

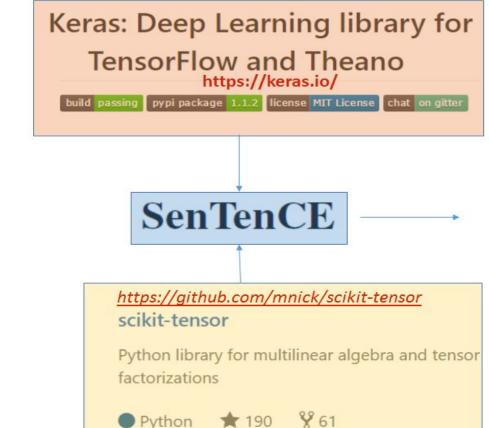
Multi-sensor data compression using tensor decompositions: A SenTenCE and more

Vinay Uday Prabhu UnifyID San Francisco CA 94107 vinay@unify.id

Paulo Arantes UnifyID San Francisco CA 94107 paulo@unify.id

John Whaley UnifyID San Francisco CA 94107 john@unify.id

UNIFYID CODE AND DATA:





Accuracy distribution for 9 activities/classes over 100 cross-validations

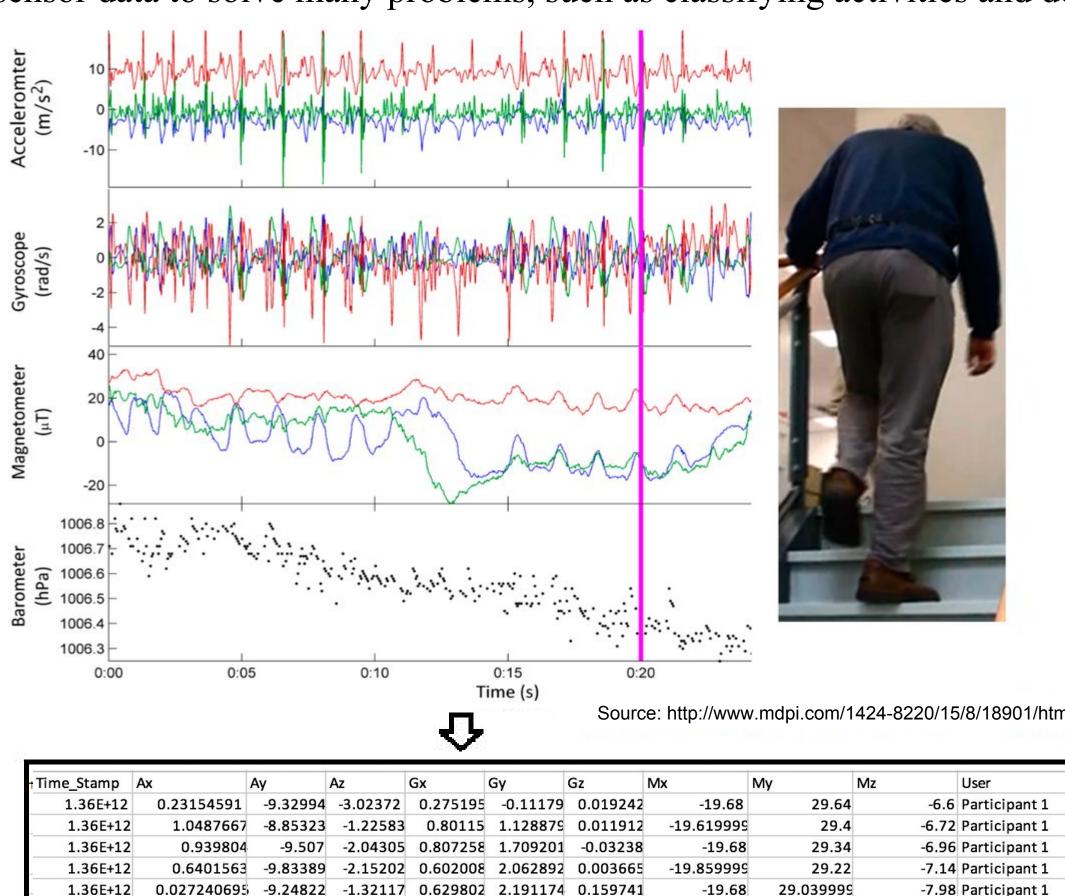
100cvs_tucker20_reconstructed median: 0.932790649208

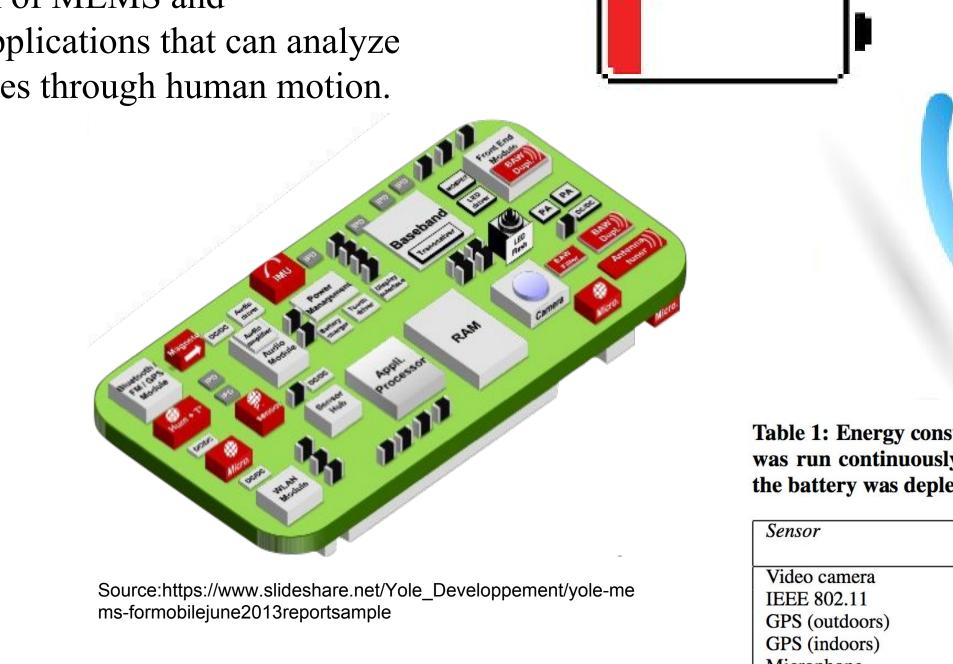
100cvs_tucker20_core median: 0.929764141197

100cvs_tucker10_reconstructed median: 0.930181590582

Motivation and Introduction:

Sensors are what make smartphones smart. In recent years, the proliferation of MEMS and advancements in Machine Learning have allowed for the development of applications that can analyze sensor data to solve many problems, such as classifying activities and devices through human motion.





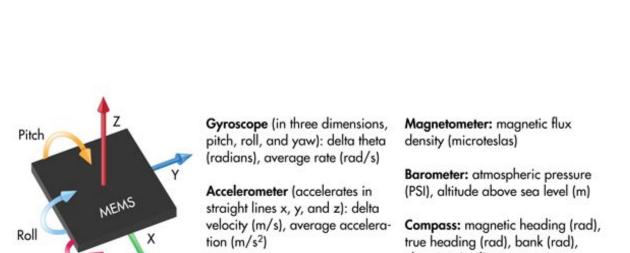


Table 1: Energy consumption of different sensors. Each sensor was run continuously on a Nokia N95 8GB smartphone until the battery was depleted.

ensor	battery life (hrs)	consumption (mW)		
ideo camera	3.5	1258	_	
EEE 802.11	6.7	661		
PS (outdoors)	7.1	623		
PS (indoors)	11.6	383		
Iicrophone	13.6	329		
luetooth	21.0	211		
ccelerometer	45.9	96		
ll sensors turned off	170.6	26		
		-		

http://conferences.sigcomm.org/sigcomm/2009/workshops/mobiheld/p

Recognition Challenge

• Kwapisz et al. (2011), and

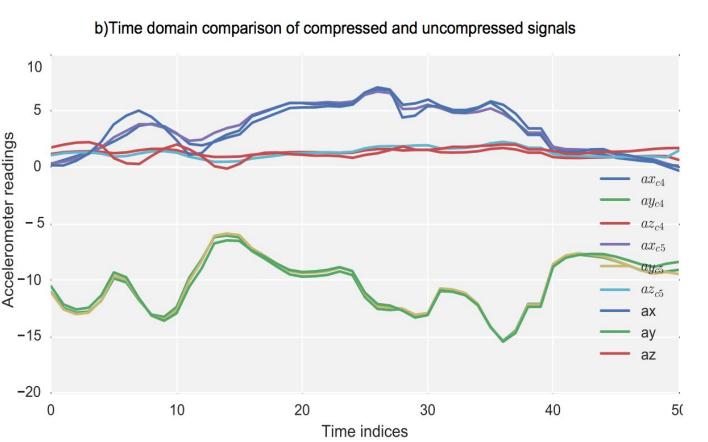
• Chen et al. (2015)

Activating sensors and collecting its data can be very expensive and battery intensive. To use deep learning or other computationally intensive algorithms, it's also necessary to transfer the data, which poses another limitation on memory.

The Solution: Smart sensor data compression via SenTenCE.

MNIST DCNN ARCHITECTURE:

Dataset and implementation:



.4380422 -9.60235 0.612916 0.627359 2.261729 0.308792

3.091819 -9.87475 0.40861 0.564745 2.422386 0.235489

Six different datasets were fused, resulting in 9 activity labels, and 10.3 million data points. The datasets were converted into a common format and resampled to 200Hz. The input to the DCNN is a 200×4 image of raw sensor data. We used the folds cross validation for each input data format. By performing the tasks on Nvidia-GPUs, the training time decreased by an order of ~18 times in comparison to using CPUs.

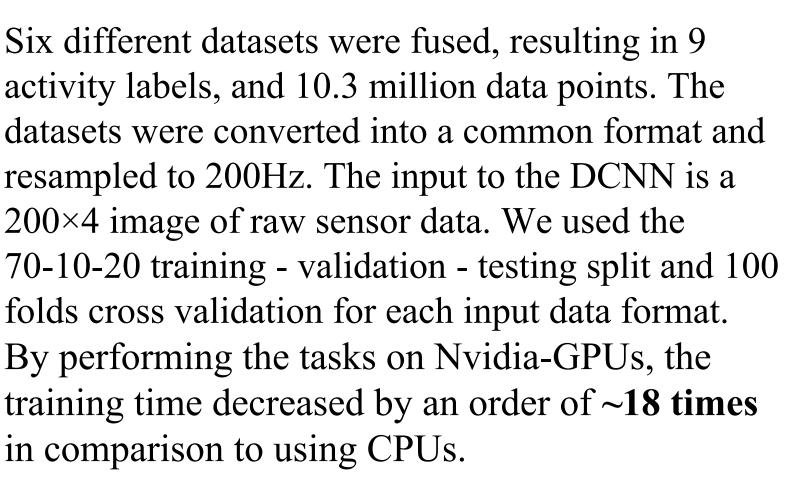
-8.4 Participant 1

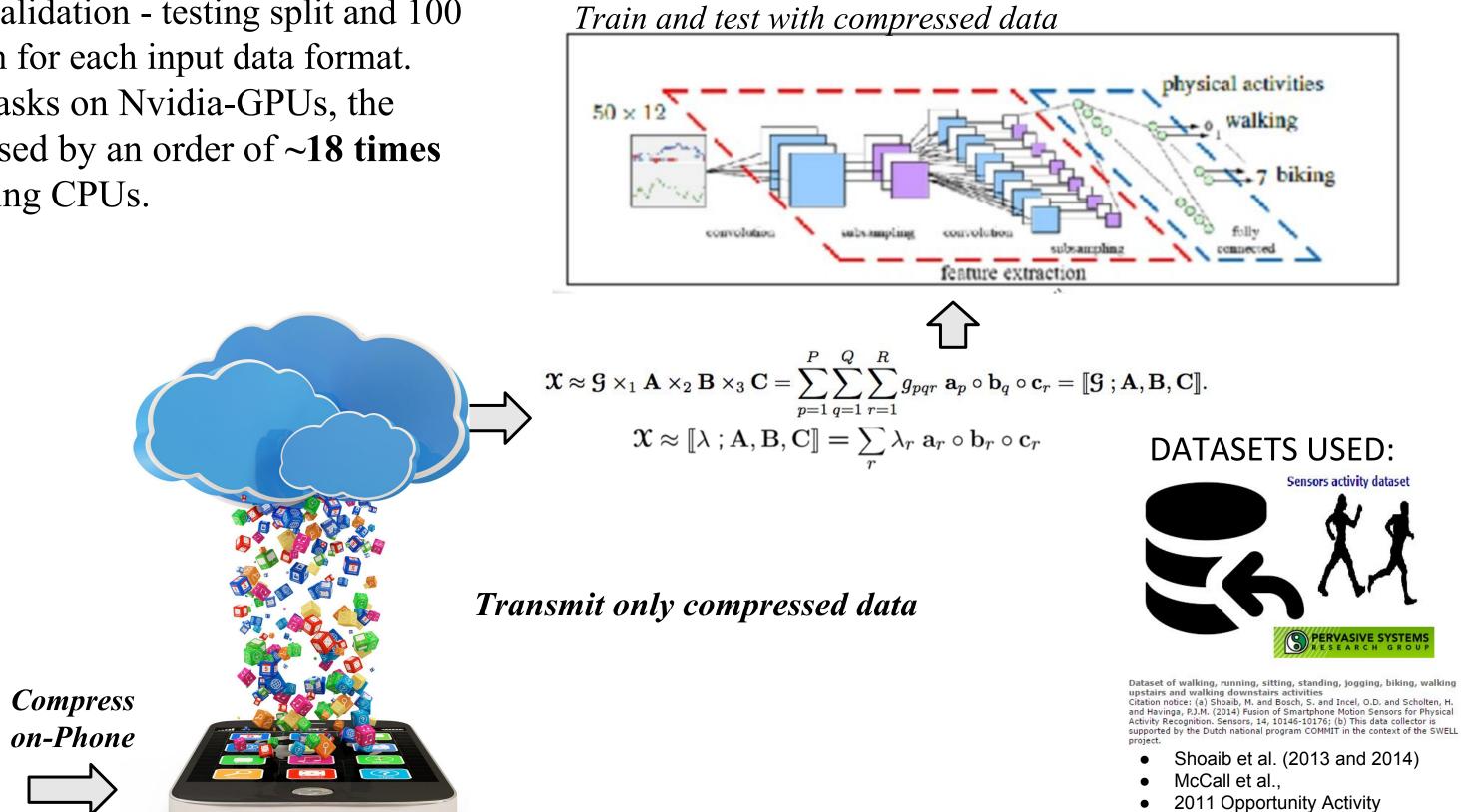
-8.76 Participant 1

-9.78 Participant 1

-10.44 Participant 1 -11.28 Participant 1

Ax	Ау	Az	Gx	Gy	Gz	Mx	My	Mz	
3154591	-9.329938	-3.0237172	0.2751948	-0.11178834	0.019242255	-19.68	29.64	-6.6	
0487667	-8.853226	-1.2258313	0.8011498	1.128879	0.011911872	-19.619999	29.4	-6.72	
.939804	-9.507003	-2.0430522	0.8072584	1.709201	-0.032375857	-19.68	29.34	-6.96	
6401563	-9.833891	-2.152015	0.6020077	2.062892	0.003665192	-19.859999	29.22	-7.14	
27240695	-9.248216	-1.3211738	0.62980205	2.1911736	0.15974127	-19.68	29.039999	-7.98	
7671217	-9.343558	-1.4573772	0.7189884	1.9602666	0.29565877	-19.5	28.92	-8.4	
0896279	-9.615966	-0.8036005	0.71868294	1.9034561	0.3472769	-19.32	28.74	-8.76	
6889231	-9.452521	0.40861043	0.7254025	2.0491474	0.3313944	-18.779999	28.74	-9.78	
$\begin{array}{c} \begin{array}{c} \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\ \\$									
Spatial axes		$\mathbb{R}^{I \times J \times K}$ = [1:200])	Sensors	1	1x J x K	Ix R A RxS	JxS Ix	DECOMPOSITION $x $	c _R b _R



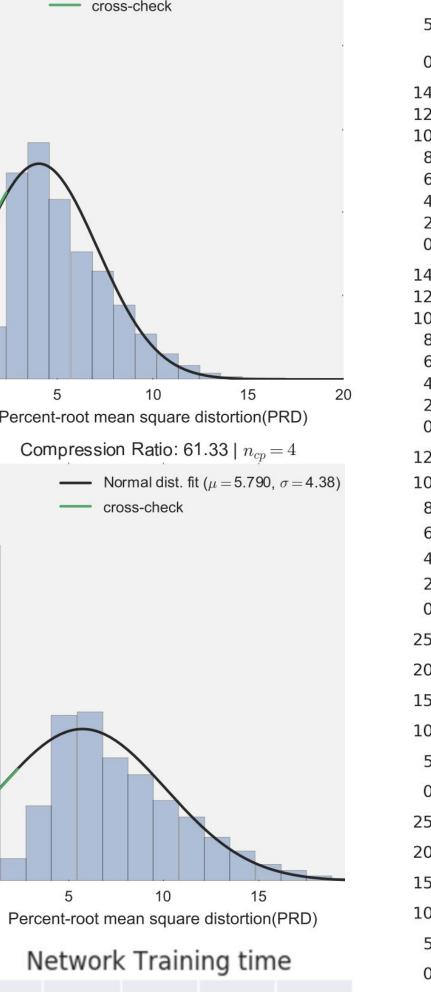


Results: Compression Ratio: 51.67 | $n_{cp} = 5$ **—** Normal dist. fit ($\mu = 4.004$, $\sigma = 3.08$)

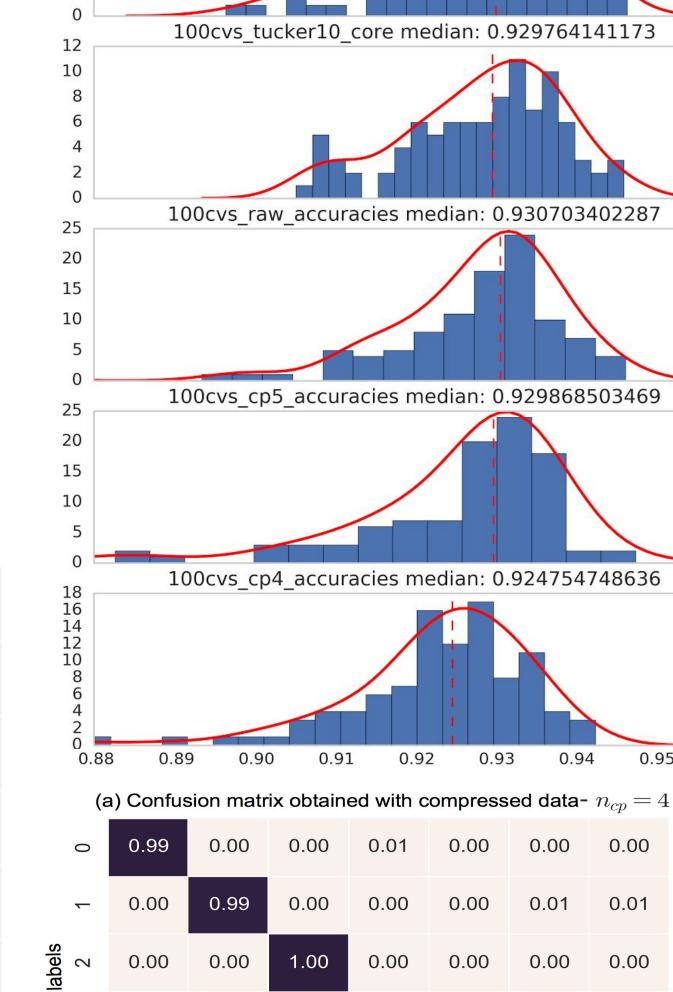
300

දු 200

8 100



vs. GPU



%		67	672,669 0%				93.104 ± 0.205%			
ata # of ression Parameters			Network params "Compression"			Mean Accuracy ↓				
0 1 2 3 4 5 6 Predicted class labels										
9	0.00	0.	04	0.00	0.00	0.00	0.07	0.89	П	0.0
2	0.00	0.	05	0.00	0.00	0.00	0.93	0.03		0.2
4	0.01	0.	13	0.00	0.00	0.85	0.01	0.01		0.4
3	0.12	0.	00	0.00	0.88	0.00	0.00	0.00		
2	0.00	0.	00	1.00	0.00	0.00	0.00	0.00	П	0.6

Input Data for Model	Data Compression	# of Parameters	Network params "Compression"	Mean Accuracy ↓
Tucker ranks [20, 2, 4] reconstruction	0%	672,669	0%	93.104 ± 0.205%
Tucker ranks [20, 2, 4] core	90%	49,269	92.7%	92.886 ± 0.204%
Tucker ranks [10, 2, 4] reconstruction	0%	672,669	0%	92.850 ± 0.207%
Tucker ranks [10, 2, 4] core	95%	41,269	93.9%	92.842 ± 0.198%
Raw uncompressed	0%	672,669	0%	92.778 ± 0.222%
CP rank 5 reconstruction	61%	672,669	0%	92.513 ± 0.289%
CP rank 4 reconstruction	51%	672,669	0%	92.328 ± 0.217%

Via Canonical Polyadic we achieve a 61% data compression, less than 6% distortion rate (PRD), and lose less than 2% accuracy in the human activity classification task using a CNN deep classifier. Further, we also harness Tucker decomposition and achieve ~95% compression rate with a consistent improvement of about 0.5% in accuracy while also decreasing the number of training parameters by ~94%.