

# HW1. NumPy and Matplotlib

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```
In [ ]: # Library
import numpy as np
import matplotlib.pyplot as plt
```

## 1. (Matrix Arithmetic)

Let consider a matrix  $A$  and a vector  $b$ ,

$$A = \begin{bmatrix} 1 & 1 & -2 \\ 3 & 3 & -5 \\ 3 & 2 & -10 \\ 1 & 1 & -7 \\ -4 & -4 & 11 \end{bmatrix}, b = \begin{bmatrix} 2 \\ 7 \\ 2 \\ -3 \\ -4 \end{bmatrix}$$

### (1) Generate arrays for A matrix and b vector using NumPy library

```
In [ ]: A = np.array([[1, 1, -2],[3, 3, -5],[3, 2, -10], [1,1,-7], [-4,-4,11]])
b = np.array([2, 7, 2, -3, -4])

print('\n','1. A is')
print(A)

print('\n','2. b is')
print(b)

1. A is
[[ 1  1 -2]
 [ 3  3 -5]
 [ 3  2 -10]
 [ 1  1 -7]
 [-4 -4 11]]

2. b is
[ 2  7  2 -3 -4]
```

### (2) Transpose A and apply matrix multiplication with the original matrix( $A^T A$ )

```
In [ ]: transA = A.T
print('\n','1. Transpose A is')
print(transA)

ATA = np.dot(transA,A)
print('\n','2. Trans(A) * A is')
print(ATA)

1. Transpose A is
[[ 1  3  3  1 -4]
 [ 1  3  2  1 -4]
 [-2 -5 -10 -7 11]]

2. Trans(A) * A is
[[ 36 33 -98]
 [ 33 31 -88]
 [-98 -88 299]]
```

### (3) Calculate x as the solution of $A^T A x = A^T b$

$$x = (A^T A)^{-1} A^T b$$

```
In [ ]: ATAinv = np.linalg.inv(ATA)
print('\n','1. inverse(trans(A)*A) is')
print(ATAinv)

B = np.dot(transA,b)
print('\n','2. trans(A)*b is')
print(B)

x = np.dot(ATAinv,B)
print('\n','3. the solution x is')
print(x)

1. inverse(trans(A)*A) is
[[ 2.03604806 -1.65954606  0.17890521]
 [-1.65954606  1.54873164 -0.08811749]
 [ 0.17890521 -0.08811749  0.03604806]]

2. trans(A)*b is
[ 42  40 -82]

3. the solution x is
[ 4.46194927 -0.52603471  1.03337784]
```

### (4) Calculate the norm of $Ax - b$ with line-by-line coding and using NumPy library.

Let  $\tilde{X} = Ax - b$ ,

$$L_p = (\sum_i^n |X(i)|^p)^{1/p}$$

```
In [ ]: print('\n 1. Line-by-Line coding')
diff_mat = np.dot(x, A) - b
print(' (1) Ax - b is')
print( diff_mat)

# L1 norm
norm1 = sum(abs(diff_mat))
print('\n (2)-1. 1-norm :', norm1)

# L2 norm
normsq = np.dot(diff_mat, diff_mat)
print(' (2)-2. (Ax - b)*(Ax - b) = ', normsq)
norm2 = np.sqrt(normsq)
print(' (2)-norm :', norm2)

# infinity-norm
norminf = abs(max(diff_mat))
print(' (2)-3. infinity-norm :', norminf)

# Using Numpy Library
print('\n 2. Using numpy norm')
norm1 = np.linalg.norm(diff_mat,1)
norm2 = np.linalg.norm(diff_mat,2)
norminf = np.linalg.norm(diff_mat,np.inf)

print(' (1) 1-norm is',norm1_)
print(' (2) 2-norm is',norm2_)
print(' (3) infinity-norm is',norminf)

1. Line-by-Line coding
(1) Ax - b is
[-1.30841121e-01 -3.59145527e-01  3.55271368e-14 -2.97730307e-01
 -3.76502003e-01]

(2)-1. 1-norm : 1.16421895861152
(2)-2. (Ax - b)*(Ax - b) =  0.37650200267022654
      2-norm : 0.6135975901763521
(2)-3. infinity-norm : 3.552713678800501e-14

2. Using numpy norm
(1) 1-norm is 1.16421895861152
(2) 2-norm is 0.6135975901763521
(3) infinity-norm is 3.552713678800501e-14
```

## 2. (Drawing Graps)

A two-dimensional Ackley function,  $f(x, y)$ , has many local minima and one global minimum in the domain,  $(x, y) \in [-4, 4] \times [-4, 4]$ .

$$f(x, y) = -a \exp \left( -b \sqrt{0.5(x^2 + y^2)} \right) - \exp (0.5(\cos(cx) + \cos(cy))) + a + \exp(1)$$

where  $a = 20, b = 0.2$ , and  $c = 2\pi$ .

### (1) Plot a 2D contour of the Ackley function on $(x, y) \in [-4, 4] \times [-4, 4]$ .

```
In [ ]: # Setting the function
def Ackley(x, y):
    a = 20
    b = 0.2
    c = 2*np.pi
    f1 = -a * np.exp(-b * np.sqrt(0.5 * (x**2 + y**2)))
    f2 = np.exp(0.5 * np.cos(c*x) + np.cos(c*y))
    f = f1 - f2 + a + np.exp(1)
    return f

In [ ]: lb = -4
ub = 4
N = 1001

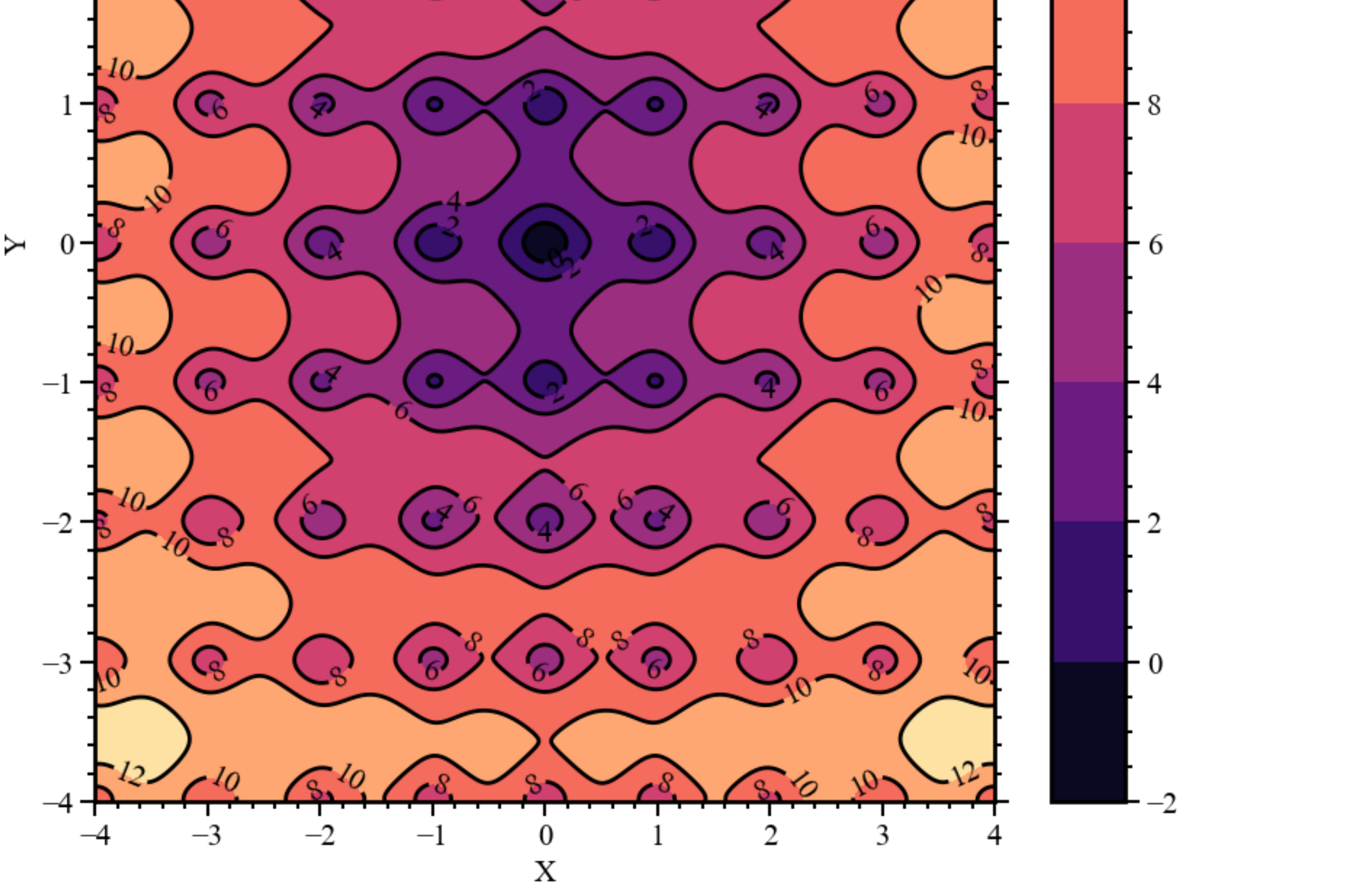
x = np.linspace(lb,ub,N)
y = np.linspace(lb,ub,N)
X, Y = np.meshgrid(x, y)
Z = Ackley(X, Y)

In [ ]: # Set plot params
plt.rcParams['figure.figsize'] = [10,10]
plt.rcParams['font.size'] = 15
plt.rcParams['font.family'] = 'Times New Roman'
plt.rcParams['axes.linewidth'] = 2
plt.rcParams['lines.linewidth'] = 2
plt.rcParams['xtick.direction'] = 'out'
plt.rcParams['ytick.direction'] = 'out'
plt.rcParams['xtick.minor.visible'] = True
plt.rcParams['ytick.minor.visible'] = True
plt.rcParams['xtick.major.size'] = 7
plt.rcParams['ytick.major.size'] = 7
plt.rcParams['xtick.minor.size'] = 3.5
plt.rcParams['ytick.minor.size'] = 3.5
plt.rcParams['xtick.major.width'] = 1.5
plt.rcParams['ytick.major.width'] = 1.5
plt.rcParams['xtick.minor.width'] = 1.5
plt.rcParams['ytick.minor.width'] = 1.5
plt.rcParams['xtick.top'] = True
plt.rcParams['ytick.right'] = True

In [ ]: from mpl_toolkits.axes_grid1 import make_axes_locatable

fig = plt.figure()
cont = plt.contourf(X,Y,Z, cmap='magma')
plt.xlabel('X')
plt.ylabel('Y')
cs=plt.contour(X,Y,Z,colors='k')
# 등고선 표현
plt.clabel(cs)
plt.title('2D contour of the Ackley function')
fig.colorbar(cont, shrink=1, aspect=15)

Out [ ]: <matplotlib.colorbar.Colorbar at 0x7f9ba5656d10>
```

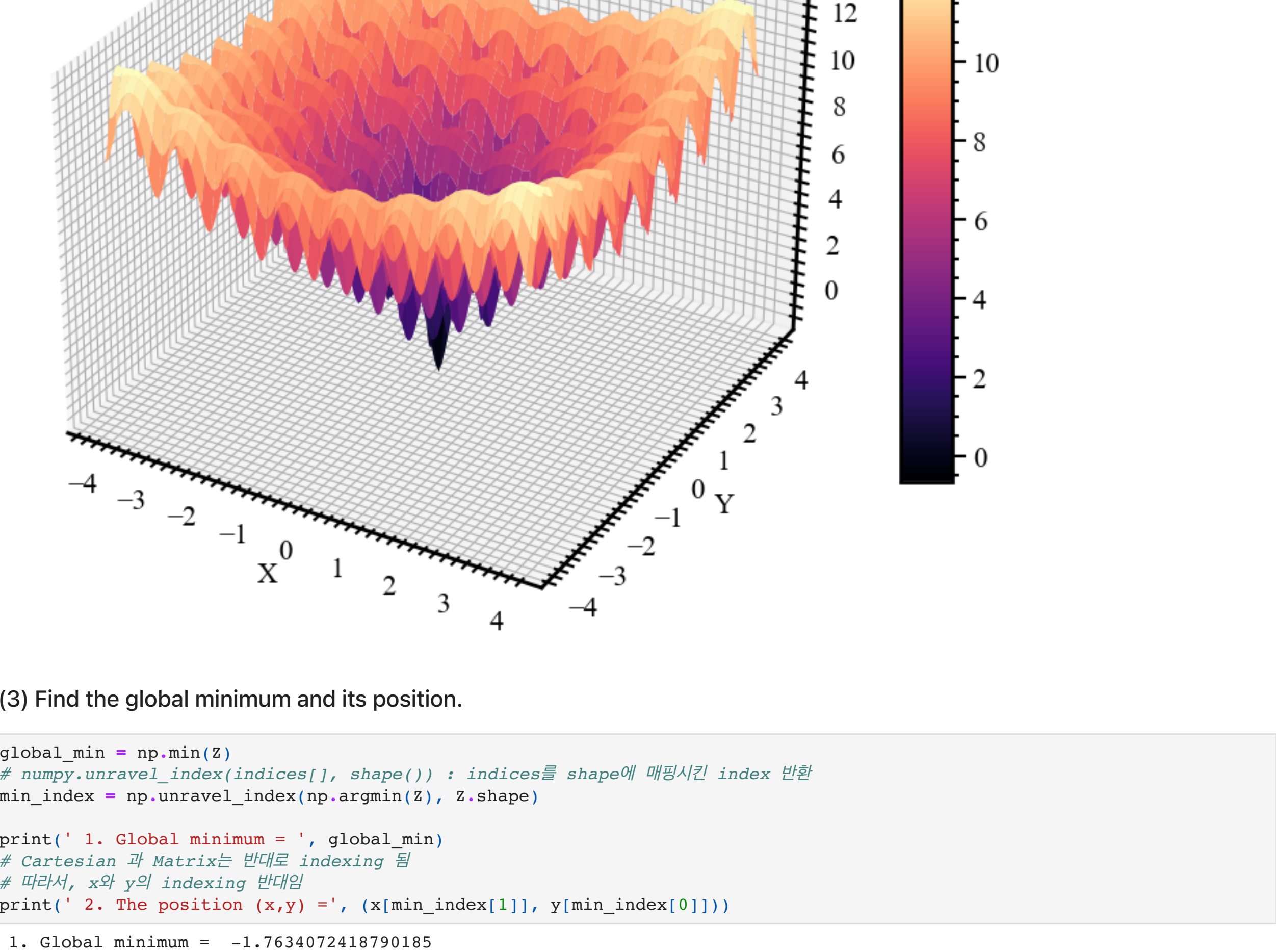


### (2) Plot a 3D graph of the Ackley function on $(x, y) \in [-4, 4] \times [-4, 4]$ .

```
In [ ]: from mpl_toolkits.mplot3d import Axes3D

fig= plt.figure()
ax=fig.add_subplot(111, projection='3d')
surf=ax.plot_surface(X,Y,Z, cmap='magma')
plt.xlabel('X')
plt.ylabel('Y')
plt.title('3D graph of the Ackley function')
fig.colorbar(surf, shrink=0.5, aspect=10)

Out [ ]: <matplotlib.colorbar.Colorbar at 0x7f9ba5713c90>
```



### (3) Find the global minimum and its position.

```
In [ ]: global_min = np.min(Z)
# numpy.unravel_index(indices[], shape()) : indices를 shape에 매핑시킨 index 반환
min_index = np.unravel_index(np.argmax(Z), Z.shape)

print(' 1. Global minimum = ', global_min)
# Cartesian 좌 Matrix는 반대로 indexing 됨
# 따라서, x와 y의 indexing 반대임
print(' 2. The position (x,y) =', (x[min_index[1]], y[min_index[0]]))

1. Global minimum = -1.7634072418790185
2. The position (x,y) = (0.0, 0.0)

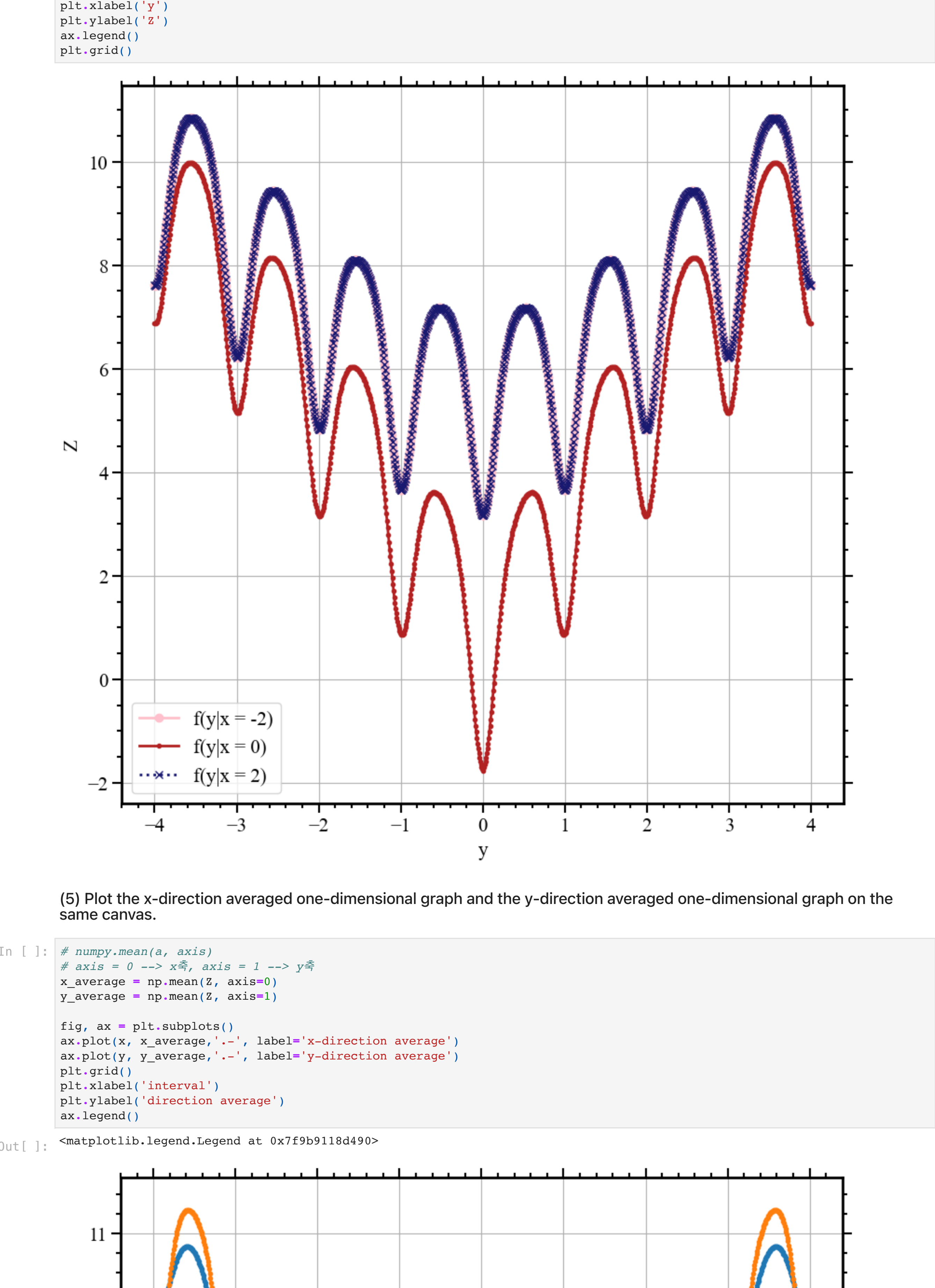
In [ ]: # Additional 실험
""" if n = 1000이라면, (0,0)을 찍지 못해서 min이 다르게 구해진 ""
lb_add = -4
ub_add = 4
N_add = 1000

x_add = np.linspace(lb,ub,N_add)
y_add = np.linspace(lb,ub,N_add)
X_add, Y_add = np.meshgrid(x_add, y_add)
Z_add = Ackley(X_add, Y_add)

global_min_add = np.min(Z_add)
# numpy.unravel_index(indices[], shape()) : indices를 shape에 매핑시킨 index 반환
min_index_add = np.unravel_index(np.argmax(Z_add), Z_add.shape)
print('\n Additional Experiment')
# Cartesian 좌 Matrix는 반대로 indexing 됨
# 따라서, x와 y의 indexing 반대임
print(' add2. The position (x,y) =', (x[min_index_add[1]], y[min_index_add[0]]))

Additional Experiment
add1. Global minimum = -1.7452708413626357
add2. The position (x,y) = (-0.008000000000000007, -0.008000000000000007)
```

### (4) Plot a graph for $f(y|x = -2), f(y|x = 0)$ , and $f(y|x = 2)$ in one plot with legends.



### (5) Plot the x-direction averaged one-dimensional graph and the y-direction averaged one-dimensional graph on the same canvas.

