

Problem 1

(a) procedure Shortest_path(s, t, t)

s, t are points containing their coordinate and path (which is a queue)

$s.x \leftarrow i \quad s.y \leftarrow j \quad t.x \leftarrow i' \quad t.y \leftarrow j'$ for $s(i, j) \quad t(i', j')$

t is the size of chess board $t \times t$ — also the # of points.

Q is a queue store points.

$dx \leftarrow \{2, 2, -2, -2, 1, 1, -1, -1\}$

$dy \leftarrow \{1, 1, 1, 1, 2, -2, 2, -2\}$

$s.path, enqueue(s.x, s.y)$

$Q.enqueue(s)$

for (i from 1 to t)

 for (j from 1 to t)

$visit[i][j] \leftarrow false$

$visit[s.x][s.y] \leftarrow true$

 while ($Q \neq \emptyset$) then

$t \leftarrow Q.dequeue()$

 if ($t.x = i$ and $t.y = j$) then

 return $t.path$

 for (k from 1 to 8)

$x \leftarrow t.x + dx[k]$

$y \leftarrow t.y + dy[k]$

 if ($IsInside(x, y, t)$ and $!visit[x][y]$) then

$v.x \leftarrow x$

$v.y \leftarrow y$

$path \leftarrow t.path$

$v.path \leftarrow path.enqueue(x, y)$

$visit[x][y] \leftarrow true$

$Q.enqueue(v)$

procedure IsInside(x, y, n)

return $x > 0$ and $x \leq n$ and $y > 0$ and $y \leq n$

Procedure PrintPath (Q)

```
while ( Q  $\neq$   $\emptyset$  ) then  
    t  $\leftarrow$  Q.dequeue ( )  
    print ( t )
```

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For this case, we use BFS to ~~at~~ solve the problem. Each point (or ~~the~~ position) have 8 possible positions that the knight may move to. So we traverse them one by one, if the possible position is in the txt chessboard and hasn't been visited before then add them into the path Queue and keep traversing its next step. Until we reach the finish position (i', j') , we get the shortest path that stored in $t.path$ (is a queue).

This is the shortest steps path \rightarrow has been proved in BFS.

In the worst case, we need to traversing all txt positions:

- we need to Initialize $visit[txt]$ take $O(t^2)$ time
- we need to dequeue t^2 points which take $O(t^2)$ time
- In each iteration we will take a constant time (since we only have 8 possible points each time)

Overall, the runtime is $O(t^2)$.

(b) In this case, we still use BFS to find the shortest path. Since there will be 12 different possible operations to these bottles. (① Fill bottle 1; ② Fill bottle 2; ③ Fill bottle 3; ④ Empty bottle 1; ⑤ Empty bottle 2; ⑥ Empty bottle 3; ⑦ pour bottle 1 to bottle 2 (1 \rightarrow 2); ⑧ Pour bottle 1 to bottle 3 (1 \rightarrow 3); ⑨ Pour bottle 2 to bottle 1 (2 \rightarrow 1); ⑩ Pour bottle 2 to bottle 3 (2 \rightarrow 3); ⑪ Pour bottle 3 to bottle 1 (3 \rightarrow 1); ⑫ Pour bottle 3 to bottle 2 (3 \rightarrow 2))

Traverse all possible operations until we get to the ~~final~~ end with (a, b, c)

Then we would get the shortest sequence from $(0, 0, 0) \rightarrow$ to (a, b, c)

for (bottle 1 (k), bottle 2 (l), bottle 3 (m)) k, l, m are all integers.

procedure FindBottle (a, b, c, k, l, m) path

** Each Node will have x, y, z (the water in bottle₁ = x, bottle₂ = y, bottle₃ = z)

and the path (a queue) to reach this node

** a, b, c will be integers bottles end with (bottle₁ = a, bottle₂ = b, bottle₃ = c)

** bottle₁.capacity = k, bottle₂.capacity = l, bottle₃.capacity = m

start, x ← 0

start, y ← 0

start, z ← 0

start, path, enqueue (0, 0, 0)

Q, enqueue (start)

Visited['start'] = true

while (Q ≠ ∅) do

u ← Q.dequeue()

~~path ← u.path~~
if (u.x = a and u.y = b and u.z = c) then

return u.path

① if (u.x < k) then

new.x ← k

new.y ← u.y

new.z ← u.z

new.path ← path.enqueue ({ new.x, new.y, new.z })

if (Visited[new] = false) then

Q.enqueue (new)

Visited[new] ← true

② if (u.y < l) then

new.x ← u.x

new.y ← l

new.z ← u.z

new.path ← path.enqueue ({ new.x, new.y, new.z })

if (Visited[new] = false) then

Q.enqueue (new)

Visited[new] ← true

③ if (u.z < m) then

new.x ← u.x

new.y ← u.y

new.z ← m

new.path ← path.enqueue ({ new.x, new.y, new.z })

if (Visited[new] = false) then

Q.enqueue (new)

Visited[new] ← true

④ if (u.x > 0) then

new.x ← 0

new.y ← u.y

new.z ← u.z

new.path ← path.enqueue ({ new.x, new.y, new.z })

if (Visited[new] = false) then

Q.enqueue (new)

Visited[new] ← true

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⑤ If ($u.y > 0$) then
 $new.x \leftarrow u.x$
 $new.y \leftarrow 0$
 $new.z \leftarrow u.z$
 $path \leftarrow u.path$
 $new.path \leftarrow path.enqueue(\{ new.x, new.y, new.z \})$
 If ($Visited[new] \neq false$) then
 $Q.enqueue(new)$
 $Visited[new] \leftarrow true$

⑥ If ($u.z > 0$) then
 $new.x \leftarrow u.x$
 $new.y \leftarrow u.y$
 $new.z \leftarrow 0$
 $path \leftarrow u.path$
 $new.path \leftarrow path.enqueue(\{ new.x, new.y, new.z \})$
 If ($Visited[new] \neq false$) then
 $Q.enqueue(new)$
 $Visited[new] \leftarrow true$

⑦ If ($u.x > 0$ and $u.y < 1$) then
 $1 \rightarrow 2$
 $new.x \leftarrow \max(0, u.x + u.y - 1)$
 $new.y \leftarrow \min(u.x + u.y, 1)$
 $new.z \leftarrow u.z$
 $path \leftarrow u.path$
 $new.path \leftarrow path.enqueue(\{ new.x, new.y, new.z \})$
 If ($Visited[new] \neq false$) then
 $Q.enqueue(new)$
 $Visited[new] \leftarrow true$

⑧ If ($u.x > 0$ and $u.z < m$) then
 $1 \rightarrow 3$
 $new.x \leftarrow \max(0, u.x + u.z - m)$
 $new.y \leftarrow u.y$
 $new.z \leftarrow \min(u.x + u.z, m)$
 $path \leftarrow u.path$
 $new.path \leftarrow path.enqueue(\{ new.x, new.y, new.z \})$
 If ($Visited[new] \neq false$) then
 $Q.enqueue(new)$
 $Visited[new] \leftarrow true$

⑨ If ($u.y > 0$ and $u.x < k$) then
 $2 \rightarrow 1$
 $new.x \leftarrow \min(u.x + u.y, k)$
 $new.y \leftarrow \max(0, u.x + u.y - k)$
 $new.z \leftarrow u.z$
 $path \leftarrow u.path$
 $new.path \leftarrow path.enqueue(\{ new.x, new.y, new.z \})$
 If ($Visited[new] \neq false$) then
 $Q.enqueue(new)$
 $Visited[new] \leftarrow true$

⑩ If ($u.y > 0$ and $u.z < m$) then
 $2 \rightarrow 3$
 $new.x \leftarrow u.x$
 $new.y \leftarrow \max(0, u.y + u.z - m)$
 $new.z \leftarrow \min(u.y + u.z, m)$
 $path \leftarrow u.path$
 $new.path \leftarrow path.enqueue(\{ new.x, new.y, new.z \})$
 If ($Visited[new] \neq false$) then
 $Q.enqueue(new)$
 $Visited[new] \leftarrow true$

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⑪ If ($u.z > 0$ and $u.x < k$) then
3 → 1
new.x ← min($u.x + u.z, k$)
new.y ← $u.y$
new.z ← max($0, u.x + u.z - k$)
path ← $u.path$
new.path ← path.enqueue($\{new.x, new.y, new.z\}$)
If ($Visited[new] == false$) then
Q.enqueue(new)
Visited[new] ← true

⑫ If ($u.z > 0$ and $u.y < l$) then
3 → 2
new.x ← $u.x$
new.y ← min($u.y + u.z, l$)
new.z ← max($0, u.y + u.z - l$)
path ← $u.path$
new.path ← path.enqueue($\{new.x, new.y, new.z\}$)
If ($Visited[new] == false$) then
Q.enqueue(new)
Visited[new] ← true

end while

Print ("NOT Find")

return 0

~~procedure InVisit(Visit, new)~~

~~while (Visit $\neq \emptyset$) then~~
~~t ← Visit.dequeue()~~

~~If (t.x = new.x and t.y = new.y and t.z = new.z) then~~
~~return true~~

~~return false.~~

Runtime:

In the worst case,

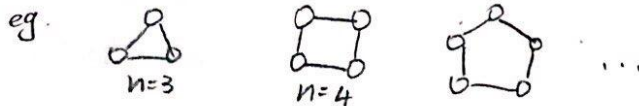
- Each bottle have 4 cases (① Fill ② Empty ③ pour to another bottle ④ pour to another bottle)
So, we have total 12 cases.
- We have $k \times l \times m$ possible nodes in total (k, l, m are all integers)
- So we will dequeue $O(k \times l \times m)$ times.

Overall It takes $O(k \times l \times m)$ time.

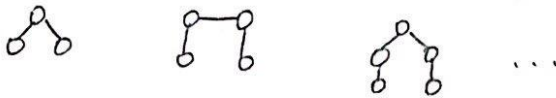
Problem 2

(a). A node is an articulation point iff removing it (and edges through it) disconnect the graph.

For any $n \geq 3$, there will be a connected graph with n edges where all nodes are not an articulation. This is true only when n nodes connected to a circle with n edges.



When we removing 1 edge from the graph, all nodes are still connected with $n-1$ edges.



However, when we try to remove one more edge, there may be a disconnected graph.



So when all connected graphs with $1 \leq n-1$ edges must have at least 1 articulation point to make ~~all~~ not all nodes are ~~the~~ nodes disconnected.

(b).

$$n = 4 \quad m = 6$$

For node a: e.g.

$a \rightarrow b \rightarrow d \rightarrow a$
 $a \rightarrow c \rightarrow d \rightarrow a$
 $a \rightarrow b \rightarrow c \rightarrow a$
 $a \rightarrow b \rightarrow c \rightarrow d \rightarrow a$
 $a \rightarrow c \rightarrow b \rightarrow d \rightarrow a$
 $a \rightarrow b \rightarrow d \rightarrow c \rightarrow a$

are 6 cycles.

And node b, c, d have the same # of cycles as a.

For d: ~~$d \rightarrow a \rightarrow b \rightarrow d$~~
 ~~$d \rightarrow a \rightarrow c \rightarrow d$~~
 ~~$d \rightarrow b \rightarrow c \rightarrow d$~~ 3 cycles

$$\therefore 4 \times 6 = 24 > 2^n = 2^4 = 16 \quad \therefore \# \text{ of cycles} \in O(2^n)$$

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(c)

For any undirected graph $G = (V, E)$, if we have a cycle in this ~~graph~~ graph G with edges e_1, \dots, e_k for k connected nodes, $(v_1 \rightarrow v_2 \rightarrow \dots \rightarrow v_k)$, we can just put the directed edges of graph G'' like $v_1 \rightarrow v_2 \rightarrow \dots \rightarrow v_{k-1}$ but put the last edge $v_{k-1} \leftarrow v_k$ which ~~can~~ ~~not~~ make (v_1, \dots, v_k) not a cycle.

So for each cycle in graph G we have a non-cycle version in G'' , for any undirected graph G , there exists an orientation G'' which is acyclic.

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Problem 3

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(a) Yes.

This is actually a greedy ~~pro~~ algorithm.

Optimal substructure: an optimal solution to the ~~with~~ original problem contains within it optimal solutions to subproblems.

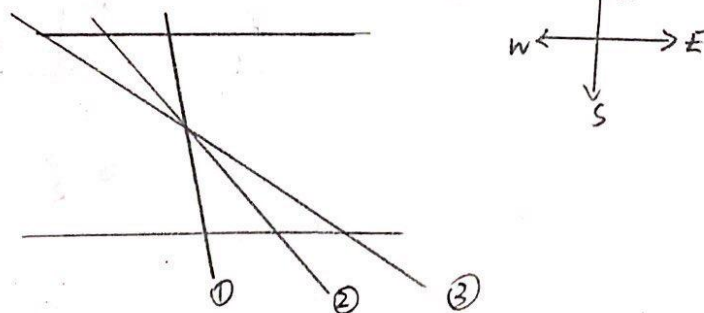
For this case, driving along the only high way ~~at~~ crossing the Australian outlook, try to go as far as I can before refueling.

Each time, I ~~chose~~ make the best choice which can be locally minimum drive as far as I can. Then overall, I will have the minimum stops ~~as well~~. by union all local \approx minimums.

(b) No.

Since, I start a direction between south and east, so the total distance I traveling can be really different according to the direction I choose.

For example,



In this case ①, ②, ③ are all directions between south and east, however, the distance is $① < ② < ③$ which implies that ② and ③ ~~can use more~~ will need more stops or gases to ~~go~~ travel through.

So for this case, I can choose the shortest distance that connects ~~at~~ Morocco and Sudan, and follow along that direction to stop at furthest possible gas station which is still within distance $\leq d$ from the last stop.

Problem 4

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(a) Procedure CheckNest (B_1, B_2, d)

$B_1 = (l_1, l_2, \dots, l_d)$, $B_2 = (m_1, m_2, \dots, m_d)$

d is the dimension of boxes.

Sort both B_1 and B_2 in a non-decreasing order.

IsNest \leftarrow true

for i from 1 to d

if ($B_1[i] > B_2[i]$)

IsNest \leftarrow false

return IsNest.

First sort B_1 and B_2 in a non-decreasing order. Then traversing their length one by one, if there exist length $l_i > m_i$ then, the box $B_1(l_1, l_2, \dots, l_d)$ can not be nested into the box $B_2(m_1, \dots, m_d)$. B_1 can be nested into B_2 only when all length $l_i < m_i$.

(b) procedure DFS (B, n, d)

$B = \{B_1, B_2, \dots, B_n\}$. n is the # of box in B , d is the dimension of boxes.

for i from 1 to n

DFS-visit ($B[i]$, d , n , Q_i)

Q_i .enqueue(Q_i)

procedure DFS-visit (B_i, d, n, Q_i)

Q_i .enqueue(B_i)

for j from 1 to n

if (checkNest ($B_i, B[j]$, d) = true) then

DFS-visit ($B[j]$, d , n , Q_i)

For this problem, we make use of DFS to find the longest sequence of each B_i in $B = \{B_1, B_2, \dots, B_n\}$. So that we can tell their relations easily and store them nicely in upbound.

We will traverse each B_i in B and then for each B_i try to find the longest sequence Q_i , store all Q_i in Q . Then we can tell their relations by getting Q .

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Problem 5

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For this claim in the ~~pro~~ problem:

We get T_i after iteration i and $f_{u,v}(i)$ denote the weight of the heaviest edge on T_i . Then we will do the next iteration $(i+1)$:

We will find the heaviest edge in T_i $e' = (u, v)$

Case I: If $w(e') \leq w(e)$ then we will do nothing. T_{i+1} is the same as T_i

$$\text{So } f_{u,v}(i+1) = f_{u,v}(i)$$

Case II: If $w(e') > w(e)$ then we ~~not~~ remove the edge e' in T_i and ~~add~~ union the edge e with T_i : $w(e) - w(e') < 0$.

$$T_{i+1} = T_i - w(e') + w(e) = T_i + (w(e) - w(e')) < T_i$$

So the heaviest edge $e' = (u, v)$ has been removed from T_i .

The heaviest edge $f_{u,v}(i+1)$ now is less than $f_{u,v}(i) = e' = (u, v)$

$$\therefore f_{u,v}(i+1) < f_{u,v}(i)$$

So the claim is true.

According to the claim above, we can tell this algorithm return a MST.

Since each time we are removing the heaviest edge connected u and v , we are actually reducing its weight, until we get the minimum weight of the edge. For each subproblem we will get its minimum weight, then after union all subproblems, we will get the MST.

Runtime:

Runtime of Kruskal's algorithm, including sorting m edges and $O(m)$ calls to $\text{findCC}()$

$$O(m \log(m)) + O(m \log(n)) = O(m \log(m)) = O(m \log(n)) \text{ for } n-1 \leq m \leq \binom{n}{2}$$

b. In Some Tree for each all back-edges B , ~~and~~ $b = |B|$

Find the ~~lightest~~ heaviest edge each time takes $O(\log b)$ and we need for each b edges which will take $O(b \log b)$ time.

SomeTree would be faster only when $b \in \Omega(n)$, we have at most $b(n-1)$ updates as we will remove at most $b(n-1)$ edges, then we will get MST with $n-1$ edges.