

# Reinforcement Learning Seminar

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## SEIAR Optimal control

- ▶ Goal1 : DQN
- ▶ Goal2 : PPO

## Mathematical models

- The influenza model : SEIAR model
- J.Kim et.al., *Constrained optimal control applied to vaccination for influenza*, 2016

$$S'(t) = -\beta S(t)\Lambda(t) - \psi\nu(t)S(t)$$

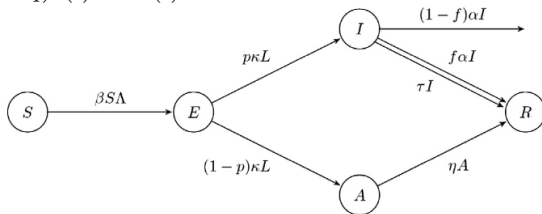
$$E'(t) = \beta S(t)\Lambda(t) - \kappa E(t)$$

$$I'(t) = p\kappa E(t) - \alpha I(t) - \tau I(t)$$

$$A'(t) = (1 - p)\kappa E(t) - \eta A(t)$$

$$R'(t) = f\alpha I(t) + \tau I(t) + \eta A(t) + \psi\nu(t)S(t)$$

with  $\Lambda(t) = \epsilon E(t) + (1 - q)I(t) + \delta A(t)$



**Fig. 1.** Flow chart for the SEIAR model.

## SEIAR model parameters

Parameter	Description	value
$\epsilon$	Infectivity reduction factor for the exposed	0
$q$	Contact reduction by isolation	0.5
$\delta$	Infectivity reduction factor for the asymptomatic	0.5
$p$	Fraction of developing symptoms	0.667
$\kappa$	Transition rate for the exposed	0.7143 / day
$f$	Complement to fatality rate (1 - fatality rate)	0.999
$\alpha$	Recovery rate for the (symptomatic) infective	0.1667 /day
$\eta$	Recovery rate for the asymptomatic	0.1667 / day
$\tau$	Antiviral treatment rate	0 / day
$\psi$	Efficacy of vaccination	70%
$\beta$	Transmission rate	6.3346e-08
$R_0$	Basic Reproduction number	1.9

►  $S_0 = 5e07$ ,  $E_0 = 0$ ,  $I_0 = 1$ ,  $A_0 = 0$ ,  $R_0 = 0$

## Goal in paper

- ▶ The goal is to **minimize the number of people who become infected** at a **minimal efforts of vaccination**.
- ▶ The objective functional is given by

$$J(\nu) = \int_0^T PI(t) + Q\nu^2(t)dt$$

with  $0 \leq \nu(t) \leq 1$  ,  $\nu(t)S(t) \leq \nu_{max}$ ,  $\int_0^T \nu(t)S(t) \leq \nu_{total}$