

Cloud Computing with Google Colab

Colaboratory is a free Jupyter notebook environment that requires no setup and runs entirely in the cloud.

With Colaboratory we can write and execute code, save and share our analyses, and access powerful computing resources (like GPU), all for free from our browser.

In this notebook, we will create a convolutional neural network for rock-paper-scissors image classification and train it in the cloud.

```
In [1]: %matplotlib inline
    from tensorflow.python.util import deprecation
    deprecation._PRINT_DEPRECATION_WARNINGS = False
    import matplotlib.pyplot as plt
    import zipfile
    import numpy as np
    import random
    import tensorflow as tf
    from tensorflow.keras.preprocessing.image import ImageDataGenerator
    from tensorflow.keras.optimizers import RMSprop, Adam
    from tensorflow.keras.models import Model
    from keras.preprocessing import image
```

Using TensorFlow backend.

1. Data Pre-Processing

1.1 Download Data

Download Data from External Link

```
In [2]: # download the training data set as a zip file and save it to the "/tmp" folder.
        # The -O option sets the output file name.
        !wget --no-check-certificate \
            https://storage.googleapis.com/laurencemoroney-blog.appspot.com/rps.zip \
            -0 /tmp/rps.zip
        --2019-08-24 10:38:57-- https://storage.googleapis.com/laurencemoroney-blog.appspot.com/rps.zip
        Resolving storage.googleapis.com (storage.googleapis.com)... 108.177.119.128, 2a00:1450:4013:c00::80
        Connecting to storage.googleapis.com (storage.googleapis.com)|108.177.119.128|:443... connected.
        HTTP request sent, awaiting response... 200 OK
        Length: 200682221 (191M) [application/zip]
        Saving to: '/tmp/rps.zip'
        /tmp/rps.zip
                            100%[=========>] 191.38M 155MB/s
                                                                           in 1.2s
        2019-08-24 10:38:58 (155 MB/s) - '/tmp/rps.zip' saved [200682221/200682221]
In [3]: # download the dev data set as a zip file and save it to the "/tmp" folder.
        !wget --no-check-certificate \
            https://storage.googleapis.com/laurencemoroney-blog.appspot.com/rps-test-set.zip \
            -0 /tmp/rps-test-set.zip
        --2019-08-24 10:39:06-- https://storage.googleapis.com/laurencemoroney-blog.appspot.com/rps-test-set.zip
        Resolving storage.googleapis.com (storage.googleapis.com)... 108.177.119.128, 2a00:1450:4013:c01::80
        Connecting to storage.googleapis.com (storage.googleapis.com) | 108.177.119.128 | :443... connected.
        HTTP request sent, awaiting response... 200 OK
        Length: 29516758 (28M) [application/zip]
        Saving to: '/tmp/rps-test-set.zip'
        /tmp/rps-test-set.z 100%[===========] 28.15M --.-KB/s in 0.1s
        2019-08-24 10:39:07 (231 MB/s) - '/tmp/rps-test-set.zip' saved [29516758/29516758]
In [0]: # the folder which saves the data zip file
        folder = '/tmp/' # if download from link
```

Download Data from Google Drive

Mount Google Drive in our virtual machine using an authorization code.

1.2 File Pre-Processing

```
In [0]: # training dataset
zipfile_path = folder + 'rps.zip'
zip_file = zipfile.ZipFile(zipfile_path, 'r')
zip_file.extractall(path = '/tmp/train_rps')

# dev dataset
zipfile_path = folder + 'rps-test-set.zip'
zip_file = zipfile.ZipFile(zipfile_path, 'r')
zip_file.extractall(path = '/tmp/dev_rps')
zip_file.close()
```

The contents of the .zip are extracted to the base directory /tmp/train_rps (for training) and /tmp/dev_rps (for dev), which in turn each contain paper, rock and scissors subdirectories.

We do not explicitly label the images. We'll use Image Generator -- and this is coded to read images from subdirectories, and automatically label them from the name of that subdirectory.

```
In [0]: # Directories with our training and dev data

train_paper_dir = os.path.join('/tmp/train_rps/rps/paper')
train_rock_dir = os.path.join('/tmp/train_rps/rps/rock')
train_scissors_dir = os.path.join('/tmp/train_rps/rps/scissors')

dev_paper_dir = os.path.join('/tmp/dev_rps/rps-test-set/paper')
dev_rock_dir = os.path.join('/tmp/dev_rps/rps-test-set/rock')
dev_scissors_dir = os.path.join('/tmp/dev_rps/rps-test-set/scissors')
```

Let's find out the total number of images in the directories:

```
In [9]: train paper fnames = os.listdir(train paper dir)
        train rock fnames = os.listdir(train rock dir)
        train scissors fnames = os.listdir(train scissors dir)
        dev_paper_fnames = os.listdir(dev_paper_dir)
        dev rock fnames = os.listdir(dev rock dir)
        dev scissors_fnames = os.listdir(dev_scissors_dir)
        print('Total training paper images:', len(train paper fnames))
        print('Total training rock images:', len(train rock fnames))
        print('Total training scissors images:', len(train scissors fnames))
        print('Total dev paper images:', len(dev paper fnames))
        print('Total dev rock images:', len(dev_rock_fnames))
        print('Total dev scissors images:', len(dev scissors fnames))
        Total training paper images: 840
        Total training rock images: 840
        Total training scissors images: 840
        Total dev paper images: 124
        Total dev rock images: 124
        Total dev scissors images: 124
```

1.3 Image Data Examples

Now let's take a look at a few pictures to get a better sense of what they look like.

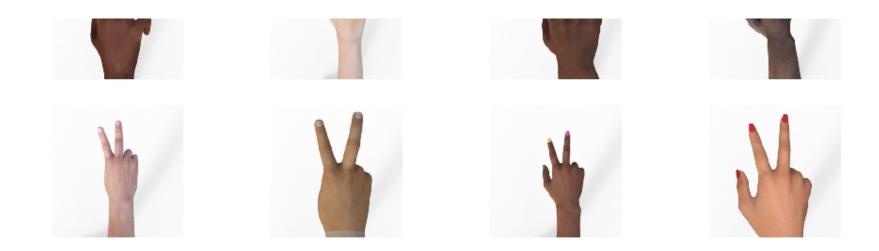
```
In [0]: # Parameters for our graph; we'll output images in a nrows x ncols configuration

nrows = 6
ncols = 4

train_paper_paths = [os.path.join(train_paper_dir, fname) for fname in train_paper_fnames]
train_rock_paths = [os.path.join(train_rock_dir, fname) for fname in train_rock_fnames]
train_scissors_paths = [os.path.join(train_scissors_dir, fname) for fname in train_scissors_fnames]
dev_paper_paths = [os.path.join(dev_paper_dir, fname) for fname in dev_paper_fnames]
dev_rock_paths = [os.path.join(dev_rock_dir, fname) for fname in dev_rock_fnames]
dev_scissors_paths = [os.path.join(dev_scissors_dir, fname) for fname in dev_scissors_fnames]
```

Display a batch of 8 paper, 8 rock and 8 scissors images.





1.4. Image Data Augmentation and Generator

```
In [12]: | # create image data
         # training set with image data augmentation
         train gen = ImageDataGenerator(
             rescale = 1. / 255,
             rotation range = 40,
             width shift range = 0.2,
             height shift range = 0.2,
             shear range = 0.2,
             zoom range = 0.2,
             horizontal flip = True,
             fill_mode = 'nearest')
         train_generator = train_gen.flow_from_directory(
             '/tmp/train_rps/rps/', # This is the source directory for training images
             target_size = (150, 150), # All images will be resized
             class mode = 'categorical')
         # dev set
         dev_gen = ImageDataGenerator(rescale = 1. / 255)
         dev_generator = dev_gen.flow_from_directory(
             '/tmp/dev_rps/rps-test-set/', # This is the source directory for dev images
             target_size = (150, 150), # All images will be resized
             class mode = 'categorical')
         print("Class index: " + str(train_generator.class_indices))
```

```
Found 2520 images belonging to 3 classes.
Found 372 images belonging to 3 classes.
Class index: {'paper': 0, 'rock': 1, 'scissors': 2}
```

2. Build the CNN Model

We add convolutional and pooling layers, and then flatten the result to feed into densely connected layers.

```
In [0]: model = tf.keras.models.Sequential([
            # The first convolution and pooling
            tf.keras.layers.Conv2D(64, (3,3), activation = 'relu', input_shape = (150, 150, 3)),
            tf.keras.layers.MaxPooling2D(2, 2),
            # The second convolution and pooling
            tf.keras.layers.Conv2D(64, (3,3), activation = 'relu'),
            tf.keras.layers.MaxPooling2D(2,2),
            # The third convolution and pooling
            tf.keras.layers.Conv2D(128, (3,3), activation = 'relu'),
            tf.keras.layers.MaxPooling2D(2,2),
            # The fourth convolution and pooling
            tf.keras.layers.Conv2D(128, (3,3), activation = 'relu'),
            tf.keras.layers.MaxPooling2D(2,2),
            # Flatten the results to feed into a DNN
            tf.keras.layers.Flatten(),
            # add dropout layer
            tf.keras.layers.Dropout(rate = 0.2),
            # 512 neuron hidden Layer
            tf.keras.layers.Dense(512, activation = 'relu'),
            # Output Layer
            tf.keras.layers.Dense(3, activation = 'softmax')
```

```
In [14]: model.summary()
         Model: "sequential"
         Layer (type)
                                       Output Shape
                                                                  Param #
         conv2d (Conv2D)
                                       (None, 148, 148, 64)
                                                                  1792
         max pooling2d (MaxPooling2D) (None, 74, 74, 64)
                                                                 0
         conv2d 1 (Conv2D)
                                       (None, 72, 72, 64)
                                                                  36928
         max pooling2d 1 (MaxPooling2 (None, 36, 36, 64)
                                                                 0
         conv2d 2 (Conv2D)
                                       (None, 34, 34, 128)
                                                                  73856
         max_pooling2d_2 (MaxPooling2 (None, 17, 17, 128)
                                                                 0
         conv2d 3 (Conv2D)
                                       (None, 15, 15, 128)
                                                                  147584
         max pooling2d 3 (MaxPooling2 (None, 7, 7, 128)
                                                                 0
         flatten (Flatten)
                                       (None, 6272)
                                                                 0
         dropout (Dropout)
                                       (None, 6272)
                                                                  0
         dense (Dense)
                                       (None, 512)
                                                                  3211776
         dense 1 (Dense)
                                                                  1539
                                       (None, 3)
         Total params: 3,473,475
         Trainable params: 3,473,475
         Non-trainable params: 0
         model.compile(loss = 'categorical crossentropy',
                        optimizer = RMSprop(lr = 1e-4),
                        metrics = ['acc'])
```

3. Model Training

```
In [0]: class myCallback(tf.keras.callbacks.Callback):
    def on_epoch_end(self, epoch, logs={}):
        if(logs.get('acc') > 0.98):
            print("\nReached target accuracy so cancelling training!")
            self.model.stop_training = True

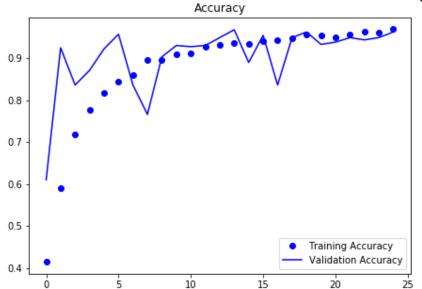
callbacks = myCallback()
```

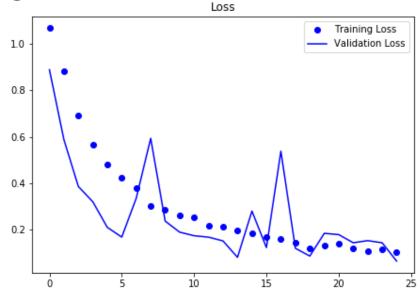
```
Epoch 1/25
Epoch 2/25
Epoch 3/25
Epoch 4/25
Epoch 5/25
Epoch 6/25
Epoch 7/25
Epoch 8/25
Epoch 9/25
Epoch 10/25
Epoch 11/25
Epoch 12/25
Epoch 13/25
Epoch 14/25
Epoch 15/25
Epoch 16/25
Epoch 17/25
Epoch 18/25
Epoch 19/25
Epoch 20/25
Epoch 21/25
Epoch 22/25
```

Plot the training progress

```
In [18]: train loss = history.history['loss']
         train acc = history.history['acc']
         val loss = history.history['val loss']
         val_acc = history.history['val_acc']
         epochs = range(len(train acc))
         fig, axes = plt.subplots(1, 2)
         fig.suptitle('Training Progress', fontsize = 20)
         fig.set_size_inches(16, 5)
         axes[0].plot(epochs, train_acc, 'bo', label = 'Training Accuracy')
         axes[0].plot(epochs, val_acc, 'b', label = 'Validation Accuracy')
         axes[0].set_title('Accuracy')
         axes[0].legend()
         axes[1].plot(epochs, train_loss, 'bo', label = 'Training Loss')
         axes[1].plot(epochs, val_loss, 'b', label = 'Validation Loss')
         axes[1].set_title('Loss')
         axes[1].legend()
         plt.show()
```







4. Model Testing

Let's now take a look at actually running a prediction using the model. This code will allow us to choose one or more files from our file system, it will then upload them, and run them through the model, giving an indication of whether the object is rock, paper or scissors.

```
In [21]: from google.colab import files
         uploaded = files.upload()
         for fn in uploaded.keys():
             file = '/content/' + fn
             img = image.load_img(file, target_size = (150, 150))
             x = image.img_to_array(img)
             x = np.expand_dims(x, axis = 0)
             x /= 255
             # predict
             classes = model.predict(x)
             print('Prediction:' + str(classes))
             # show the figure with prediction
             image_cur = plt.imread(file)
             plt.figure(figsize = (5, 5))
             plt.imshow(image_cur)
             plt.axis('off')
             if np.argmax(classes) == 0:
                 plt.title(file.split('/')[-1] + " prediction: paper")
             elif np.argmax(classes) == 1:
                 plt.title(file.split('/')[-1] + " prediction: rock")
             else:
                 plt.title(file.split('/')[-1] + " prediction: scissors")
```

Choose Files No file chosen

Upload widget is only available when the cell has been executed in the current browser session. Please rerun this cell to enable.

Saving paper3.png to paper3.png Saving rock5.png to rock5.png

Saving scissors-hires1.png to scissors-hires1.png

Prediction:[[9.9919707e-01 3.5891432e-08 8.0299174e-04]] Prediction:[[2.0382703e-04 9.7035855e-01 2.9437628e-02]] Prediction:[[2.936445e-06 6.132690e-08 9.999970e-01]]

paper3.png prediction: paper



rock5.png prediction: rock



scissors-hires1.png prediction: scissors



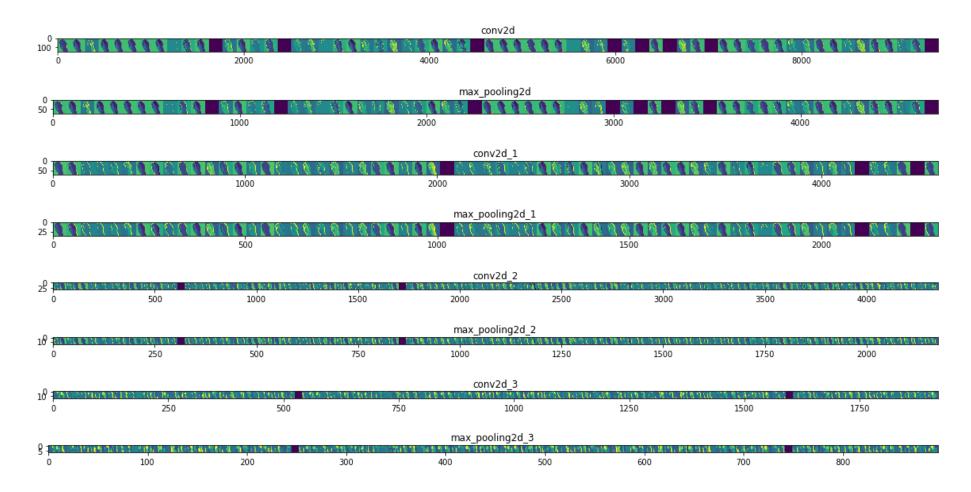
5. Visualizing Intermediate Representations

We randomly pick an image from the training set, and then generate a figure where each row is the output of a layer, and each image in the row is a specific filter in that output feature map.

```
In [22]: # Define a new model that will take an image as input, and will output intermediate representations for all layers in
         # the previous model
         outputs = [layer.output for layer in model.layers]
         vis model = Model(inputs = model.input, outputs = outputs)
         # Get a random input image from the training set.
         random.seed(0)
         img_path = random.choice(train_paper_paths + train_rock_paths + train_scissors_paths)
         img = plt.imread(img path)
         plt.imshow(img)
         plt.axis('off')
         img = image.load_img(img_path, target_size = (150, 150)) # this is a PIL image
         x = image.img to array(img) # Numpy array with shape (150, 150, 3)
         x = x.reshape((1,) + x.shape) # Numpy array with shape (1, 150, 150, 3)
         x /= 255
         # Let's run our image through our network, thus obtaining all intermediate representations for this image.
         feature_maps = vis_model.predict(x)
         # Get the names of the layers
         layer names = [layer.name for layer in model.layers]
```

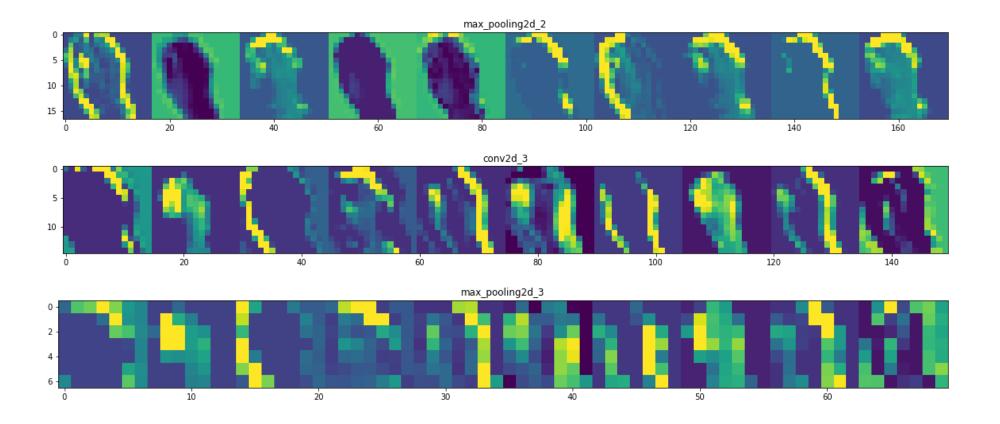


```
In [23]: # Now let's display our representations
         for layer name, feature map in zip(layer names, feature maps):
             # Only for the conv / pooling layers, not the fully-connected layers
             if len(feature map.shape) == 4:
                 n channels = feature_map.shape[-1] # number of channels in current feature map
                 # The feature map has shape (1, size, size, n channels)
                 size = feature map.shape[1]
                 # We will tile our images in this matrix
                 display_grid = np.zeros((size, size * n_channels))
                 # Postprocess the feature to make it visually palatable
                 for i in range(n_channels):
                     x = feature_map[0, :, :, i]
                     x -= x.mean()
                     x /= x.std()
                     x *= 64
                     x += 128
                     x = np.clip(x, 0, 255).astype('uint8')
                     # We'll tile each filter into this big horizontal grid
                     display_grid[:, i * size : (i + 1) * size] = x
                     # Display the grid
                 height = 20. / n channels # figure height
                 plt.figure(figsize = (height * n channels, height)) # each small figure has the same height and width
                 plt.title(layer_name)
                 plt.grid(False)
                 plt.imshow(display_grid, aspect='auto', cmap='viridis')
```



It is hard to see the pictures of a layer when the number of channels is too large. In the following code, we only plot the first 10 channels for each layer.

```
In [24]: for layer_name, feature_map in zip(layer_names, feature_maps):
             if len(feature_map.shape) == 4:
                 n channels = 10
                 size = feature_map.shape[1]
                 display_grid = np.zeros((size, size * n_channels))
                 for i in range(n_channels):
                     x = feature_map[0, :, :, i]
                     x -= x.mean()
                     x /= x.std()
                     x *= 64
                     x += 128
                     x = np.clip(x, 0, 255).astype('uint8')
                     display_grid[:, i * size : (i + 1) * size] = x
                 height = 20. / n_channels # figure height
                 plt.figure(figsize = (height * n_channels, height))
                 plt.title(layer_name)
                 plt.grid(False)
                 plt.imshow(display_grid, aspect='auto', cmap='viridis')
```



6. Clean Up

Run the following cell to terminate the kernel and free memory resources.

In [0]: #os.kill(os.getpid(), signal.SIGKILL)