - `pthread_rwlock_wrlock()` – Get an Exclusive Write Lock
  - `pthread_rwlock_unlock()` – Unlock an Exclusive Write or Shared Read Lock
  - `pthread_rwlock_tryrdlock()` – Get a Shared Read Lock with No Wait
  - `pthread_rwlock_trywrlock()` – Get an Exclusive Write Lock with No Wait
  - `pthread_rwlock_timedrdlock()` – Get a Shared Read Lock with Time-out
  - `pthread_rwlock_timedwrlock()` – Get an Exclusive Write Lock with Time-out

Condition Variables

Overview

- Synchronization mechanism
- Block the execution of a thread until a boolean predicate becomes true
- Require dedicated instructions to wait without busy-waiting

Principles

- A mutex is used to test a predicate and according to its value:
  - either the execution continues and the mutex is released
  - or the execution is blocked until a signal (called *condition variable*) is received
- Once the signal is received, the execution is resumed and the predicate is being checked again
- The *same mutex* is used to protect any modifications to the predicate's value and to protect the signal emission
- Mutexes act as a protection to prevent race-condition e.g. a thread going to wait while a signal is send

System Call: `pthread_cond_wait()`

Blocking a thread according to a given condition

```
#include <pthread.h>
int pthread_cond_wait(pthread_cond_t *cond,pthread_mutex_t *mutex);
```

Semantics

- Atomically block the execution of a thread and release the lock hold by `mutex`
- Execution is resumed once the condition variable `cond` is signaled by another thread
- The `mutex` lock is then immediately acquired

- Return **0** on success, or a non-null error condition
- Like mutex variables, condition variables have to be initialized
- `pthread_cond_timedwait()` can also resume the execution after the end of a given timeout

System Call: pthread_cond_*signal/broadcast*()

Signaling or broadcasting a condition

```
#include <pthread.h>

int pthread_cond_broadcast(pthread_cond_t *cond);
int pthread_cond_signal(pthread_cond_t *cond);
```

Semantics

- Signal *one* (pthread_cond_signal) or *every* (pthread_cond_broadcast) threads waiting on the condition variable cond.
- If no thread is waiting, nothing happens. Signal is *lost*.
- Return **0** on success, or a non-null error condition

Example: Typical use of Condition Variables

```
int x, y;
pthread_mutex_t mutex = PTHREAD_MUTEX_INITIALIZER;
pthread_cond_t cond = PTHREAD_COND_INITIALIZER;

void *thread_one(void *param) {
   // ...
   pthread_mutex_lock(&mutex);
   while (x <= y) {
      pthread_cond_wait(&cond, &mutex);
   }
   //  Now we can be sure that x > y
   pthread_mutex_unlock(&mutex);
   //  No more guarantee on the value of x > y
}
void *thread_two(void *param) {
    // ...
    pthread_mutex_lock(&mutex);
    // modification of x and y
    // no need to send a signal if the predicate is false
    if (x > y)
      pthread_cond_broadcast(&cond);
    pthread_mutex_unlock(&mutex);
}
```

pthread Implementation: Futexes

Futexes Overview

- Futex: fast userspace mutex
- *Low level* synchronization primitives used to program *higher-level* locking abstractions
- Appeared recently in the Linux kernel *(since 2.5.7)*
- Rely on:
  - a *shared integer in user space* to synchronize threads
  - two system calls (*kernel space*) to make a thread wait or to wake up a thread
- *Fast:* most of the time only the shared integer is required
- *Difficult to use:* no deadlock protection, subtle correctness and performance issues
- For more informations: read *futexes are tricky* by Ulrich Drepper `http://people.redhat.com/drepper/futex.pdf`