Types for Deadlock-Free Higher-Order Programs

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A bit of context

Behavioural Types for Reliable Large-Scale Software Systems

- COST Action IC1201
- http://www.behavioural-types.eu

"...integration of behavioural types into mainstream programming languages..."

A type system for deadlock freedom

Padovani, Deadlock and lock freedom in the linear π -calculus, CSL-LICS 2014

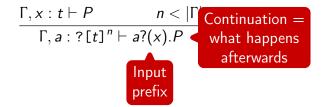
In a process calculus

$$\frac{\Gamma, x: t \vdash P \qquad n < |\Gamma|}{\Gamma, a: ?[t]^n \vdash a?(x).P}$$

A type system for deadlock freedom

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In a process calculus



A type system for deadlock freedom

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In a process calculus

$$\frac{\Gamma, x : t \vdash P \qquad n \leqslant |\Gamma|}{\Gamma, a : ?[t]^n \vdash a?(x) P}$$

What about a structured programming language?

- I/O may happen within functions, methods, objects, ...
- ... for which we rarely know the "continuation"
- ⇒ how do we transpose this typing rule?

Outline

- The language
- 2 Types for deadlock freedom
- 3 Level polymorphism
- 4 Properties
- 6 Conclusion

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A minimal programming language

- call-by-value λ -calculus
- open, send, recv, fork
- linear channels

```
\langle \text{ send } a \text{ (recv } b) \rangle | \langle \text{ send } b \text{ (recv } a) \rangle
```

Example: parallel recursive function

```
let rec fibo n c = 

if n \leq 1 then send c n

else let a = open () in

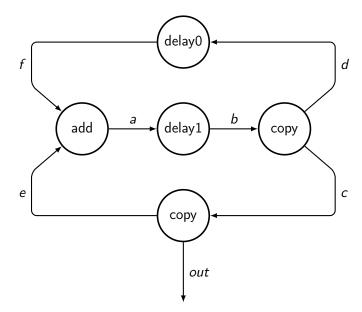
let b = open () in

fork (fun \_ \rightarrow fibo (n - 1) a);

fork (fun \_ \rightarrow fibo (n - 2) b);

send c (recv a + recv b)
```

Example: Kahn process network



Example: Kahn process network

```
let rec link x y = let rec copy x y z =
  let v, x' = recv x in let v, x' = recv x in
  let y' = open () in    let y' = open () in
  send y(v, y'); let z' = open() in
  link x'y'
                     send y (v, y');
                         send z (v, z');
                       copy x, y, z,
let delay v x y =
  let y' = open () in
  send y (v, y');
                    let fibo out =
  link x y'
                          let a, b = open (), open () in
                          let c, d = open(), open() in
let rec add x y z = let e, f = open (), open () in
  let v, x' = recv x in fork (fun \_ \rightarrow add e f a);
  let w, y' = recv y in fork (fun \_ \rightarrow delay 1 a b);
  let z' = open () in
                         fork (fun \_ \rightarrow copy b c d);
  send z (v + w, z'); fork (fun \_ \rightarrow copy c e out);
  add x' y' z'
                         fork (fun \_ \rightarrow delay 0 d f)
```

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Channel levels in types

$$p[t]^n$$



```
\langle send a (recv b) \rangle | \langle send b (recv a) \rangle
```

```
! [int]^{n} $$ $ \langle \underline{\mathtt{send}} \ a \ (\mathtt{recv} \ b) \ \rangle | \langle \ \mathtt{send} \ b \ (\mathtt{recv} \ a) \ \rangle $$ $$ ! [int]^{n} \to \mathtt{int} \to \mathtt{unit} $$
```

```
\langle \underline{\text{send } a} \text{ (recv } b) \rangle | \langle \text{ send } b \text{ (recv } a) \rangle
int \rightarrow \text{ unit}
```

```
?[int]^m \rightarrow int
\langle \underline{\text{send } a} (\overline{\text{recv } b}) \rangle | \langle \underline{\text{send } b} (\text{recv } a) \rangle
int \rightarrow unit ?[int]^m
```

```
int \langle \  \       send a \  \   (recv b) \rangle | \langle \  \    send b \  \   (recv a) \rangle int 	o unit
```

```
int \langle \  \       send a \  \   (recv b) \rangle |\langle \  \   send b \  \   (recv a) \rangle int \rightarrow unit
```

```
\langle \text{ send } a \text{ (recv } b) \rangle | \langle \text{ send } b \text{ (recv } a) \rangle
```

```
! [int]^{n} \& \bot
\langle \underline{\texttt{send}} \ \widehat{a} \ (\texttt{recv} \ b) \ \rangle | \langle \ \texttt{send} \ b \ (\texttt{recv} \ a) \ \rangle
! [int]^{n} \to \texttt{int} \to^{n} \texttt{unit} \& \bot
```

```
\langle \underline{\text{send } a} \text{ (recv } b) \rangle | \langle \text{ send } b \text{ (recv } a) \rangle
int \rightarrow^n unit \& \bot
```

```
?[int]^m \to^m int & \bot
\langle \text{ send } a \text{ (recv } b) \rangle | \langle \text{ send } b \text{ (recv } a) \rangle
?[int]^m \& \bot
```

```
int & m \langle \underline{\text{send } a} \ (\overline{\text{recv } b}) \ \rangle | \langle \underline{\text{send } b} \ (\overline{\text{recv } a}) \ \rangle int \rightarrow^n unit & \bot
```

```
int & m int & n  \langle \underline{\text{send } a} \ (\overline{\text{recv } b}) \ \rangle | \langle \underline{\text{send } b} \ (\overline{\text{recv } a}) \ \rangle  int \rightarrow^n unit & \bot int \rightarrow^m unit
```

More on arrow types

$$f \equiv \lambda x. \text{ (send } a^m x; \text{ send } b^n x)$$

Which type for *f*?

 $f: \text{int} \to^m \text{unit}$ $f: \text{int} \to^n \text{unit}$

More on arrow types

$$f \equiv \lambda x$$
. (send $a^m x$; send $b^n x$)

Which type for *f*?

```
f: \operatorname{int} \to^m \operatorname{unit} f: \operatorname{int} \to^n \operatorname{unit} \operatorname{int} \& n \langle (f 3); \operatorname{recv} b \rangle | \langle \operatorname{recv} a \rangle \operatorname{int} \& m
```

More on arrow types

$$f \equiv \lambda x. \text{ (send } a^m x; \text{ send } b^n x)$$

Which type for *f*?

```
f: \operatorname{int} \to^m \operatorname{unit} f: \operatorname{int} \to^n \operatorname{unit} \operatorname{int} \& m \operatorname{int} \to^n \operatorname{unit} \& \bot
```

Typing abstractions

$$t
ightharpoonup^{
ho,\sigma} s$$

$$\frac{\Gamma, x: t \vdash e: s \& \rho}{\Gamma \vdash \lambda x. e: t \rightarrow^{|\Gamma|, \rho} s \& \bot}$$

 $\vdash \lambda x.x$

 $: \mathtt{int} \to^{\top,\perp} \mathtt{int}$

$$t
ightharpoonup^{
ho,\sigma} s$$

$$\frac{\Gamma, x : t \vdash e : s \& \rho}{\Gamma \vdash \lambda x . e : t \rightarrow^{|\Gamma|, \rho} s \& \bot}$$

 $\vdash \lambda x.x$: int $\to^{\top,\perp}$ int $a: ![int]^n \vdash \lambda x.(x, a)$: int $\to^{n,\perp}$ int $\times ![int]^n$

$$t
ightharpoonup^{
ho,\sigma} s$$

$$\frac{\Gamma, x : t \vdash e : s \& \rho}{\Gamma \vdash \lambda x . e : t \rightarrow^{|\Gamma|, \rho} s \& \bot}$$

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```
 \vdash \lambda x.x \qquad : \operatorname{int} \to^{\top,\perp} \operatorname{int} 
 a: ! [\operatorname{int}]^n \vdash \lambda x. (x, a) \qquad : \operatorname{int} \to^{n,\perp} \operatorname{int} \times ! [\operatorname{int}]^n 
 \vdash \lambda x. (\operatorname{send} x 3) \qquad : ! [\operatorname{int}]^n \to^{\top,n} \operatorname{unit} 
 a: ? [\operatorname{int}]^n \vdash \lambda x. (\operatorname{recv} a + x) \qquad : \operatorname{int} \to^{n,n} \operatorname{int}
```

$$\frac{\Gamma_1 \vdash e_1 : t \to^{\rho,\sigma} s \& \tau_1 \qquad \Gamma_2 \vdash e_2 : t \& \tau_2}{\Gamma_1 + \Gamma_2 \vdash e_1 e_2 : s \& \sigma \sqcup \tau_1 \sqcup \tau_2} \qquad \tau_1 < |\Gamma_2| \qquad \qquad \tau_2 < \rho$$

$$\frac{\Gamma_1 \vdash e_1 : t \to^{\rho,\sigma} s \& \tau_1 \qquad \Gamma_2 \vdash e_2 : t \& \tau_2}{\Gamma_1 + \Gamma_2 \vdash e_1 e_2 : s \& \sigma \sqcup \tau_1 \sqcup \tau_2} \qquad \tau_1 < |\Gamma_2| \qquad \tau_2 < \rho$$

 $\vdash (\lambda x.x)$ 3

$$\frac{\Gamma_1 \vdash e_1 : t \rightarrow^{\rho,\sigma} s \& \tau_1 \qquad \Gamma_2 \vdash e_2 : t \& \tau_2}{\Gamma_1 + \Gamma_2 \vdash e_1 e_2 : s \& \sigma \sqcup \tau_1 \sqcup \tau_2} \qquad \tau_1 < |\Gamma_2|$$

$$\vdash (\lambda x.x) \ 3$$
$$a: ?[t]^n \vdash (\lambda x.x) \ (recv \ a)$$





$$\frac{\Gamma_1 \vdash e_1 : t \to^{\rho,\sigma} s \& \tau_1 \qquad \Gamma_2 \vdash e_2 : t \& \tau_2}{\Gamma_1 + \Gamma_2 \vdash e_1 e_2 : s \& \sigma \sqcup \tau_1 \sqcup \tau_2} \qquad \frac{\tau_1 < |\Gamma_2|}{\tau_2 < \rho}$$

$$\vdash (\lambda x.x) \ 3$$
$$a: ?[t]^n \vdash (\lambda x.x) \ (\text{recv } a)$$



$$a:?[t]^n\vdash(\lambda x.x)$$
 (recv a)



$$a:?[t]^n \vdash (\lambda x.(x, a)) \text{ (recv } a)$$



Typing applications

$$\frac{\Gamma_1 \vdash e_1 : t \rightarrow^{\rho,\sigma} s \& \tau_1 \qquad \Gamma_2 \vdash e_2 : t \& \tau_2}{\Gamma_1 + \Gamma_2 \vdash e_1 e_2 : s \& \sigma \sqcup \tau_1 \sqcup \tau_2} \qquad \tau_1 < |\Gamma_2| \qquad \tau_2 < \rho$$

$$\vdash (\lambda x.x) \ 3$$

$$a:?[t]^n \vdash (\lambda x.x) \text{ (recv a)}$$

$$a:?[t]^n \vdash (\lambda x.(x, a)) \text{ (recv a)}$$

$$a:?[t \rightarrow s]^0, b:?[t]^1 \vdash (\text{recv a}) \text{ (recv b)}$$

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```
let rec fibo n c =

if n \leq 1 then send c 1

else let a = open () in

let b = open () in

fork (fun \_ \rightarrow fibo (n - 1) a );

fork (fun \_ \rightarrow fibo (n - 2) b );

send c (recv a + recv b )
```

```
let rec fibo n c^{\bullet} =

if n \leq 1 then send c^{\bullet} 1

else let a = open () in

let b = open () in

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let b^{\bullet} = open () in

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fork (fun \_ \rightarrow fibo (n - 2) b^{\bullet});

send c^{\bullet} (recv a + recv b^{\bullet})
```

```
let rec fibo n c^{\bullet} =

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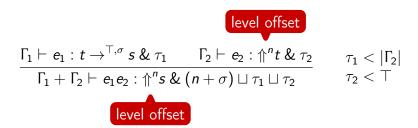
fork (fun \_ \rightarrow fibo (n - 2) b^{\bullet});

send c^{\bullet} (recv a^{\bullet} + recv b^{\bullet})
```

Different calls with different levels (types)

- fibo is well typed only if it is level polymorphic
- fibo is recursive ⇒ polymorphic recursion

Polymorphic application



Polymorphic application

$$\frac{\Gamma_1 \vdash e_1 : t \to^{\top,\sigma} s \& \tau_1 \qquad \Gamma_2 \vdash e_2 : \Uparrow^n t \& \tau_2}{\Gamma_1 + \Gamma_2 \vdash e_1 e_2 : \Uparrow^n s \& (n + \sigma) \sqcup \tau_1 \sqcup \tau_2} \qquad \frac{\tau_1 < |\Gamma_2|}{\tau_2 < \top}$$

Only unlimited functions are level polymorphic

- an unlimited function has no channels in its closure
- the absolute level of its argument does not matter

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Well-typed programs are deadlock free

Definition (deadlock freedom)

P is deadlock free if $P \longrightarrow^* Q \longrightarrow$ implies $Q \equiv \langle () \rangle$

Theorem (soundness)

If $\emptyset \vdash P$, then P is deadlock free

Well-typed programs are deadlock free

Definition (deadlock freedom)

P is deadlock free if $P \longrightarrow^* Q \longrightarrow$ implies $Q \equiv \langle () \rangle$

Theorem (soundness)

If $\emptyset \vdash P$, then P is deadlock free

Note

- apparently weak result
- every process P becomes deadlock free if composed with

$$\langle \text{fix } \lambda x.x \rangle$$

Well-typed programs are interactive

Definition (convergent process)

Convergence is the largest relation s.t. P convergent implies:

- **1** P has no infinite reduction $P \stackrel{\tau}{\longmapsto} P_1 \stackrel{\tau}{\longmapsto} P_2 \stackrel{\tau}{\longmapsto} \cdots$
- 2 if $P \stackrel{a!v}{\longmapsto} Q$, then Q is convergent
- 3 if $P \stackrel{a?x}{\longrightarrow} Q$, then $Q\{v/x\}$ is convergent for some v

Theorem (interactivity)

Let P be a convergent process such that $a \in fn(P)$. Then $P \xrightarrow{\mu_1} P_1 \xrightarrow{\mu_2} \cdots \xrightarrow{\mu_n} P_n$ for some μ_1, \ldots, μ_n such that $a \notin fn(P_n)$

Note

interactivity is still weaker than lock freedom

Well-typed programs are interactive

Definition (convergent process)

Convergence is the largest relation s.t. P convergent implies:

- **1** P has no infinite reduction $P \stackrel{\tau}{\longmapsto} P_1 \stackrel{\tau}{\longmapsto} P_2 \stackrel{\tau}{\longmapsto} \cdots$
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Theorem (interactivity)

Let P be a convergent process such that $a \in fn(P)$. Then $P \stackrel{\mu_1}{\longmapsto} P_1 \stackrel{\mu_2}{\longmapsto} \cdots \stackrel{\mu_n}{\longmapsto} P_n$ for some μ_1, \ldots, μ_n such that $a \notin fn(P_n)$

Note

interactivity is still weaker than lock freedom

Example: Kahn process network

. . .

```
let fibo out =
  let a, b = open (), open () in
  let c, d = open (), open () in
  let e, f = open (), open () in
  fork (fun _ → add e f a);
  fork (fun _ → delay 1 a b);
  fork (fun _ → copy b c d);
  fork (fun _ → copy c e out);
  fork (fun _ → delay 0 d f)
```

- fibo is well typed, hence deadlock free
- the whole network is interactive
- ⇒ each Fibonacci number is produced in finite time

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Wrap-up

- use effects for tracking levels of used channels
- arrow types need two decorations
 - latent effect
 - static information about channels in the closure
- non-trivial programs require some non-trivial features
 - polymorphic recursion
 - non-regular types (not discussed, see paper)
- the approach scales to call-by-need languages
 - no effects, but annotations on the IO monad

Related work

Deadlock freedom and higher-order session calculi

- Wadler, Propositions as sessions, ICFP 2012
- Toninho, Caires, Pfenning, Higher-Order Processes, Functions, and Sessions: A Monadic Integration, ESOP 2013
 - simpler type systems (no channel levels ⇒ no effects)
 - acyclic network topologies only

Type reconstruction

• tomorrow at COORDINATION, for π calculus