

XII. Wavelet Transform

371

Main References

- [1] R. C. Gonzalez and R. E. Woods, *Digital Image Processing*, Chap. 7, 4th edition, Prentice Hall, New Jersey, 2017. (適合初學者閱讀)

- [2] S. Mallat, *A Wavelet Tour of Signal Processing*, Academic Press, 3rd edition, 2009. (適合想深入研究的人閱讀)
(若對時頻分析已經有足夠的概念，可以由這本書 Chapter 4 開始閱讀)

- [3] I. Daubechies, “Orthonormal bases of compactly supported wavelets,” *Comm. Pure Appl. Math.*, vol. 4, pp. 909-996, Nov. 1988.
- [4] S. Mallat, “Multiresolution approximations and wavelet orthonormal bases of $L^2(\mathbb{R})$,” *Trans. Amer. Math. Soc.*, vol. 315, pp. 69-87, Sept. 1989.
- [5] C. Heil and D. Walnut, “Continuous and discrete wavelet transforms,” *SIAM Rev.*, vol. 31, pp. 628-666, 1989.
- [6] I. Daubechies, “The wavelet transform, time-frequency localization and signal analysis,” *IEEE Trans. Information Theory*, pp. 961-1005, Sept. 1990.
- [7] R. K. Young, *Wavelet Theory and Its Applications*, Kluwer Academic Pub., Boston, 1995.
- [8] S. Qian and D. Chen, *Joint Time-Frequency Analysis: Methods and Applications*, Chapter 4, Prentice-Hall, New Jersey, 1996.
- [9] L. Debnath, *Wavelet Transforms and Time-Frequency Signal Analysis*, Birkhäuser, Boston, 2001.
- [10] B. E. Usevitch, “A Tutorial on Modern Lossy Wavelet Image Compression: Foundations of JPEG 2000,” *IEEE Signal Processing Magazine*, vol. 18, pp. 22-35, Sept. 2001.
- [11] A. Kirsanov, “Wavelets: A mathematical microscope,” 影片：
<https://www.youtube.com/watch?v=jnxqHcObNK4>

(1) Conventional method for signal analysis

- Fourier transform : $X(f) = \int_{-\infty}^{\infty} x(t) e^{-j2\pi f t} dt$
- Cosine and Sine transforms: if $x(t)$ is even and odd
- Orthogonal Polynomial Expansion

傳統方法共通的問題：

(2) Time frequency analysis

For example , STFT

$$X(t, f) = \int_{-\infty}^{\infty} w(t - \tau) x(\tau) e^{-j2\pi f \tau} d\tau$$

Time frequency analysis 共通的問題：

12-A Haar Transform

一種最簡單又可以反應 time-variant spectrum 的 signal representation

8-point Haar transform

$$H[m,n] = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & -1 & -1 & -1 & -1 \\ 1 & 1 & -1 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 & -1 & -1 \\ 1 & -1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix}$$

8-point Haar transform

$$\begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \\ y_5 \\ y_6 \\ y_7 \\ y_8 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & -1 & -1 & -1 & -1 \\ 1 & 1 & -1 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 & -1 & -1 \\ 1 & -1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \\ x_8 \end{bmatrix}$$

y_1 : low frequency component $y_2 \sim y_8$: high frequency component

$$y_1 = x_1 + x_2 + x_3 + x_4 + x_5 + x_6 + x_7 + x_8$$

$$y_2 = x_1 + x_2 + x_3 + x_4 - x_5 - x_6 - x_7 - x_8$$

$$y_3 = x_1 + x_2 - x_3 - x_4$$

$$y_4 = x_5 + x_6 - x_7 - x_8$$

$$y_5 = x_1 - x_2$$

$$N = 2$$

$$\mathbf{H}_2 = \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

$$N = 4$$

$$\mathbf{H}_4 = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & -1 & -1 \\ 1 & -1 & 0 & 0 \\ 0 & 0 & 1 & -1 \end{bmatrix}$$

$$N = 8$$

$$\mathbf{H}_8 = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & -1 & -1 & -1 & -1 \\ 1 & 1 & -1 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 & -1 & -1 \\ 1 & -1 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & -1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & -1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 & -1 \end{bmatrix}$$

General way to generate the Haar transform:

$$\mathbf{H}_{2N} = \begin{bmatrix} \mathbf{H}_N \otimes [1, 1] \\ \mathbf{I}_N \otimes [1, -1] \end{bmatrix} \quad \text{where } \otimes \text{ means the Kronecker product}$$

$$\mathbf{I}_N = \begin{bmatrix} 1 & 0 & \cdots & 0 & 0 \\ 0 & 1 & \cdots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \cdots & 1 & 0 \\ 0 & 0 & \cdots & 0 & 1 \end{bmatrix}$$

$$\mathbf{A} \otimes \mathbf{B} = \begin{bmatrix} a_{1,1}\mathbf{B} & a_{1,2}\mathbf{B} & \cdots & a_{1,N}\mathbf{B} \\ a_{2,1}\mathbf{B} & a_{2,2}\mathbf{B} & \cdots & a_{2,N}\mathbf{B} \\ \vdots & \vdots & \ddots & \vdots \\ a_{M,1}\mathbf{B} & a_{M,2}\mathbf{B} & \cdots & a_{M,N}\mathbf{B} \end{bmatrix}$$

$$\text{where } \mathbf{A} = \begin{bmatrix} a_{1,1} & a_{1,2} & \cdots & a_{1,N} \\ a_{2,1} & a_{2,2} & \cdots & a_{2,N} \\ \vdots & \vdots & \ddots & \vdots \\ a_{M,1} & a_{M,2} & \cdots & a_{M,N} \end{bmatrix}$$

$N = 2^k$ 時

$$\mathbf{H} = \begin{bmatrix} \phi \\ h_{0,1} \\ h_{1,1} \\ h_{1,2} \\ \vdots \\ \vdots \\ h_{k-1,1} \\ h_{k-1,2} \\ \vdots \\ h_{k-1,2^{k-1}} \end{bmatrix}$$

\mathbf{H} 除了第 1 個row 為 $\underbrace{\phi = [1 \ 1 \ 1 \ \cdots \ 1]}_{N \text{ 個 } 1}$ 以外

第 $2^p + q$ 個row 為 $h_{p,q}[n]$

$$p = 0, 1, \dots, k-1, \quad q = 1, 2, \dots, 2^p$$

$$k = \log_2 N$$

$$h_{p,q}[n] = 1 \quad \text{when } (q-1)2^{k-p} < n \leq (q-1/2)2^{k-p}$$

$$h_{p,q}[n] = -1 \quad \text{when } (q-1/2)2^{k-p} < n \leq q2^{k-p}$$

- Inverse 2^k -point Haar Transform

$$\mathbf{H}^{-1} = \mathbf{H}^T \mathbf{D}$$

$$D[m, n] = 0 \text{ if } m \neq n$$

$$D[1, 1] = 2^{-k}, \quad D[2, 2] = 2^{-k},$$

$$D[n, n] = 2^{-k+p} \text{ if } 2^p < n \leq 2^{p+1}$$

When $k = 3$,

$$\mathbf{D} = \begin{bmatrix} 1/8 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1/8 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1/4 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1/4 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1/2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1/2 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1/2 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1/2 \end{bmatrix}$$

12-B Characteristics of Haar Transform

380

- (1) No multiplications
- (2) Input 和 Output 點數相同
- (3) 頻率只分兩種：低頻 (全為 1) 和高頻 (一半為 1，一半為 -1)
- (4) 可以分析一個信號的 localized feature
- (5) **Very fast**, but not accurate

Example:

$$\mathbf{H} \begin{bmatrix} 1.2 \\ 1.2 \\ 1.8 \\ 0.8 \\ 2 \\ 2 \\ 1.9 \\ 2.1 \end{bmatrix} = \begin{bmatrix} 13 \\ -3 \\ -0.2 \\ 0 \\ 0 \\ 1 \\ 0 \\ -0.2 \end{bmatrix}$$

Transforms	Running Time	terms required for $\text{NRMSE} < 10^{-5}$
DFT	9.5 sec	43
Haar Transform	0.3 sec	128

References

- A. Haar, “Zur theorie der orthogonalen funktionensysteme ,” *Math. Annal.*, vol. 69, pp. 331-371, 1910.
- H. F. Harmuth, *Transmission of Information by Orthogonal Functions*, Springer-Verlag, New York, 1972.

The Haar Transform is closely related to the Wavelet transform (especially the discrete wavelet transform).

12-C History of the Wavelet Transform

- 1910, Haar families.
- 1981, Morlet, wavelet concept.
- 1984, Morlet and Grossman, "wavelet".
- 1985, Meyer, "orthogonal wavelet".
- 1987, International conference in France.
- 1988, Mallat and Meyer, multiresolution.
- 1988, Daubechies, compact support orthogonal wavelet.
- 1989, Mallat, fast wavelet transform.
- 1990s, Discrete wavelet transforms
- 1999, Directional wavelet transform
- 2000, JPEG 2000

12-D Three Types of Wavelets

Wavelet 以 continuous / discrete 來分，有 3 種

	Input	Output	Name
Type 1	Continuous	Continuous	Continuous Wavelet Transform
Type 2	Continuous	Discrete	有時被稱為 discrete wavelet transform，但其實是 continuous wavelet transform with discrete coefficients
Type 3	Discrete	Discrete	Discrete Wavelet Transform

比較：Fourier
transform 有四種

12-E Continuous Wavelet Transform (WT)

384

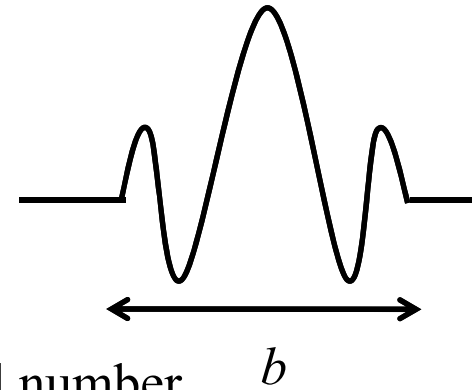
Definition:
$$X_w(a, b) = \frac{1}{\sqrt{b}} \int_{-\infty}^{\infty} x(t) \psi\left(\frac{t-a}{b}\right) dt$$

$x(t)$: input, $\psi(t)$: mother wavelet

a : location, b : scaling

a is any real number, b is any positive real number

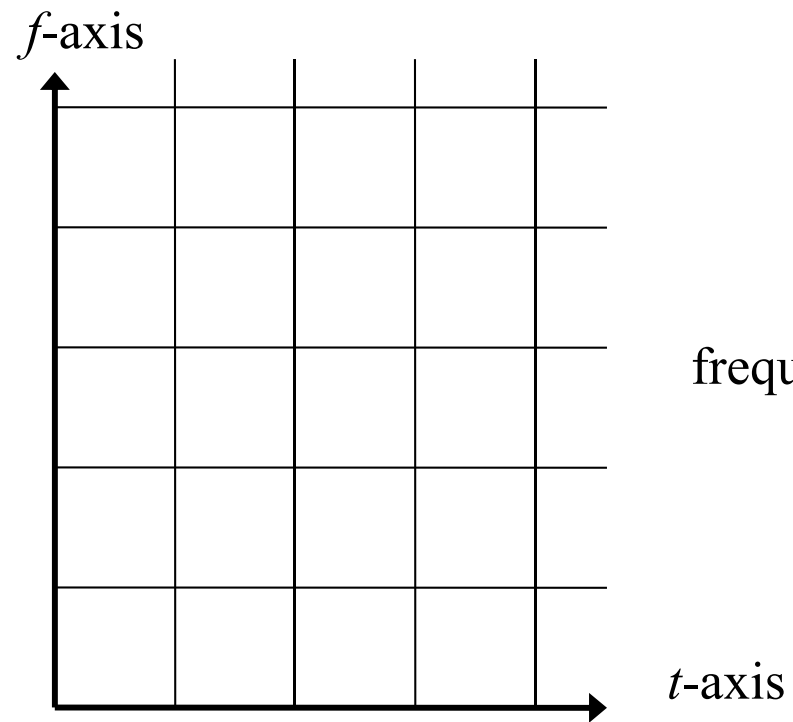
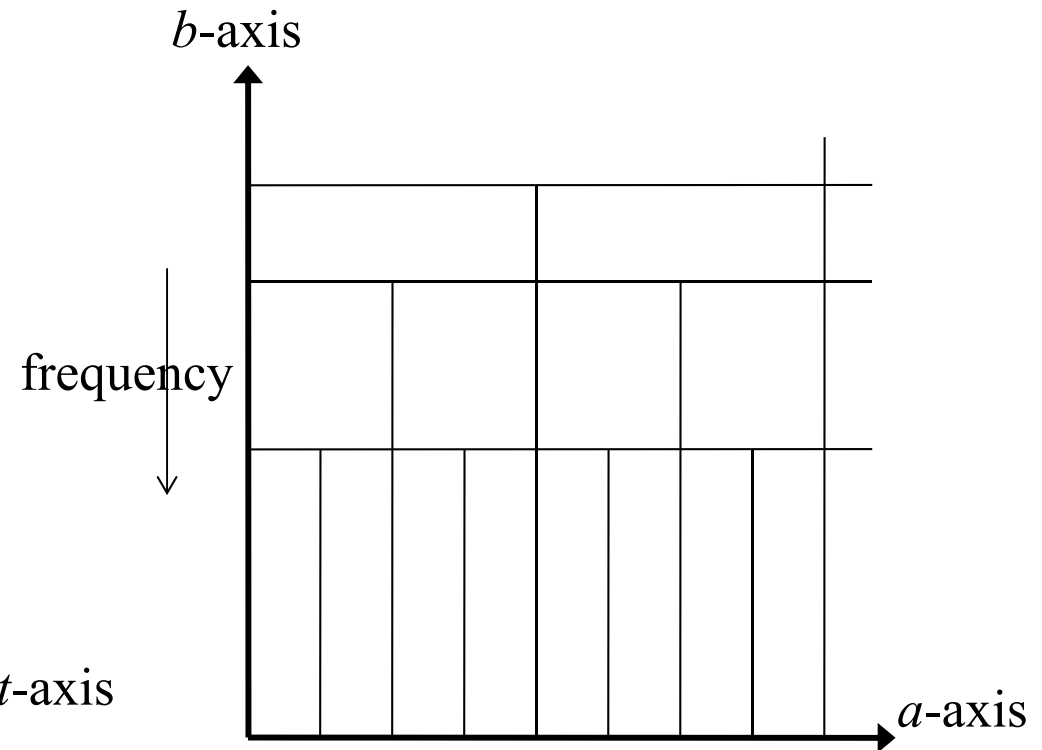
$a \in (-\infty, \infty)$, $b \in (0, \infty)$.



Compare with time-frequency analysis:

location + modulation

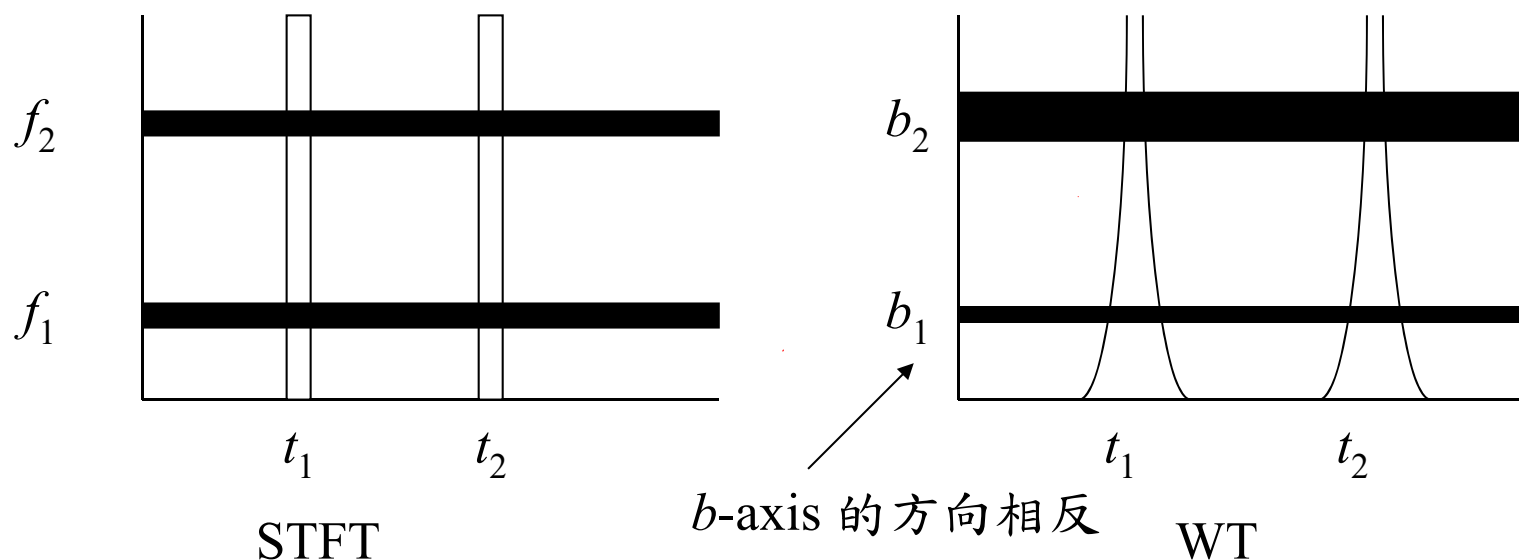
Gabor Transform
$$G_x(t, f) = \int_{-\infty}^{\infty} e^{-\pi(\tau-t)^2} e^{-j2\pi f\tau} x(\tau) d\tau$$

Gabor**Wavelet transform**

$$X_w(a, b) = \frac{1}{\sqrt{b}} \int_{-\infty}^{\infty} x(t) \psi\left(\frac{t-a}{b}\right) dt \quad a: \text{location}, \quad b: \text{scaling}$$

- The resolution of the wavelet transform is invariant along a (location-axis) but variant along b (scaling axis).

If $x(t) = \delta(t - t_1) + \delta(t - t_2) + \exp(j2\pi f_1 t) + \exp(j2\pi f_2 t)$,

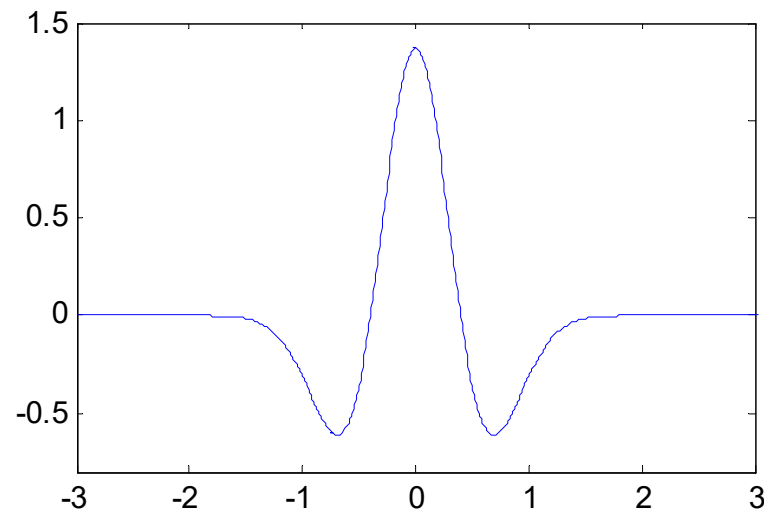


12-F Mother Wavelet

There are many ways to choose the mother wavelet. For example,

- Haar basis
- Mexican hat function $\psi(t) = \frac{2^{5/4}}{\sqrt{3}}(1 - 2\pi t^2)e^{-\pi t^2}$

In fact, the Mexican hat function is the 2nd order derivation of the Gaussian function.

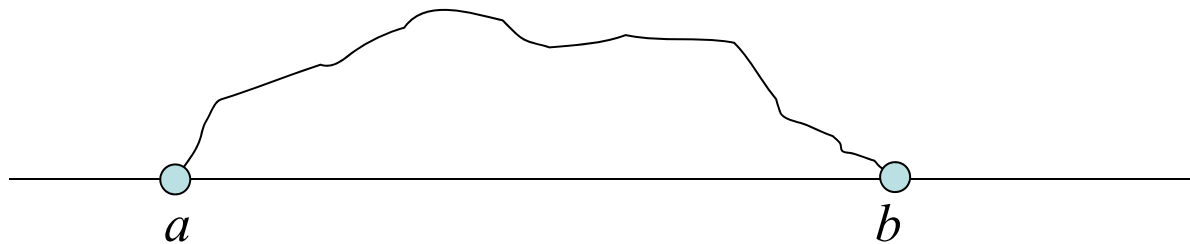


Constraints for the mother wavelet:

(1) Compact Support

support: the region where a function is not equal to zero

compact support: the width of the support is not infinite



(2) Real

(3) Even Symmetric or Odd Symmetric

(4) Vanishing Moments

k^{th} moment: $m_k = \int_{-\infty}^{\infty} t^k \psi(t) dt$

If $m_0 = m_1 = m_2 = \dots = m_{p-1} = 0$ but $m_p \neq 0$, then $\psi(t)$ has p vanishing moments.

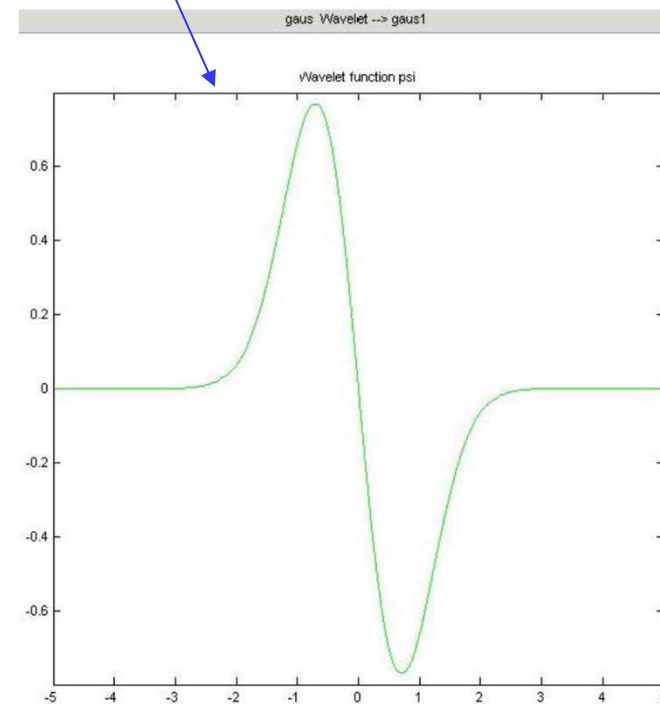
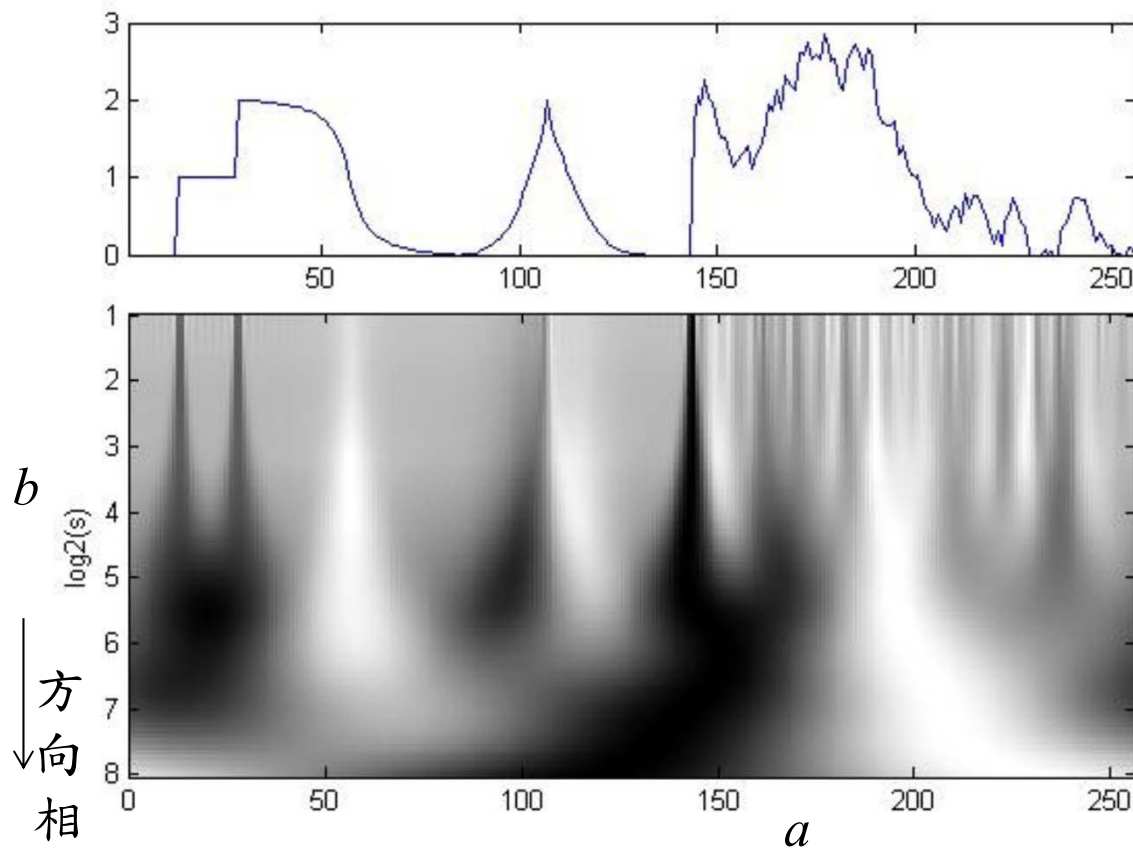
Vanishing moment 越高，經過內積後被濾掉的低頻成分越多

Question：為什麼要求 $\int_{-\infty}^{\infty} \psi(t) dt = 0$ ？

註：感謝 2006 年修課的張育思同學

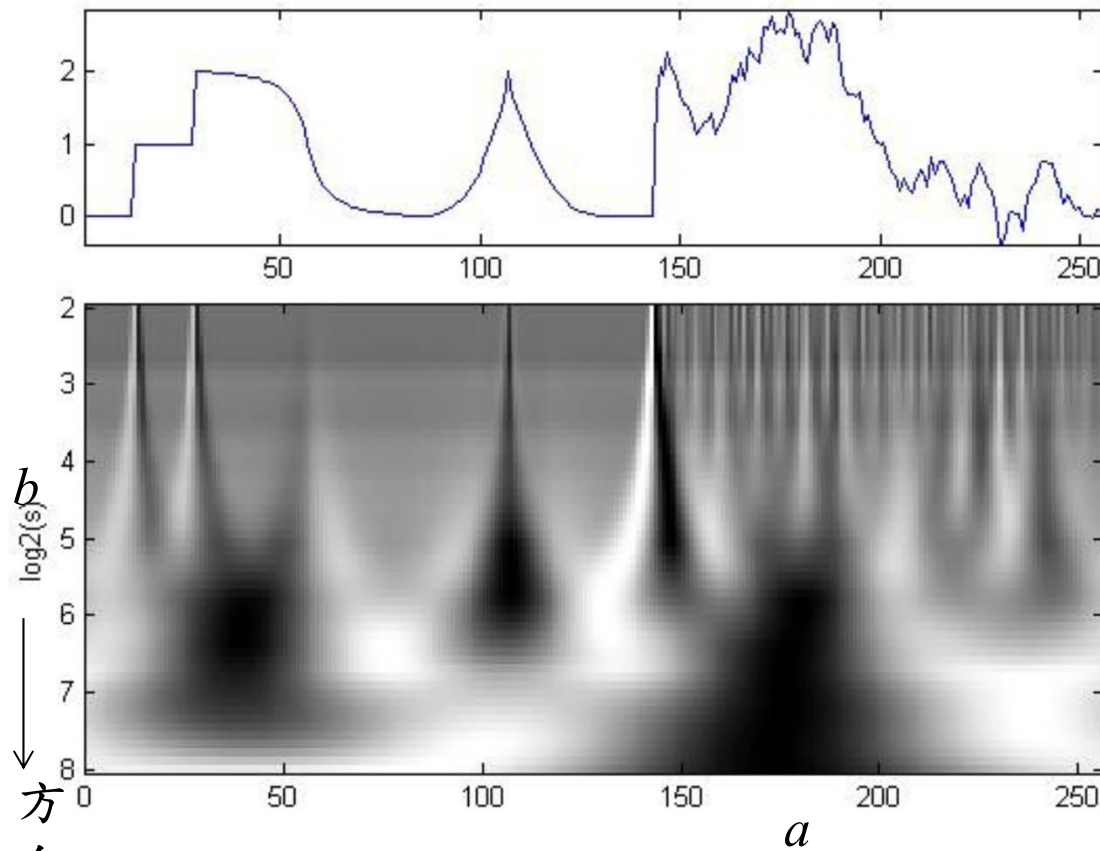
vanishing moment = 1

the 1st order derivation of
the Gaussian function



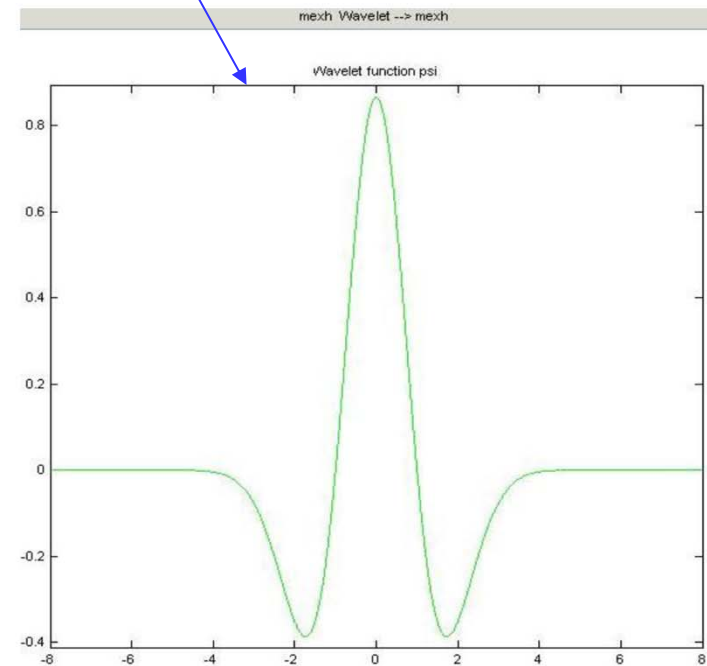
[Ref] S. Mallat, *A Wavelet Tour of Signal Processing*, 2nd Ed., Academic Press, San Diego, 1999.

vanishing moment = 2



b
 $\log_2(s)$
方向相反

391
the 2nd order derivation of
the Gaussian function



Similarly, when

$$\psi(t) = \frac{d^p}{dt^p} e^{-\pi t^2}$$

the vanishing moment is p

(5) Admissibility Criterion

$$C_{\psi} = \int_0^{\infty} \frac{|\Psi(f)|^2}{|f|} df < \infty, \text{ where } \Psi(f) \text{ is the Fourier transform of } \psi(t)$$

For reversible

[Ref] A. Grossman and J. Morlet, “Decomposition of hardy functions into square integrable wavelets of constant shape,” *SIAM J. Appl. Math.*, vol. 15, pp. 723-736, 1984.

12-G Inverse Wavelet Transform

394

$$x(t) = \frac{1}{C_\psi} \int_0^\infty \int_{-\infty}^\infty \frac{1}{b^{5/2}} X_w(a, b) \psi\left(\frac{t-a}{b}\right) da db$$

where $C_\psi = \int_0^\infty \frac{|\Psi(f)|^2}{|f|} df < \infty$

simplified $x(t) \simeq \frac{1}{C_\psi} \int_0^\infty \int_{t-bt_0}^{t+bt_0} \frac{1}{b^{5/2}} X_w(a, b) \psi\left(\frac{t-a}{b}\right) da db$ if $\psi(t) \cong 0$ for $|t| > t_0$

(Proof): Since $X_w(a, b) = x(a) * \frac{1}{\sqrt{b}} \psi\left(\frac{-a}{b}\right)$

if $y(t) = \frac{1}{C_\psi} \int_0^\infty \int_{-\infty}^\infty \frac{1}{b^{5/2}} X_w(a, b) \psi\left(\frac{t-a}{b}\right) da db$

then $y(t) = \frac{1}{C_\psi} \int_0^\infty x(t) * \psi\left(\frac{-t}{b}\right) * \psi\left(\frac{t}{b}\right) \frac{db}{b^3}$

$$y(t) = \frac{1}{C_\psi} \int_0^\infty x(t) * \psi\left(\frac{-t}{b}\right) * \psi\left(\frac{t}{b}\right) \frac{db}{b^3}$$

$$Y(f) = \frac{1}{C_\psi} \int_0^\infty X(f) \Psi(-bf) \Psi(bf) \frac{db}{b} \quad \text{where} \quad \begin{aligned} Y(f) &= FT[y(t)] \\ X(f) &= FT[x(t)] \\ \Psi(f) &= FT[\psi(t)] \end{aligned}$$

If $\psi(t)$ is real, $\Psi(-f) = \Psi^*(f)$, $\Psi(-bf) \Psi(bf) = \Psi^*(bf) \Psi(bf) = |\Psi(bf)|^2$

$$\begin{aligned} Y(f) &= X(f) \frac{1}{C_\psi} \int_0^\infty |\Psi(bf)|^2 \frac{db}{b} \\ &= X(f) \frac{1}{C_\psi} \int_0^\infty |\Psi(f_1)|^2 \frac{df_1}{bf} \quad (f_1 = bf, df_1 = fdb) \\ &= X(f) \frac{1}{C_\psi} \int_0^\infty |\Psi(f_1)|^2 \frac{df_1}{f_1} \\ &= X(f) \end{aligned}$$

Therefore, $y(t) = x(t)$.

12-H Scaling Function

定義 scaling function 為

$$\phi(t) = \int_{-\infty}^{\infty} \Phi(f) e^{j2\pi f t} df$$

where $|\Phi(f)|^2 = \int_f^{\infty} \frac{|\Psi(f_1)|^2}{|f_1|} df_1$ for $f > 0$, $\Phi(-f) = \Phi^*(f)$

$\phi(t)$ is usually a lowpass filter (Why?)

修正型的 Wavelet transform

$$(1) \quad X_w(a, b) = \frac{1}{\sqrt{b}} \int_{-\infty}^{\infty} x(t) \psi\left(\frac{t-a}{b}\right) dt$$

a is any real number, $0 < b < b_0$

$$(2) \quad LX_w(a, b_0) = \frac{1}{\sqrt{b_0}} \int_{-\infty}^{\infty} x(t) \phi\left(\frac{t-a}{b_0}\right) dt$$

reconstruction:

$$x(t) = \frac{1}{C_\psi} \left[\int_0^{b_0} \int_{-\infty}^{\infty} \frac{1}{b^{5/2}} X_w(a, b) \psi\left(\frac{t-a}{b}\right) da db + \int_{-\infty}^{\infty} \frac{1}{b_0^{3/2}} LX_w(a, b_0) \phi\left(\frac{t-a}{b_0}\right) da \right]$$

由 b_0 至 ∞ 的積分被第二項取代

If $\psi(t) \cong 0$ for $|t| > t_0$, $\phi(t) \cong 0$ for $|t| > t_1$

$$x(t) \cong \frac{1}{C_\psi} \left[\int_0^{b_0} \int_{t-bt_0}^{t+bt_0} \frac{1}{b^{5/2}} X_w(a, b) \psi\left(\frac{t-a}{b}\right) da db + \int_{t-b_0t_1}^{t+b_0t_1} \frac{1}{b_0^{3/2}} LX_w(a, b_0) \phi\left(\frac{t-a}{b_0}\right) da \right]$$

(Proof): If $y_1(t) = \frac{1}{C_\psi} \int_0^{b_0} \int_{-\infty}^{\infty} \frac{1}{b^{5/2}} X_w(a, b) \psi\left(\frac{t-a}{b}\right) da db$

$$y_2(t) = \frac{1}{C_\psi} \int_{-\infty}^{\infty} \frac{1}{b_0^{3/2}} L X_w(a, b_0) \phi\left(\frac{t-a}{b_0}\right) da$$

$$\begin{aligned} Y_1(f) &= X(f) \frac{1}{C_\psi} \int_0^{b_0} |\Psi(bf)|^2 \frac{db}{b} \\ &= X(f) \frac{1}{C_\psi} \int_0^{b_0 f} |\Psi(f_1)|^2 \frac{df_1}{f_1} \end{aligned}$$

(from the similar process on
pages 394 and 395)

$$y_2(t) = \frac{1}{b_0^2 C_\psi} x(t) * \phi\left(\frac{-t}{b_0}\right) * \phi\left(\frac{t}{b_0}\right)$$

$$\begin{aligned} Y_2(f) &= X(f) \frac{1}{C_\psi} \Phi(-b_0 f) \Phi(b_0 f) = X(f) \frac{1}{C_\psi} \Phi^*(b_0 f) \Phi(b_0 f) \\ &= X(f) \frac{1}{C_\psi} |\Phi(b_0 f)|^2 \\ &= X(f) \frac{1}{C_\psi} \int_{b_0 f}^{\infty} \frac{|\Psi(f_1)|^2}{|f_1|} df_1 \end{aligned}$$

Key process



Therefore, if $y(t) = y_1(t) + y_2(t)$,

$$\begin{aligned}
 Y(f) &= Y_1(f) + Y_2(f) \\
 &= X(f) \frac{1}{C_\psi} \int_0^{b_0 f} |\Psi(f_1)|^2 \frac{df_1}{f_1} + X(f) \frac{1}{C_\psi} \int_{b_0 f}^{\infty} |\Psi(f_1)|^2 \frac{df_1}{f_1} \\
 &= X(f) \frac{1}{C_\psi} \int_0^{\infty} |\Psi(f_1)|^2 \frac{df_1}{f_1} \\
 &= X(f)
 \end{aligned}$$

$$y(t) = x(t)$$

12-I Property

400

(1) real input \longrightarrow real output

(2) If $x(t) \longrightarrow X_w(a, b)$, then $x(t - \tau) \longrightarrow X_w(a - \tau, b)$,

(3) If $x(t) \longrightarrow X_w(a, b)$, then $x(t / \sigma) \longrightarrow \sqrt{\sigma} X_w(a / \sigma, b / \sigma)$

(4) Parseval's Theory:

$$\int |x(t)|^2 dt = \frac{1}{C} \int_0^\infty \int_{-\infty}^\infty \frac{1}{b^2} |X_w(a, b)|^2 da db$$

12-J Scalogram

Scalogram 即 Wavelet transform 的絕對值平方

$$Sc_x(a, b) = |X_w(a, b)|^2 = \frac{1}{|b|} \left| \int_{-\infty}^{\infty} x(t) \psi\left(\frac{t-a}{b}\right) dt \right|^2$$

有時，會將 Scalogram 定義成

$$Sc_x(a, \zeta) = \left| X_w\left(a, \frac{\eta}{\zeta}\right) \right|^2$$

$$\eta = \frac{\int_0^{\infty} f |\Psi(f)|^2 df}{\int_0^{\infty} |\Psi(f)|^2 df}$$

$$\Psi(f) = \int_{-\infty}^{\infty} \psi(t) e^{-j2\pi f t} dt$$

Problems of the continuous WT

- (1) hard to implement
- (2) hard to find $\phi(t)$

Continuous WT is good in mathematics.

In practical, the discrete WT and the continuous WT with discrete coefficients are more useful.

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莊炳煌 (語音信號處理，2006年當選院士)
黃煦濤 (圖形辨識，2006年當選院士)
舒維都 (信號處理與人工智慧，2006年當選院士)
李雄武 (電磁學，2006年當選院士)
孟懷縈 (無線通信與信號處理，2010年當選院士)
李澤元 (電力電子，2012年當選院士)
馬佐平 (微電子，2012年當選院士)
張懋中 (電子元件，2012年當選院士)
林本堅 (積體電路與傅氏光學，2014年當選院士)
陳陽閏 (高速半導體，2016年當選院士)
王康隆 (自旋電子學，2016年當選院士)
李琳山 (語音訊號處理，2016年當選院士)
戴聿昌 (微積電系統與醫工，2016年當選院士)

張世富 (多媒體信號處理，2018年當選院士)

盧志遠 (半導體技術，2018年當選院士)

吳詩聰 (光電技術，2022年當選院士)

郭宗杰 (多媒體信號處理，2022年當選院士)

陳自強 (半導體技術，2022年當選院士)

余振華 (半導體技術，2024年當選院士)

李建平 (半導體技術，2024年當選院士)

金智潔 (半導體技術，2024年當選院士)

註：歷年中研院院士當中，屬於電機+資訊相關領域的有44人，佔了全部的 8 %

其中和通信、信號處理、影像處理相關的有10位，大多是2004年以後當選院士