

RescueRobot::get_repaired
ThisRound



```
graph LR; A[RescueRobot::export_info] --> B[RescueRobot::get_repaired ThisRound];
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The box on the left is shaded gray and contains the text 'RescueRobot::get_repaired' on the top line and 'ThisRound' on the bottom line. The box on the right is white and contains the text 'RescueRobot::export_info'. A dark blue arrow points from the right side of the white box to the left side of the gray box.

RescueRobot::export_info