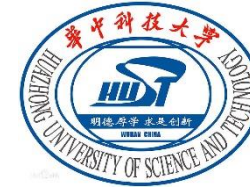


Paper No: 20PESGM0131

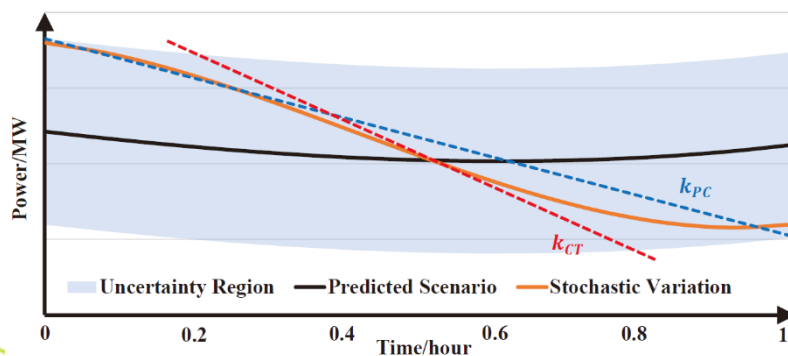


# Continuous-Trajectory Robust Unit Commitment Considering Beyond-the-Resolution Uncertainty

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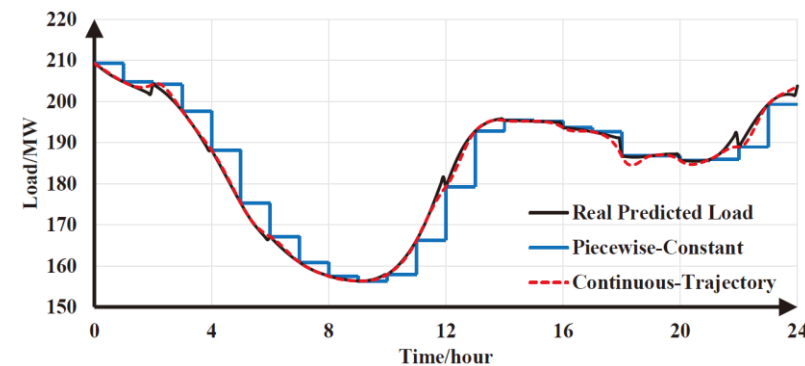
# Background

- Beyond-the-resolution (BtR) uncertainty
  - Renewable generation develops rapidly, yet its uncertainty challenges the power system operating security.
  - Existing piecewise-constant (PC) scheduling can not access the **power variation inside scheduling periods**, which is unreasonable when renewable penetration gets higher.
- Continuous-Trajectory (CT) Method
  - Derive an **analytical continuous trajectory** with more information to approximate the load curve for more accurate and secure scheduling.
  - Break scheduling horizon into some periods and use **Bernstein splines** to approximate BtR variation of each period.



$$B_{3,k}(t) = C_3^k t^k (1-t)^{3-k}, \quad k = 0, 1, 2, 3$$

$$P(t) = \sum_{k=0}^3 P^{Bk} B_{3,k}(t) = (\mathbf{P}^B)^T \mathbf{B}_3(t), \quad t \in [0, 1]$$



# Proposed method

- Basic BtR Variations
  - Any BtR variation can be linearly combined by Basic BtR Variations.

$$\begin{cases} (1-\gamma)P_{u0}(t) \leq P_u(t) \leq (1+\gamma)P_{u0}(t) \\ P_u(t) = (P_u^B)^T B_3(t), P_{u0}(t) = (P_{u0}^B)^T B_3(t) \end{cases}$$

$$\begin{cases} [(1-\gamma)P_{u0}^B - P_u^B]^T B_3(t) \leq 0 \\ [P_u^B - (1+\gamma)P_{u0}^B]^T B_3(t) \leq 0 \end{cases}$$

$$\begin{cases} \max\{(1-\gamma)P_{u0}^B - P_u^B\} \leq 0 \\ \max\{P_u^B - (1+\gamma)P_{u0}^B\} \leq 0 \end{cases}$$

$$(1-\gamma)P_{u0}^B \leq P_u^B \leq (1+\gamma)P_{u0}^B$$

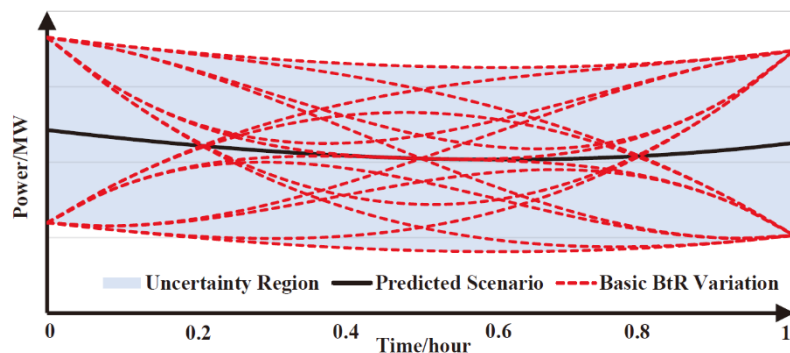
$$\begin{cases} P_u^B = [P_{u,e1}^B \ P_{u,e2}^B \ \dots \ P_{u,eN}^B] \omega \\ \omega \geq 0, \mathbf{1}^T \omega \leq 1 \end{cases}$$

$$\begin{cases} P_{u,en}^{Bk} = P_{u0}^{Bk} + \alpha_k \gamma P_{u0}^{Bk} - (1-\alpha_k) \gamma P_{u0}^{Bk}, k=0,1,2,3 \\ n=1+\alpha_0+2\alpha_1+4\alpha_2+8\alpha_3, \alpha_k \in \{0,1\} \end{cases}$$

$$P_u(t) = (P_u^B)^T B_3(t) = ([P_{u,e1}^B \ P_{u,e2}^B \ \dots \ P_{u,eN}^B] \omega)^T B_3(t)$$

$$= \omega^T [P_{u,e1}^B \ P_{u,e2}^B \ \dots \ P_{u,eN}^B]^T B_3(t) = \sum_{n=1}^N \omega_n P_{u,en}(t)$$

convex hull property



- CT Robust UC (CT-RUC)
  - CT-RUC can be shifted from the time domain to the time-function space for tractable computation.

$$\begin{cases} G(t) = 0 \Rightarrow \mathbf{G}^B = 0 \\ G(t) \leq 0 \Rightarrow \mathbf{G}^B \leq 0 \\ \int_0^T G(t) dt = (G^{B0} + G^{B1} + G^{B2} + G^{B3})T/4 \end{cases}$$

$$\mathbf{g}(\mathbf{x}(\tau), \mathbf{y}(\tau), \mathbf{u}(\tau)) \leq 0 \xrightarrow{\text{red arrow}} \mathbf{Ax} + \mathbf{By} + \mathbf{Cu} \leq \mathbf{D}$$

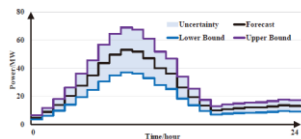
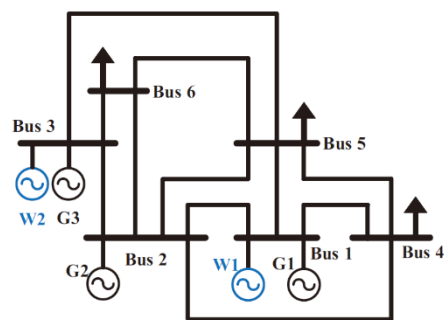
**CT-RUC:**  $\min \sum_t \sum_i (C_{suit} + C_{sdit} + C_{fuel,it}^E)$

$$s.t. \mathbf{Ax} + \mathbf{By}^E + \mathbf{Cu}^E \leq \mathbf{D}$$

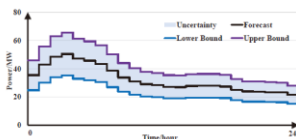
$$\mathbb{F} = \left\{ \mathbf{x} \mid \mathbb{U} = \{ \mathbf{u} \mid (1-\gamma)P_{u0,it}^B \leq P_{uit}^B \leq (1+\gamma)P_{u0,it}^B \} \right. \\ \left. \forall \mathbf{u} \in \mathbb{U}, \exists \mathbf{y}, \text{ such that } \mathbf{Ax} + \mathbf{By} + \mathbf{Cu} \leq \mathbf{D} \right\}$$

# Case studies

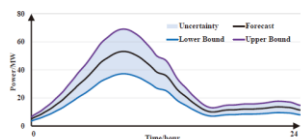
- Case settings
- Simulation results



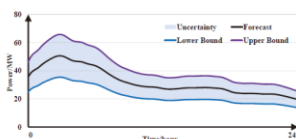
(a) Wind Farm1 in PC-RUC



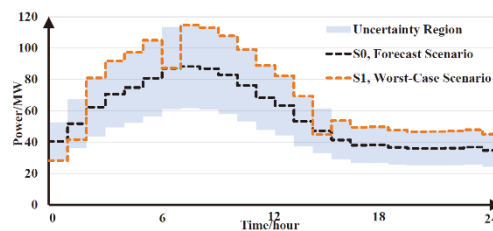
(b) Wind Farm2 in PC-RUC



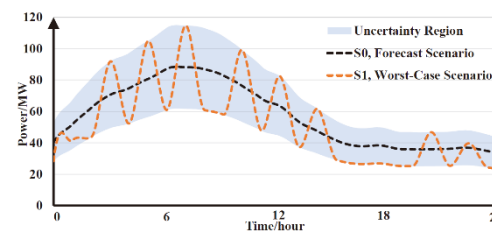
(c) Wind Farm1 in CT-RUC



(d) Wind Farm2 in CT-RUC



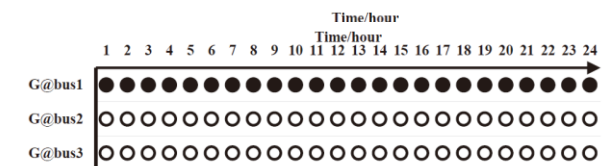
(a) PC-RUC



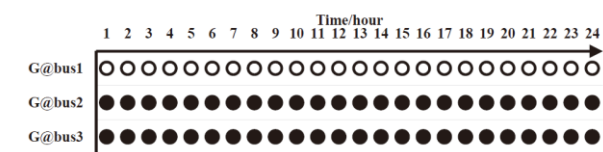
(b) CT-RUC

Scheduling scheme	PC	CT
Load demand/MWh	4427.33	4423.79
Wind energy/MWh	1368.50	1365.74
Unit generation/MWh	3058.83	3058.05
Iteration number of C&CG	2	2
Computation time/s	1.40	5.68
Startup/shutdown Number	0	0
Online-unit-time/hour	24	48
Total cost in forecast scenario/\$	43054.34	44639.83
Startup/shutdown cost in forecast scenario/\$	0	0
Fuel cost in forecast scenario/\$	43054.34	44639.83
Robustness in 10000 test scenarios	31.82%	100%

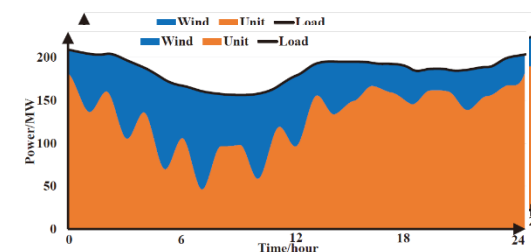
CT-RUC is much more robust!



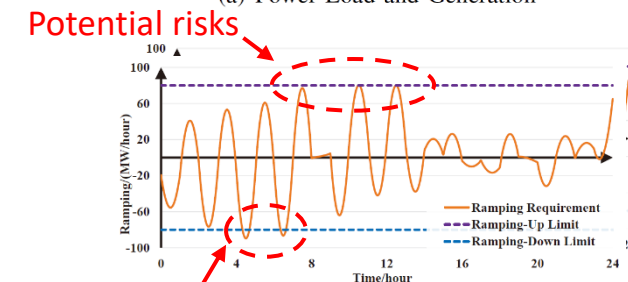
(a) PC-RUC



(b) CT-RUC



(a) Power Load and Generation



(b) Ramping Requirement

Ramping scarcity events

# Conclusions

- This paper proposes the continuous-trajectory robust unit commitment considering the beyond-the-resolution uncertainty in the computationally tractable formulation. With the BtR uncertainty considered, the proposed CT-RUC can provide a **more robust solution than traditional PC-RUC**, especially in the high renewable energy penetrated power system. The numerical comparison between PC-RUC and CT-RUC demonstrates that,
  - in CT-RUC, the worse scenario with the BtR variation is considered, and **sufficient ramping capacity** is scheduled.
  - The **robustness** of the proposed CT-RUC is **higher** than that of traditional PC-RUC.
- Future works include **more accurate modeling** of CT-RUC and the coordination of the operational security and economy under BtR uncertainties.