

A Scalable and Flexible Cox Proportional Hazards Model for High-Dimensional Survival Prediction and Functional Selection

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Background

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“It is extremely unlikely that the true (effect) function $f(X)$ (on the outcome) is actually linear in X .”

— *Hastie, Tibshirani, and Friedman (2009) PP. 139*

Question

How to model nonlinear effects for survival outcome in **high-dimensional** setting?

Additive Cox Proportional Hazards Model

Following all necessary assumptions, a Cox proportional hazards model with event time t_i and predictors $x_{ij}, j = 1, \dots, p$, is expressed as

$$h(t_i) = h_0(t_i) \exp\left(\sum_{j=1}^p B_j(x_{ij})\right), \quad i = 1, \dots, n.$$

► Spline functions

$$B(x) = \sum_{k=1}^K \beta_k b_k(x) \equiv \mathbf{x}^T \boldsymbol{\beta}$$

$b_k(x)$ are the *basis functions*, possibly truncated power basis and b-spline basis. (Wood 2017)

Function Smoothing

- ▶ Smoothing penalty $\text{pen}_\lambda(B_j(X_j)) = \lambda \int B''(X)^2 dx = \lambda \beta^T \mathbf{S} \beta$
 - ▶ The smoothing penalty matrix \mathbf{S} is known given \mathbf{X}
 - ▶ \mathbf{S} is symmetric and positive semi-definite
- ▶ Penalized Partial Likelihood Function

$$pl(\beta) = \sum_{i=1}^n d_i \log \frac{\exp(\beta^T \mathbf{x}_i)}{\sum_{i' \in R(t_i)} \exp(\beta^T \mathbf{x}_{i'})} - \sum_{j=1}^p \text{pen}_\lambda(B_j(X_j)),$$

- ▶ The smoothing parameter λ is a tuning parameter, selected via cross-validation

High-dimensional Additive Cox Model

Primary Challenges:

- ▶ Jointly model signal sparsity versus function smoothness
 - ▶ Smooth penalty only overfits the model
 - ▶ Sparsity penalty only overshinks the coefficients
 - ▶ Damage predictive performance
- ▶ Adaptive shrinkage
 - ▶ Global shrinkage assumes similar function smoothness
- ▶ Bi-level selection that simultaneously answers
 - ▶ if a variable is predictive to the outcome, $B_j(X_j) = 0$
 - ▶ if a variable has a nonlinear relationship with the outcome, $B_j(X_j) = \beta_j X_j$

Bayesian Hierarchical Additive Model

Bayesian Hierarchical Additive Model

- ▶ Two-part spike-and-slab LASSO prior for spline functions
 - ▶ Variable selection via inclusion indicator
 - ▶ Bi-level selection accounting for effect hierarchy
 - ▶ Adaptive shrinkage via Bayesian regularization
- ▶ EM-Coordinate Descent algorithm
 - ▶ Expedited computation
 - ▶ Seamless variable selection via sparse solution

Two-part Spike-and-slab LASSO (SSL) Prior

Follow Marra and Wood (2011), a spline function $B(X) = \mathbf{X}^T \boldsymbol{\beta}$ can be decomposed to linear and nonlinear components with respect to the smoothing penalty matrix S

$$\mathbf{X}^T \boldsymbol{\beta} = X^0 \beta + \mathbf{X}^* \boldsymbol{\beta}^*$$

Two-part spike-and-slab LASSO prior

$$\beta_j | \gamma_j, s_0, s_1 \sim DE(0, (1 - \gamma_j)s_0 + \gamma_j s_1)$$

$$\beta_{jk}^* | \gamma_j^*, s_0, s_1 \stackrel{\text{iid}}{\sim} DE(0, (1 - \gamma_j^*)s_0 + \gamma_j^* s_1), k = 1, \dots, K - 1$$

- ▶ γ_j controls the inclusion of linear component
- ▶ γ_j^* controls the inclusion of nonlinear component

Effect Hierarchy and Adaptive Shrinkage

Effect hierarchy assumes lower-order effects are more likely to be active than higher-order effects

- ▶ Structured prior on latent indicators γ_j and γ_j^*

$$\gamma_j | \theta_j \sim \text{Bin}(\gamma_j | 1, \theta_j), \quad \gamma_j^* | \gamma_j, \theta_j \sim \text{Bin}(1, \gamma_j \theta_j),$$

- ▶ Simplification via analytic integration

$$\gamma_j^* | \theta_j \sim \text{Bin}(1, \theta_j^2),$$

- ▶ Adaptive shrinkage

$$\theta_j \sim \text{Beta}(a, b)$$

EM-Coordinate Descent Algorithm

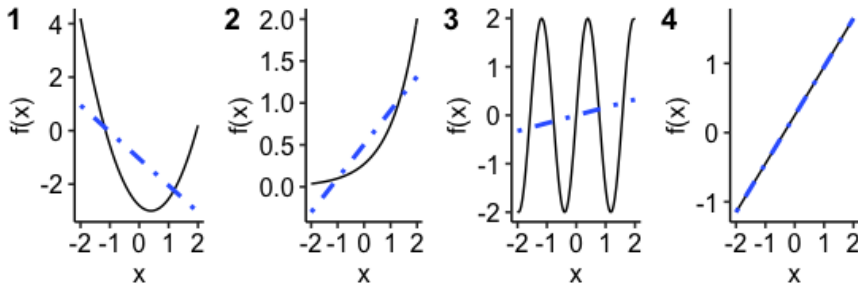
We are interested in estimating $\Theta = \{\beta, \theta\}$ using optimization based algorithm for scalability purpose

- ▶ Treat γ s as the “missing data” in the EM procedure
 - ▶ Construct the conditional expectation of the posterior density function
- ▶ Decompose the posterior density function to two pieces
 - ▶ L_1 penalized partial likelihood function of β
 - ▶ Posterior density function of θ
- ▶ Maximize the two pieces independently
 - ▶ Optimize β with coordinate descent algorithm
 - ▶ Optimize θ with beta-binomial conjugate relationship

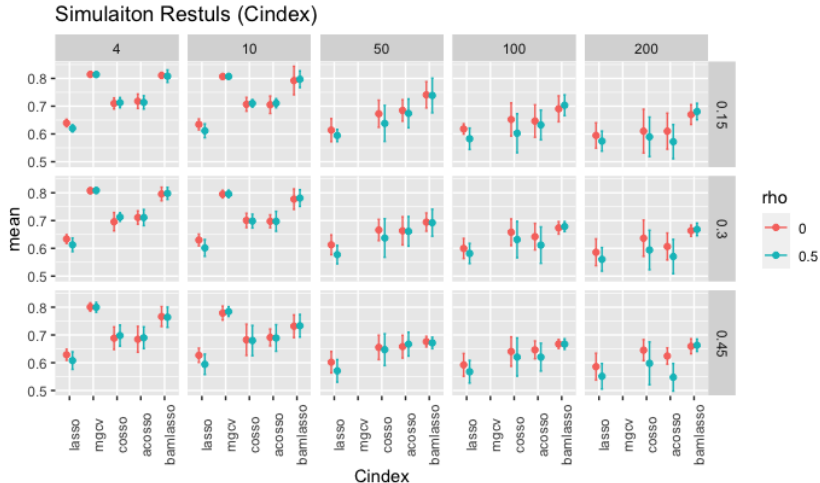
Numeric Studies

Simulation Study

- ▶ $n_{train} = 500$, $n_{test} = 1000$
- ▶ $p = 4, 10, 50, 100, 200$
- ▶ Survival and censoring time follow Weibull distribution
 - ▶ Censoring rate is controlled at $\{0.15, 0.3, 0.45\}$

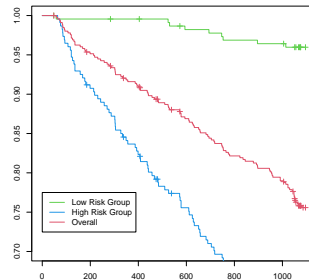


Prediction Performance



Emory Cardiovascular Biobank

- ▶ All-cause mortality among patents undergoing cardiac catheterization
- ▶ Sample size $N=454$ and number of features $p=200$
- ▶ 5-knot cubic spline



Conclusion

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- ▶ A scalable and flexible Cox Model for high-dimensional survival data analysis
 - ▶ Two-part spike-and-slab LASSO prior for spline functions
 - ▶ Jointly model signal sparsity and function smoothness with adaptive regularization
 - ▶ Bi-level selection that accounts the effect hierarchy principle
 - ▶ EM-Coordinate Descent algorithm
 - ▶ Computation advantage and sparse solution
- ▶ R package: BHAM
 - ▶ Ancillary functions for high-dimensional formulation
 - ▶ Model summary and variable selection
 - ▶ Website via *boyiguo1.github.io/BHAM*

References

References I

- Hastie, Trevor, Robert Tibshirani, and Jerome Friedman. 2009. *The Elements of Statistical Learning: Data Mining, Inference, and Prediction*. Springer Science & Business Media.
- Marra, Giampiero, and Simon N Wood. 2011. "Practical Variable Selection for Generalized Additive Models." *Computational Statistics & Data Analysis* 55 (7): 2372–87.
- Wood, Simon N. 2017. *Generalized additive models: An introduction with R, second edition*. <https://doi.org/10.1201/9781315370279>.