

## Ordering the sample space for p-value and confidence interval computation in group sequential trials with delayed outcome

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## Group sequential design (GSD)

Statistical framework to perform repeated significance testing:

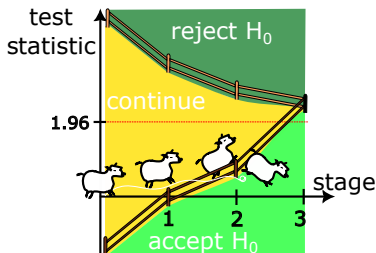
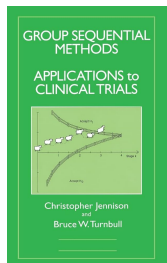
- early stopping for efficacy or futility

Uses sets of boundaries to control type I and type II error

- boundaries evaluated once the data is collected

Key result: test statistics are asymptotically multivariate normal

- integration of the multivariate Gaussian density



## An example of trial

**Endpoint:** clinical score measured at week 0, 6, 12  $Y(t)$

**Exposure:** drug vs. placebo  $E$

**Estimand:**  $\mathbb{E}[Y(12)|E=1] - \mathbb{E}[Y(12)|E=0]$   $\theta$

**Design:** 2 interim analyses and a final analysis  $k \in \{1, 2, 3\}$

- maximum planned information  $\mathcal{I}_{\max}$
- sample size at each stage  $n_k$
- ...

**Model:** mixed model each stage

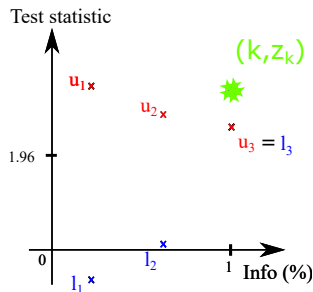
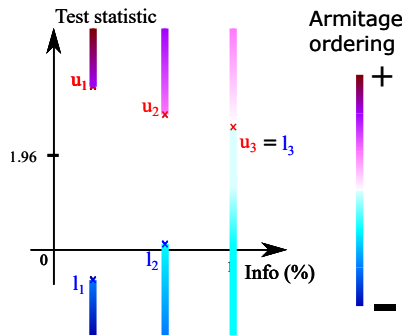
- estimate and test statistic  $\hat{\theta}_k, Z_k$
- current information  $\sigma_{\hat{\theta}_k}^{-2}$   $\mathcal{I}_k$
- current information fraction  $\mathcal{I}_k/\mathcal{I}_{\max}$  Info (%)

## Estimating p-values

Suppose we stop at stage  $k$  with a test statistic  $z_k$ .

**P-value:** Probability to obtain a result that is at least as extreme as the observed result under the null:

$$p = \mathbb{P}_0[(\kappa, Z_\kappa) \succeq (k, z_k)] \text{ where } \kappa = \min(k : Z_k \notin [l_k, u_k])$$

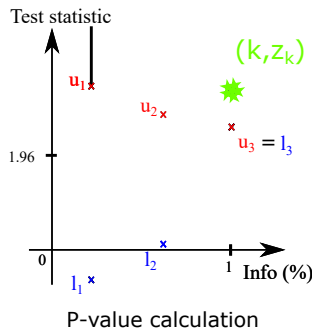
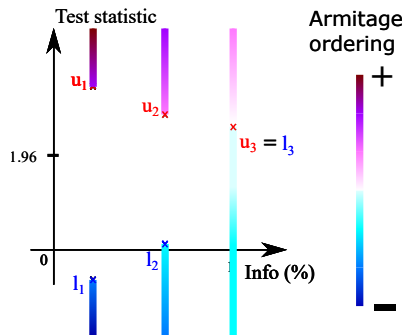


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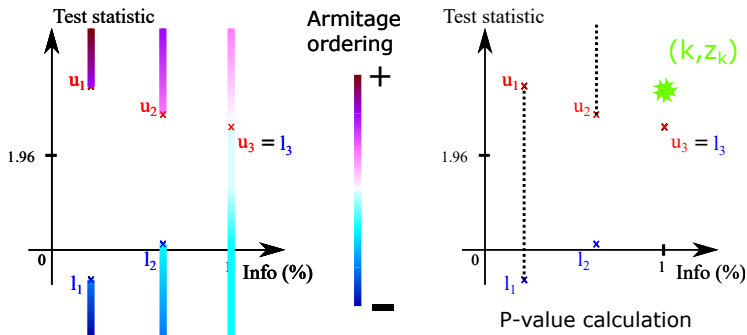


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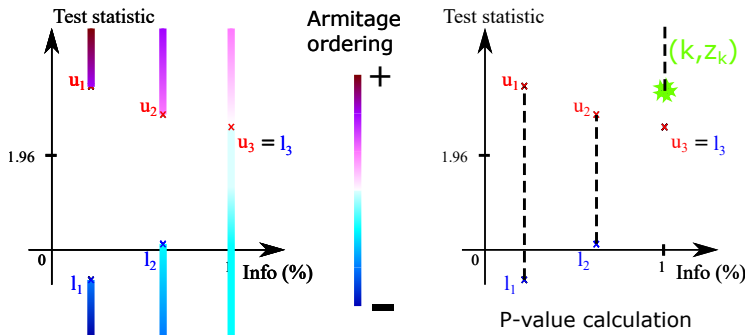


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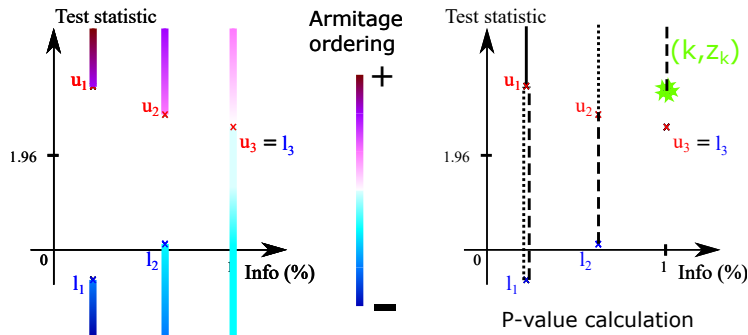


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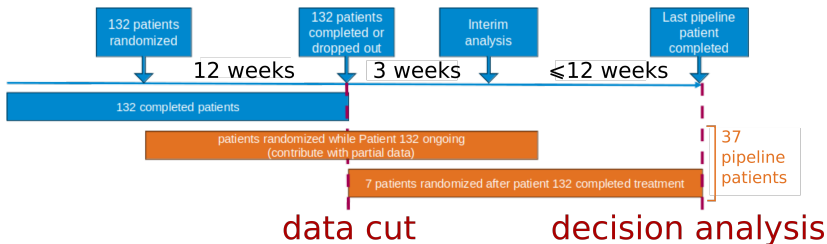
## Need for extending GSD methodology

GSD is a well established methodology

... for outcomes measured immediately after treatment.

In practice, delayed outcome are common

- leading to incomplete data at interim



## Adding a decision analysis

### At the k-th interim:

$u_k$  efficacy boundary

$l_k$  futility boundary

$\mathcal{I}_k$  information

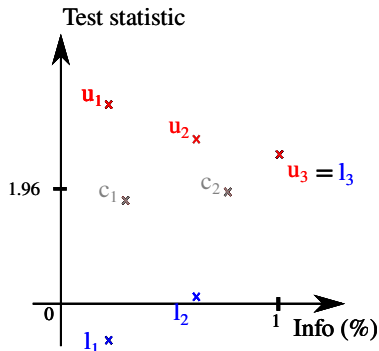
$Z_k$  test statistic

### At the k-th decision:

$c_k$  decision boundary

$\tilde{\mathcal{I}}_k$  information

$\tilde{Z}_k$  test statistic



Hampson and Jennison (2013); Jennison (2022) define the boundaries to control the type 1 and type 2 error.

- Method 1-3: Corine Baayen's talk (Friday morning)

## Adding a decision analysis

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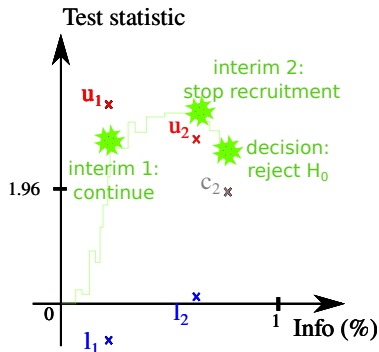
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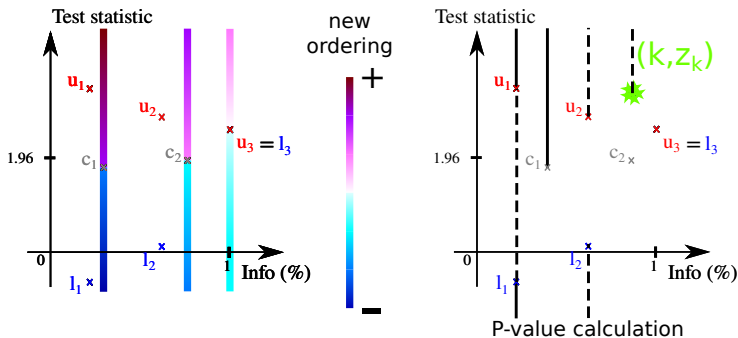
$\tilde{Z}_k$  test statistic



Hampson and Jennison (2013); Jennison (2022) define the boundaries to control the type 1 and type 2 error.

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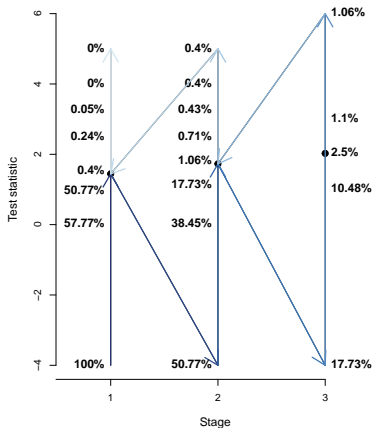
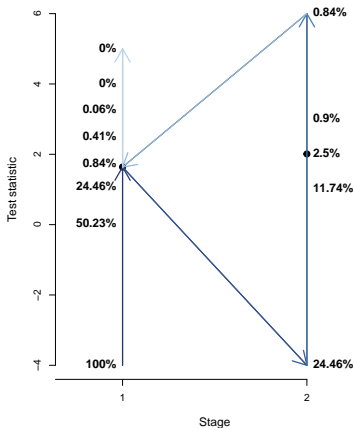
# What is more extreme? (Hampson and Jennison, 2013)



$$p = \mathbb{P}_0 \left[ \left( \kappa, \tilde{Z}_\kappa \right) \succeq (k, \tilde{z}_k) \right]$$

- ✓ p-values agree with boundaries and spent type 1 error
- ✓ continuous p-values taking all values between 0 and 1
- ✓ only depends on current and past information
- does not depend on test statistic(s) at interim

## P-value space (Method 1, binding)



- 2 stage:  $\mathcal{I}_1^0 = 58\%$ ,  $\tilde{\mathcal{I}}_1^0 = 68\%$
- 3 stages:  $\mathcal{I}_1^0 = 40\%$ ,  $\tilde{\mathcal{I}}_1^0 = 50\%$ ,  $\mathcal{I}_2^0 = 65\%$ ,  $\tilde{\mathcal{I}}_2^0 = 75\%$

Simulation results ( $n \approx 500$ , 10000 datasets)

Binding futility	Method 1	
	2 stages	3 stages
Type 1 error	2.42%	2.50%
Power	81.00%	80.87%
CI=[NA;NA]	0	0.01%
Coverage	94.85%	95.30%

**Confidence interval:**  $[\hat{\theta}_L; \hat{\theta}_U]$

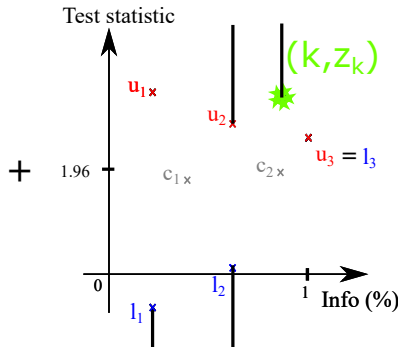
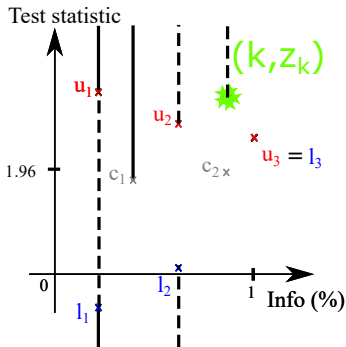
Suppose we stop at stage  $k$  with test statistics  $z_k$  and  $\tilde{z}_k$

Find  $\hat{\theta}_L$  solving  $\mathbb{P}_{\hat{\theta}_L} \left[ \left( \kappa, \tilde{Z}_\kappa \right) \succeq (k, \tilde{z}_k) \right] = \alpha/2$

Find  $\hat{\theta}_U$  solving  $\mathbb{P}_{\hat{\theta}_U} \left[ \left( \kappa, \tilde{Z}_\kappa \right) \succeq (k, \tilde{z}_k) \right] = 1 - \alpha/2$

## Modification for non-binding futility

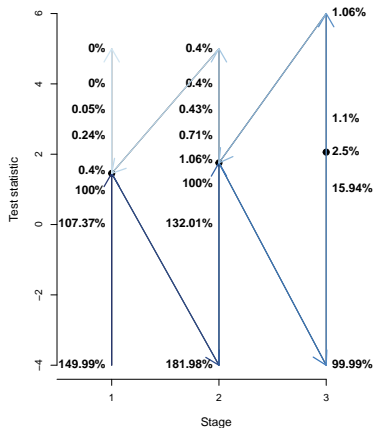
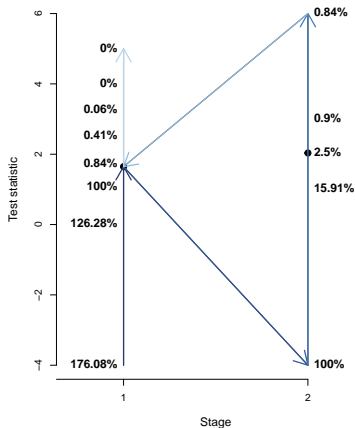
- continuation is possible even when  $z_k < l_k$



Conservative p-value: some path are counted twice, e.g.

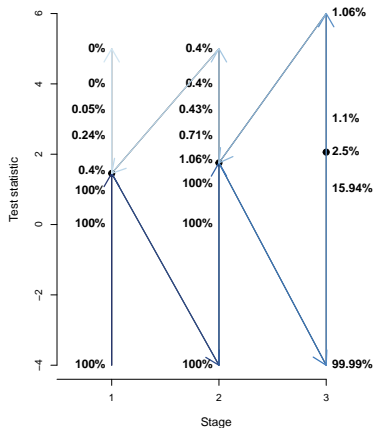
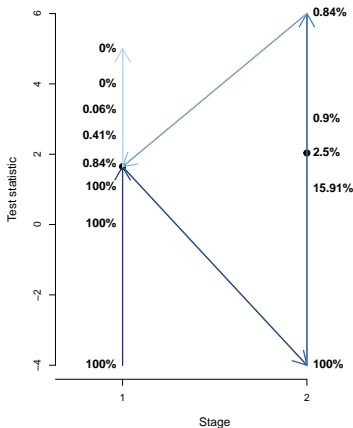
- stage 1 stop for futility and conclude efficacy
- stage 1 continue despite futility, conclude efficacy at stage 2

# P-value space (Method 1, non-binding)





# P-value space (Method 1, non-binding)



After numerical integration, p-values greater than 1 are set to 1.

## Simulation results ( $n \approx 500$ , 10000 datasets)

non-Binding futility	Method 1	
	2 stages	3 stages
Type 1 error	2.53%	2.54%
Power	80.50%	80.52%
CI=[NA;NA]	<b>5.93%</b>	<b>8.11%</b>
Coverage	95.92%	96.09%

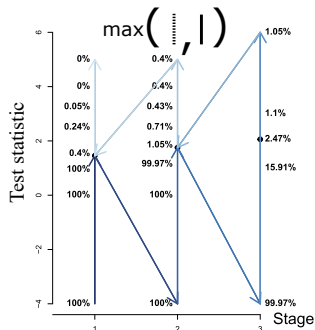
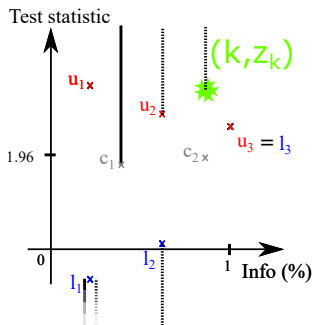
When rejecting early for futility,

$$x \mapsto \mathbb{P}_x \left[ \left( \kappa, \tilde{Z}_\kappa \right) \succeq (k, \tilde{z}_k) \right]$$

is essentially constant equal to 1 so the CI cannot be estimated.

## A possible improvement?


Instead of summing the rejection probability of duplicated paths, evaluate the maximal rejection probability.



- all p-values  $\in [0, 1]$  otherwise very similar values

## Conclusion

P-values and CI can be estimated in a GSD with delayed outcome

- extension of Armitage ordering
- median unbiased estimator also available
- implemented in DeLayedGSD,  package available on [Github](#)

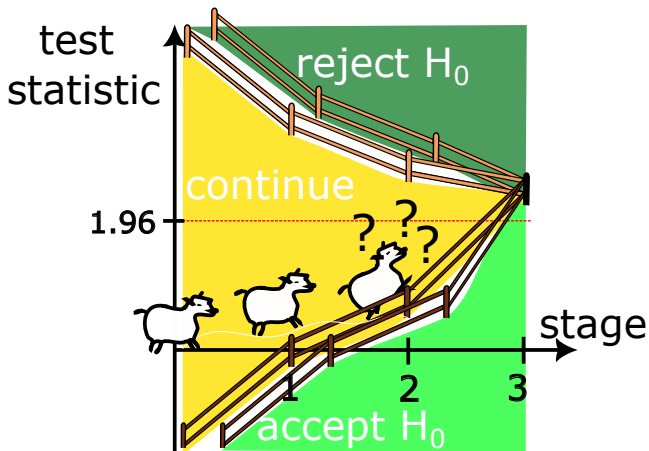
Difficulties:

- non-binding futility stopping rule
  - conservative p-value
  - no reliable CI when concluding early for futility
- constraints on boundaries (e.g.  $c_k \geq 1.96$ )

More to come:

- Corine Baayen's talk Friday morning
- Upcoming paper

## Questions



## Reference I

- Agency, E. M. (2007). Reflection paper on methodological issues in confirmatory clinical trials planned with an adaptive design.
- Hampson, L. V. and Jennison, C. (2013). Group sequential tests for delayed responses (with discussion). *Journal of the Royal Statistical Society Series B: Statistical Methodology*, 75(1):3–54.
- Jennison, C. (2022). The Design of Group Sequential and Adaptive Clinical Trials. *Course Slides*.

## Planned information and sample size

$$\mathcal{I}_{\max} = R \frac{(\Phi^{-1}(1 - \alpha) + \Phi^{-1}(1 - \beta))^2}{\theta_0^2}$$

where  $\theta_0$  is the expected effect under the alternative hypothesis  
 $\Phi$  is the cumulative distribution function of a standard normal  
distribution.  $R$  is the inflation factor which depends on  $\alpha_1, \alpha_2, \alpha,$   
 $\beta_1, \beta_2, \beta$ .

Denoting by  $n$  the sample size in one arm and  $nw$  in the other arm:

$$n = R(1 + 1/w)\sigma^2 \frac{(\Phi^{-1}(1 - \alpha) + \Phi^{-1}(1 - \beta))^2}{\theta_0^2}$$

where  $\sigma^2$  is the variance of the outcome.

## Efficient estimators have canonical covariance

Suppose  $\mathbb{Cov} [\hat{\theta}_1, \hat{\theta}_2] \neq \mathbb{Var} [\hat{\theta}_1]$  so  $\mathbb{Cov} [\hat{\theta}_1 - \hat{\theta}_2, \hat{\theta}_2] \neq 0$ .

Let  $\varepsilon$  be a small number of sign opposite to  $\mathbb{Cov} [\hat{\theta}_1 - \hat{\theta}_2, \hat{\theta}_2]$ .

Consider a new estimator:

- $\tilde{\theta}_2 = \hat{\theta}_2 + \varepsilon(\hat{\theta}_1 - \hat{\theta}_2)$

$$\mathbb{E} [\tilde{\theta}_2] = \theta + \varepsilon(\theta - \theta) = \theta$$

$$\begin{aligned}\mathbb{Var} [\tilde{\theta}_2] &= \mathbb{Var} [\hat{\theta}_2] + \varepsilon^2 \mathbb{Var} [\hat{\theta}_1 - \hat{\theta}_2] + 2\varepsilon \mathbb{Cov} [\hat{\theta}_1 - \hat{\theta}_2, \hat{\theta}_2] \\ &\approx \mathbb{Var} [\hat{\theta}_2] + 2\varepsilon \mathbb{Cov} [\hat{\theta}_1 - \hat{\theta}_2, \hat{\theta}_2] \\ &< \mathbb{Var} [\hat{\theta}_1]\end{aligned}$$

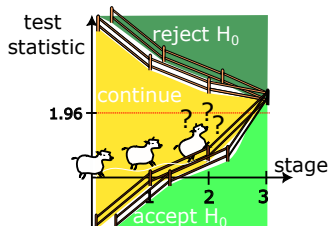
contradicting that  $\hat{\theta}_2$  is efficient.



## EMA (Agency, 2007)

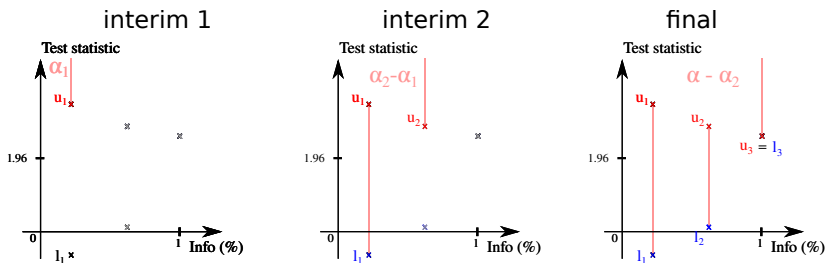
"If a trial is to be terminated as a result of an interim analysis it is always important to carry out an additional analysis including all of these further patients that did not contribute to the interim analysis.

It may be that when this analysis is carried out, the null hypothesis can no longer be rejected [...]. In such a situation, it is accepted regulatory practice to base decision making on the final results of the trial (not the interim analysis)."



## Estimating boundaries

Boundaries should be such that the probability of rejection under the null equals the type 1 error to be spent



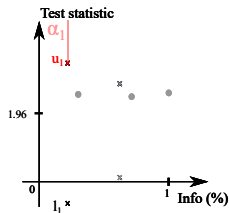
**x-axis:** information fraction  $\mathcal{I}^{\%} = \mathcal{I}_k / \mathcal{I}_{\max}$

**Key result:**  $(\hat{\theta}_1, \hat{\theta}_2, \hat{\theta}_3)$  are asymptotically multivariate normal  
 → numerical integration of the multivariate Gaussian density

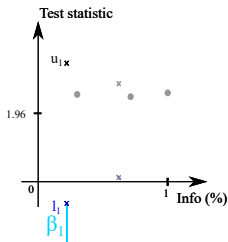
## Boundary with method 1 (stage 1)

At any interim analysis 1

Efficacy boundary

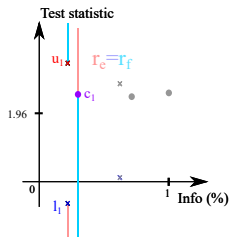


Futility boundary



At the decision analysis 1

Decision boundary



$$\mathbb{P}_0[Z_1 \geq u_1] = f(\mathcal{I}_1^{\%})$$

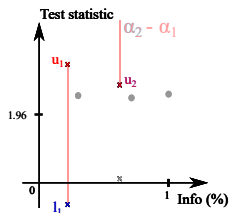
$$\mathbb{P}_{\theta_0}[Z_1 \leq l_1] = g(\mathcal{I}_1^{\%})$$

$$\mathbb{P}_0[Z_1 \geq u_1, \tilde{Z}_1 < c_1] = \mathbb{P}_0[Z_1 \leq l_1, \tilde{Z}_1 \geq c_1]$$

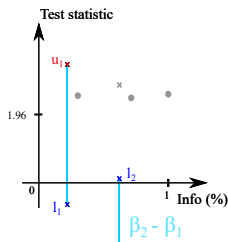
# Boundary with method 1 (stage 2)

At any interim analysis 2

Efficacy boundary

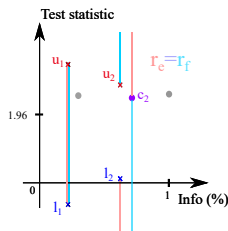


Futility boundary



At the decision analysis 2

Decision boundary



$$\mathbb{P}_0[Z_1 \in ]l_1, u_1[, Z_2 \geq u_2] = f(\mathcal{I}_2^0) - f(\mathcal{I}_1^0)$$

$$\mathbb{P}_{\theta_0}[Z_1 \in ]l_1, u_1[, Z_2 \leq l_2] = g(\mathcal{I}_2^0) - g(\mathcal{I}_1^0)$$

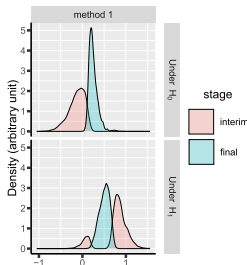
$$\mathbb{P}_0[Z_1 \in ]l_1, u_1[, Z_2 \geq u_2, \tilde{Z}_2 < c_2] = \mathbb{P}_0[Z_1 \in ]l_1, u_1[, Z_2 \leq l_2, \tilde{Z}_2 \geq c_2]$$

## Corrected point estimate

The standard maximum likelihood estimator (MLE) is biased.

Typically:

- positive bias for  $\theta > 0$
- negative bias for  $\theta < 0$



There is no uniformly minimum variance unbiased estimator for  $\theta$

Median unbiased estimator (MUE) is easy to compute

$$\text{Find } \theta' \text{ solving } \mathbb{P}_{\theta'} \left[ \left( \kappa, \tilde{Z}_{\kappa} \right) \succeq (k^*, \tilde{z}^*) \right] = 0.5$$

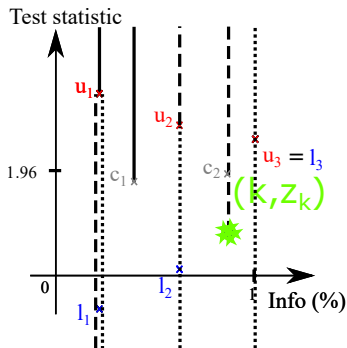
## Simulation setting

Inspired by a real dataset from Lundbeck

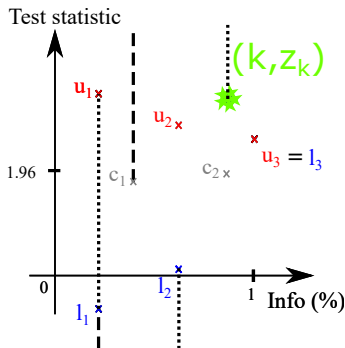
- $K = 2$  or  $K = 3$
- $n_K \in [491, 557]$ ,  
from a power calculation to get 80% power with method 3
- $\hat{\theta}$ : MLE from a linear mixed model
- 3 measurements:  $(Y_0, Y_1, Y_2)$ , correlation range  $[-0.15, 0.68]$
- group difference:  $(0, 0.3, 0.6)$
- about 10% observations with one or more missing values
- Information rate:  
2 stages  $\mathcal{I}_1^{\circ} = 58\%$ ,  $\tilde{\mathcal{I}}_1^{\circ} = 68\%$   
3 stages:  $\mathcal{I}_1^{\circ} = 40\%$ ,  $\tilde{\mathcal{I}}_1^{\circ} = 50\%$ ,  $\mathcal{I}_2^{\circ} = 65\%$ ,  $\tilde{\mathcal{I}}_2^{\circ} = 75\%$
- 10 000 datasets

## Modification for non-binding futility

When concluding futility at stage 2



+



## Modification for $c_k \geq \Phi^{-1}(1 - \alpha)$

With decision boundary  $\underline{c}_k = \max(c_k, \Phi^{-1}(1 - \alpha))$ ,

$\mathbb{P}_0 \left[ \left( \kappa, \tilde{Z}_\kappa - (\underline{c}_k - c_k) \right) \succeq (k, \tilde{z}_k) \right]$  is a conservative p-value.

